On the Tangent Space to the Space of Algebraic Cycles on a Smooth Algebraic Variety

PUTangSp March 1, 2004

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PUTangSp March 1, 2004

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#### Abstract

In this work we shall propose definitions for the tangent spaces $T Z^{n}(X)$ and $T Z^{1}(X)$ to the groups $Z^{n}(X)$ and $Z^{1}(X)$ of 0 -cycles and divisors, respectively, on a smooth $n$-dimensional algebraic variety. Although the definitions are algebraic and formal, the motivation behind them is quite geometric and much of the text is devoted to this point. It is noteworthy that both the regular differential forms of all degrees and the field of definition enter significantly into the definition. An interesting and subtle algebraic point centers around the construction of the map $T \operatorname{Hilb}^{p}(X) \rightarrow T Z^{p}(X)$. Another interesting algebraic/geometric point is the necessary appearance of spreads and absolute differentials in higher codimension.

For an algebraic surface $X$ we shall also define the subspace $T Z_{\text {rat }}^{2}(X) \subset$ $T Z^{2}(X)$ of tangents to rational equivalences, and we shall show that there is a natural isomorphism $$
T_{f} C H^{2}(X) \cong T Z^{2}(X) / T Z_{\mathrm{rat}}^{2}(X)
$$ where the left hand side is the formal tangent space to the Chow groups defined by Bloch. This result gives a geometric existence theorem, albeit at the infinitesimal level. The "integration" of the infinitesimal results raises very interesting geometric and arithmetic issues that are discussed at various places in the text.


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## Chapter One

## Introduction

### 1.1 GENERAL COMMENTS

In this work we shall define the tangent spaces

$$
T Z^{n}(X)
$$

and

$$
T Z^{1}(X)
$$

to the spaces of 0 -cycles and of divisors on a smooth, $n$-dimensional complex algebraic variety $X$. We think it may be possible to use similar methods to define $T Z^{p}(X)$ for all codimensions, but we were not able to do this because of one significant technical point. Although the final definitions, as given in sections 7 and 8 below, are algebraic and formal the motivation behind them is quite geometric. This is explained in the earlier sections; we have chosen to present the exposition in the monograph following the evolution of our geometric understanding of what the tangent spaces should be rather than beginning with the formal definition and then retracing the steps leading to the geometry.

Briefly, for 0-cycles an arc is in $Z^{n}(X)$ is given by $\mathbb{Z}$-linear combination of arcs in the symmetric products $X^{(d)}$, where such an arc is given by a smooth algebraic curve $B$ together with a regular map $B \rightarrow X^{(d)}$. If $t$ is a local uniformizing parameter on $B$ we shall use the notation $t \rightarrow x_{1}(t)+\cdots+x_{d}(t)$ for the arc in $X^{(d)}$. Arcs in $Z^{n}(X)$ will be denoted by $z(t)$. We set $|z(t)|=$ support of $z(t)$, and if $o \in B$ is a reference point we denote by $Z_{\{x\}}^{n}(X)$ the subgroup of arcs in $Z^{n}(X)$ with $\lim _{t \rightarrow 0}|z(t)|=x$. The tangent space will then be defined to be

$$
T Z^{n}(X)=\left\{\operatorname{arcs} \text { in } Z^{n}(X)\right\} / \equiv_{1^{\text {st }}}
$$

where $\equiv_{1}$ st is an equivalence relation. Although we think it should be possible to define $\equiv_{1^{\text {st }}}$ axiomatically, as in differential geometry, we have only been able to do this in special cases.

Among the main points uncovered in our study we mention the following:
(a) The tangent spaces to the space of algebraic cycles is quite different from - and in some ways richer than - the tangent space to Hilbert schemes.

This reflects the group structure on $Z^{p}(X)$ and properties such as

$$
\left\{\begin{array}{l}
(z(t)+\widetilde{z}(t))^{\prime}=z^{\prime}(t)+\widetilde{z}^{\prime}(t)  \tag{1.1}\\
(-z(t))^{\prime}=-z^{\prime}(t)
\end{array}\right.
$$

where $z(t)$ and $\widetilde{z}(t)$ are $\operatorname{arcs}$ in $Z^{p}(X)$ with respective tangents $z^{\prime}(t)$ and $\widetilde{z}^{\prime}(t)$. As a simple illustration, on a surface $X$ an irreducible curve $Y$ with a normal vector field $\nu$ may be obstructed in $\operatorname{Hilb}^{1}(X)-$ e.g., the $1^{\text {st }}$ order variation of $Y$ in $X$ given by $\nu$ may not be extendable to $2^{\text {nd }}$ order. However, considering $Y$ in $Z^{1}(X)$ as a codimension- 1 cycle the $1^{\text {st }}$ order variation given by $\nu$ extends to $2^{\text {nd }}$ order. In fact, it can be shown that both $T Z^{1}(X)$ and $T Z^{n}(X)$ are smooth, in the sense that for $p=1, n$ every map $\operatorname{Spec}\left(\mathbb{C}[\epsilon] / \epsilon^{2}\right) \rightarrow Z^{p}(X)$ is tangent to a geometric arc in $Z^{p}(X)$.

For the second point, it is well known that algebraic cycles in codimension $p \geqq 2$ behave quite differently from the classical case $p=1$ of divisors. It turns out that infinitesimally this difference is reflected in a very geometric and computable fashion. In particular,
(b) The differentials $\Omega_{X / \mathbb{C}}^{k}$ for all degrees $k$ with $1 \leq k \leq n$ necessarily enter into the definition of $T Z^{n}(X)$.

Remark that a tangent to the Hilbert scheme at a smooth point is uniquely determined by evaluating 1 -forms on the corresponding normal vector field to the subscheme. However, for $Z^{n}(X)$ the forms of all degrees are required to evaluate on a tangent vector, and it is in this sense that again the tangent space to the space of 0-cycles has a richer structure than the Hilbert scheme. Moreover, we see in (b) that the geometry of higher codimensional algebraic cycles is fundamentally different from that of divisors.

A third point is the following: For an algebraic curve one may give the definition of $T Z^{1}(X)$ either complex-analytically or algebro-geometrically with equivalent end results. However, it turns out that
(c) For $n \geq 2$, even if one is only interested in the complex geometry of $X$ the field of definition of an arc $z(t)$ in $Z^{n}(X)$ necessarily enters into the description of $z^{\prime}(0)$.

Thus, although one may formally define $T Z^{n}(X)$ in the analytic category, it is only in the algebraic setting that the definition is satisfactory from a geometric perspective. One reason is the following: Any reasonable set of axiomatic properties on first order equivalence of arcs in $Z^{n}(X)$ - including (1.1) above - leads for $n \geqq 2$ to the defining relations for absolute Kähler differentials (cf. section 6.2 below). However, only in the algebraic setting is it the case that the sheaf of Kähler differentials over $\mathbb{C}$ coincides with the sheaf of sections of the cotangent bundle (essentially, one cannot differentiate an infinite series term by term using Kähler differentials). For subtle geometric reasons, (b) and (c) turn out to be closely related.
(d) A fourth significant difference between divisors and higher codimensional cycles is the following: For divisors it is the case that

$$
\text { If } z_{u_{k}} \equiv_{\text {rat }} 0 \text { for a squence } u_{k} \text { tending to } 0 \text {, then } z_{0} \equiv_{\text {rat }} 0 \text {. }
$$

For higher codimension this is false; rational equivalence has an intrinsic "graininess" in codimension $\geqq 2$. If one enhances rational equivalence by closing it up under this property, one obtains the kernel of the Abel-Jacobi map. As will be seen in the text, this graininess in codimension $\geqq 2$ manifests itself in the tangent spaces to cycles in that absolute differentials appear. This is related to the spread construction referred to later in this introduction.
(e) Although creation/annihilation arcs are present for divisors on curves they play a relatively inessential role. However, for $n \geqq 2$ it is crucial to understand the infinitesimal behaviour of creation/annihilation arcs as these represent the tangencies to "irrelevant" rational equivalences which, in some sense, are the key new apsects in the study of higher codimensional cycles.

One may of course quite reasonably ask:
Why should one want to define $T Z^{p}(X)$ ?
One reason is that we wanted to understand if there is geometric significance to Spencer Bloch's expression for the formal tangent space to the higher Chow groups, in which absolute differentials mysteriously appear. One of our main results is a response to this question, given by Theorem (8.47) in section 8.3 below. A perhaps deeper reason is the following: The basic Hodge-theoretic invariants of an algebraic cycle are expressed by integrals which are generally transcendental functions of the algebraic parameters describing the cycle. Some of the most satisfactory studies of these integrals have been when they satisfy some sort of functional equation, as is the situation for elliptic functions. However, this will not be the case in general. The other most fruitful approach has been by infinitesimal methods, such as the Picard-Fuchs differential equations and infinitesimal period relations (including the infinitesimal form of functional equations), both of which are of an algebraic character. Just as the infinitesimal period relations for variation of Hodge structure are expressed in terms of the tangent spaces to moduli, it seemed to us desirable to be able to express the infinitesimal Hodge-theoretic invariants of an algebraic cycle - especially those beyond the usual Abel-Jacobi images - in terms of the tangent spaces to cycles. In this monograph we will give such an expression for 0-cycles on a surface.

In the remainder of this introduction we shall summarize the different sections of this paper and in so doing explain in more detail the above points.

In section 2 we begin by defining $T Z^{1}(X)$ when $X$ is a smooth algebraic curve, a case that is both suggestive and misleading. Intuitively, we consider arcs $z(t)$ in the space $Z^{1}(X)$ of 0 -cycles on $X$, and we want to define an equivalence relation $\equiv_{1}$ st on such arcs so that

$$
T Z^{1}(X)=\left\{\text { set of } \operatorname{arcs} \text { in } Z^{1}(X)\right\} / \equiv_{1^{\text {st }}} .
$$

The considerations are clearly local, ${ }^{1}$ and locally we may take

$$
z(t)=\operatorname{div} f(t)
$$

[^0]where $f(t)$ is an arc in $\mathbb{C}(X)^{*}$. We set $|z(t)|=$ "support of $z(t)$ " and assume that $\underset{t}{\rightarrow} 0 \rightarrow \lim |z(t)|=x$. Writing $f(t)=f+t g+\cdots$ elementary geometric considerations suggest that, with the obvious notation, we should define
$$
\operatorname{div} f(t) \equiv_{1^{\text {st }}} \operatorname{div} \widetilde{f}(t) \Leftrightarrow[g / f]_{x}=[\widetilde{g} / \widetilde{f}]_{x}
$$
where $[h]_{x}$ is the principal part of the rational function $h$ at the point $x \in X$. Thus, letting $T_{\{x\}} Z^{1}(X)=: T Z_{\{x\}}^{1}(X)$ be the tangents to $\operatorname{arcs} z(t)$ with $\lim _{t \rightarrow 0}|z(t)|=x$, we have as a provisional description
\[

$$
\begin{equation*}
T_{\{x\}} Z^{1}(X)=\mathcal{P} \mathcal{P}_{X, x} \tag{1.2}
\end{equation*}
$$

\]

where $\mathcal{P} \mathcal{P}_{X, x}=\underline{\mathbb{C}}(X)_{x} / \mathcal{O}_{X, x}$ is the stalk at $x$ of the sheaf of principal parts.
Another possible description of $T_{\{x\}} Z^{1}(X)$ is suggested by the classical theory of abelian sums. Namely, working in a neighborhood of $x \in X$ and writing

$$
z(t)=\sum_{i} n_{i} x_{i}(t)
$$

for $\omega \in \Omega_{X / \mathbb{C}, x}^{1}$ we set

$$
I(z, \omega)=\frac{d}{d t}\left(\sum_{i} n_{i} \int_{x}^{x_{i}(t)} \omega\right)_{t=0}
$$

Then $I(z, \omega)$ should depend only on the equivalence class of $z(t)$, and in fact we show that

$$
I(z, \omega)=\operatorname{Res}_{x}\left(z^{\prime} \omega\right)
$$

where $z^{\prime} \in \mathcal{P} \mathcal{P}_{X, x}$ is the tangent to $z(t)$ using the description (1.2). This leads to a non-degenerate pairing

$$
T_{\{x\}} Z^{1}(X) \otimes_{\mathbb{C}} \Omega_{X / \mathbb{C}, x}^{1} \rightarrow \mathbb{C}
$$

so that with either of the above descriptions we have

$$
\begin{equation*}
T_{\{x\}} Z^{1}(X) \cong \operatorname{Hom}_{\mathbb{C}}^{c}\left(\Omega_{X / \mathbb{C}, x}^{1}, \mathbb{C}\right) \tag{1.3}
\end{equation*}
$$

where $\operatorname{Hom}_{\mathbb{C}}^{c}\left(\Omega_{X / \mathbb{C}, x}^{1}, \mathbb{C}\right)$ are the continuous homomorphisms in the $\mathfrak{m}_{x}$-adic topology.

Now (1.3) suggests "duality", and indeed it is easy to see that a third possible description

$$
\begin{equation*}
T_{\{x\}} Z^{1}(X) \cong \lim _{i \rightarrow \infty} \mathcal{E} x t_{\mathcal{O}_{X, x}}^{1}\left(\mathcal{O}_{X} / \mathfrak{m}_{x}^{i}, \mathcal{O}_{X}\right) \tag{1.4}
\end{equation*}
$$

is valid. Of the three descriptions (1.2)-(1.4) of $T_{\{x\}} Z^{1}(X)$, it will turn out that (1.3) and (1.4) suggest the correct extensions to the case of 0 -cycles on $n$-dimensional varieties. However, the extension is not straightforward. For example, one might suspect that similar consideration of abelian sums
also denote by $\mathbb{C}(X)$ the field of rational functions on $X$, with $\mathbb{C}(X)^{*}$ being the multiplicative group of non-zero functions.
would lead to the description (1.3) using 1-forms in general. For interesting geometric reasons, this turns out not to be correct, since as was suggested above and will be explained below, the correct notion of abelian sums will involve integrals of differential forms of all degrees. Thus, on a smooth variety of dimension $n$ the analogue of the right hand side of (1.3) will only give part of the tangent space.

As will be explained below, (1.4) also extends but again not in the obvious way. The correct extension which gives the formal definitions of the tangent spaces $T_{\{x\}} Z^{n}(X)$ and tangent sheaf $\underline{\underline{T}} Z^{n}(X)$ is

$$
\begin{equation*}
T_{\{x\}} Z^{n}(X):=\lim _{i \rightarrow \infty} \mathcal{E} x t_{\mathcal{O}_{X, x}}^{n}\left(\mathcal{O}_{X} / \mathfrak{m}_{x}^{i}, \Omega_{X / \mathbb{Q}}^{n-1}\right) \tag{1.5}
\end{equation*}
$$

and

$$
\underline{\underline{T}}^{n} Z^{n}(X)={\underset{x \in X}{ }}^{\lim _{i \rightarrow \infty}} \underline{\underline{\varepsilon x t}}_{\mathcal{O}_{X}}^{n}\left(\mathcal{O}_{X} / \mathfrak{m}_{x}^{i}, \Omega_{X / \mathbb{Q}}^{n-1}\right)
$$

The geometric reasons why absolute differentials appear have to do with the points (b) and (c) above and will be discussed below.

The basic building blocks for 0 -cycles on a smooth variety $X$ are the configuration spaces consisting of sets of $m$ points $x_{i}$ on $X$. As a variety this is just the $m^{\text {th }}$ symmetric product $X^{(m)}$, whose points we write as effective 0 -cycles

$$
z=x_{1}+\cdots+x_{m} .
$$

We wish to study the geometry of the $X^{(m)}$ collectively, and for this one is interested in differential forms $\varphi_{m}$ on $X^{(m)}$ that have the hereditary property

$$
\begin{equation*}
\varphi_{m+1} \mid X_{x}^{(m)}=\varphi_{m} \tag{1.6}
\end{equation*}
$$

where for each fixed $x \in X$ the inclusion $X_{x}^{(m)} \hookrightarrow X^{(m+1)}$ is given by $z \rightarrow z+x$. One such collection of differential forms on the various $X^{(m)}$ 's is given by the traces $\operatorname{Tr} \varphi$ of a form $\varphi \in \Omega_{X / \mathbb{C}}^{q}$. Here, we come to the first geometric reason why forms of higher degree necessarily enter when $n \geqq 1$ :

$$
\begin{equation*}
\Omega_{X^{(m) / \mathbb{C}}}^{*} \text { is generated over } \mathcal{O}_{X^{(m)}} \text { by sums of elements of the form } \tag{1.7}
\end{equation*}
$$

$$
\operatorname{Tr} \omega_{1} \wedge \cdots \wedge \operatorname{Tr} \omega_{k}, \quad \omega_{i} \in \Omega_{X / \mathbb{C}}^{q_{i}}
$$

Moreover, we must add generators $\operatorname{Tr} \omega$ where $\omega \in \Omega_{X / \mathbb{C}}^{q}$ for all $q$ with $1 \leqq q \leqq n$ to reach all of $\Omega_{X^{(m)} / \mathbb{C}}^{*}$.
Of course, forms of higher degree are needed only in neighborhoods of singular points on the $X^{(m)}$, and for $n \geqq 2$ the singular locus is exactly the diagonals where two or more points coincide.

Put differently, the structure of point configurations is reflected by the geometry of the $X^{(m)}$. The infinitesimal structure of point configurations is then reflected along the diagonals where two or more points have come together and where the $X^{(m)}$ are singular for $n \geqq 2$. The geometric properties of point configurations is in turn reflected by the regular differential
forms on the symmetric products, particularly those having the hereditary property (1.6). There is new geometric information measured by the traces of $q$-forms for each $q$ with $1 \leqq q \leqq n$, and thus the definition of the tangent space to 0-cycles should involve the differential forms of all degrees. This is clearly illustrated by the coordinate calculations given in section 3.

What is this new geometric information reflected by the differential forms of higher degree? One answer stems from E. Cartan, who taught us that when there are natural parameters in a geometric structure then those parameters should be included as part of that structure. In the present situation, if in terms of local uniformizing parameters on $B$ and on $X$ we represent arcs in the space of 0 -cycles as sums of Puiseaux series, then the coefficients of these series provide natural parameters for the space of arcs in $Z^{n}(X)$. It turns out that for $n \geqq 2$ there is new infinitesimal information in these parameters arising from the higher degree forms on $X$. This phenomenon occurs only in higher codimension and is an essential ingredient in the geometric understanding of the infinitesimal structure of higher codimensional cycles.

The traces of forms $\omega \in \Omega_{X / \mathbb{C}}^{q}$ give rise to what are provisionally called universal abelian invariants $\widetilde{I}(z, \omega)$ (cf. section 3 ), which in coordinates are certain expressions in the Puiseaux coefficients and their differentials of degree $q-1$. In order to define the relation of equivalence of arcs in the space of 0 -cycles what is needed is some way to map the $q-1$ forms in the Puiseaux coefficients to a fixed vector space; i.e., a method of comparing the infinitesimal structure at different arcs. Such a map exists, provided that instead of the usual differential forms we take absolute differentials. Recall that for any algebraic or analytic variety $Y$ and any subfield $k$ of the complex numbers we may define the Kähler differentials over $k$ of degree $r$, denoted $\Omega_{\mathcal{O}_{Y} / k}^{r}$. For any subvariety $W \subset Y$ there are restriction maps

$$
\Omega_{\mathcal{O}_{Y} / k}^{r} \rightarrow \Omega_{\mathcal{O}_{W} / k}^{r}
$$

Taking $W$ to be a point $y \in Y$ and the field $k$ to be $\mathbb{Q}$, since $\mathcal{O}_{y} \cong \mathbb{C}$ there is an evaluation map

$$
\begin{equation*}
e_{y}: \Omega_{\mathcal{O}_{Y, y} / \mathbb{Q}}^{r} \rightarrow \Omega_{\mathbb{C} / \mathbb{Q}}^{r} . \tag{1.9}
\end{equation*}
$$

Applying this when $Y$ is the space of Puiseaux coefficients, for an arc $z$ in the space of 0 -cycles and form $\omega \in \Omega_{\mathcal{O}_{X} / \mathbb{Q}}^{q}$ we may finally define the universal abelian invariants

$$
I(z, \omega)=e_{z} \widetilde{I}(z, \omega)
$$

Two $\operatorname{arcs} z$ and $\widetilde{z}$ are said to be geometrically equivalent to $1^{\text {st }}$ order, written $z \equiv_{1^{\text {st }}} \widetilde{z}$, if

$$
I(z, \omega)=I(\widetilde{z}, \omega)
$$

for all $\omega \in \Omega_{\mathcal{O}_{X} / \mathbb{Q}}^{q}$ and all $q$ with $1 \leqq q \leqq n$. It turns out that here it is sufficient to only consider $\omega \in \Omega_{X / \mathbb{Q}}^{n}$. The space is filtered with $G r^{q} \Omega_{X / \mathbb{Q}}^{n} \cong$ $\Omega_{\mathbb{C} / \mathbb{Q}}^{n-q} \otimes \Omega_{X / \mathbb{C}}^{1}$, and roughly speaking we may think of $\Omega_{X / \mathbb{Q}}^{n}$ as encoding

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the information in the $\Omega_{X / \mathbb{C}}^{q}$ 's for $1 \leqq q \leqq n$. Intuitively, $\equiv_{1^{\text {st }}}$ captures the invariant information in the differentials at $t=0$ of Puiseaux series, where the coefficients are differentiated in the sense of $\Omega_{\mathbb{C} / \mathbb{Q}}^{1}$. The simplest interesting case is when $X$ is a surface defined over $\mathbb{Q}, \xi$ and $\eta \in \mathbb{Q}(X)$ give local uniformizing parameters and $z(t)$ is an arc in $Z^{2}(X)$ given by

$$
z(t)=z_{+}(t)+z_{-}(t)
$$

where

$$
z_{ \pm}(t)=\left(\xi_{ \pm}(t), \eta_{ \pm}(t)\right)
$$

with

$$
\left\{\begin{aligned}
\xi_{ \pm}(t) & = \pm a_{1} t^{1 / 2}+a_{2} t+\cdots \\
\eta_{ \pm}(t) & = \pm b_{1} t^{1 / 2}+b_{2} t+\cdots
\end{aligned}\right.
$$

The information in the universal abelian invariants $I(z, \varphi)$ for $\varphi \in \Omega_{X / \mathbb{C}}^{1}$ is

$$
a_{1}^{2}, a_{1} b_{1}, b_{1}^{2} ; a_{2}, b_{2}
$$

The additional information in $I(z, \omega)$ for $\omega \in \Omega_{X / \mathbb{C}}^{2}$ is

$$
a_{1} d b_{1}-b_{1} d a_{1}
$$

which is not a consequence of the differentials of the $I(z, \varphi)$ 's for $\varphi \in \Omega_{X / \mathbb{C}}^{1}$.
We then give a geometric description of the tangent space as

$$
T Z^{n}(X)=\left\{\arcsin Z^{n}(X)\right\} / \equiv_{1^{\text {st }}}
$$

The calculations given in section 3 show that this definition is independent of the particular coordinate system used to define the space of Puiseaux coefficients. We emphasize that this is not the formal definition of $T Z^{n}(X)$ - that definition is given by (1.5), and as we shall show it is equivalent to the above geometric description.

So far this discussion applies to the analytic as well as to the algebraic category. However, only in the algebraic setting is it the case that

$$
\begin{equation*}
\Omega_{\mathcal{O}_{X} / \mathbb{C}}^{1} \cong \mathcal{O}_{X}\left(T^{*} X\right) \tag{1.10}
\end{equation*}
$$

i.e., only in the algebraic setting is it the case that Kähler differentials over $\mathbb{C}$ give the right geometric object. Thus, the above sleight of hand where we used Kähler differentials to define the universal abelian invariants

$$
I(z, \omega) \in \Omega_{\mathbb{C} / \mathbb{Q}}^{q-1}
$$

will only give the correct geometric notion in the algebraic category. In section 4 we give a heurestic, computational approach to absolute differentials. In particular we explain why (1.10) only works in the algebraic setting. The essential point is that the axioms for Kähler differentials extend to allow term by term differentiation of the power series expansion of an algebraic function, but this does not hold for a general analytic function.

In the algebraic setting $\Omega_{\mathcal{O}_{X} / \mathbb{Q}}^{1}=\Omega_{X / \mathbb{Q}}^{1}$, and there is an additional geometric interpretation of the "arithmetic part" $\Omega_{\mathbb{C} / \mathbb{Q}}^{1} \otimes \mathcal{O}_{X}$ of the absolute
differentials $\Omega_{X / \mathbb{Q}}^{1}$. This deals with the notion of a spread, and again in section 4 we give a heurestic, geometric discussion of this concept. Given a 0 -cycle $z$ on an algebraic variety $X$, both defined over a field $k$ that is finitely generated over $\mathbb{Q}$, the spread will be a family


$$
\mathcal{X}=\left\{X_{s}\right\}_{s \in S}, \mathcal{Z}=\left\{z_{s}\right\}_{s \in S}
$$

where $\mathcal{X}, \mathcal{Z}$, and $S$ are all defined over $\mathbb{Q}$ and $\mathbb{Q}(S) \cong k$, and where the fibre over a generic point $s_{0} \in S$ is our original $X$ and $z$. Roughly speaking we may think of spreads as arising from the different embeddings of $k$ into $\mathbb{C}$; thus, for $s \in S$ not lying in a proper subvariety defined over $\mathbb{Q}$ the algebraic properties of $X_{s}$ and $z_{s}$ are the same as those of $X$ and $z$. There is a canonical mapping

$$
\begin{equation*}
T_{s_{0}}^{*} S \rightarrow \Omega_{k / \mathbb{Q}}^{1} \tag{1.11}
\end{equation*}
$$

and under this mapping the extension class of

$$
0 \rightarrow \Omega_{k / \mathbb{Q}}^{1} \otimes_{k} \mathcal{O}_{X(k)} \rightarrow \Omega_{X(k) / \mathbb{Q}}^{1} \rightarrow \Omega_{X(k) / k}^{1} \rightarrow 0
$$

corresponds to the Kodaira-Spencer class of the family $\left\{X_{s}\right\}_{s \in S}$ at $s_{0}$. The facts that the spread gives in higher codimension the natural parameters of a cycle and that infinitesimally the spread is expressed in terms of $\Omega_{X / \mathbb{Q}}^{1}$ are two reasons why absolute differentials necessarily appear.

Using this discussion of absolute differentials and spreads in section 4 , in section 5 we turn to the geometric description of the tangent space $T Z^{n}(X)$ to the space of 0 -cycles or a smooth $n$-dimensional algebraic variety $X$. We say "geometric" because the formal algebraic definition of the tangent spaces $T Z^{n}(X)$ will be given in section 7 using an extension of the Ext construction discussed above in the $n=1$ case. This definition will then be proved to coincide with the description using the universal abelian invariants discussed above. In section 5 we give an alternate, intrinsic definition of the $I(z, \omega)$ 's based on functorial properties of absolute differentials.

In section 4 we have introduced absolute differentials as a means of mapping the differentials of the parameters of an $\operatorname{arc}$ in $Z^{n}(X)$ expressed in terms of local uniformizing parameters to a reference object. Geometrically, using (1.11) this construction reflects infinitesimal variation in the spread directions. Algebraically, for an algebraic variety $Y$ and point $y \in Y$, the evaluation mapping (1.9) is for $r=1$ given by

$$
f d g \xrightarrow{e_{y}} f(y) d(g(y))
$$

where $d=d_{\mathbb{C} / \mathbb{Q}}$ and $f, g \in \mathbb{C}(Y)$ are rational functions on $Y$ that are regular near $y$. If $Y$ is defined over $\mathbb{Q}$ and $f, g \in \mathbb{Q}(Y)$, then $e_{y}$ reflects the field of definition of $y$ - it is thus measuring arithmetic information.

One may reasonably ask: Is there an alternate, purely geometric way of defining $\equiv_{1^{\text {st }}}$ for arcs in $Z^{n}(X)$ that leads to absolute differentials? In other words, even if one is only interested in the complex geometry of the space of 0-cycles, is there a geometric reason why arithmetic considerations enter the picture? Although we have not been able to completely define $\equiv_{1^{\text {st }}}$ axiomatically, we suspect that this can be done and in a number of places we will show geometrically how differentials over $\mathbb{Q}$ necessarily arise.

For example, in section 6.2 we consider the free group $F$ generated by the $\operatorname{arcs}$ in $Z^{2}\left(\mathbb{C}^{2}\right)$ given by differences $z_{\alpha \beta}(t)-z_{1 \beta}(t)$ where $z_{\alpha \beta}(t)$ is the 0 -cycle given the equations

$$
z_{\alpha \beta}(t)=\left\{\begin{array}{l}
x^{2}-\alpha y^{2}=0 \\
x y-\beta t=0 .
\end{array}\right.
$$

There we list a set of "evident" geometric axioms for $1^{\text {st }}$ order equivalence of arcs in $F$, and then an elementary but somewhat intricate calculation shows that the map

$$
F / \equiv_{1^{\text {st }}} \rightarrow \Omega_{\mathbb{C} / \mathbb{Q}}^{1}
$$

given by

$$
z_{\alpha \beta}(t) \rightarrow \beta \frac{d \alpha}{\alpha} \quad\left(d=d_{\mathbb{C} / \mathbb{Q}}\right)
$$

is a well-defined isomorphism. Essentially, the condition that the tangent map be a homomorphism to a vector space that factors through the tangent map to the Hilbert scheme leads directly to the defining relations for absolute Kähler differentials.

Another example, one that will be used elsewhere in the monograph, begins with the observation that $Z^{n}(X)$ is the group of global sections of the Zariski sheaf

$$
\underset{x \in X}{\oplus} \mathbb{Z}_{x}
$$

Taking $X$ to be a curve we may consider the Zariski sheaf

$$
\underset{x \in X}{\oplus} \mathbb{C}_{x}^{*}
$$

whose global sections we denote by $Z_{1}^{1}(X)$. This sheaf arises naturally when one localizes the tame symbol mappings $T_{x}$ that arise in the Weil reciprocity law. In section 6.2 we give a set of geometric axioms on $\operatorname{arcs}$ in $Z_{1}^{1}(X)$ that define an equivalence relation yielding a description of the sheaf $\underline{\underline{\underline{T}}} Z_{1}^{1}(X)$ as

$$
\underline{\underline{T}} Z_{1}^{1}(X) \cong \underset{x \in X}{\oplus}{\underline{\underline{\operatorname{Hom}^{2}}}}^{o}\left(\Omega_{X / \mathbb{Q}, x}^{1}, \Omega_{\mathbb{C} / \mathbb{Q}}^{1}\right)
$$

here $\operatorname{Hom}^{o}\left(\Omega_{X / \mathbb{Q}, x}^{1}, \Omega_{\mathbb{C} / \mathbb{Q}}^{1}\right)$ are the continuous $\mathbb{C}$-linear homomorphims $\Omega_{X / \mathbb{Q}, x}^{1} \xrightarrow{\varphi} \Omega_{\mathbb{C} / \mathbb{Q}}^{1}$ that satisfy

$$
\varphi(f \alpha)=\varphi_{0}(f) \alpha
$$

where $f \in \mathcal{O}_{X, x}, \alpha \in \Omega_{\mathbb{C} / \mathbb{Q}}^{1}$ and $\varphi_{0}: \mathcal{O}_{X, x} \rightarrow \mathbb{C}$ is a continuous $\mathbb{C}$-linear homomorphism. The point is that again purely geometric considerations lead naturally to differentials over $\mathbb{Q}$. Essentially, the reason again comes down to the assumption that

$$
(z \pm \widetilde{z})^{\prime}=z^{\prime} \pm \widetilde{z}^{\prime}
$$

i.e., the tangent map should be a homomorphism from $\operatorname{arcs}$ in $Z_{1}^{1}(X)$ to a vector space.

In (d) at the beginning of the introduction we mentioned different limiting properties of rational equivalence for divisors and higher codimensional cycles. One property that our tangent space construction has is the following: Let $z_{u}(t)$ be a family of arcs in $Z^{p}(X)$. Then

$$
\text { If } z_{u}^{\prime}(0)=0 \text { for all } u \neq 0, \text { then } z_{0}^{\prime}(0)=0
$$

Once again the statement

$$
\lim z_{u_{k}}^{\prime}(0)=0 \text { for a sequence } u_{k} \rightarrow 0 \text { implies that } z_{0}^{\prime}(0)=0
$$

is true for divisors but false in higher codimension. The reason is essentially this: Any algebraic construction concerning algebraic cycles survives when we take the spread of the variety together with the cycles over their field of definition. Geometric invariants arising in the spread give invariants of the original cycle. Infinitesimally, related to (b) above there is in higher codimensions new information arising from evaluating $q$-forms $(q \geqq 2)$ on multivectors $v \wedge w_{1} \wedge \cdots \wedge w_{q-1}$ where $v$ is the tangent to the arc in the usual "geometric" sense and $w_{1}, \ldots, w_{q-1}$ are tangents in the spread directions. Thus arithmetic considerations appear at the level of the tangent space to cycles (we did not expect this) and survive in the tangent space to Chow groups where they appear in Bloch's formula.

Above, we mentioned the tame symbol $T_{x}(f, g) \in \mathbb{C}^{*}$ of $f, g \in \mathbb{C}(X)^{*}$. It has the directly verified properties

$$
\left\{\begin{array}{l}
T_{x}\left(f^{m}, g\right)=T_{x}(f, g)^{m} \text { for } m \in \mathbb{Z} \\
T_{x}\left(f_{1} f_{2}, g\right)=T_{x}\left(f_{1}, g\right) T_{x}\left(f_{2}, g\right) \\
T_{x}(f, g)=T_{x}(g, f)^{-1} \\
T_{x}(f, 1-f)=1
\end{array}\right.
$$

which show that the tame symbol gives mappings

$$
T_{x}: K_{2}(\mathbb{C}(X)) \rightarrow \mathbb{C}^{*}, \text { and } T: K_{2}(\mathbb{C}(X)) \rightarrow \underset{x}{\oplus} \mathbb{C}_{x}^{*}
$$

A natural question related to the definition of $\underline{\underline{T}} Z_{1}^{1}(X)$ is:
What is the differential of the tame symbol?
According to van der Kallen [12], for any field or local ring $F$ in characteristic zero the formal tangent space to $K_{2}(F)$ is given by

$$
\begin{equation*}
T K_{2}(F) \cong \Omega_{F / \mathbb{Q}}^{1} \tag{1.12}
\end{equation*}
$$

Thus, we are seeking to calculate

$$
\Omega_{\mathbb{C}(X) / \mathbb{Q}}^{1} \stackrel{d}{T}_{x} \rightarrow \operatorname{Hom}^{o}\left(\Omega_{X / \mathbb{Q}, x}^{1}, \Omega_{\mathbb{C} / \mathbb{Q}}^{1}\right)
$$

In part (iii) of section 6 we give this evaluation in terms of residues; this calculation again illustrates the linking of arithmetic and geometry. As an aside, we also show that the infinitesimal form of the Weil and Suslin reciprocity laws follow from the residue theorem.

Beginning with the work of Bloch, Gersten and Quillen (cf. [5] and [16]) one has understood that there is an intricate relationship between $K$-theory and higher codimensional algebraic cycles. For $X$ an algebraic curve, the Chow group $C H^{1}(X)$ is defined as the cokernel of the mapping obtained by taking global sections of the surjective mapping of Zariski sheaves

$$
\begin{equation*}
\underline{\underline{\mathbb{C}}}(X)^{*} \xrightarrow{\text { div }} \underset{x \in X}{\oplus} \underline{\underline{Z}}_{x} \rightarrow 0 \tag{1.13}
\end{equation*}
$$

This sheaf sequence completes to the exact sequence

$$
\begin{equation*}
0 \rightarrow \mathcal{O}_{X}^{*} \rightarrow \underset{\underline{\mathbb{C}}}{ }(X)^{*} \rightarrow \underset{x \in X}{\oplus_{\underline{Z}}} \rightarrow 0 \tag{1.14}
\end{equation*}
$$

and the exact cohomology sequence gives the well-known identification

$$
\begin{equation*}
C H^{1}(X) \cong H^{1}\left(\mathcal{O}_{X}^{*}\right) \tag{1.15}
\end{equation*}
$$

For $X$ an algebraic surface, the analogue of (1.13) is

$$
\begin{equation*}
\underset{\substack{Y \text { irred } \\ \text { curve }}}{\oplus} \stackrel{\mathbb{C}}{=}(Y)^{*} \xrightarrow{\text { div }} \underset{x \in X}{\oplus}{\underset{\underline{Z}}{x}}^{\underline{Z}} \rightarrow 0 \tag{1.16}
\end{equation*}
$$

Whereas the kernel of the map in (1.13) is evidently $\mathcal{O}_{X}^{*}$, for (1.16) it is a non-trivial result that the kernel is the image of the map

$$
\underline{\underline{K}}_{2}(\mathbb{C}(X)) \xrightarrow{T} \underset{\substack{Y \\ \text { curve } \\ \text { curred }}}{\oplus} \mathbb{C}(Y)^{*}
$$

given by the tame symbol. It is at this juncture that $K$-theory enters the picture in the study of higher codimension algebraic cycles. The sequence (1.16) then completes to the analogue of (1.14), the Bloch-Gersten-Quillen exact sequence

$$
0 \rightarrow \mathcal{K}_{2}\left(\mathcal{O}_{X}\right) \rightarrow \underline{\underline{K}}_{2}(\mathbb{C}(X)) \rightarrow \underset{\substack{Y \\ \text { curve } \\ \text { curre }}}{\oplus} \mathbb{C}(Y)^{*} \rightarrow \underset{x \in X}{\oplus} \oplus_{x}^{\mathbb{Z}} \rightarrow 0
$$

which in turn leads to Bloch's analogue

$$
\begin{equation*}
C H^{2}(X) \cong H^{2}\left(\mathcal{K}_{2}\left(\mathcal{O}_{X}\right)\right) \tag{1.17}
\end{equation*}
$$

of (1.15) which opened up a whole new perspective in the study of algebraic cycles.

The infinitesimal form of (1.17) is also due to Bloch (cf. [4] and [27]) with important amplifications by Stienstra [6]. In this work the van der Kallen result is central. Because it is important for our work to understand in detail the infinitesimal properties of the Steinberg relations that give the (Milnor)
$K$-groups, we have in the appendix to section 6 given the calculations that lie behind (1.12). At the end of this appendix we have amplified on the above heuristic argument that shows from a geometric perspective how $K$ theory and absolute differentials necessarily enter into the study of higher codimensional algebraic cycles.

In section 7 we give the formal definition

$$
\underline{\underline{T}} Z^{2}(X)=\lim _{\substack{Z \text { codim } 2 \\ \text { subscheme }}} \mathcal{E x} t_{\mathcal{O}_{X}}^{2}\left(\mathcal{O}_{Z}, \Omega_{X / \mathbb{Q}}^{1}\right)
$$

for the tangent sheaf to the sheaf of 0-cycles on a smooth algebraic surface $X$. We show that this is equivalent to the geometric description discussed above. Then, based on a construction of Angeniol and Lejeune-Jalabert [19], we define a map

$$
T \operatorname{Hilb}^{2}(X) \rightarrow T Z^{2}(X)
$$

thereby showing that the tangent to an arc in $Z^{2}(X)$ given as the image in $Z^{2}(X)$ of an arc in $\operatorname{Hilb}^{2}(X)$ depends only on the tangent to that arc in $T \operatorname{Hilb}^{2}(X)$.

In summary, the geometric description has the advantages

- it is additive
- it depends only on $z(t)$ as a cycle
- it depends only on $z(t)$ up to $1^{\text {st }}$ order in $t$
- it has clear geometric meaning.

It is however not clear that two families of effective cycles that represent the same element of $T \operatorname{Hilb}^{2}(X)$ have the same tangent under the geometric description. The formal definition has the properties

- it clearly factors through $T \operatorname{Hilb}^{2}(X)$
- it is easy to compute in examples.

But additivity does not make sense for arbitrary schemes, and in the formal definition it is not clear that $z^{\prime}(0)$ depends only on the cycle structure of $z(t)$. For this reason it is important to show their equivalence.

In section 8 we give the definitions of some related spaces, beginning with the definition

$$
\underline{\underline{T}} Z^{1}(X)=\lim _{\left\{\begin{array}{c}
\text { codim1 } \\
\text { subscheme }
\end{array}\right.} \mathcal{E} x t_{\mathcal{O}_{X}}^{2}\left(\mathcal{O}_{Z}, \mathcal{O}_{X}\right)
$$

for the sheaf of divisors on a smooth algebraic surface $X$. Actually, this definition contains interesting geometry not present for divisors on curves. In section 8.2 this geometry is discussed both directly and dually using differential forms and residues. As background for this, in the two appendices to section 8.2 we have given a review of duality with emphasis on how one may use the theory to compute in examples.

In section 8.2 we give the definition

$$
\underline{\underline{T}} Z_{1}^{1}(X)=\underset{\substack{Y \\ Y \text { codim } 1 \\ Y \text { ired }}}{\oplus} \underline{\underline{H}}_{y}^{1}\left(\Omega_{X / \mathbb{Q}}^{1}\right)
$$

for the tangent sheaf to the Zariski sheaf $\underset{Y}{\oplus} \underline{\underline{C}}(Y)^{*}$. Underlying this definition is an interesting mix of arithmetic and geometry which is illustrated in a number of examples. With this definition there is a natural map $\underline{\underline{T}} Z_{1}^{1}(X) \rightarrow$ $\underline{\underline{T}} Z^{2}(X)$ and passing to global sections we may define the geometric tangent space to the Chow group $C H^{2}(X)$ by

$$
T_{\text {geom }} C H^{2}(X)=T Z^{2}(X) / \text { image }\left\{T Z_{1}^{1}(X) \rightarrow T Z^{2}(X)\right\}
$$

Both the numerator and denominator on the RHS have geometric meaning and are amenable to computation in examples. The main result of this work is then given by the

Theorem: (i) There is a natural surjective map

$$
\binom{\arcsin }{\underset{Y}{\oplus} \underline{\underline{\mathbb{C}}}(Y)^{*}} \rightarrow \underline{\underline{T}} Z_{1}^{1}(X) .
$$

(ii) Denoting by $T_{\text {formal }} C H^{2}(X)$ the formal tangent space to the Chow group given by Bloch [4], [27], there is a natural identification

$$
T_{\text {geom }} C H^{2}(X) \cong T_{\text {formal }} C H^{2}(X)
$$

Contained in (i) and (ii) in this theorem is a geometric existence result, albeit at the infinitesimal level. The interesting but significant difficulties in "integrating" this result are discussed there and again in section 10.

In section 9 we give some applications and examples. Classically, on an algebraic curve Abel's differential equations - by which we mean the infinitesimal form of Abel's theorem - express the infinitesimal constraints that a 0 -cycle move in a rational equivalence class. An application of our work gives an extension of Abel's differential equations to 0 -cycles on an $n$-dimensional smooth variety $X$. For $X$ a regular algebraic surface defined over $\mathbb{Q}$ these conditions take the following form: Let $z=\sum_{i} x_{i}$ be a 0 -cycle, where for simplicity of exposition we assume that the $x_{i}$ are distinct. Given $\tau_{i} \in T_{x_{i}} X$ we ask when is

$$
\begin{equation*}
\tau=\sum_{i}\left(x_{i}, \tau_{i}\right) \in T Z^{2}(X) \tag{1.18}
\end{equation*}
$$

tangent to a rational equivalence? Here there are several issues that one does not see in the curve case. One is that because of the cancellation phenomenon in higher codimension discussed above it is essential to allow creation/annihilation arcs in $Z^{2}(X)$, so it is understood that a picture like

$$
\begin{aligned}
& x_{-}(t) \\
& \leftarrow \cdot \vec{~} \cdot \vec{~} \\
& x_{+}(t)
\end{aligned}
$$

$$
\left\{\begin{array}{l}
x(t)=x_{+}(t)-x_{-}(t) \\
x_{+}(0)=x_{-}(0) \text { and } \\
x_{+}^{\prime}(0)=-x_{-}^{\prime}(0)
\end{array}\right.
$$

is allowed, and a picture like

could be the tangent to a simple arc $x(t)$ in $X$ with $x(0)=x$ and $x^{\prime}(0)=\tau$, or it could be the tangent to an arc

$$
z(t)=x_{1}(t)+x_{2}(t)-x_{3}(t)
$$

where

$$
\left\{\begin{array}{l}
x_{1}(0)=x_{2}(0)=x_{3}(0)=x \\
x_{1}^{\prime}(0)+x_{2}^{\prime}(0)-x_{3}^{\prime}(0)=\tau
\end{array}\right.
$$

and so forth. ${ }^{2}$
Secondly, we can only require that $\tau$ be tangent to a first order arc in $Z_{\text {rat }}^{2}(X)$. Alternatively, we could require (i) that $\tau$ be tangent to a formal arc in $Z_{\text {rat }}^{2}(X)$, or (ii) that $\tau$ be tangent to a geometric arc in $Z_{\text {rat }}^{2}(X)$. There are heuristic geometric reasons that (i) may be the same as tangent to a $1^{\text {st }}$-order arcs, but although (ii) may be equivalent for 0 -cycles on a surface (essentially Bloch's conjecture), there are Hodge-theoretic reasons why for higher dimensional varieties the analogue of (ii) cannot in general be equivalent to tangency to a first order rational equivalence for general codimension 2 cycles (say, curves on a threefold). In any case, there are natural pairings

$$
\begin{equation*}
\langle,\rangle: \Omega_{X / \mathbb{Q}, x}^{2} \otimes T_{x} X \rightarrow \Omega_{\mathbb{C} / \mathbb{Q}}^{1} \tag{1.19}
\end{equation*}
$$

and the condition that (1.18) be tangent to a first order rational equivalence class is

$$
\begin{equation*}
\langle\omega, \tau\rangle=: \sum_{i}\left\langle\omega, \tau_{i}\right\rangle=0 \quad \text { in } \quad \Omega_{\mathbb{C} / \mathbb{Q}}^{1} \tag{1.20}
\end{equation*}
$$

for all $\omega \in H^{0}\left(\Omega_{X / \mathbb{Q}}^{2}\right)$. If the $x_{i} \in X(k)$ then the pairing (1.19) lies in $\Omega_{k / \mathbb{Q}}^{1}$.
At one extreme, if $z=\sum_{i} x_{i} \in Z^{2}(X(\overline{\mathbb{Q}}))$ then all $\left\langle\omega, \tau_{i}\right\rangle=0$ and the main theorem stated above gives a geometric existence result which is an infinitesimal version of the conjecture of Bloch-Beilinson [22]. At the other extreme, taking the $x_{i}$ to be independent transcendentals we obtain a quantitative version of the theorem of Mumford-Roitman (cf. [1] and [2]). In between, the behavior of how a 0-cycle moves infinitesimally in a rational equivalence class is very reminiscent of the behavior of divisors on curves where $h^{2,0}(X)$ together with $\operatorname{tr} \operatorname{deg}(k)$ play the role of the genus of the curve.

[^1]In section 9.2 we shall discuss the integration of Abel's differential equations. The exact meaning of "integration" will be explained there - roughly it means defining a Hodge-theoretic object $\mathcal{H}$ and map

$$
\begin{equation*}
\psi: Z^{n}(X) \rightarrow \mathcal{H} \tag{1.21}
\end{equation*}
$$

whose codifferential factors through the map

$$
T^{*} C H^{n}(X) \rightarrow T^{*} Z^{n}(X)
$$

For curves, denoting by $Z^{1}(X)_{0}$ the divisors of degree zero the basic classical construction is the pairing

$$
H^{0}\left(\Omega_{X / \mathbb{C}}^{1}\right) \otimes Z^{1}(X)_{0} \rightarrow \mathbb{C} \text { mod periods }
$$

given by

$$
\omega \otimes z \xrightarrow{\psi} \int_{\gamma} \omega, \quad \partial \gamma=z
$$

As $z$ varies along an arc $z_{t}$

$$
\frac{d}{d t}\left(\psi\left(\omega \otimes z_{t}\right)\right)=\left\langle\omega, z^{\prime}\right\rangle
$$

where the right hand side is the usual pairing

$$
H^{0}\left(\Omega_{X / \mathbb{C}}^{1}\right) \otimes T Z^{1}(X) \rightarrow \mathbb{C}
$$

of differential forms on tangent vectors. This of course suggests that the usual abelian sums should serve to integrate Abel's differential equations in the case of curves.

In [32] we have discussed the integration of Abel's differential equations in general. Here we consider the first non-classical case of a regular surface $X$ defined over $\mathbb{Q}$, and we shall explain how the geometric interpretation of (1.20) suggests how one may construct a map (1.21) in this case. What is needed is a pairing

$$
\begin{equation*}
H^{0}\left(\Omega_{X / \mathbb{C}}^{2}\right) \otimes Z^{2}(X)_{0} \rightarrow \int_{\Gamma} \omega \quad \text { mod periods } \tag{1.22}
\end{equation*}
$$

where $\Gamma$ is a (real) 2-dimensional chain that is constructed from $z$ using the assumptions that $\operatorname{deg} z=0$ and that $X$ is regular. If $z \in Z^{2}(X(k))_{0}$, then using the spread construction together with (1.10) we have a pairing

$$
\begin{equation*}
H^{0}\left(\Omega_{X / \mathbb{Q}}^{2}\right) \otimes T_{z} Z^{2}(X)_{0} \rightarrow T_{s_{0}}^{*} S \tag{1.23}
\end{equation*}
$$

which if we compare with (1.10) will, according to (1.19) and (1.20), give the conditions that $z$ move infinitesimally in a rational equivalence class. Writing (1.23) as a pairing

$$
H^{0}\left(\Omega_{X / \mathbb{Q}}^{2}\right) \otimes T Z^{2}(X) \otimes T S \rightarrow \mathbb{C}
$$

suggests in analogy to the curve case that in (1.21) the 2-chain $\Gamma$ should be traced out by 1-chains $\gamma_{s}$ in $X$ parametrized by a curve $\lambda$ in $S$. Choosing
$\gamma_{s}$ so that $\partial \gamma_{s}=z_{s}$ and taking for $\lambda$ a closed curve in $S$, we are led to set $\Gamma=\bigcup_{s \in \lambda} \gamma_{s}$ and define for $\omega \in H^{0}\left(\Omega_{X / \mathbb{C}}^{2}\right)$

$$
\begin{equation*}
I(z, \omega, \lambda)=\int_{\Gamma} \omega \quad \bmod \text { periods. } \tag{1.24}
\end{equation*}
$$

As is shown in section 9.2 this gives a differential character on $S$ that depends only on the $k$-rational equivalence class of $z .{ }^{3}$ If one assumes the conjecture of Bloch and Beilinson, then the triviality that of $I(z, \cdot, \cdot)$ implies that $z$ is rationally equivalent to zero; this would be an analogue of Abel's theorem for 0 -cycles on a surface.
In section 9.3 we give explicit computations for surfaces in $\mathbb{P}^{3}$ leading to the following results:

Let $X$ be a general surface in $\mathbb{P}^{3}$ of degree $d \geqq 5$. Then, for any point $p \in X$

$$
T_{p} X \cap T Z^{2}(X)_{\text {rat }}=0
$$

If $d \geqq 6$, then for any distinct points $p, q \in X$

$$
\left(T_{p} X+T_{q} X\right) \cap T Z^{2}(X)_{\text {rat }}=0 .
$$

The first statement implies that a general $X$ contains no rational curve i.e. a $g_{1}^{1}$ - which is a well known result of Clemens. The second statement implies that a general $X$ of degree $\geqq 6$ does not contain a $g_{2}^{1}$. It may well be that the method of proof can be used to show that for each integer $k$ there is a $d(k)$ such that for $d \geqq d(k)$ a general $X$ does not contain a $g_{k}^{1}$.
In the last subsection 4 in section 9 we discuss what seems to be the only non-classical case where the Chow group is explicitly known; namely, one has the isomorphism

$$
\begin{equation*}
G r^{2} C H^{2}\left(\mathbb{P}^{2}, T\right) \cong K_{2}(\mathbb{C}) \tag{1.25}
\end{equation*}
$$

due to Bloch and Suslin [26], [21]. We give a proof of (1.25) similar to that of Totaro [9], showing that it is a consequence of the Suslin reciprocity law together with elementary geometric constructions. This example was of particular importance to us as it was one where the infinitesimal picture could be understood explicitly. In particular, we show that if $\operatorname{tr} \operatorname{deg} k=1$ so that $S$ is an algebraic curve, the invariant (1.24) coincides with the regulator and the issue of whether it captures rational equivalence, modulo torsion, reduces to an analogue of a well known conjecture about the injectivity of the regulator.

In the last section we discuss briefly some of the larger issues that this study has raised. One is whether or not the space of codimension $p$ cycles $Z^{p}(X)$ is at least "formally reduced". That is, given a tangent vector $\tau \in$ $T Z^{p}(X)$, is there a formal $\operatorname{arc} z(t)$ in $Z^{p}(X)$ with tangent $\tau$ ? If so, is $Z^{p}(X)$

[^2]"actually reduced"; i.e., can we choose $z(t)$ to be a geometric arc? Here we are assuming that a general definition of $T Z^{p}(X)$ has been given extending that given in this work when $p=1$ and $p=n$, and that there is a natural map
$$
T \operatorname{Hilb}^{p}(X) \rightarrow T Z^{p}(X)
$$

The first part of the following proposition is proved in this work and the second is a result of Ting Fai Ng [39], the idea of whose proof is sketched in section 10 :

$$
\begin{equation*}
Z^{p}(X) \text { is reduced for } p=n, 1 \tag{1.26}
\end{equation*}
$$

What this means is that for $p=n, 1$ every tangent vector in $T Z^{p}(X)$ is the tangent to a geometric arc in $Z^{p}(X)$. For $p=n$ this is essentially a local result. However, for $p=1$ and $n \geqq 2$ it is well known that $\operatorname{Hilb}^{1}(X)$ may not be reduced. Already when $n=2$ there exist examples of a smooth curve $Y$ in an algebraic surface and a normal vector field $\nu \in H^{0}\left(N_{Y / X}\right)$ which is not tangent to a geometric definition of $Y$ in $X$; i.e., $\nu$ may be obstructed. However, when we consider $Y$ as a codimension one cycle on $X$ the above result implies that there is an arc $Z(t)$ in $Z^{1}(X)$ with

$$
\left\{\begin{array}{c}
Z(0)=Y \\
Z^{\prime}(0)=\nu ;
\end{array}\right.
$$

in particular, allowing $Y$ to deform as a cycle kills the obstructions.
For Hodge theoretic reasons, (1.26) cannot be true in general - as discussed in section 10 , when $p=2$ and $n=3$ the result is not true. Essentially there are two possibilities:
(i) $Z^{p}(X)$ is not reduced
(ii) $Z^{p}(X)$ is formally, but not actually, reduced.

Here we are using "reduced" as if $Z^{p}(X)$ had a scheme structure, which of course it does not. What is meant is that first an $m^{\text {th }}$-order arc is given by a finite linear combination of the map to the space of cycles induced by maps

$$
\operatorname{Spec}\left(\mathbb{C}[t] / t^{m+1}\right) \rightarrow \operatorname{Hilb}^{p}(X), \quad m \geqq 1.4
$$

The tangent to such an arc factors as in


[^3]where the top row is the finite linear combination of the above maps, and where the bottom row is surjective. To say that $\tau \in T Z^{p}(X)$ is unobstructed to order $m$ means that it is in the image of the dotted arrow. To say that it is formally reduced means that it is obstructed to order $m$ for all $m$. To say that it is actually reduced means that it comes from a geometric arc
$$
B \rightarrow Z^{p}(X)
$$

Another anomaly of the space of cycles is the presence of null curves in the Chow group, these being curves $z(t)$ in $C H^{p}(X)$ that are non-constant but whose derivative is identically zero. They arise from tangent vectors to rational equivalences that do not arise from actual rational equivalences (nonreduced property of $T Z_{\text {rat }}^{n}(X)=$ : image $\left\{T Z_{1}^{n}(X) \rightarrow T Z^{n}(X)\right\}-$ see below for notations). Thus, if one thinks it is the language of differential equations
(1.27) Because of the presence of null curves, there can be no uniqueness in the integration of Abel's differential equations.
Thus, both the usual existence and uniqueness theorems of differential equations will fail in our context. Heuristic considerations suggest that one must add additional arithmetic considerations to even have the possibility of convergent iterative constructions. The monograph concludes with a discussion of this issue in section 10.4.

In this paper we have used classical terminology in discussing the spaces of cycles on an algebraic variety, as if the $Z^{p}(X)$ were themselves some sort of variety. However, because of properties such as (1.26) and (1.27) the $Z^{p}(X)$ are decidedly non-classical objects. This non-classical behaviour is combined Hodge-theoretic and arithmetic in origin, and in our view understanding it presents a deep challenge in the study of algebraic cycles.

To conclude this introduction we shall give some references and discuss the relationship of this material to some other works on the space of cycles on an algebraic variety.

Our original motivation stems from the work of David Mumford and Spencer Bloch some thirty odd years ago. The paper [Rational equivalence of 0-cycles on surfaces., J. Math. Kyoto Univ. 9 (1968), 195-204] by Mumford showed that the story for Chow groups in higher codimensions would be completely different from the classical case of divisors. Certainly one of the questions in our minds was whether Mumford's result and the subsequent important extensions by Roitman [Rational equivalence of zero-dimensional cycles (Russian), Mat. Zametki 28(1) (1980), 85-90, 169] and [The torsion of the group of 0-cycles modulo rational equivalence, Ann. of Math. 111 (2) (1980), 553-569] could be understood, and perhaps refined, by defining the tangent space to cycles and then passing to the quotient by infinitesimal rational equivalence - this turned out to be the case.

The monograph [Lectures on algebraic cycles. Duke University Mathematics Series, IV. Duke University, Mathematics Department, Durham, N.C., 1980. 182 pp.] by Bloch was one of the major milestones in the study of Chow groups and provided significant impetus for this work. The initial
paper [ $K_{2}$ and algebraic cycles, Ann. of Math. 99(2) (1974), 349-379] by Bloch its successor [Bloch, S., Algebraic cycles and higher $K$-theory, Adv. in Math. 61(3) (1986), 267-304] together with [16] brought $K$-theory into the study of cycles, and trying to understand geometrically what is behind this was one principal motivation for this work. We feel that we have been able to do this infinitesimally by giving a geometric understanding of how absolute differentials necessarily enter into the description of the tangent space to the space of 0 -cycles on a smooth variety. One hint that this should be the case came from Bloch's early work [Bloch, S., On the tangent space to Quillen K-theory, L.N.M. 341 (1974), Springer-Verlag] and summarized in [4] and with important extensions by Stienstra [On $K_{2}$ and $K_{3}$ of truncated polynomial rings, Algebraic $K$-theory, Evanston 1980 (Proc. Conf., Northwestern Univ., Evanston, Ill., 1980), pp. 409-455, Lecture Notes in Math. 854, Springer, Berlin, 1981].

Another principal motivation for us has been provided by the conjectures of Bloch and Beilinson. These are explained in sections 6 and 8 of [Ramakrishnan, Dinakar, Regulators, algebraic cycles, and values of L-functions, Contemp. Math. 88 (1989), 183-310] and in [Jannsen, U., Motivic sheaves and filtrations on Chow groups. Motives (Seattle, WA, 1991), 245-302, Proc. Sympos. Pure Math. 55, Part 1, Amer. Math. Soc., Providence, RI, 1994]. Our work provides a geometric understanding and verification of these conjectures at the infinitesimal level, and it also points out some of the major obstacles to "integrating" these results.

In an important work, Blaine Lawson introduced a topology on the space $Z^{p}(X)$ of codimension $p$ algebraic cycles on a smooth complex projective variety. Briefly, two codimension- $p$ cycles $z, z^{\prime}$ written as

$$
\left\{\begin{array}{l}
z=z_{+}-z_{-} \\
z^{\prime}=z_{+}^{\prime}-z_{-}^{\prime}
\end{array}\right.
$$

where $z_{ \pm}, z_{ \pm}^{\prime}$ and effective cycles are close, if $z_{+}, z_{+}^{\prime}$ and $z_{-}, z_{-}^{\prime}$ are close in the usual sense of closed subsets of projective space. Lawson then shows that $Z^{p}(X)$ has the homotopy type of a CW complex, and from this he proceeds to define the Lawson homology of $X$ in terms of the homotopy groups of $Z^{p}(X)$. His initial work triggered an extensive development, many aspects of which are reported on in his talk at ICM Zürich (cf. [Lawson, Spaces of Algebraic Cycles - Levels of Holomorphic Approximation, Proc. ICM Zürich, pages 574-584] and the references cited therein).

In this monograph, although we do not define a topology on $Z^{p}(X)$, we do define and work with the concept of a (regular) arc in $Z^{p}(X)$. Implicit in this is the condition that two cycles $z, z^{\prime}$ as above should be close: First, there should be a common field of definition for $X, z$, and $z^{\prime}$. This leads to the spreads

as discussed in section 4 below, and $z, z^{\prime}$ should be considered close if $\mathcal{Z}$, $Z^{\prime} \in Z^{p}(X)$ are close in the Lawson sense (taking care to say what this means, since the spread is not uniquely defined). Because of a picture like

two cycles may be Lawson close without being close in our sense. We do not attempt to formalize this, but rather wish only to point out one relationship between the theory here and that of Lawson and his coworkers.

Finally, we mention that some of the early material in this study has appeared in [23].

## Chapter Two

## The Classical Case when $n=1$

We begin with the case $n=1$, which is both suggestive and in some ways misleading. Most of the material in this section is standard but will help to motivate what comes later. We want to define the tangent to an arc

$$
z(t)=\sum_{i} n_{i} x_{i}(t)
$$

in the space $Z^{1}(X)$ of 0-cycles on a smooth algebraic curve $X$. Later on we will more precisely define what we mean by such an arc - for the moment one may think of the $x_{i}(t)$ as being given in local coordinates by a Puiseaux series in $t$.

The degree

$$
\operatorname{deg} z(t)=: \sum_{i} n_{i}
$$

is constant in $t$. Among all arcs $z(t)$, those with

$$
\left\{\begin{array}{l}
z(0)=0 \\
z(t) \not \equiv 0
\end{array}\right.
$$

are of particular interest. The presence of such arcs is one main difference between the configuration spaces $X^{(m)}$ - i.e., sets of $m$ points on $X$ - and the space $Z^{1}(X)$ of 0 -cycles. We may write such an arc as sum of arcs

$$
z(t)=z^{+}(t)-z^{-}(t)
$$

where $z^{ \pm}(t)$ are arcs in $X^{(m)}$ with $z^{+}(0)=z^{-}(0)$, and we think of $z(t)$ as a creation/annihilation arc.

We denote by $|z(t)|$ the support of the 0-cycle $z(t)$, and for $x \in X$ denote by $Z_{\{x\}}^{1}(X)$ the set of $\operatorname{arcs} z(t)$ with

$$
\lim _{t \rightarrow 0}|z(t)|=x
$$

It will suffice to define the tangent space $T_{\{x\}} Z^{1}(X)$ to $\operatorname{arcs}$ in $Z_{\{x\}}^{1}(X)$. From a sheaf theoretic perspective, in the Zariski topology we denote by $\underline{\underline{Z}}^{1}(X)$ the Zariski sheaf of 0-cycles on $X$, and by $\underline{\underline{T}} Z^{1}(X)$ the to be defined tangent sheaf to $Z^{1}(X)$. The stalks of $\underline{\underline{T}} Z^{1}(X)$ are then given by

$$
\underline{\underline{T}} Z^{1}(X)_{x}=T_{\{x\}} Z^{1}(X)
$$

In fact, the sheaf-theoretic perspective suggests one possible definition of $T_{\{x\}} Z^{1}(X)$. Namely, we have the standard exact sheaf sequence

$$
\begin{equation*}
0 \rightarrow \mathcal{O}_{X}^{*} \rightarrow \underset{\mathbb{C}}{=}(X)^{*} \xrightarrow{\text { div }} \underline{\underline{Z}}^{1}(X) \rightarrow 0 \tag{2.1}
\end{equation*}
$$

With any reasonable definition the tangent sheaf to $\mathcal{O}_{X}^{*}$ is $\mathcal{O}_{X}$, with the map being

$$
\text { tangent to }\{f+t g+\cdots\}=g / f
$$

where $f \in \mathcal{O}_{X, x}^{*}$ and $g \in \mathcal{O}_{X, x}$, and similarly the tangent sheaf to $\mathbb{C}(X)^{*}$ should be $\mathbb{C}(X)$. This suggests that the tangent sheaf sequence to (2. $\overline{\overline{1}})$ can be defined $\overline{\text { and }}$ should be the well-known sequence

$$
\begin{equation*}
0 \rightarrow \mathcal{O}_{X} \rightarrow \underset{\mathbb{C}}{=}(X) \rightarrow \mathcal{P} \mathcal{P}_{X} \rightarrow 0 \tag{2.2}
\end{equation*}
$$

where $\mathcal{P} \mathcal{P}_{X}$ is the sheaf of principal parts. Thus, we should at least provisionally define

$$
\underline{\underline{T}} Z^{1}(X)=\mathcal{P} \mathcal{P}_{X}
$$

More explicitly, we consider an arc

$$
f(t)=f+t g+\cdots
$$

in $\underline{\underline{C}}(X)_{x}^{*}$ where $f \in \mathbb{C}(X)^{*}$ and $g \in \mathbb{C}(X)$. Then

$$
z(t)=\operatorname{div} f(t)
$$

is an arc in $Z^{1}(X)$ which we assume to be in $Z_{\{x\}}^{1}(X)$, and with the above provisional definition the tangent to $z(t)$ is given by

$$
z^{\prime}(0)=[g / f]_{x}
$$

where $[g / f]_{x}$ is the principal part at $x$ of the rational function $g / f$. More formally
Definition: Two arcs $z(t)$ and $\widetilde{z}(t)$ in $Z_{\{x\}}^{1}(X)$ are said to be equivalent to first order, written

$$
\begin{equation*}
z(t) \equiv_{1^{\mathrm{st}}} \widetilde{z}(t) \tag{2.3}
\end{equation*}
$$

if with the obvious notation we have

$$
[g / f]_{x}=[\widetilde{g} / \widetilde{f}]_{x}
$$

The tangent space to $Z_{\{x\}}^{1}(X)$ is then provisionally defined by

$$
\begin{equation*}
T_{\{x\}} Z^{1}(X)=Z_{\{x\}}^{1}(X) / \equiv_{1^{\text {st }}} \tag{2.4}
\end{equation*}
$$

This is not the formal definition, which will be given later and will be shown to be equivalent to the provisional definition.

Note: Below we will explicitly write out what this all means. There it will be seen that (2.3) is equivalent to having

$$
\widetilde{z}(t)=\operatorname{div}(f+t g+\cdots)
$$

i.e., we may take $\widetilde{f}=f$ and $\widetilde{g}=g$.

THE CLASSICAL CASE WHEN $N=1$
Perhaps the most natural notion of first order equivalence to use is the tangent space to the Hilbert scheme. A family of effective 0 -cycles $z(t)$ with $z(0)=z$ gives a map

$$
\begin{aligned}
\mathcal{J}_{z} & \rightarrow \mathcal{O}_{X} / \mathcal{J}_{z} \\
f & \mapsto \frac{d f}{d t}
\end{aligned}
$$

For families of effective 0-cycles $z_{1}(t), z_{2}(t)$ with

$$
z_{1}(0)=z_{2}(0)=z
$$

one says

$$
z_{1}(t) \cong_{1^{\text {st }}} z_{2}(t)
$$

if they induce the same map $\mathcal{J}_{z} \rightarrow \mathcal{O}_{X} / \mathcal{J}_{z}$. The subgroup of effective arcs in $Z^{1}(X)$ starting at a $z$ with $|z|=x$ generates an equivalence relation $\cong_{1^{\text {st }}}$ which will be seen to be the same as that given by Definition (2.4). Thus, for 0 -cycles on a curve, if we denote by $\operatorname{Hilb}_{k}^{1}(X)$ the 0 -dimensional subschemes of degree $k$ we have that

$$
T \operatorname{Hilb}_{k}^{1}(X) \rightarrow T Z^{1}(X)
$$

injects and

$$
\lim _{k \rightarrow \infty} T_{k x} \operatorname{Hilb}_{k}^{1}(X) \cong T_{\{x\}} Z^{1}(X)
$$

This will not be the case in higher codimension.
Classically, the tangent to an arc in the space of divisors on an algebraic curve appeared in the theory of abelian sums (see below). This suggests that the dual space to $T_{\{x\}} Z^{1}(X)$ should be related to differential forms. In fact there is a non-degenerate pairing

$$
\begin{equation*}
\mathcal{P} \mathcal{P}_{X, x} \otimes_{\mathbb{C}} \Omega_{X / \mathbb{C}, x}^{1} \rightarrow \mathbb{C} \tag{2.5}
\end{equation*}
$$

given by

$$
\tau \otimes \omega \rightarrow \operatorname{Res}_{x}(\tau \omega)
$$

Here, in terms of a local uniformizing parameter $\xi$ centered at $x$, we are thinking of $\mathcal{P} \mathcal{P}_{X, x}$ as the space of finite Laurent tails

$$
\mathcal{P} \mathcal{P}_{X, x} \cong\left\{\tau=\sum_{k=1}^{N} \frac{a_{k}}{\xi^{k}}\right\} .
$$

For $\omega=\left(\sum_{\ell \geqq 0} b_{\ell} \xi^{\ell}\right) d \xi$

$$
\operatorname{Res}_{x}(\tau \omega)=\sum_{\ell \geqq 0} a_{\ell+1} b_{\ell}
$$

from which we see that the pairing (2.5) is non-degenerate. A consequence is the natural identification of the provisional tangent space

$$
\begin{equation*}
T_{\{x\}} Z^{1}(X) \cong \operatorname{Hom}_{\mathbb{C}}^{c}\left(\Omega_{X / \mathbb{C}, x}^{1}, \mathbb{C}\right) \tag{2.6}
\end{equation*}
$$

where $\operatorname{Hom}_{\mathbb{C}}^{c}(\cdot, \cdot)$ denotes the continuous $\mathbb{C}$-linear homomorphisms; i.e., those $\varphi$ that annihilate $\mathfrak{m}_{x}^{N} \Omega_{X / \mathbb{C}, x}^{1}$ for some $N=N(\varphi)$.

Turning to abelian sums, we consider an arc of effective 0 -cycles

$$
z(t)=\sum_{i=1}^{m} x_{i}(t), \quad x_{i}(0)=x
$$

in $Z_{\{x\}}^{1}(X)$, given by a regular mapping

$$
B \rightarrow X^{(m)}
$$

from an algebraic curve $B$ with local uniformizing parameter $t$ into the $m$ fold symmetric product of $X$. Here, there is a reference point $b_{0} \in B$ with $t\left(b_{0}\right)=0$. The corresponding abelian sum is

$$
\sum_{i} \int_{x_{0}}^{x_{i}(t)} \omega
$$

It is well known that this abelian sum is regular in $t$ for $t$ near 0 , and we set

$$
\begin{equation*}
I(z, \omega)=\frac{d}{d t}\left(\sum_{i} \int_{x_{0}}^{x_{i}(t)} \omega\right)_{t=0} \tag{2.7}
\end{equation*}
$$

Proposition: Denoting by $z^{\prime}(0)$ the Laurent tail corresponding to the tangent vector to $z(t)$, we have

$$
\begin{equation*}
I(z, \omega)=\operatorname{Res}_{x}\left(z^{\prime}(0) \omega\right) \tag{2.8}
\end{equation*}
$$

Thus, the first order terms in abelian sums give an alternate description of the isomorphism (2.6).

Proof: If

$$
z(t)=\text { divisor of } f+t g
$$

then we need to show that

$$
\operatorname{Res}_{x}((g / f) \omega)=I(z, \omega)
$$

This follows from the general
Lemma: Expressed in terms of a complex variable $x$, if we write $f+t g=$ $\prod_{i=1}^{m}\left(x-x_{i}(t)\right) \bmod o\left(t^{1+\epsilon}\right)$ and

$$
\omega=x^{k} d x
$$

then

$$
\operatorname{Res}_{0}\left(\frac{g \omega}{f}\right)=-\lim _{t \rightarrow 0} \sum_{i=1}^{m} x_{i}(t)^{k} x_{i}^{\prime}(t)
$$

Proof: We give two independent proofs.

## First proof:

$$
\begin{aligned}
f+t g=x^{m}+\sum_{j=1}^{m}(-1)^{j} \sigma_{j}\left(x_{1}(t), \ldots,\right. & \left.x_{m}(t)\right) x^{m-j} \\
& \bmod O\left(t^{1+\epsilon}\right)
\end{aligned}
$$

So

$$
g(x)=\left.\sum_{j=1}^{m}(-1)^{j} \frac{d}{d t} \sigma_{j}\left(x_{1}(t), \ldots x_{m}(t)\right) x^{m-j}\right|_{t=0}
$$

and thus

$$
\operatorname{Res}_{0}\left(\frac{g \omega}{f}\right)=\left.(-1)^{k+1} \frac{d}{d t} \sigma_{k+1}\left(x_{1}(t) \cdots x_{m}(t)\right)\right|_{t=0}
$$

By Newton's identities,

$$
\begin{aligned}
\sum_{i=1}^{m} x_{i}(t)^{k+1}=- & (k+1) \sigma_{k+1}\left(x_{1}(t), \ldots x_{m}(t)\right)+ \\
& \text { terms of } \operatorname{deg} \geq 2 \text { in } \sigma_{1}, \ldots, \sigma_{m}
\end{aligned}
$$

Thus

$$
\begin{aligned}
\sum_{i=1}^{m} x_{i}(t)^{k} x_{i}^{\prime}(t)= & -\frac{d}{d t} \sigma_{k+1}\left(x_{1}(t), \ldots x_{m}(t)\right) \\
& +\sum_{i=1}^{m} p_{i}\left(\sigma_{1}, \ldots \sigma_{m}\right) \sigma_{i}\left(x_{1}(t), \ldots x_{m}(t)\right)
\end{aligned}
$$

where every term of $p_{i}$ has positive total degree in $\sigma_{i}$.
Since $\sigma_{j}\left(x_{1}(0), \cdots x_{i}(0)\right)=0$ for all $j=1, \ldots, m$, it follows that $p_{i}\left(\sigma_{1}, \cdots \sigma_{i}\right)=0$ at $t=0$. So

$$
\begin{aligned}
\lim _{t \rightarrow 0} \sum_{i} x_{i}(t)^{k} x_{i}^{\prime}(t) & =-\left.\frac{d}{d t} \sigma_{k+1}\left(x_{1}(t), \ldots x_{m}(t)\right)\right|_{t=0} \\
& =-\operatorname{Res}_{0}\left(\frac{g \omega}{f}\right)
\end{aligned}
$$

## Second proof:

$$
\begin{aligned}
\operatorname{Res}_{0}\left(\frac{g \omega}{f}\right) & =\lim _{t \rightarrow 0} \sum_{i=1}^{m} \operatorname{Res}_{x_{i}(t)}\left(\frac{g \omega}{f+t g}\right) \\
& =\lim _{t \rightarrow 0} \sum_{i=1}^{m} \operatorname{Res}_{x_{i}(t)} \frac{g x^{k} d x}{\prod_{j-1}^{m}\left(x-x_{j}(t)\right)} \\
& =\lim _{t \rightarrow 0} \sum_{i=1}^{m} \frac{g\left(x_{i}(t)\right) x_{i}(t)^{k}}{\prod_{j \neq i}\left(x_{i}(t)-x_{j}(t)\right)}
\end{aligned}
$$

Differentiating

$$
f+t g=\prod_{i=1}^{m}\left(x-x_{i}(t)\right)
$$

with respect to $t$ gives

$$
g(x)=\sum_{i=1}^{m}-x_{i}^{\prime}(t) \cdot \prod_{j \neq i}\left(x-x_{j}(t)\right)
$$

so

$$
g\left(x_{i}(t)\right)=-x_{i}^{\prime}(t) \cdot \prod_{j \neq i}\left(x_{i}(t)-x_{j}(t)\right)
$$

and plugging into the earlier formula gives

$$
\operatorname{Res}_{0}\left(\frac{g \omega}{f}\right)=-\lim _{t \rightarrow 0} \sum_{i} x_{i}(t)^{k} x_{i}^{\prime}(t)
$$

For later use it is instructive to examine the abelian sum approach in local analytic coordinates, which we may take to be an analytic disc $\{b:|t(b)|<\delta\}$ where $t$ is a local uniformizing parameter on $X$ and $\delta>0$ is a positive constant. Call an arc in $X^{(m)}$

$$
z(t)=\sum_{i=1}^{m} x_{i}(t), \quad x_{i}(0)=x
$$

irreducible if $x_{i}(t) \neq x_{j}(t)$ for $i \neq j$ and $t \neq 0$, and if analytic continuation around $t=0$ permutes the $x_{i}(t)$ transitively. Any arc in $Z_{\{x\}}^{1}(X)$ is a $\mathbb{Z}$ linear combination of constant arcs and irreducible arcs. Since the tangent map is additive on arcs, it suffices to consider the tangents to irreducible arcs.

An irreducible arc is represented by a convergent Puiseaux series

$$
x_{i}(t)=\sum_{j=0}^{m} a_{j} \epsilon^{i j} t^{j / m}+0\left(t^{1+1 / m}\right)
$$

where $\epsilon=e^{2 \pi \sqrt{-1} / m}$. Then

$$
\begin{aligned}
\left.\frac{d}{d t}\left(\sum_{i} \int_{x}^{x_{i}(t)} \xi^{k} d \xi\right)\right|_{t=0} & =\left.\sum_{i=1}^{m}\left(\sum_{j=1}^{m} a_{j} \epsilon^{j} t^{j / m}\right)^{k} \sum_{j} j a_{j} \epsilon^{j} t^{(j / m)-1}\right|_{t=0} \\
& =\sum_{\substack{j_{1}+\cdots+j_{k+1}=m \\
0 \leqq j_{1}, \cdots, j_{k+1} \leqq m \\
j}} j_{k+1} a_{j} a_{j_{1}} \cdots a_{j_{k+1}}
\end{aligned}
$$

This calculation tells us several things. One is that it establishes directly the non-degeneracy of the pairing

$$
T_{\{x\}} Z^{1}(X) \otimes_{\mathbb{C}} \Omega_{X / \mathbb{C}, x}^{1} \rightarrow \mathbb{C}
$$

given by

$$
z \otimes \omega \rightarrow I(z, \omega)
$$

in (2.7) above. The second is that the multiplicity $m$ of an irreducible arc is uniquely determined by

$$
I\left(z, \mathfrak{m}_{x}^{k} \Omega_{X / \mathbb{C}, x}^{1}\right)=0, \quad k \geqq m
$$

Finally, it is instructive to illustrate the proof of the above proposition and the Puiseaux series calculation in the simplest non-trivial case.

Example: A Puiseaux expansion for $m=2$ is given by

$$
\begin{aligned}
& x_{1}(t)=a_{1} t^{1 / 2}+a_{2} t+\cdots \\
& x_{2}(t)=-a_{1} t^{1 / 2}+a_{2} t+\cdots
\end{aligned}
$$

and is defined by $\operatorname{div}(f+t g)$ where

$$
f+t g=\xi^{2}+t\left(-2 a_{2} \xi-a_{1}^{2}\right)+o\left(t^{1+\epsilon}\right)
$$

for some $\epsilon>0$. If we set

$$
z(t)=\operatorname{div}(f+t g)
$$

then

$$
\begin{aligned}
& I(z, d \xi)=\lim _{t \rightarrow 0} \sum_{i=1}^{2} \xi_{i}^{\prime}(t)=2 a_{2} \\
& I(z, \xi d \xi)=\lim _{t \rightarrow 0} \sum_{i=1}^{2} \xi_{i}(t) \xi_{i}^{\prime}(t)=a_{1}^{2}
\end{aligned}
$$

Note that

$$
\begin{aligned}
& \operatorname{Res}_{o}\left(\frac{g d \xi}{f}\right)=-2 a_{2} \\
& \operatorname{Res}_{0}\left(\frac{g \xi d \xi}{f}\right)=-a_{1}^{2}
\end{aligned}
$$

Anticipating future discussions, we observe that there is a natural identification

$$
\mathcal{P} \mathcal{P}_{X, x} \simeq \lim _{i \rightarrow \infty} E x t_{\mathcal{O}_{X, x}}^{1}\left(\mathcal{O}_{X, x} / \mathfrak{m}_{x}^{i}, \mathcal{O}_{X, x}\right)
$$

To describe this, we resolve

$$
\begin{array}{rc}
0 \rightarrow \mathcal{O}_{X, x} & \xrightarrow{g^{i}} \mathcal{O}_{X, x} \rightarrow \mathcal{O}_{X, x} / \mathfrak{m}_{x}^{i} \rightarrow 0 \\
\| & \| \\
E_{1} & E_{0}
\end{array}
$$

where $g$ is a local defining equation for $x$ and

$$
\operatorname{Hom}_{\mathcal{O}_{X, x}}\left(E_{1}, \mathcal{O}_{X, x}\right) \simeq \mathcal{O}_{X, x}
$$

while

$$
\left(g^{i}\right)^{*} \operatorname{Hom}_{\mathcal{O}_{X, x}}\left(E_{0}, \mathcal{O}_{X, x}\right) \subseteq \operatorname{Hom}_{\mathcal{O}_{X, x}}\left(E_{1}, \mathcal{O}_{X, x}\right)
$$

is equal to

$$
g^{i} \mathcal{O}_{X, x}
$$

So if

$$
f \in \operatorname{Hom}_{\mathcal{O}_{X, x}}\left(E_{1}, \mathcal{O}_{X, x}\right)
$$

then we may identify

$$
[f] \in \operatorname{Ext}_{\mathcal{O}_{X, x}}^{1}\left(\mathcal{O}_{X, x} / \mathfrak{m}_{x}^{i}, \mathcal{O}_{X, x}\right) \leftrightarrow \frac{f}{g^{i}} \in \mathcal{P} \mathcal{P}_{X, x}
$$

The natural map, for $j>i$

$$
E x t_{\mathcal{O}_{X, x}}^{1}\left(\mathcal{O}_{X, x} / \mathfrak{m}_{x}^{i}, \mathcal{O}_{X, x}\right) \rightarrow \operatorname{Ext}_{\mathcal{O}_{X, x}}^{1}\left(\mathcal{O}_{X, x} / \mathfrak{m}_{x}^{j}, \mathcal{O}_{X, x}\right)
$$

takes

$$
f \longmapsto f g^{j-i}
$$

and since

$$
\frac{f}{g^{i}}=\frac{f g^{j-i}}{g^{j}}
$$

we get

$$
\lim _{i \rightarrow \infty} \operatorname{Ext}_{\mathcal{O}_{X, x}}^{1}\left(\mathcal{O}_{X, x} / \mathfrak{m}_{x}^{i}, \mathcal{O}_{X, x}\right) \simeq \mathcal{P} \mathcal{P}_{X, x}
$$

We remark that this limit may be expressed using local cohomology as

$$
\lim _{i \rightarrow \infty} E x t_{\mathcal{O}_{X, x}}^{1}\left(\mathcal{O}_{X, x} / \mathfrak{m}_{x}^{i}, \mathcal{O}_{X, x}\right) \cong H_{\mathfrak{m}_{x}}^{1}\left(\mathcal{O}_{X, x}\right) \cong H_{x}^{1}\left(\mathcal{O}_{X}\right)
$$

With this in mind we give the formal
Definition: We define the tangent sheaf
to be

$$
\underline{\underline{T}} Z^{1}(X)
$$

$$
\underline{\underline{T}} Z^{1}(X)=\underset{x \in X}{\oplus} \lim _{k \rightarrow \infty} \mathcal{E} x t_{\mathcal{O}_{X}}^{1}\left(\mathcal{O}_{X} / \mathfrak{m}_{x}^{k}, \mathcal{O}_{X}\right)
$$

We observe that the tangent map

$$
\operatorname{arcs} \text { in } Z_{\{x\}}^{1}(X) \rightarrow \underline{\underline{T}} Z^{1}(X)_{x}
$$

is surjective.
The tangent sequence to (2.1) can then be defined and is the exact sheaf sequence

$$
\begin{equation*}
0 \rightarrow \mathcal{O}_{X} \rightarrow \underset{\underline{\mathbb{C}}}{\underline{=}}(X) \rightarrow \underline{\underline{T}}^{1}(X) \rightarrow 0 \tag{2.9}
\end{equation*}
$$

Setting

$$
T Z^{1}(X)=H^{0}\left(\underline{\underline{T}} Z^{1}(X)\right)
$$

the exact cohomology sequence of (2.9) is

$$
\begin{equation*}
\mathbb{C}(X) \xrightarrow{\rho} T Z^{1}(X) \rightarrow H^{1}\left(\mathcal{O}_{X}\right) \rightarrow 0 \tag{2.10}
\end{equation*}
$$

This is the tangent sequence to the exact sequence

$$
\begin{equation*}
\mathbb{C}(X)^{*} \xrightarrow{\text { div }} Z^{1}(X) \rightarrow \operatorname{Pic}(X) \rightarrow 1 \tag{2.11}
\end{equation*}
$$

It follows from (2.10) and (2.11) first that

$$
\text { image } \rho=T Z_{\mathrm{rat}}^{1}(X)
$$

is the tangent space to the subgroup $Z_{\text {rat }}^{1}(X) \subset Z^{1}(X)$ of 0 -cycles that are rationally equivalent to zero. Secondly, we have

$$
\begin{align*}
T Z^{1}(X) / T Z_{\mathrm{rat}}^{1}(X) & \cong H^{1}\left(\mathcal{O}_{X}\right)  \tag{2.12}\\
& \cong T C H^{1}(X)
\end{align*}
$$

Now we have a natural map

$$
H_{x}^{1}\left(\mathcal{O}_{X}\right) \rightarrow H^{1}\left(\mathcal{O}_{X}\right)
$$

from local to global cohomology. The diagram

brings together these two maps.
It is this picture that we want to generalize. The description

$$
T_{\{x\}} Z^{1}(X) \cong \operatorname{Hom}_{\mathbb{C}}^{c}\left(\Omega_{X / \mathbb{C} . x}^{1}, \mathbb{C}\right)
$$

generalizes to 0 -cycles on a $n$-dimensional smooth variety $X$, but gives the wrong answer - in particular the analogue of (2.12) fails to hold. ${ }^{1}$ The geometric reasons for this are rather subtle and will be discussed below. The Ext definition holds generally, but also in a subtle way. Suffice it to say here that two new but closely related phenomena must enter when $n \geqq 2$ :
(i) all the forms $\Omega_{X / \mathbb{C}, x}^{q}, 1 \leqq q \leqq n$ must be used
(ii) absolute differentials - i.e., as it turns out $\Omega_{X / \mathbb{Q}}^{n} / \Omega_{\mathbb{C} / \mathbb{Q}}^{n}$ - must be used.

Of course, (i) is automatic when $n=1$. As to (ii), when $n=1$ the quotient $\Omega_{X / \mathbb{Q}}^{1} / \Omega_{\mathbb{C} / Q}^{1}$ is isomorphic to $\Omega_{X / \mathbb{C}}^{1}$, and thus absolute differentials do not enter the picture in this case.

[^4]PUTangSp March 1, 2004

## Chapter Three

## Differential Geometry of Symmetric Products

Let $X$ be a smooth variety of dimension $n$, We are interested in the geometry of configurations of $m$ points on $X$, which we represent as effective 0 -cycles

$$
z=x_{1}+\cdots+x_{m}
$$

of degree $m$. Set theoretically such configurations are given by the $m$-fold symmetric product

$$
X^{(m)}=\underbrace{X \times \cdots \times X}_{m} / \Sigma_{m}
$$

where $\Sigma_{m}$ is the group of permutations.
We will be especially concerned with arcs of 0-cycles, given by a regular mapping

$$
B \xrightarrow{z} X^{(m)}
$$

from a smooth (not necessarily complete) curve into $X^{(m)}$. If $t$ is a local uniformizing parameter on $B$, such an arc may be thought of as

$$
\begin{equation*}
z(t)=x_{1}(t)+\cdots+x_{m}(t) \tag{3.1}
\end{equation*}
$$

where, in terms of local uniformizing parameters on $X$, the $x_{i}(t)$ are given by Puiseaux series in $t$. We denote by $Z_{\{x\}}^{n}(X)$ the space given by $\mathbb{Z}$-linear combinations of $\operatorname{arcs} z(t)$ as above where all $x_{i}(0)=x$; i.e., which satisfy

$$
z(0)=m x
$$

for some $m$. For example, if $n=2$ and $\xi, \eta$ are local uniformizing parameters on $X$ centered at $x$, then we will have Puiseaux series expansions convergent for $|t|<\delta$ for some constant $\delta>0$

$$
\left\{\begin{array}{l}
\xi_{k}=a_{1} \epsilon^{k} t^{1 / m}+a_{2} \epsilon^{2 k} t^{2 / m}+\cdots+a_{m} t+\cdots  \tag{3.2}\\
\eta_{k}=b_{1} \epsilon^{k} t^{1 / m}+b_{2} \epsilon^{2 k} t^{2 / m}+\cdots+b_{m} t+\cdots
\end{array}\right.
$$

where $\epsilon=e^{2 \pi \sqrt{-1} / m}$.
It is well known that for $n \geqq 2$ the symmetric products are singular along the diagonals, and in particular along the principal diagonal $\{m x: x \in X\} .{ }^{1}$ However, essentially because we are interested in 0-cycles and not 0-dimensional subschemes, at this point we will not need to get into

[^5]the finer aspects of the various candidates for smooth models of the $X^{(m)}$ 's (however, see the discussion in section 7 below). What we do need is the concept of the regular differential forms of degree $q$
$$
\Omega_{X^{(m)} / \mathbb{C}, z}^{q}
$$
at a point $z \in X^{(m)}$. This is given by a regular $q$-form $\varphi$ defined on the smooth points in a neighborhood of $z$ and which, for any map $f: Y \rightarrow X^{(m)}$ where $Y$ is smooth and $f(Y)$ contains a neighborhood of $z, f^{*} \varphi$ is a regular $q$-form on $Y$ (cf. [33]). It can then be shown that (loc. cit)
\[

$$
\begin{equation*}
\Omega_{X^{(m)} / \mathbb{C} . m x}^{q} \cong(\Omega_{X^{m} / \mathbb{C},(\underbrace{q}_{m} x, \ldots, x}^{q})^{\Sigma_{m}} \tag{3.3}
\end{equation*}
$$

\]

For us two basic facts concerning the regular forms on symmetric products are
(3.4) Every $\omega \in \Omega_{X / \mathbb{C}, x}^{q}$ induces in $\Omega_{X^{(m)} / \mathbb{C}, m x}^{q}$ a regular form $\operatorname{Tr} \omega$, called the trace of $\omega$.

Explicitly, $\operatorname{Tr} \omega$ is induced from the diagonal form $(\omega, \cdots, \omega)$ on $X^{m}$, which being invariant under $\Sigma_{m}$ descends to a regular form on the smooth points of $X^{(m)}$. We write symbolically

$$
(\operatorname{Tr} \omega)(z)=\omega\left(x_{1}\right)+\cdots+\omega\left(x_{m}\right)
$$

Among forms on symmetric products traces have a number of special properties, including the one of heredity: Fixing $x_{0} \in X$ there are natural inclusions

$$
X^{(m)} \hookrightarrow X^{(m+1)}
$$

and the trace of $\varphi$ on $X^{(m+1)}$ restricts to $\operatorname{Tr} \varphi$ on $X^{(m)}$. Moreover, under the natural map

$$
X^{\left(m_{1}\right)} \times X^{\left(m_{2}\right)} \rightarrow X^{\left(m_{1}+m_{2}\right)}
$$

traces pull back to a sum of traces. Thus, traces are especially suitable to be thought of as differential forms on the space of 0 -cycles.

A second basic fact is the following result which has been proved by Ting Fai Ng [39]
(3.5) $\Omega_{X^{(m)} / \mathbb{C}, m x}^{*}$ is generated over $\mathcal{O}_{X^{(m)}, m x}$ by sums of elements of form

$$
\operatorname{Tr} \omega_{1} \wedge \cdots \wedge \operatorname{Tr} \omega_{k}, \quad \omega_{i} \in \Omega_{X / \mathbb{C}, x}^{q_{i}}
$$

This is clear when $n=1$, since in this case $X^{(m)}$ is smooth (see below). However, when $n \geqq 2$ and $m \geqq 2$, due to the singularities of symmetric products along the diagonals one may show that we must add generators $\operatorname{Tr} \omega$ for $\omega \in \Omega_{X / \mathbb{C}, x}^{q}$ and all $q$ with $1 \leqq q \leqq n$ to reach all of $\Omega_{X^{(m)} / \mathbb{C}, m x}^{*}$.

For example, when $n=m=2$ and $\xi, \eta$ are local uniformizing parameters and we set $\xi_{i}=\xi\left(x_{i}\right), \eta_{i}=\eta\left(x_{i}\right)$,

$$
\begin{equation*}
\operatorname{Tr} d \xi \wedge d \eta=d \xi_{1} \wedge d \eta_{1}+d \xi_{2} \wedge d \eta_{2} \tag{3.6}
\end{equation*}
$$

is not generated over $\mathcal{O}_{X^{(2)}, 2 x}$ by traces of 1-forms in $\Omega_{X / \mathbb{C}, x}^{1}$. The traces of 1-forms together with (3.6) do generate $\Omega_{X^{(2)} / \mathbb{C}, 2 x}^{2}$; e.g.

$$
d \xi_{1} \wedge d \eta_{2}+d \xi_{2} \wedge d \eta_{1}=(\operatorname{Tr} d \xi) \wedge(\operatorname{Tr} d \eta)-\operatorname{Tr}(d \xi \wedge d \eta)
$$

We will not use (3.5) in the logical development of the theory, and therefore we shall not reproduce Ng's formal proof. However, we feel that it is instructive to see how the first few special cases go.

Let $X$ be an algebraic curve with local uniformizing parameter $\xi$ centered at a point $x \in X$. On the $m$-fold cartesian product $X^{m}$, let $\xi_{i}$ denote $\xi$ in the $i^{\text {th }}$ coordinate. It follows from the theorem on elementary symmetric functions that every function on $X^{m}$ invariant under the symmetric group $\Sigma_{m}$ is uniquely expressible in terms of

$$
\left\{\begin{array}{l}
\operatorname{Tr} \xi=\xi_{1}+\cdots+\xi_{m} \\
\operatorname{Tr} \xi^{2}=\xi_{1}^{2}+\cdots+\xi_{m}^{2} \\
\vdots \\
\operatorname{Tr} \xi^{m}=\xi_{1}^{m}+\cdots+\xi_{m}^{m}
\end{array}\right.
$$

It is a general fact that

$$
\operatorname{Tr}(d \varphi)=d(\operatorname{Tr} \varphi)
$$

and this implies (3.5) in the case $n=1$.
Turning to the case $n=2$, let $X$ be an algebraic surface and $\xi, \eta$ local coordinates centered at $x \in X$. If we expand forms on $X^{m}$ around $(x, \ldots, x) \in X^{m}$, then $\Sigma_{m}$ acts homogeneously and the issue is one of the occurrence of the trivial representation in the homogeneous pieces of total degree $p+q$ in

$$
\mathbb{C}\left[\xi_{1}, \eta_{1}, \ldots, \xi_{m}, \eta_{m}\right] \otimes \wedge^{q}\left\{d \xi_{1}, d \eta_{1}, \ldots, d \xi_{m}, d \eta_{m}\right\}
$$

For example, when $q=1$ the first non-trivial case is when $p=1$. The terms in $\xi_{i} d \xi_{j}$ and $\eta_{i} d \eta_{j}$ follow from the $n=1$ case. By symmetry it will suffice to consider

$$
\varphi=\sum_{i j} a_{i j} \xi_{i} d \eta_{j}
$$

Clearly $a_{21}=a_{31}=\ldots=a_{m 1}$. It follows that

$$
\varphi-a_{21} \operatorname{Tr}(\xi) \operatorname{Tr}(d \eta)-\left(a_{11}-a_{21}\right) \operatorname{Tr}(\xi d \eta)
$$

does not involve $d \eta_{1}$, and hence again it must be zero.
The next case is when $q=2$ and $p=0$. Again, the terms in $d \xi_{i} \wedge d \xi_{j}$ and $d \eta_{i} \wedge d \eta_{j}$ follow from the $n=1$ case. Thus we may assume that

$$
\varphi=\sum_{i, j} a_{i j} d \xi_{i} \wedge d \eta_{j}
$$

Clearly $a_{11}=\ldots=a_{m m}$ and $a_{21}=\cdots=a_{m 1}$. It follows that

$$
\varphi-a_{21}(\operatorname{Tr} d \xi)(\operatorname{Tr} d \eta)-\left(a_{11}-a_{21}\right) \operatorname{Tr}(d \xi \wedge d \eta)
$$

does not involve $d \eta_{1}$, and hence it must be zero.

The next case is when $q=2$ and $p=1$. As before we are reduced to considering

$$
\varphi=\sum_{i, j, k} a_{i j k} \xi_{i} d \xi_{j} \wedge d \eta_{k}
$$

We want to show that $\varphi$ is expressible in terms of the three 2 -forms $(\operatorname{Tr} \xi)(\operatorname{Tr} d \xi) \wedge(\operatorname{Tr} d \eta),(\operatorname{Tr} \xi d \xi) \wedge(\operatorname{Tr} d \eta)$ and $(\operatorname{Tr} d \xi) \wedge(\operatorname{Tr} \xi d \eta)$. Since clearly

$$
a_{i j 1}=a_{j i 1} \quad \text { for } \quad 2 \leq i, j \leq n
$$

it follows that only three distinct constants $a_{111}, a_{211}, a_{121}$ appear in terms containing $\eta_{1}$. We may therefore subtract from $\varphi$ a linear combination of the three trace terms to obtain an invariant expression not containing $d \eta_{1}$, which must then be zero.

The fact that when $n \geqq 2$, we must add traces of higher degree forms to generate $\Omega_{X^{(m)} / \mathbb{C}, m x}^{*}$ is a rather subtle differential geometric fact which reflects essential differences in the correct definition of $T_{\{x\}} Z^{n}(X)$ between the situation discussed above when $n=1$ and when $n \geqq 2$.

We will now explain how the pairing (2.7) above extends to give in general

$$
\begin{equation*}
Z_{\{x\}}^{n}(X) \otimes_{\mathbb{C}} \Omega_{X / \mathbb{C}, x}^{1} \rightarrow \mathbb{C} \tag{3.7}
\end{equation*}
$$

which is non-degenerate in the second factor. The basic fact is that an arc (3.1) pulls back a regular 1-form in $\Omega_{X^{(m)} / \mathbb{C}, m x}^{1}$ to a regular 1-form on $B$. Thus we will have, for $\omega \in \Omega_{X / \mathbb{C}, x}^{1}$, an expansion

$$
\begin{equation*}
z(t)^{*}(\operatorname{Tr} \omega)=I(z, \omega) d t+O(t)+(\text { terms not involving } d t) \tag{3.8}
\end{equation*}
$$

where $I(z, \omega)$ is defined by the right hand side of this equation; i.e., $I(z, \omega)$ is given by $z(t) \rightarrow \operatorname{Tr} \omega\rfloor \partial / \partial t \bmod (t)$. We note that where $n=1$ this definition of $I(z, \omega)$ agrees with that in (2.7) above.

In coordinates, if $z(t)$ is given by (3.1) where the $x_{k}(t)=\left(\xi_{k}(t), \eta_{k}(t)\right)$ are given by Puiseaux series (3.2), then for

$$
\omega=f(\xi, \eta) d \xi+g(\xi, \eta) d \eta
$$

we will have

$$
z(t)^{*}(\operatorname{Tr} \omega)=\sum_{k} f\left(\xi_{k}, \eta_{k}\right) d \xi_{k}+g\left(\xi_{k}, \eta_{k}\right) d \eta_{k}
$$

Expanding $f$ and $g$ in series, using $\sum_{k=0}^{m-1} \epsilon^{k}=0$ only integral powers of $t$ survive and, in particular no negative powers $t^{-\ell / m}$ arising from the $d t^{(n-\ell) / m}$ terms appear. Thus $z(t)^{*}(\operatorname{Tr} \omega)$ has the form (3.8).

The pairing (3.7) is non-degenerate in the second factor, for the following reason. First observe another nice general property of traces is that for any smooth subvariety $Y \subset X$ traces are natural for inclusions, in the sense that for $Y^{(m)} \subset X^{(m)}$ we have

$$
\left.\operatorname{Tr} \omega\right|_{Y^{(m)}}=\operatorname{Tr}\left(\left.\omega\right|_{Y}\right)
$$

Secondly, given any non-zero $\omega \in \Omega_{X / \mathbb{C}, x}^{1}$ we may find a smooth algebraic curve $Y$ passing through $x$ such that $\left.\omega\right|_{Y}$ is non-zero. We know that the pairing

$$
Z_{\{x\}}^{1}(Y) \otimes_{\mathbb{C}} \Omega_{Y / \mathbb{C}, x}^{1} \rightarrow \mathbb{C}
$$

is non-degenerate in the second factor, and our claim follows.
The kernel of the surjective mapping

$$
Z_{\{x\}}^{n}(X) \rightarrow \operatorname{Hom}_{\mathbb{C}}^{c}\left(\Omega_{X / \mathbb{C}, x}^{1}, \mathbb{C}\right)
$$

defines an equivalence relation $\sim$ on $Z_{\{x\}}^{n}(X)$, and our first guess was that the tangent space $T_{\{x\}} Z^{n}(X)$ should be defined by

$$
T_{\{x\}} Z^{n}(X)=Z_{\{x\}}^{n}(X) / \sim
$$

As will be explained below, this turned out to be incorrect. In fact, in some sense one knows it must be wrong because of the property (3.5). However, $\sim$ is interesting and for later use it is instructive to get some feeling for what it is.

When $n=2$, working in local coordinates as above we suppose that

$$
z(t)=x_{1}(t)+\cdots+x_{m}(t)
$$

where each

$$
x_{j}(t)=\left(a_{j} t, b_{j} t\right)+0\left(t^{2}\right) \cdots
$$

The condition that $z(t)$ be $\sim$ equivalent to zero is

$$
\left\{\begin{array}{l}
\sum a_{j}=0 \\
\sum b_{j}=0
\end{array}\right.
$$

i.e.

$$
\sum_{j}\left(a_{j}, b_{j}\right)=0
$$

which is the usual tangent vector property.
Next suppose that

$$
\begin{aligned}
z(t) & =x_{1}(t)+\ldots+x_{m}(t) \\
x_{j}(t) & =x_{j}^{+}(t)+x_{j}^{-}(t) \\
x_{j}^{+}(t) & =\left(a_{j_{1}} t^{1 / 2}+a_{j_{2}} t, b_{j_{1}} t^{1 / 2}+b_{j_{2}} t\right)+O\left(t^{3 / 2}\right) \\
x_{j}^{-}(t) & =\left(-a_{j_{1}} t^{1 / 2}+a_{j_{2}} t,-b_{j_{1}} t^{1 / 2}+b_{j_{2}} t\right)+O\left(t^{3 / 2}\right) .
\end{aligned}
$$

Now

$$
\begin{aligned}
I(z(t), d \xi) & =2 \sum_{j} a_{j_{2}} \\
I(z(t), d \eta) & =2 \sum_{j} b_{j_{2}} \\
I(z(t), \xi d \xi) & =\sum_{j} a_{j_{1}}^{2} \\
I(z(t), \eta d \xi) & =\sum_{j} a_{j_{1}} b_{j_{1}} \\
I(z(t), \xi d \eta) & =\sum_{j} a_{j_{1}} b_{j_{1}} \\
I(z(t), \eta d \eta) & =\sum_{j} b_{j_{1}}^{2} \\
I(z(t), \omega) & =0 \text { if } \omega \in \mathfrak{m}_{x}^{2} \Omega_{X / \mathbb{C}, x}^{1}
\end{aligned}
$$

Then the condition that $z(t)$ be $\sim$ equivalent to zero is expressed by

$$
\left\{\begin{array}{l}
\sum_{j} a_{j_{1}}^{2}=0, \sum_{j} a_{j_{2}}=0 \\
\sum_{j} a_{j_{1}} b_{j_{1}}=0 \\
\sum_{j} b_{j_{1}}^{2}=0, \sum_{j} b_{j_{2}}=0
\end{array}\right.
$$

In particular, for an irreducible $t^{1 / 2}$ Puiseaux series

$$
\begin{aligned}
z(t)= & \left(a_{1} t^{1 / 2}+a_{2} t+\cdots, b_{1} t^{1 / 2}+b_{2} t+\cdots\right) \\
& +\left(-a_{1} t^{1 / 2}+a_{2} t+\cdots,-b_{1} t^{1 / 2}+b_{2} t+\cdots\right)
\end{aligned}
$$

the information in the equivalence relation $\sim$ is

$$
a_{1}^{2}, a_{1} b_{1}, b_{1}^{2}, a_{2}, b_{2}
$$

Thus, $b_{1} / a_{1}$ is determined and to first order $z(t)$ satisfies the equations

$$
\begin{aligned}
& b_{1} \xi-a_{1} \eta+\left(a_{1} b_{2}-a_{2} b_{1}\right) t=0 \\
& \xi^{2}-2 a_{2} t \xi-a_{1}^{2} t=0
\end{aligned}
$$

We now turn to the question:
Why should higher degree forms be relevant to tangents to arcs in the space of 0-cycles? One answer stems from Elie Cartan, who taught us that when there are natural parameters in a geometric structure, they should be included as part of that structure. Moreover, any use of infinitesimal analysis should include the infinitesimal analysis applied to the parameters as well. ${ }^{2}$ In the situation of 0 -cycles, there is an infinite-dimensional space of parameters - namely those given in coordinates by the coefficients of all

[^6]possible Puiseaux series. More interestingly in the algebraic case the spread constructions will give us finite dimensional parameter spaces in which all algebraic relations are preserved.

To systematize this, for a general smooth variety $X$ in terms of local uniformizing parameters around $x$ we denote by $P_{m}$ the (infinite dimensional) space of coefficients of all formal Puiseaux series as given above for $x_{i}(t)$. There is a formal map

$$
z: \Delta \times P_{m}--\rightarrow X^{(m)}
$$

given by these Puiseaux series. For any holomorphic $q$-form $\Phi$ defined on $X^{(m)}$ we define the holomorphic $(q-1)$-form $\widetilde{I}(z, \Phi)$ on $P_{m}$ by

$$
\begin{equation*}
z^{*}(\Phi)=\widetilde{I}(z, \Phi) \wedge d t+O(t)+(\text { terms not involving } d t)^{3} \tag{3.9}
\end{equation*}
$$

As we have seen above, $\widetilde{I}(x, \Phi)$ only involves the coefficients of $t^{k / m}$ for $k \leqq m$, and thus it is well-defined and holomorphic on a finite dimensional subspace of $P_{m}$. In particular we need not worry about issues of convergence. We will see below how $\widetilde{I}(z, \Phi)$ changes when we change the local uniformizing parameters.

Now this construction will make sense when $\operatorname{dim} X=n$ is arbitrary. However, when $n=1$ so that $X^{(m)}$ is smooth, the 1 -forms will generate the holomorphic $q$-forms as an exterior algebra over $\mathcal{O}_{X^{(m)}}$. This will mean that there is no new intrinsic information in the $\widetilde{I}(z, \Phi)$ 's beyond that in the $I(z, \omega)$ 's for $\omega \in \Omega_{X / \mathbb{C}, x}^{1}$. As observed in section 8 below, $I(z, \omega)$ as defined in (3.1) is the same as $\widetilde{I}(z, \operatorname{Tr} \omega)$ as defined in (3.9) above.

For example, when $X$ is an algebraic curve if $z_{1}, \ldots, z_{N}$ are Puiseaux series for which

$$
\sum_{\nu} n_{\nu} I\left(z_{\nu}, \omega\right)=0, \quad n_{\nu} \in \mathbb{Z}
$$

for all $\omega \in \Omega_{X / \mathbb{C}, x}^{1}$, then we will have

$$
\sum_{\nu} n_{\nu} \widetilde{I}\left(z_{\nu}, \Phi\right)=0
$$

for all $\Phi$. However, as will now be explained this will change when $n \geqq 2$. Thus, when $n \geqq 2$ new geometric information will arise when we introduce the differentials of the Puiseaux series coefficients.

We will work this out in coordinates in the case $n=2$, as this case will clearly exhibit the central geometric ideas. In $\S 5$ we shall reformulate the coordinate discussion intrinsically.

Recall that $Z_{\{x\}}^{2}(X)$ denotes the group of regular $\operatorname{arcs} z(t)$ in $Z^{2}(X)$ such that $\lim |z(t)|=x$ where $|z(t)|$ is the support of $z(t)$. Any such $z(t)$ may

[^7]be represented in terms of local uniformizing parameters $\xi, \eta$ as a sum of irreducible Puiseaux series centered at $x$. We denote by $P$ the space of coefficients of such Puiseaux series. For any $\Phi \in \Omega_{X^{(m)} / \mathbb{C}, m x}^{q}$ we provisionally define an abelian invariant $\widetilde{I}(z, \Phi) \in \Omega_{P / \mathbb{C}, z}^{q-1}$ by
\[

$$
\begin{equation*}
z(t)^{*} \Phi=\widetilde{I}(z, \Phi) \wedge d t+O(t)+(\text { terms not involving } d t) \tag{3.10}
\end{equation*}
$$

\]

Because of (3.5) above, all of the information in abelian invariants is captured by the abelian invariants when $\Phi=\operatorname{Tr} \varphi$ is the trace of $\varphi \in \Omega_{X / \mathbb{C}, x}^{q}$ and $q=1,2$. In this case we set

$$
\widetilde{I}(z, \Phi)=\widetilde{I}(z, \varphi)
$$

and provisionally refer to $\widetilde{I}(z, \varphi)$ as a universal abelian invariant. ${ }^{4}$ The term "universal" refers to the hereditary property of traces discussed above.

Below we will show that the information in the universal abelian invariants $\widetilde{I}(z, \omega)$ for $\omega \in \Omega_{X / \mathbb{C}, x}^{1}$ is invariant under reparametrization of arcs and changes of coordinates. Then we will show that, modulo this information, the information in the universal abelian invariants $\widetilde{I}(z, \varphi)$ for $\varphi \in \Omega_{X / \mathbb{C}, x}^{2}$ is also invariant under reparametrization and coordinate changes. It is here that the differentials of the parameters appear, and the fact that there is new information via the universal abelian invariants corresponding to 2 forms is a harbinger of the difference between divisors and cycles in higher codimension.

We consider an arc which is a sum of Puiseaux series in $t$ and $t^{1 / 2}$ - from this the general pattern should be clear. Our family of 0 -cycles will thus be a sum

$$
\begin{equation*}
z(t)=\sum_{\lambda} x_{\lambda}(t)+\sum_{\nu} x_{\nu}^{+}(t)+x_{\nu}^{-}(t) \tag{3.11}
\end{equation*}
$$

where

$$
x_{\lambda}(t)=\left(\alpha_{\lambda_{1}} t+\cdots, \beta_{\lambda_{1}} t+\cdots\right)
$$

and

$$
\begin{aligned}
& x_{\nu}^{+}(t)=\left(a_{\nu_{1}} t^{1 / 2}+a_{\nu_{2}} t+\cdots, b_{\nu_{1}} t^{1 / 2}+b_{\nu_{2}} t+\cdots\right) \\
& x_{\nu}^{-}(t)=\left(-a_{\nu_{1}} t^{1 / 2}+a_{\nu_{2}} t+\cdots,-b_{\nu_{1}} t^{1 / 2}+b_{\nu_{2}} t+\cdots\right) .
\end{aligned}
$$

Since universal abelian invariants are additive in cycles it will suffice to consider them on

$$
z_{\alpha, \beta}(t)=\left(\alpha_{1} t+\cdots, \beta_{1} t+\cdots\right)
$$

and

$$
\begin{aligned}
z_{a, b}=\left(a_{1} t^{1 / 2}\right. & \left.+a_{2} t+\cdots, b_{1} t^{1 / 2}+b_{2} t+\cdots\right) \\
& +\left(-a_{1} t^{1 / 2}+a_{2} t+\cdots,-b_{1} t^{1 / 2}+b_{2} t+\cdots\right)
\end{aligned}
$$

[^8]Then

$$
\begin{aligned}
& I\left(z_{\alpha \beta}, d \xi\right)=\alpha_{1} \\
& I\left(z_{\alpha \beta}, d \eta\right)=\beta_{1}
\end{aligned}
$$

and

$$
\widetilde{I}\left(z_{\alpha \beta}, d \xi \wedge d \eta\right)=0
$$

all others are also zero.
The situation for $z_{a, b}$ is more interesting. We have

$$
\begin{aligned}
& I\left(z_{a b}, d \xi\right)=2 a_{2} \\
& I\left(z_{a b}, d \eta\right)=2 b_{2} \\
& I\left(z_{a b}, \xi d \xi\right)=a_{1}^{2} \\
& I\left(z_{a b}, \eta d \eta\right)=b_{1}^{2} \\
& I\left(z_{a b}, \xi d \eta\right)=I\left(z_{a b}, \eta d \xi\right)=a_{1} b_{1}
\end{aligned}
$$

and

$$
\widetilde{I}\left(z_{a b}, d \xi \wedge d \eta\right)=a_{1} d b_{1}-b_{1} d a_{1}
$$

all others are zero. Note that the information in $\widetilde{I}\left(z_{a b}, d \xi \wedge d \eta\right)$ is not a consequence of that in $I\left(z_{a b}, \omega\right)$ and its derivatives for $\omega \in \Omega_{X / \mathbb{C}, x}^{1}$. Also, we note that this new information arises from a 2 -form whose trace is not generated by traces of 1-forms.

Referring to (3.11) we see that the universal abelian invariants determine the quantities

$$
\left\{\begin{array}{l}
\sum_{\lambda} \alpha_{\lambda, 1}+\sum_{\nu} a_{\nu, 2}  \tag{3.12}\\
\sum_{\lambda} \beta_{\lambda, 1}+\sum_{\nu} b_{\nu, 2} \\
\sum_{\nu} a_{\nu, 1}^{2}, \sum_{\nu} b_{\nu, 1}^{2} \\
\sum_{\nu} a_{\nu, 1} b_{\nu, 1}
\end{array}\right.
$$

and

$$
\begin{equation*}
\sum_{\nu} a_{v, 1} d b_{\nu, 1}-b_{v, 1} d a_{v, 1} \tag{3.13}
\end{equation*}
$$

We note several aspects implied by these computations. The first is that if $z(t)$ is an irreducible Puiseaux series in $t^{1 / k}$, only the degree $<k$ homogeneous part of a differential shows up in the universal abelian invariants. We saw this phenomenon earlier for 0-cycles on a curve.

The second is that for a Puiseaux series

$$
z(t)=x_{1}(t)+\cdots+x_{k}(t)
$$

where
$x_{\ell}(t)=\left(a_{1} \epsilon^{\ell} t^{1 / k}+a_{2} \epsilon^{2 \ell} t^{2 / k}+\cdots, b_{1} \epsilon^{\ell} t^{\ell / k}+b_{2} \epsilon^{2 \ell} t^{2 / k}+\cdots\right), \quad \epsilon=e^{2 \pi \sqrt{-1} / k}$ only the coefficients of $t^{m / k}$ for $0 \leqq m \leqq k$ appear in the expression for universal abelian invariants.

The third is that (3.12) may be zero but (3.13) non-zero - the universal abelian invariants arising from 2-forms will detect subtle geometric/arithmetic information. More precisely, we see exactly that the new information coming from the 2 -forms arises from $\operatorname{Tr}(d \xi \wedge d \eta)$, which as we have seen above is not expressible in terms of traces of lower degree forms. Thus the phenomenon just observed is directly a reflection of (3.5).

We now turn to the behaviour of the universal abelian invariants under coordinate changes. For the purposes of illustration we shall take $\alpha_{\lambda, 1}=$ $\alpha_{\lambda}, \beta_{\lambda, 1}=\beta_{\lambda}, a_{\nu, 1}=a_{\nu}$ and $b_{\nu, 1}=b_{\nu}$. The conclusion we shall draw will hold in generality.

The first fact is

Under a scaling $t \rightarrow \mu t$, the universal abelian invariants scale by $\mu^{-1}$
The point is that no terms $d \mu$ appear. The second fact is that

$$
\begin{align*}
& \text { Under under a coordinate change }  \tag{3.15}\\
& \qquad \begin{array}{c}
\xi^{\#}=f(\xi, \eta) \\
\eta^{\#}=g(\xi, \eta)
\end{array}
\end{align*}
$$

the universal abelian invariants change by

$$
\left(\begin{array}{c}
\sum_{\nu} a_{\nu}^{\# 2}  \tag{3.16}\\
\sum_{\nu} a_{\nu}^{\#} b_{\nu}^{\#} \\
\sum_{\nu} b_{\nu}^{\# 2} \\
\sum_{\lambda} a_{\lambda}^{\#} \\
\sum_{\lambda} \beta_{\lambda}^{\#} \\
\sum_{\nu} a_{\nu}^{\#} d b_{\nu}^{\#}-b_{\nu}^{\#} d a_{\nu}^{\#}
\end{array}\right)=\left(\begin{array}{cc} 
& 0 \\
\cdot & \cdot \\
\cdot & \cdot \\
\cdot & \cdot \\
A & \cdot \\
\cdot & \cdot \\
\cdot & \cdot \\
\cdot & \cdot \\
& 0 \\
B & C
\end{array}\right)\left(\begin{array}{c}
\sum_{\nu} a_{\nu}^{2} \\
\sum_{\nu} a_{\nu} b_{\nu} \\
\sum_{\nu} b_{\nu}^{2} \\
\sum_{\lambda} \alpha_{\lambda} \\
\sum_{\lambda} \beta_{\lambda} \\
\sum_{\nu} a_{\nu} d b_{\nu}-b_{\nu} d a_{\nu}
\end{array}\right)
$$

where $A, C$ are square matrices of complex numbers and $B$ is a matrix with entries in $\Omega_{P / \mathbb{C}}^{1}$.

The proofs of (3.14) and (3.15) are by direct computation. For example, for

$$
z(t)=\left(a t^{1 / 2}+\cdots, b t^{1 / 2}+\cdots\right)+\left(-a t^{1 / 2}+\cdots,-b t^{1 / 2}+\cdots\right)+(\alpha t, \beta t)
$$

under a coordinate change

$$
\left\{\begin{array}{l}
\xi^{\#}=f(\xi, \eta) \\
\eta^{\#}=g(\xi, \eta)
\end{array}\right.
$$

we have

$$
\begin{aligned}
a^{\#} & =a f_{\xi}+b f_{\eta} \\
b^{\#} & =a g_{\xi}+b g_{\eta} \\
\alpha^{\#} & =\alpha f_{\xi}+\beta f_{\eta}+\frac{a^{2}}{2} f_{\xi \xi}+a b f_{\xi \eta}+\frac{b^{2}}{2} f_{\eta \eta} \\
\beta^{\#} & =\alpha g_{\xi}+\beta g_{\xi \eta}+\frac{a^{2}}{2} g_{\xi \xi}+a b g_{\xi \eta}+\frac{b^{2}}{2} g_{\eta \eta}
\end{aligned}
$$

where all partial derivatives are evaluated at $x$. It follows that the matrix in (3.16) is

$$
\left(\begin{array}{cccccc}
f_{\xi}^{2} & 2 f_{\xi} f_{\eta} & f_{\eta}^{2} & 0 & 0 & 0  \tag{3.17}\\
f_{\xi} g_{\xi} & f_{\xi} g_{\eta}+f_{\eta} g_{\xi} & f_{\eta} g_{\eta} & 0 & 0 & 0 \\
g_{\xi}^{2} & 2 g_{\xi} g_{\eta} & g_{\eta}^{2} & 0 & 0 & 0 \\
\frac{1}{2} f_{\xi \xi} & f_{\xi \eta} & \frac{1}{2} f_{\eta \eta} & f_{\xi} & f_{\eta} & 0 \\
\frac{1}{2} g_{\xi \xi} & g_{\xi \eta} & \frac{1}{2} g_{\eta \eta} & g_{\xi} & g_{\eta} & 0 \\
f_{\xi} d g_{\xi}-g_{\xi} d f_{\xi} & * & f_{\eta} d g_{\eta}-g_{\eta} d f_{\eta} & 0 & 0 & f_{\xi} g_{\eta}-f_{\eta} g_{\xi}
\end{array}\right)
$$

where $*=f_{\xi} d g_{\eta}+f_{\eta} d g_{\xi}-g_{\eta} d f_{\xi}-g_{\xi} d f_{\eta}$.
We may summarize this discussion as follows:
For any $z=z(t)$ in $Z_{\{x\}}^{n}(X)$, the universal abelian invariants

$$
\begin{equation*}
\widetilde{I}(z, \varphi) \in \Omega_{P / \mathbb{C}, z}^{p-1} \tag{3.18}
\end{equation*}
$$

are defined for $\varphi \in \Omega_{X / \mathbb{C}, x}^{p}$. Here, $P$ is the space of coefficients of Puiseaux series in terms of a choice of parameter $t$ and local uniformizing parameters on $X$. The vanishing of the universal abelian invariants for all $\varphi$ and all $p \leqq q$ for fixed $q$ with $1 \leqq q \leqq n$ is independent of these choices.

Looking ahead, there is one more step to be taken before we can define the relation of first order equivalence, to be denoted $\equiv_{1^{\text {st }}}$, on $Z_{\{x\}}^{n}(X)$. Once this has been done then we can geometrically define the tangent space by

$$
T_{\{x\}} Z^{n}(X)=Z_{\{x\}}^{n}(X) / \equiv_{1^{\text {st }}}
$$

This step, which will be seen to only make good geometric sense in the algebraic setting, will consist in working with the absolute differentials $\Omega_{X / \mathbb{Q}}^{\bullet}$. In this case, for $\varphi \in \Omega_{X / \mathbb{Q}, x}^{p}$ we will have in place of (3.18) that

$$
z(t)^{*} \varphi=\widetilde{I}(z, \varphi) d t+O(t)+\text { terms not involving } d t
$$

where

$$
\widetilde{I}(z, \varphi) \in \Omega_{P / \mathbb{Q}, z}^{p-1}
$$

Then, and this is the point, there is an evaluation map

$$
\Omega_{P / \mathbb{Q}, z}^{p-1} \xrightarrow{\mathrm{ev}_{z}} \Omega_{\mathbb{C} / \mathbb{Q}}^{p-1}
$$

and we may use this map to define the universal abelian invariants $I(z, \varphi)$ by

$$
\begin{equation*}
I(z, \varphi)=\operatorname{ev}_{z}(\widetilde{I}(z, \varphi)) \in \Omega_{\mathbb{C} / \mathbb{Q}}^{p-1} \tag{3.19}
\end{equation*}
$$

We will then define

$$
z \equiv_{1^{\text {st }}} 0
$$

by the condition

$$
\begin{equation*}
I(z, \varphi)=0 \text { for all } \varphi \in \Omega_{X / \mathbb{Q}, x}^{p} \quad \text { and } \quad 1 \leqq p \leqq n \tag{3.20}
\end{equation*}
$$

Since automatically $I(z, \varphi)=0$ if $\varphi \in \Omega_{\mathbb{C} / \mathbb{Q}}^{p} \subset \Omega_{X / \mathbb{Q}, x}^{p}$, we need only have (3.20) for all

$$
\varphi \in \Omega_{X / \mathbb{Q}, x}^{p} / \Omega_{\mathbb{C} / \mathbb{Q}}^{p} .
$$

When $n=1$ we only have the case $p=1$ to consider and then

$$
\Omega_{X / \mathbb{Q}, x}^{1} / \Omega_{\mathbb{C} / \mathbb{Q}}^{1} \cong \Omega_{X / \mathbb{C}, x}^{1}
$$

this is the reason why absolute differentials did not enter in this case. One reason why forms of higher degree enter when $n \geqq 2$ was explained above.

The above discussion reflects the correct thing to do when $X$ is defined over $\mathbb{Q}$. For more general $X$, a slight modification is necessary and one must use spreads.

In the next section we will first present, from a complex analysts' perspective, a digression on absolute differentials and on their geometric meaning. There we will then give an informal, geometric discussion of spreads. Then in the subsequent sections we will return to the more formal definitions and properties of $\underline{\underline{T}} Z^{n}(X)$.

## Chapter Four

## Absolute differentials (I)

### 4.1 GENERALITIES

Given a commutative ring $R$ and subring $S$, one defines the Kähler differentials of $R$ over $S$, denoted

$$
\Omega_{R / S}^{1},
$$

to be the $R$-module generated by all symbols of the form

$$
a d b \quad a, b \in R
$$

subject to the relations

$$
\left\{\begin{array}{l}
d(a+b)=d a+d b  \tag{4.1}\\
d(a b)=a d b+b d a \\
d s=0 \text { if } s \in S
\end{array}\right.
$$

In this paper $R$ will be a field $k$ of characteristic zero, a polynomial ring over $k$ or a local ring $\mathcal{O}$ with residue field $k$ of characteristic zero. From

$$
d(a+a)=2 d a
$$

it follows that $d 2=0$, and in fact

$$
d p=0 \quad p \in \mathbb{Z}
$$

and then from $d\left(q^{-1}\right)=-q^{-2} d q=0$ we have

$$
d(p / q)=0 \quad p, q \in \mathbb{Z}
$$

The Kähler differentials $\Omega_{R / \mathbb{Q}}^{1}$ are called absolute differentials. We shall be primarily concerned with the cases

$$
\left\{\begin{array}{l}
\Omega_{k / \mathbb{Q}}^{1} \\
\Omega_{\mathcal{O} / k}^{1}, \Omega_{\mathcal{O} / \mathbb{Q}}^{1}
\end{array}\right.
$$

If $k$ is a finite extension field of $\mathbb{Q}$, say

$$
k=\mathbb{Q}(\alpha)
$$

where $\alpha \in \mathbb{C}$ satisfies an irreducible equation

$$
f(\alpha)=0
$$

where $f(x) \in \mathbb{Q}[x]$, then taking the absolute differentials of this equation we have

$$
\begin{aligned}
f^{\prime}(\alpha) d \alpha & =0 \\
\Rightarrow d \alpha & =0 \\
\Rightarrow \Omega_{k / \mathbb{Q}}^{1} & =0 .
\end{aligned}
$$

More generally, if $k$ is a finitely generated field extension of $\mathbb{Q}$, and if there is

$$
f\left(x_{1}, \ldots, x_{n}\right) \in \mathbb{Q}\left[x_{1}, \ldots, x_{n}\right]
$$

with

$$
f\left(\alpha_{1}, \ldots, \alpha_{n}\right)=0 \quad \alpha_{1}, \ldots, \alpha_{n} \in k
$$

then

$$
\sum_{i} f_{x_{i}}\left(\alpha_{1}, \ldots, \alpha_{n}\right) d \alpha_{i}=0
$$

This gives a linear relation on $d \alpha_{1}, \ldots, d \alpha_{n}$ in $\Omega_{k / \mathbb{Q}}^{1}$; in fact, one sees by this line of reasoning (cf. [34]) that

$$
\operatorname{dim}_{k} \Omega_{k / \mathbb{Q}}^{1}=\operatorname{tr} \operatorname{deg}(k / \mathbb{Q})
$$

Similarly,

$$
\operatorname{dim} \Omega_{\mathbb{C} / \mathbb{Q}}^{1}=\infty
$$

with basis $d \alpha_{1}, d \alpha_{2}, \ldots$ where $\alpha_{1}, \alpha_{2}, \ldots$ is a transcendence basis for $\mathbb{C} / \mathbb{Q}$.
If $X$ is a variety defined over a field $K$ with $K \supseteq k$, we will use the notation

$$
\Omega_{X(K) / k}^{1}
$$

for the sheaf $\mathcal{O}_{X(K)}$-modules with stalks

$$
\Omega_{X(K) / k, x}^{1}=\Omega_{\mathcal{O}_{X(K), x / k}}^{1}, \quad x \in X(K)
$$

the Kähler differentials of $\mathcal{O}_{X(K), x}$ over $k$. When $X$ is defined over $\mathbb{C}$, we will generally write

$$
\Omega_{X / k}^{1}=\Omega_{X(\mathbb{C}) / k}^{1}
$$

There is a natural exact sequence

$$
0 \rightarrow \Omega_{K / k}^{1} \otimes \mathcal{O}_{X(K)} \rightarrow \Omega_{X(K) / k}^{1} \rightarrow \Omega_{X(K) / K}^{1} \rightarrow 0
$$

that we will most often use in the form

$$
\begin{equation*}
0 \rightarrow \Omega_{\mathbb{C} / \mathbb{Q}}^{1} \otimes \mathcal{O}_{X} \rightarrow \Omega_{X / \mathbb{Q}}^{1} \rightarrow \Omega_{X / \mathbb{C}}^{1} \rightarrow 0 \tag{4.2}
\end{equation*}
$$

In general we set

$$
\Omega_{R / S}^{q}=\wedge^{q} \Omega_{R / S}^{1}
$$

This gives rise to a complex $\left(\Omega_{R / S}^{\bullet}, d\right)$ were $d\left(a d b_{1} \wedge \cdots \wedge d b_{q}\right)=d a \wedge d b_{1} \wedge$ $\cdots \wedge d b_{q}$. From (4.2) the $R$-module $\Omega_{X / \mathbb{Q}}^{q}$ inherits a decreasing filtration

$$
F^{m} \Omega_{X / \mathbb{Q}}^{q}=\operatorname{image}\left(\Omega_{\mathbb{C} / \mathbb{Q}}^{m} \otimes \Omega_{X / \mathbb{Q}}^{q-m} \rightarrow \Omega_{X / \mathbb{Q}}^{q}\right) ;
$$

a differential form belongs to $F^{m} \Omega_{X / \mathbb{Q}}^{q}$ if it has at least $m$ differentials of constants. The graded pieces are

$$
G r^{m} \Omega_{X / \mathbb{Q}}^{q} \cong \Omega_{\mathbb{C} / \mathbb{Q}}^{m} \otimes \Omega_{X / \mathbb{C}}^{q-m}
$$

In particular we note that

$$
\Omega_{X / \mathbb{Q}}^{q} \neq 0 \text { if } q>\operatorname{dim} X
$$

For example, when $X$ is a curve there is an exact sequence

$$
0 \rightarrow \Omega_{\mathbb{C} / \mathbb{Q}}^{2} \otimes \mathcal{O}_{X} \rightarrow \Omega_{X / \mathbb{Q}}^{2} \rightarrow \Omega_{\mathbb{C} / \mathbb{Q}}^{1} \otimes \Omega_{X / \mathbb{C}}^{1} \rightarrow 0
$$

and we may think of $\Omega_{X / \mathbb{Q}}^{2}$ as consisting of expressions

$$
\begin{cases}d \alpha \wedge d \beta & \alpha, \beta \in \mathbb{C} \\ d \alpha \wedge \omega & \alpha \in \mathbb{C}, \omega \in \Omega_{X / \mathbb{C}}^{1}\end{cases}
$$

where in the second expression $\omega$ is a "geometric" object (see (4.4) below).
If we have a mapping

$$
f: Y \rightarrow X
$$

between algebraic varieties, then for $x \in X$ the pull-back $f^{*}: \mathcal{O}_{Y, f(x)} \rightarrow \mathcal{O}_{X, x}$ gives an induced mapping of Kähler differentials, and in particular we have

$$
f^{*}: \Omega_{X / \mathbb{Q}}^{q} \rightarrow \Omega_{Y / \mathbb{Q}}^{q}
$$

Taking for $Y$ a closed point $x$ of $X$, we have

$$
\Omega_{x / \mathbb{Q}}^{q} \cong \Omega_{\mathbb{C} / \mathbb{Q}}^{q}
$$

and the inclusion $x \hookrightarrow X$ induces an evaluation map

$$
e_{x}: \Omega_{X / \mathbb{Q}}^{q} \rightarrow \Omega_{\mathbb{C} / \mathbb{Q}}^{q} .
$$

Explicitly, for $f, g \in \mathcal{O}_{X, x}$ and $\alpha \in \mathbb{C}$

$$
\left\{\begin{array}{l}
e_{x}(g d \alpha)=g(x) d \alpha \\
e_{x}(g d f)=g(x) d(f(x))
\end{array}\right.
$$

If $X$ is defined over a field $k$ and $f \in \mathcal{O}_{X(k), x}$, then

$$
e_{x}(d f)=d(f(x))
$$

reflects the field of definition of $x$.
To give another very concrete example suppose that $f(x, y) \in \mathbb{C}[x, y]$ so that

$$
f(x, y)=0
$$

defines a plane curve $X$. The on $X$ we have the relation

$$
\begin{equation*}
f_{x} d x+f_{y} d y+\bar{d} f=0 \tag{4.3}
\end{equation*}
$$

where $\bar{d}$ means "apply $d_{\mathbb{C} / \mathbb{Q}}$ to the coefficients of $f$ ". If $f$ is defined over $\mathbb{Q}$ - or even over $\overline{\mathbb{Q}}$ - this is just the usual relation

$$
f_{x} d x+f_{y} d y=0
$$

but (4.3) is more complicated and in some ways more interesting if there are transcendentals among the coefficients of $f$. We note that a consequence of (4.3) is that on $X$

$$
f_{x} d x \wedge d y=-\bar{d} f \wedge d y
$$

This allows us to explicitly convert $d x \wedge d y$ into an element of $\Omega_{\mathbb{C} / \mathbb{Q}}^{1} \otimes \Omega_{X / \mathbb{C}}^{1}$ as in the above discussion for $\Omega_{X / \mathbb{Q}}^{2}$ for a curve $X$.

We also note that for $p \in X$

$$
e_{p}(d x \wedge d y)=-\frac{\bar{d} f(p) \wedge d(y(p))}{f_{x}(p)}
$$

or equivalently

$$
e_{p}(d x \wedge d y)=d(x(p)) \wedge d(y(p))
$$

Thus, $e_{p}(d x \wedge d y)=0$ is equivalent to $p$ being defined over an extension field of $\mathbb{Q}$ of transcendence degree at most 1 .

Side Discussion: Kähler differentials don't work analytically
A basic principle in complex algebraic geometry is Serre's GAGA (cf. [Serre, J.-P., Géométrie algébrique et géométrie analytique, Ann. Inst. Fourier $\mathbf{6}$ (1956), 1-42]), which operationally says that in the study of complex projective varieties one may work either complex algebraically (Zariski topology, algebraic coherent sheaf cohomology, etc.) or complex analytically (analytic topology, analytic coherent sheaf cohomology, etc.) with the same end result. From the perspective of this paper a central geometric fact is the following: In the algebraic category, there is a natural isomorphism of $\mathcal{O}_{X}$ modules

$$
\begin{equation*}
\Omega_{X / \mathbb{C}}^{1} \cong \mathcal{O}_{X}\left(T^{*} X\right) \tag{4.4}
\end{equation*}
$$

Here, the LHS is the sheaf of Kähler differentials and the RHS is the sheaf of regular sections of the cotangent bundle $T^{*} X \rightarrow X$. This identifies the algebraic object $\Omega_{X / \mathbb{C}}^{1}$ with the geometric object $\mathcal{O}_{X}\left(T^{*} X\right)$. As we shall explain in a moment, (4.4) is false in the analytic category.

The reason this is important for our study of the tangent spaces to the space of cycles is this: As explained in sections 6(i), 6(ii), and 7(iii) below, elementary geometric considerations of what the relations for $1^{\text {st }}$ order equivalence of arcs in $Z^{p}(X)$ should be lead directly to the defining relations (4.1) for Kähler differentials. Because of (4.2) and (4.4) above, in the algebraic category these defining relations then relate directly to the geometry of the variety. But this is no longer true in the analytic category, and this has the implication that our discussion of $T Z^{p}(X)$ only works in the algebraic setting.

Turning to (4.4) and its failure in the analytic setting, the most näive way to understand the Kähler differential

$$
\begin{equation*}
d: \mathcal{O}_{X} \rightarrow \Omega_{X / \mathbb{Q}}^{1} \tag{4.5}
\end{equation*}
$$

for an algebraic variety $X$ is as follows: First, for $f\left(x_{1}, \ldots x_{n}\right) \in \mathbb{C}\left[x_{1}, \ldots x_{n}\right]$ we have

$$
\begin{equation*}
d f=\sum_{i} f_{x_{i}} d x_{i}+\bar{d} f \tag{4.6}
\end{equation*}
$$

as above. The axioms for Kähler differentials enable us to differentiate a polynomial - viewed as a finite power series - term by term thus giving an explicit formula for $d f$. Using (4.6) we may differentiate a rational function $f / g$ by the quotient rule (restricted, of course, to the open set where $g \neq 0$ ). Finally, any $X$ is locally an algebraic subvariety of $\mathbb{C}^{n}$ defined by polynomial equations

$$
f_{\nu}\left(x_{1}, \ldots, x_{n}\right)=0
$$

and (4.5) is defined by considering $\mathcal{O}_{X, x}$ to be given by the restrictions to $X$ of the rational functions $r=f / g$ on $\mathbb{C}^{n}$ that are regular near $x$, defining

$$
d r=\frac{d f}{g}-\frac{f d g}{g^{2}}
$$

using (4.6), and imposing the relations

$$
\sum_{i} f_{\nu, x_{i}} d x_{i}+\bar{d} f_{\nu}=0
$$

Remark: An interesting fact is that the axioms for Kähler differentials extend formally to allow us to at least formally differentiate term by term the local analytic power series of an algebraic function, and when this is done the resulting series converges and gives the correct answer for the absolute differential of the function.

For example, suppose that $f(x, y)=\sum_{p, q=0}^{n} a_{p, q} x^{p} y^{q} \in \mathbb{C}[x, y]$ where

$$
\left\{\begin{aligned}
f(0, b) & =0 \\
f_{y}(0, b) & \neq 0
\end{aligned}\right.
$$

Then there is a unique convergent series

$$
\begin{equation*}
y(x)=\sum_{i} b_{i} x^{i}, \quad b_{0}=b \tag{4.7}
\end{equation*}
$$

satisfying

$$
f(x, y(x))=0
$$

We note that the coefficients

$$
b_{i} \in \overline{\mathbb{Q}\left(a_{00}, \ldots, a_{n n}\right)},
$$

so that the differentials $d b_{i}$ lie in a finite dimensional subspace $\Omega_{\mathbb{C} / \mathbb{Q}}^{1}$. Thus the expression

$$
\begin{equation*}
\sum_{i}\left(d b_{i}+(i+1) b_{i+1} d x\right) x^{i} \tag{4.8}
\end{equation*}
$$

is a well-defined formal series. We claim that:
(4.9) If (4.7) converges for $|x|<c$, then (4.8) also converges for $|x|<c$ and represents the absolute differential $d y(x)$ in the sense that we have the identity

$$
-\frac{1}{f y}\left(\bar{d} f+f_{x} d x\right)=\sum_{i}\left(d b_{i}+(i+1) b_{i+1} d x\right) x^{i}
$$

when the LHS is expanded in a series using (4.7).
Before giving the proof we note the
(4.10) Corollary: For $a \in \mathbb{C}$ with $|a|<c$ we have

$$
d_{\mathbb{C} / \mathbb{Q}}(y(a))=\sum_{i} d b_{i} a^{i}+\left(\sum_{i}(i+1) b_{i+1} a^{i}\right) d a .
$$

As will be noted below, this is false for a general analytic function. In fact, it is the case that

$$
\lim _{n} a_{n}=a \Rightarrow \lim _{n} d_{\mathbb{C} / \mathbb{Q}}\left(a_{n}\right)=d_{\mathbb{C} / \mathbb{Q}} a
$$

only for very special limits such as in the finite approximations in (4.7).
Proof of (4.9): Suppose first that $f[x, y] \in \mathbb{Q}[x, y]$. Then the desired identity

$$
-f_{x} / f_{y}=\sum_{i}(i+1) b_{i+1} x^{i}
$$

follows from the usual analytic result over $\mathbb{C}$.
Suppose next that $f\left(x_{0}, \ldots, x_{n}, y\right) \in \mathbb{Q}\left[x_{0}, \ldots, x_{n}, y\right]$ and the proposed identity in (4.9) is extended to this case to read

$$
\begin{equation*}
-\frac{1}{f_{y}}\left(\bar{d} f+\sum_{\alpha} f_{x_{\alpha}} d x_{a}\right)=\sum_{I}\left\{d b_{I}+\left(\left|i_{\alpha}\right|+1\right) b_{I+\{\alpha\}} d x_{\alpha}\right\} x^{I} \tag{4.11}
\end{equation*}
$$

where $x^{I}=x_{0}^{i_{0}} \cdots x_{n}^{i_{n}}$ and $I+\{\alpha\}=\left(i_{a}, \ldots i_{\alpha}+1, \ldots, i_{n}\right)$. By our assumption, $\bar{d} f=0$ and all $d b_{I}=0$ so that again (4.11) follows from the usual analytic result.

In general, $f(x, y) \in k[x, y]$ where $k$ is finitely generated over $\mathbb{Q}$. We may write

$$
k \cong \mathbb{Q}\left[x_{1}, \ldots, x_{n}\right] /\left\{g_{1}, \ldots, g_{m}\right\}
$$

where each $g_{j} \in \mathbb{Q}\left[x_{1}, \ldots, x_{n}\right]$. Setting $x_{0}=x$ we may lift $f(x, y)$ to $f\left(x_{0}, x_{1}, \ldots, x_{n}, y\right) \in \mathbb{Q}\left[x_{0}, \ldots, x_{n}, y\right]$, and then the previous argument applies, taking note of the fact that dividing by $g_{1}, \ldots, g_{m}$ does not affect the calculation.

Remark: In the case when $k$ is a number field the above result follows from Eisenstein's characterization of the power series expansions of algebraic functions defined over $k$.

Now for a complex analytic variety $X^{a n}$ and subfield $k$ of $\mathbb{C}$ we may define the sheaf of Kähler differentials, denoted

$$
\Omega_{\mathcal{O}_{X^{a n} / k}}^{1},
$$

as before. This is a sheaf of $\mathcal{O}_{X^{a n}}$-modules and as in the algebraic case there is a map

$$
\Omega_{\mathcal{O}_{X^{a n} / \mathbb{C}}}^{1} \rightarrow \mathcal{O}_{X^{a n}}\left(T^{*} X^{a n}\right)
$$

However, essentially because the axioms for Kähler differentials only allow finite operations, this mapping is not an isomorphism of $\mathcal{O}_{X^{a n}}$ modules.

Concretely, for $X^{a n}=\mathbb{C}$ with coordinate $z$ and letting $d$ denote the Kähler differential map

$$
\mathcal{O}_{X^{a n}} \rightarrow \Omega_{\mathcal{O}_{X^{a n}} / \mathbb{C}}^{1}
$$

we cannot say that

$$
d e^{z}=e^{z} d z
$$

Note that even though term by term differentiation of the series for $e^{z}$ makes sense, we have that

$$
d\left(e^{z}\right) \neq \sum_{n} d\left(\frac{z^{n}}{n!}\right)=\sum_{n} \frac{z^{n-1}}{(n-1)!} d z
$$

where the second equality follows from $d(1 / n!)=0$. In fact

$$
0 \neq d e=\left.\left(d\left(e^{z}\right)\right)\right|_{z=1} \neq \sum \frac{d 1}{(n-1)!}=0
$$

in contrast to Corollary (4.10).
In concluding this section for later use we will give one observation that results from the above discussion. Namely, suppose that $X$ is an algebraic variety defined over a field $k$. If $x_{1}, \ldots, x_{n} \in k(X)$ give local uniformizing parameters in a neighborhood of $x \in X$, then the $d x_{i} \in \Omega_{X / \mathbb{Q}, x}^{1}$ give generators for $\Omega_{X / \mathbb{C}, x}^{1}$ as an $\mathcal{O}_{X, x}$-module. If $y_{1}, \ldots, y_{n} \in k(X)$ is another set of local uniformizing parameters, then each $y_{i}=y_{i}(x)$ is an algebraic function of the $x_{j}$ and we have in $\Omega_{X / \mathbb{Q}, x}^{1}$

$$
d y_{i}=\sum_{j} \frac{\partial y_{i}(x)}{\partial x_{j}} d x_{j} \quad \bmod \Omega_{k / \mathbb{Q}}^{1} .
$$

We will write this as

$$
\left(\begin{array}{c}
d y_{1}  \tag{4.12}\\
\vdots \\
d y_{n}
\end{array}\right)=J\left(\begin{array}{c}
d x_{1} \\
\vdots \\
d x_{n}
\end{array}\right)+\left(\begin{array}{c}
\alpha_{1} \\
\vdots \\
\alpha_{n}
\end{array}\right)
$$

where $J$ is the Jacobian matrix and the $\alpha_{i} \in \Omega_{\mathbb{C} / \mathbb{Q}}^{1} \otimes \mathcal{O}_{X, x}$. We may symbolically write

$$
\alpha_{i}=\bar{d} y_{i}(x)
$$

where the notation means: "Apply $d_{k / \mathbb{Q}}$ to the coefficients in the series expansion of $y_{i}(x)$ ".

Turning to $q$-forms of higher degree, from (4.12) we have for $q=2$

$$
\begin{align*}
d y_{i} \wedge d y_{j} \equiv & \sum_{k, l} \frac{\partial\left(y_{i}, y_{j}\right)}{\partial\left(x_{k}, x_{l}\right)} d x_{k} \wedge d x_{l}  \tag{4.13}\\
& +\sum_{k}\left(\frac{\partial y_{i}}{\partial x_{k}} d_{j}-\frac{\partial y_{j}}{\partial x_{k}} d i\right) \wedge d x_{k} \quad \bmod \Omega_{k / \mathbb{Q}}^{2}
\end{align*}
$$

Comparing with (3.16) and (3.17) above, we see that the second term in (4.13) has exactly the same formal expression as the marix $B$. This will be explained below.

### 4.2 SPREADS

The fundamental concept of a spread dates at least to the mathematicians - especially Weil - who were concerned with the foundations of arithmetic geometry. The modern formulation is due especially to Grothendieck and has been used by Deligne and others in a geometric setting. The idea is that whenever one has an algebraic variety $X$ defined over a field $k \supseteq \mathbb{Q}$, one obtains a family $X_{s}$ of complex varieties parametrized by the different embeddings

$$
s: k \hookrightarrow \mathbb{C} .
$$

Anything algebro-geometric that one wishes to study - e.g., the configurations of the subvarieties of $X$ that are defined over $k-$ can and should be done for the entire family.

If we have a presentation

$$
k=\mathbb{Q}\left(\alpha_{1}, \ldots, \alpha_{N}\right)
$$

where

$$
g_{\lambda}\left(\alpha_{1}, \ldots, \alpha_{N}\right)=0
$$

generate the relations over $\mathbb{Q}$ satisfied by the $\alpha_{i}$. Then

$$
g_{\lambda}\left(s_{1}, \ldots, s_{N}\right) \in \mathbb{Q}\left[s_{1}, \ldots, s_{N}\right]
$$

and one may take for the parameter space of the spread the variety

$$
S=\operatorname{Var}\left\{g_{\lambda}\right\}
$$

Then $S$ is defined over $\mathbb{Q}$ and

$$
\mathbb{Q}(S) \cong k .
$$

Every $s \in S(\mathbb{C})$ that does not lie in a proper subvariety of $S$ defined over $\mathbb{Q}$ corresponds to a complex embedding

$$
k \hookrightarrow \mathbb{C}
$$

given by

$$
\alpha_{i} \rightarrow s_{i}
$$

and this is a one-to-one correspondence. ${ }^{1}$
If $X$ is an algebraic variety defined over $k$, then for each $s \in S(\mathbb{C})$ as above one obtains a complex variety $X_{s}$ defined over $\mathbb{Q}\left(s_{1}, \ldots, s_{N}\right)$. In terms of any algebraic construction, $X_{s}$ and $X_{s^{\prime}}$ are indistinguishable if $s$ and $s^{\prime}$ do not lie in any proper subvariety of $S(\mathbb{C})$ defined over $\mathbb{Q}$. However, the transcendental geometry of $X_{s}$ and $X_{s^{\prime}}$ as complex manifolds will generally

[^9]be quite different. The $X_{s}$ fit together to form a family
where $S=S(\mathbb{C})$, that we call the spread of $X$ over $k$.
Given an algebraic cycle $Z$ on $X$ defined over $k-$ i.e., $Z \in Z^{p}(X(k))-$ one obtains a family of cycles $Z_{s} \in Z^{p}\left(X_{s}\right)$ that form a cycle $Z$ on $X$ that is defined over $\mathbb{Q}$ - i.e., $Z \in Z^{p}(\mathcal{X}(\mathbb{Q}))$. For our purposes, everything is local in the sense that we need only consider the points of $S$ that satisfy no further algebraic relations over $\mathbb{Q}$.

Turning matters around, if we begin with a complex variety $X$, then $X$ will be defined over a field $k$ as above and we obtain a spread family (4.14) together with a reference point $s_{0} \in S$ with

$$
X=X_{s_{0}} \cdot{ }^{2}
$$

Such spread families are in general very special among the local moduli spaces (Kuranishi families) of complex varieties.

The "spread philosophy" is that in any algebro-geometric situation there will be some finitely generated field extension of $\mathbb{Q}$ over which everything is defined, and it is geometrically natural to make use of the resulting spread. This is an essential element in our approach to studying the tangent space to algebraic cycles, and geometrically it is one door through which absolute differentials enter the story.

From a very concrete perspective, let $X$ be an algebraic variety given locally in affine $(n+1)$-space by an equation

$$
f(x)=\sum_{I} \alpha_{I} x^{I}=0
$$

where $I=\left(i_{1}, \ldots, i_{n+1}\right)$ and $x^{I}=x_{1}^{i_{1}} \cdots x_{n+1}^{i_{n+1}}$ (the case where $X$ is defined by several equations will be similar). We may take

$$
k=\mathbb{Q}\left(\cdot \cdot, \alpha_{I}, \cdot \cdot\right)
$$

to be the field generated by coefficients of $f(x)$, and we let

$$
g_{\nu}\left(\cdot \cdot, \alpha_{I}, \cdot \cdot\right)=0
$$

generate the relations defined over $\mathbb{Q}$ satisfied by these coefficients. We set

$$
f(x, s)=\sum_{I} s_{I} x^{I}
$$

[^10]and may think of the spread as given in $\left(x_{i}, s_{I}\right)$-space by the equations
\[

\left\{$$
\begin{array}{c}
f(x, s)=0  \tag{4.15}\\
g_{\nu}(s)=0
\end{array}
$$\right.
\]

where $x=\left(x_{1}, \ldots, x_{n+1}\right)$ and $s=\left(\cdot \cdot, s_{I}, \cdot \cdot\right)$.
As noted above, the algebraic properties over $k$ of $X$ depend only on the polynomial relations over $\mathbb{Q}$ among the coefficients of the defining equation of $X$. For example, suppose that the equations

$$
l_{\lambda}(x)=\sum_{i} l_{\lambda i} x_{i}=0 \quad \lambda=1, \ldots, n
$$

where $l_{\lambda i} \in k$ define a line $L \subset X$. This condition may be expressed by

$$
f(x)=\sum_{\nu} h_{\lambda}(x) l_{\lambda}(x)
$$

where $h_{\lambda}(x) \in k\left[x_{1}, \ldots, x_{n+1}\right]$. We may express the $l_{\lambda i}$ and the coefficients of $h_{\lambda}(x)$ as being rational functions in $\mathbb{Q}\left(\cdot \cdot, \alpha_{I}, \cdot \cdot\right)$. Replacing $\alpha=\left(\cdot, \alpha_{I}, \cdot \cdot\right)$ by $s=\left(\cdot \cdot, s_{I}, \cdot \cdot\right) \in S$ we obtain a family of lines $L_{s} \subset X_{s}$.

Let now $X$ be a smooth complex algebraic variety defined over a field $k$, and consider the spread (4.14) with distinguished point $s_{0} \in S$ where $X=X_{s_{0}}$. Then there are fundamental natural identifications

$$
\begin{equation*}
\Omega_{X(k) / \mathbb{Q}}^{1} \cong \Omega_{X(\mathbb{Q}) / \mathbb{Q}}^{1} \tag{4.16a}
\end{equation*}
$$

and

$$
\begin{equation*}
\Omega_{S(\mathbb{Q}) / \mathbb{Q}, s_{0}}^{1} \cong \Omega_{k / \mathbb{Q}}^{1} \otimes \mathcal{O}_{S(\mathbb{Q}), s_{0}} \tag{4.16~b}
\end{equation*}
$$

Here, (4.16a) means the following: Given $x \in X(k)$ there is the corresponding point $\left(x, s_{0}\right) \in \mathcal{X}(\mathbb{Q})$, and we have

$$
\begin{equation*}
\mathcal{O}_{X(k), x} \cong \mathcal{O}_{X(\mathbb{Q}),\left(x, s_{0}\right)} \tag{4.16c}
\end{equation*}
$$

and

$$
\begin{equation*}
\Omega_{X(k) / \mathbb{Q}, x}^{1} \cong \Omega_{X(\mathbb{Q}) / \mathbb{Q},\left(x, s_{0}\right)}^{1} \tag{4.16~d}
\end{equation*}
$$

where the LHS is considered as an $\mathcal{O}_{X(k), x}$-module, the RHS as an $\mathcal{O}_{X(\mathbb{Q}),\left(x, s_{0}\right) \text {-module and the identification (4.16c) is made. The differentials }}$ are all Kähler differentials over the evident local rings and fields of constants. It is via (4.16a) that absolute differentials may be interpreted as geometric objects; specifically as linear functions on tangent vectors to spreads.

This mechanism is quite clear using the above coordinate description of spreads. Let $f(x, \alpha)$ be the $f(x)$ defining the original $X$; thus $\alpha_{I}=s_{0_{I}}$. Then $\mathcal{O}_{X(k), x}$ is the localization at $x \in X(k)$ of the coordinate ring

$$
\begin{equation*}
R_{X}=k\left[x_{1}, \ldots, x_{n+1}\right] /(f(x, \alpha)) \tag{4.17a}
\end{equation*}
$$

and $\Omega_{X(k) / k, x}^{1}$ is the $\mathcal{O}_{X(k)}$-module generated by the $d x_{i}$ and $d \alpha_{I}$, subject to the relations

$$
\left\{\begin{array}{l}
\sum_{i} f_{x_{i}}(x, \alpha) d x_{i}+\sum_{I} f_{s_{I}}(x, \alpha) d \alpha_{I}=0  \tag{4.17b}\\
\sum_{I} g_{\nu, s_{I}}(x, \alpha) d \alpha_{I}=0
\end{array}\right.
$$

obtained by differentiation of (4.15) and setting $s=s_{0}$. On the other hand, $\mathcal{O}_{X(\mathbb{Q}),\left(x, s_{0}\right)}$ is the localization at $\left(x, s_{0}\right)$ of the coordinate ring

$$
\begin{equation*}
R_{x}=\mathbb{Q}\left[x_{1}, \ldots, x_{n+1}, \ldots, s_{I}, \ldots\right] /\left(f(x, s), \ldots g_{\nu}(s), \ldots\right) \tag{4.18a}
\end{equation*}
$$

and $\Omega_{X(\mathbb{Q}) / \mathbb{Q},\left(x, s_{0}\right)}^{1}$ is the $\mathcal{O}_{X(\mathbb{Q}),\left(x, s_{0}\right)}$-module generated by the $d x_{i}$ and $d s_{I}$, subject to the relations

$$
\left\{\begin{array}{l}
\sum_{i} f_{x_{i}}(x, s) d x_{i}+\sum_{I} f_{s_{I}}(x, s) d s_{I}=0  \tag{4.18b}\\
\sum_{I} g_{\nu, s_{I}}(x, s) d s_{I}=0
\end{array}\right.
$$

obtained from (4.15). Comparing (4.17a), (4.17b) with (4.18a), (4.18b) we see that the map

$$
\alpha_{I} \rightarrow s_{I}
$$

establishes the identifications (4.16c), (4.16d).
Finally, among local families of smooth varieties centered at $X$, spreads have a number of special properties of which we shall single out three. The first refers to the exact sheaf sequence (4.2) and is:
(4.19) The extension class of (4.2) may be identified with the KodairaSpencer class of the spread family (4.14).
More precisely, as above fixing a field $k$ over which $X$ is defined, we have the analogue

$$
\begin{equation*}
0 \rightarrow \Omega_{k / \mathbb{Q}}^{1} \otimes \mathcal{O}_{X(k)} \rightarrow \Omega_{X(k) / \mathbb{Q}}^{1} \rightarrow \Omega_{X(k) / k}^{1} \rightarrow 0 \tag{4.20}
\end{equation*}
$$

of (4.2) for $X(k)$. The extension class of this sequence is an element

$$
\begin{gathered}
\rho \in H^{1}\left(\operatorname{Hom}\left(\Omega_{X(k) / k}^{1}, \Omega_{k / \mathbb{Q}}^{1} \otimes \mathcal{O}_{X(k)}\right)\right) \\
2 \| \\
\operatorname{Hom}\left(\Omega_{k / \mathbb{Q}}^{1}, H^{1}\left(\Theta_{X(k)}\right)\right) \\
2 \| \\
\operatorname{Hom}\left(T_{s_{0}} S, H^{1}\left(\Theta_{X(k)}\right)\right)
\end{gathered}
$$

where the second identification results from the isomorphism (4.16b). Passing to the corresponding complex varieties, the map

$$
T_{s_{0}} S \xrightarrow{\rho} H^{1}\left(\Theta_{X}\right)
$$

is the Kodaira-Spencer map of the spread family (4.14).
The second property has to do with the evaluation mappings

$$
\begin{equation*}
\mathrm{ev}_{x}: \Omega_{X / \mathbb{Q}, x}^{1} \rightarrow \Omega_{\mathbb{C} / \mathbb{Q}}^{1} \tag{4.21}
\end{equation*}
$$

These maps are $\mathbb{C}$-linear but not $\mathcal{O}_{X, x}$-linear, and satisfy

$$
\mathrm{ev}_{x}(f d \alpha)=f(x) d \alpha
$$

for $d \alpha \in \Omega_{\mathbb{C} / \mathbb{Q}}^{1}$ and $f \in \mathcal{O}_{X, x}$. Thus we have a $\mathbb{C}$-linear splitting of the exact sequence (4.2), which geometrically may be thought of something like a connection for the spread family (4.14) but which is only defined along the fibre $X_{s_{0}}$


A third property of spreads, one that has been mentioned above, is the following. Let $Z \in Z^{p}(X(k))$ be an algebraic cycle defined over $k$. Then the defining ideals for the irreducible components in the support of $Z$ extend naturally from the local rings $\mathcal{O}_{X(k), x}$ to $\mathcal{O}_{\mathbb{Q}(x),\left(x, s_{0}\right)}$ (cf. (4.16c)). This gives a map

$$
\begin{equation*}
Z^{p}(X(k)) \rightarrow Z^{p}(X(\mathbb{Q})) \tag{4.22}
\end{equation*}
$$

where in the RHS it is understood that we are considering only a Zariski neighborhood of $X=X_{s_{0}}$ in $X$. In fact, with this understanding the mapping (4.22) is a bijection. We shall denote by

$$
\begin{array}{r}
z \subset x \\
\downarrow \\
S
\end{array}
$$

the spread of the cycle $Z$.
Finally, we emphasize again that the spread construction is not unique; we may have different $S$ 's for the same $k$ (but always $\mathbb{Q}(S) \simeq k$ ), and different Z's for the same $Z$. As a simple example of the later, suppose that

$$
k=\mathbb{Q}\left(\alpha_{1}, \ldots, \alpha_{m}\right) /\left(g_{1}, \ldots, g_{k}\right)
$$

and $Z$ is given by

$$
p\left(x_{1}, \ldots, x_{n}\right)=0, \quad p \in k\left[x_{1}, \ldots x_{n}\right] .
$$

Then if we replace $p$ by $a p$ where

$$
a=r\left(\alpha_{1}, \ldots, \alpha_{m}\right) \in k
$$

then $Z$ is changed by $\operatorname{div} r\left(s_{1}, \ldots, s_{m}\right)$ over $S$.
In [32] we have given a systematic discussion of the ambiguities in the spread construction and of the Hodge-theoretic invariants that remain when one factors them out.

## Chapter Five

## Geometric Description of $\underline{\underline{T}} Z^{n}(X)$

### 5.1 THE DESCRIPTION

Following a standard method in differential geometry, we will describe the tangent space

$$
T Z_{\{x\}}^{n}(X)=: T_{\{x\}} Z^{n}(X)=Z_{\{x\}}^{n}(X) / \equiv_{1^{\text {st }}}
$$

where $\equiv_{1^{\text {st }}}$ is an equivalence relation given by a subgroup of $Z_{\{x\}}^{n}(X)$ that we will call first order equivalence.

The coordinate description of $\equiv_{1^{\text {st }}}$ is as follows: Denoting by $P$ the space of coefficients of Puiseaux series of arcs in $X^{(m)}$ reducing to $m x$ at $t=0$, we have a mapping

$$
\Omega_{X / \mathbb{Q}, x}^{q} \rightarrow \Omega_{P / \mathbb{Q}, z}^{q-1}
$$

given by

$$
\begin{equation*}
\varphi \rightarrow \widetilde{I}(z, \varphi) \tag{5.1}
\end{equation*}
$$

where $\widetilde{I}(z, \varphi)$ is the provisional universal abelian invariant associated to an arc

$$
z(t)=x_{1}(t)+\cdots+x_{m}(t)
$$

in $X^{(m)}$ with all $x_{i}(0)=x$. This map depends on the choice of parameter $t$ and choice of local uniformizing parameters on $X$ used to express the Puiseaux series. We think of $P$ as the union over all $m$ of the coefficients of $t^{k / m}$ for $k \leqq m$. We may compose (5.1) with the evaluation mappings

$$
\Omega_{P / \mathbb{Q}, z}^{q-1} \rightarrow \Omega_{\mathbb{C} / \mathbb{Q}}^{q-1}
$$

and extend by linearity in $z$ to obtain a bilinear mapping

$$
\begin{equation*}
\Omega_{X / \mathbb{Q}, x}^{q} \otimes_{\mathbb{Z}} Z_{\{x\}}^{n}(X) \xrightarrow{I} \Omega_{\mathbb{C} / \mathbb{Q}}^{q-1} \tag{5.2}
\end{equation*}
$$

denoted by

$$
z \otimes \varphi \rightarrow I(z, \varphi)
$$

This construction gives our final definition of universal abelian invariants. From the explicit expression for these universal abelian invariants it follows that

$$
\begin{equation*}
I(z, \alpha \wedge \psi)=\alpha \wedge I(z, \psi) \tag{5.3}
\end{equation*}
$$

for $\alpha \in \Omega_{\mathbb{C} / \mathbb{Q}}^{q-r}$ and $\psi \in \Omega_{X / \mathbb{Q}, x}^{r}$. Taking $r=0$ we see that

$$
I(z, \alpha)=0 \text { for } \alpha \in \Omega_{\mathbb{C} / \mathbb{Q}}^{q}
$$

and therefore the pairing (5.2) induces

$$
\begin{equation*}
\left(\Omega_{X / \mathbb{Q}, x}^{q} / \Omega_{\mathbb{C} / \mathbb{Q}}^{q}\right) \otimes_{\mathbb{Z}} Z_{\{x\}}^{n}(X) \rightarrow \Omega_{\mathbb{C} / \mathbb{Q}}^{q-1} \tag{5.4}
\end{equation*}
$$

Proposition: The pairing (5.4) is non-degenerate on the left; i.e.,

$$
\begin{equation*}
I(z, \varphi)=0 \text { for all } z \Rightarrow \varphi \in \Omega_{\mathbb{C} / \mathbb{Q}}^{q} \tag{5.5}
\end{equation*}
$$

The proof of this proposition may be given as follows: First, one filters $\Omega_{X / \mathbb{Q}, x}^{q}$ by the images of $\Omega_{\mathbb{C} / \mathbb{Q}}^{r} \otimes \Omega_{X / \mathbb{Q}, x}^{q-r} \rightarrow \Omega_{X / \mathbb{Q}, x}^{q}$ and uses (5.3) and induction on $q$ to reduce to proving the result for $\Omega_{X / \mathbb{C}, x}^{q}$. By this we mean that in terms of a fixed set of local uniformizing parameters we use the coordinate formulas as in section 3 above where we map forms in $\Omega_{X / \mathbb{C}, x}^{q}$ to $\Omega_{\mathbb{C} / \mathbb{Q}}^{q-1}$ by the prescriptions given there. Next, we filter $\Omega_{X / \mathbb{C}, x}^{q}$ by $\mathfrak{m}_{x}^{k} \Omega_{X / \mathbb{C}, x}^{q}$ with associated graded denoted $G r^{k} \Omega_{X / \mathbb{C}, x}^{q}$. Calculations as in section 3 then show that
(i) The pairing

$$
\binom{\text { Puiseaux series of }}{\text { order } k+q} \otimes G r^{k} \Omega_{X / \mathbb{C}, x}^{q} \rightarrow \Omega_{\mathbb{C} / \mathbb{Q}}^{q-1}
$$

is well-defined, and
(ii) this pairing is non-degenerate on the right.

We illustrate the argument for (ii) when $q=2$. Pairing a Puiseaux series whose $t$ term is

$$
\left(a t^{1 / l}, b t^{1 / l}\right)
$$

against

$$
\varphi=\sum A_{m} \xi^{m} \eta^{k-m} d \xi \wedge d \eta, \quad l=k+2
$$

gives

$$
\sum_{m} A_{m} a^{m} b^{k-m}(a d b-b d a)
$$

Clearly, if this is zero for all $a, b$ then all the $A_{m}$ vanish and hence $\varphi=0$.

Description: (geometric) We say that an arc $z(t)$ is first order equivalent to zero, written

$$
z(t) \equiv_{1^{\text {st }}} 0
$$

if

$$
\begin{equation*}
I(z, \varphi)=0 \text { for all } \varphi \in \Omega_{X / \mathbb{Q}, x}^{q} \text { and } 1 \leqq q \leqq n \tag{5.6}
\end{equation*}
$$

When the formal definition of $T_{\{x\}} Z^{n}(X)$ is given in section 7.1 below we will show that

$$
T_{\{x\}} Z^{n}(X)=Z_{\{x\}}^{n}(X) / \equiv_{1^{\text {st }}}
$$

By the discussion in section 3 - c.f. (3.18) - together with (5.3), the condition (5.6) is independent of parameter $t$ and local uniformizing parameters on $X$. In fact, in a moment we shall express $I(z, \varphi)$ in a coordinate-free manner so that this point will be clear.

The reason that the description is said to be "geometric" is that in section 7.1 below we shall reformulate it in terms of $\mathcal{E x t}$ 's, and although perhaps less intuitive geometrically this will provide a more satisfactory mathematical definition. In that section, we will give a further justification why the definition takes the form that it does.

Before turning to the intrinsic formulation we want to use (5.3) and the proposition to give an expression for $T_{\{x\}} Z^{n}(X)$ purely in terms of differentials. For this we have the
Definition: We define

$$
\operatorname{Hom}^{o}\left(\Omega_{X / \mathbb{Q}, x}^{n}, \Omega_{\mathbb{C} / \mathbb{Q}}^{n-1}\right)
$$

to be the collections of continuous $\mathbb{C}$-linear maps

$$
\tau_{i}: \Omega_{X / \mathbb{Q}, x}^{i} \rightarrow \Omega_{\mathbb{C} / \mathbb{Q}}^{i-1}
$$

that are $\Omega_{\mathbb{C} / \mathbb{Q}}^{\bullet}$ linear in the sense that

$$
\tau_{i+1}(\alpha \wedge \varphi)=\alpha \wedge \tau_{i}(\varphi)
$$

for $\alpha \in \Omega_{\mathbb{C} / \mathbb{Q}}^{n-i}$ and $\varphi \in \Omega_{X / \mathbb{Q}, x}^{i}$.
It is easy to see that the $\tau_{i}$ are uniquely determined by $\tau_{n}$. We set $\tau_{n}=\tau$ and will think of the elements of $\operatorname{Hom}^{o}\left(\Omega_{X / \mathbb{Q}, x}^{n}, \Omega_{\mathbb{C} / \mathbb{Q}}^{n-1}\right)$ as given by $\tau: \Omega_{X / \mathbb{Q}, x}^{n} \rightarrow$ $\Omega_{\mathbb{C} / \mathbb{Q}}^{n-1}$ that satisfy the condition that $\tau(\alpha \wedge \varphi)=\alpha$ (something) for $\alpha \in \Omega_{\mathbb{C} / \mathbb{Q}}^{n-i}$. The "something" is then a uniquely determined element $\tau_{i}(\varphi) \in \Omega_{\mathbb{C} / \mathbb{Q}}^{i-1}$. We obviously have that any such $\tau$ is zero on the subspace $\Omega_{\mathbb{C} / \mathbb{Q}}^{n}$ of $\Omega_{X / \mathbb{Q}, n}^{n}$, so that

$$
\operatorname{Hom}^{o}\left(\Omega_{X / \mathbb{Q}, x}^{n}, \Omega_{\mathbb{C} / \mathbb{Q}}^{n-1}\right) \subset \operatorname{Hom}_{\mathbb{C}}^{o}\left(\Omega_{X / \mathbb{Q}, x}^{n} / \Omega_{\mathbb{C} / \mathbb{Q}}^{n}, \Omega_{\mathbb{C} / \mathbb{Q}}^{n-1}\right) .
$$

In particular, for $n=1$

$$
\begin{equation*}
\operatorname{Hom}^{o}\left(\Omega_{X / \mathbb{Q}, x}^{1}, \mathbb{C}\right) \cong \operatorname{Hom}_{\mathbb{C}}^{c}\left(\Omega_{X / \mathbb{C}, x}^{1}, \mathbb{C}\right) \tag{5.7}
\end{equation*}
$$

which is the reason that differentials over $\mathbb{Q}$ do not appear in the definition of $T_{\{x\}} Z^{n}(X)$ when $n=1$.

From (5.3) and (5.5) we have the
Proposition: For the stalk at $x \in X$ of the tangent sheaf $\underline{\underline{T}} Z^{n}(X)$ described above we have

$$
\begin{equation*}
T_{\{x\}} Z^{n}(X) \cong{\underline{\underline{\operatorname{Hom}^{o}}}}^{o}\left(\Omega_{X / \mathbb{Q}, x}^{n}, \Omega_{\mathbb{C} / \mathbb{Q}}^{n-1}\right)_{x} . \tag{5.8}
\end{equation*}
$$

In general we note that.

$$
\begin{align*}
& \text { If } I(z, \psi)=0 \text { for all } \psi \in \Omega_{X / \mathbb{Q}, x}^{p-1} \text {, then } I(z, \varphi) \text { is well-defined for } \\
& \varphi \in \Omega_{X / \mathbb{C}, x}^{p} \text {. }
\end{align*}
$$

Thus, we may loosely think of the tangent to an $\operatorname{arc} z(t)$ in $Z^{n}(X)$ to be given by pairing $z(t)$ against all the usual $p$-forms $\varphi \in \Omega_{X / \mathbb{C}, x}^{p}$ for $1 \leqq p \leqq n$. Here, it is understood that this pairing is given by

$$
I(z, \varphi)
$$

where $I(z, \varphi)$ is computed in local coordinates as in section 3 above, and where for a Puiseaux series coefficient $a$ we understand that

$$
d a=d_{\mathbb{C} / \mathbb{Q}} a .
$$

This is well illustrated by the proof of proposition (5.5) given above.

### 5.2 INTRINSIC FORMULATION

We shall now formulate the above construction in a coordinate free manner. Beginning with the case $n=1$, for a smooth algebraic curve $X$ an arc in $Z^{1}(X)$ is given by an algebraic curve $B$ with a marked point $t_{0} \in B$ together with an algebraic 1-cycle

$$
Z \subset B \times X
$$

such that for each $t \in B$ the intersection

$$
z(t)=Z \cdot(\{t\} \times X)
$$

is a 0 -cycle on $X$. Here, we assume that $B$ is smooth but it need not be complete. To obtain on arc in $Z_{\{x\}}^{1}(X)$ we assume that

$$
|Z| \cdot\left(\left\{t_{0}\right\} \times X\right)=\{x\}
$$

where $|Z|$ is the support of $Z$ and $\{x\}$ is the support of $x$ (i.e., we ignore multiplicities). With these assumptions we have a natural map

$$
\begin{equation*}
\Omega_{X / \mathbb{C}, x}^{1} \rightarrow \Omega_{B / \mathbb{C}, t_{0}}^{1} \tag{5.10}
\end{equation*}
$$

given by

$$
\omega \rightarrow\left(\pi_{B}\right)_{*}\left(\left.\pi_{X}^{*} \omega\right|_{Z}\right) .
$$

If we compose (5.10) with the evaluation map

$$
\Omega_{B / \mathbb{C}, t_{0}}^{1} \rightarrow T_{t_{0}}^{*} B
$$

then denoting by $Z_{\{x\}}^{1}(X, B)$ the arcs as above and parametrized by $B$ we have a bilinear pairing

$$
\begin{equation*}
\Omega_{X / \mathbb{Q}, x}^{1} \otimes Z_{\{x\}}^{1}(X, B) \rightarrow T_{t_{0}}^{*} B . \tag{5.11}
\end{equation*}
$$

Varying $B$ and $Z \subset B \times X$, this pairing is non-degenerate on the left and

GEOMETRIC DESCRIPTION OF $\underline{\underline{T}} Z^{N}(X)$
may be used to define

$$
\equiv_{1^{\text {st }}} \subset Z_{\{x\}}^{1}(X)
$$

for curves in a coordinate-free manner.
Of course, for 0-cycles on algebraic curves this construction coincides with the one given in section 2. For example, if $z(t)$ is an effective 0 -cycle of degree $m$, then we have a regular mapping

$$
f: B \rightarrow X^{(m)}
$$

with $t_{0} \rightarrow m x$, and one may verify that

$$
\left(\pi_{B}\right)_{*}\left(\left.\pi_{X}^{*} \omega\right|_{Z}\right)=f^{*}(\operatorname{Tr} \omega)
$$

Turning to the general case of 0 -cycles when $\operatorname{dim} X=n$, we again consider a picture

$$
Z \subset B \times X
$$

where $\operatorname{dim} B=1$ and $Z$ is a codimension- $n$ cycle meeting the $\{t\} \times X^{\prime}$ 's properly as above and with

$$
|Z| \cdot\left(\left\{t_{0}\right\} \times X\right)=\{x\}
$$

Beginning with $\omega \in \Omega_{X / \mathbb{Q}, x}^{n}$ we have $\pi_{X}^{*} \omega \in \Omega_{B \times X / \mathbb{Q},\left(t_{0}, x\right)}^{n}$. We may restrict $\pi_{X}^{*} \omega$ to $Z$ to obtain

$$
\begin{equation*}
\left.\left(\pi_{X}^{*} \omega\right)\right|_{Z}=: \omega_{Z} \in \Omega_{Z / \mathbb{Q},\left(t_{0}, x\right)}^{n} \tag{5.12}
\end{equation*}
$$

Then, as discussed in section 3 the trace map

$$
\left(\pi_{B}\right)_{*}: \Omega_{Z / \mathbb{Q},\left(t_{0}, x\right)}^{n} \rightarrow \Omega_{B / \mathbb{Q}, t_{0}}^{n}
$$

is defined and

$$
\begin{equation*}
\left(\pi_{B}\right)_{*} \omega_{Z}=: \omega_{B} \in \Omega_{B / \mathbb{Q}, t_{0}}^{n} \tag{5.13}
\end{equation*}
$$

Since $\operatorname{dim} B=1$, there is a canonical mapping

$$
\begin{equation*}
\Omega_{B / \mathbb{Q}, t_{0}}^{n} \rightarrow \Omega_{\mathbb{C} / \mathbb{Q}}^{n-1} \otimes \Omega_{B / \mathbb{C}, t_{0}}^{1} \tag{5.14}
\end{equation*}
$$

Composing (5.12)-(5.14) gives finally

$$
\Omega_{X / \mathbb{Q}, x}^{n} \rightarrow \Omega_{\mathbb{C} / \mathbb{Q}}^{n-1} \otimes \Omega_{B / \mathbb{C}, t_{0}}^{1}
$$

This mapping may now be used as in the $n=1$ case to give a bilinear pairing

$$
\Omega_{X / \mathbb{Q}, x}^{n} \otimes Z_{\{x\}}^{n}(X, B) \xrightarrow{\mathcal{I}_{n}} \rightarrow \Omega_{\mathbb{C} / \mathbb{Q}}^{n-1} \otimes \Omega_{B / \mathbb{C}, t_{0}}^{1}
$$

whose left kernel, when we vary $B$ and $Z$, is by proposition (5.5) given by $\Omega_{\mathbb{C} / \mathbb{Q}}^{n}$.

As in the $n=1$ case, one may verify that the composition of $\mathcal{I}_{n}$ with the evaluation map $\Omega_{B / \mathbb{C}, t_{0}}^{1} \rightarrow T_{t_{0}}^{*} B$ is the same as the construction via universal abelian invariants given above. The proof depends on the extension to general $n$ of the following lemma, stated here for $n=2$.

Lemma: Let $X$ be a smooth algebraic surface and $x, y \in \mathbb{C}(X)$ rational functions that give local uniformizing parameters in a neighborhood of a point $p \in X$. Let $Y \subset X$ be an algebraic curve with $p \in Y$ and given by

$$
f(x, y)=0
$$

where $f(x, y)$ is an algebraic function of $x, y$ that is regular in a neighborhood of $(x(p), y(p))$. Suppose that $t$ is a local uniformizing parameter on $Y$ so that the map $Y \rightarrow X$ is given by $t \rightarrow(x(t), y(t))$ where $x(t), y(t)$ are algebraic Puiseaux series in $t$ and where $p=\left(x\left(t_{0}\right), y\left(t_{0}\right)\right)$. Then

$$
\left.d x \wedge d y\right|_{f=0}=d x(t) \wedge d y(t)
$$

where each side of the equation is interpreted as an element of $\Omega_{\mathbb{C}\{t\} / \mathbb{Q}, t_{0}}^{1}$. Here, $\mathbb{C}\{t\}$ are the power series of algebraic functions of $t$ that are regular near $t=t_{0}$.

The proof is by an explicit calculation of the sort done in the preceding section, the point being to use the relation

$$
0=d f(x(t), y(t))=f_{x} d x(t)+f_{y} d y(t)+\bar{d} f
$$

where $d=d_{\mathbb{C}\{t\} / \mathbb{Q}}$ and the right hand side is evaluated on $(x(t), y(t))$.
We observe that this construction may be used for $\omega \in \Omega_{X / \mathbb{Q}, x}^{q}$ for all $1 \leqq q \leqq n$ to define

$$
\Omega_{X / \mathbb{Q}, x}^{q} \otimes Z_{\{x\}}^{n}(X, B) \xrightarrow{\mathcal{I}_{q}} \Omega_{\mathbb{C} / \mathbb{Q}}^{q-1} \otimes \Omega_{B / \mathbb{C} . t_{0}}^{1} .
$$

For $\alpha \in \Omega_{\mathbb{C} / \mathbb{Q}}^{p}$ and $\varphi \in \Omega_{X / \mathbb{Q}, x}^{n-p}$ one sees directly that

$$
\mathcal{I}_{n}((\alpha \wedge \varphi) \otimes z)=\alpha \wedge \mathcal{I}_{n-p}(\varphi \otimes z)
$$

where $\mathcal{I}_{n-p}(\varphi \otimes z) \in \Omega_{\mathbb{C} / \mathbb{Q}}^{n-p-1} \otimes \Omega_{B / \mathbb{C}, t_{0}}^{1}$ and the notation $\alpha \wedge \mathcal{I}_{n-p}(\varphi \otimes z)$ means to wedge $\alpha$ with the first factor in $\mathcal{I}_{n-p}(\varphi \otimes z)$. This is the intrinsic formulation of the compatibility condition (5.3) above.

This now leads, in the evident way, to the definition of the mapping

$$
\begin{equation*}
Z_{\{x\}}^{n}(X, B) \otimes T_{t_{0}} B \rightarrow \operatorname{Hom}^{o}\left(\Omega_{X / \mathbb{Q}, x}^{n}, \Omega_{\mathbb{C} / \mathbb{Q}}^{n-1}\right) \tag{5.15}
\end{equation*}
$$

Varying $B$ and $Z$, the mapping (5.15) is surjective and the kernel defines in a coordinate-free manner the relation $\equiv_{1^{\text {st }}}$ of first order equivalence of arcs and tangent space

$$
T_{\{x\}} Z^{n}(X)=Z_{\{x\}}^{n}(X) / \equiv_{1^{\text {st }}}
$$

We may also use spreads to define the pairing

$$
\begin{equation*}
\Omega_{X / \mathbb{Q}, x}^{n} \otimes Z_{\{x\}}^{n}(X, B) \rightarrow \Omega_{\mathbb{C} / \mathbb{Q}}^{n-1} \otimes T_{t_{0}}^{*} B . \tag{5.16}
\end{equation*}
$$

If $X, z$ and $B$ are defined over $k$, then we have the corresponding spreads $\mathcal{X}, \mathcal{B}$ and a cycle $\mathcal{Z}$ on $\mathcal{X} \times{ }_{S} \mathcal{B}$, together with mappings of differential forms


With the identifications (cf. §4)

$$
\left\{\begin{array}{l}
\Omega_{X(\mathbb{Q}) / \mathbb{Q},\left(x, s_{0}\right)}^{n} \cong \Omega_{X(k) / \mathbb{Q}, x}^{n} \\
\Omega_{S(\mathbb{Q}) / \mathbb{Q}, s_{0}}^{n} \cong \Omega_{k / \mathbb{Q}}^{1} \\
\Omega_{\mathcal{B}(\mathbb{Q}) / S}^{1} \cong \Omega_{\mathcal{B}(k) / k}^{1}
\end{array}\right.
$$

we obtain a map

$$
\Omega_{X(k) / \mathbb{Q}}^{n} \rightarrow \Omega_{k / \mathbb{Q}}^{n-1} \otimes \Omega_{B(k) / k}^{1}
$$

that induces (5.16).

PUTangSp March 1, 2004

## Chapter Six

## Absolute Differentials (II)

### 6.1 ABSOLUTE DIFFERENTIALS ARISE FROM PURELY GEOMETRIC CONSIDERATIONS

In differential geometry the tangent space to a manifold may be defined axiomatically in terms of an equivalence relation on arcs. It would of course be desirable to do the same for the tangent space to the space of cycles. Denoting by $\equiv$ the equivalence we would like to define on an arc $z(t)$ in $Z_{\{x\}}^{n}(X)$, it should have the following properties:
(i) if $z_{1}(t) \equiv \widetilde{z}_{1}(t)$ and $z_{2}(t) \equiv \widetilde{z}_{2}(t)$, then

$$
\begin{gather*}
z_{1}(t)+z_{2}(t) \equiv \widetilde{z}_{1}(t)+\widetilde{z}_{2}(t) \\
z(\alpha t) \equiv \alpha z(t) \text { for } \alpha \in \mathbb{Z} \tag{ii}
\end{gather*}
$$

(iii) if $z(t)$ and $\widetilde{z}(t)$ are two arcs in $\operatorname{Hilb}_{0}(X)$ with the same tangent in $T \operatorname{Hilb}_{0}(X)$, then

$$
z(t) \equiv \widetilde{z}(t)
$$

(iv) if $z(t)=\widetilde{z}(t)$ as arcs in $Z_{\{x\}}^{n}(X)$, then

$$
z(t) \equiv \widetilde{z}(t) ; \quad \text { and }
$$

(v) if $\alpha z(t) \equiv \alpha \widetilde{z}(t)$ for some non-zero $\alpha \in \mathbb{Z}$, then

$$
z(t) \equiv \widetilde{z}(t)
$$

(vi) If $z(t, u)$ is a 2-parameter family of 0 -cycles and we set

$$
z_{u}(t)=z(t, u) \text { for all } t, u
$$

then if

$$
z_{u}(t) \equiv 0 \text { for all } u \text { with } 0<|u|<\epsilon
$$

then

$$
z_{0}(t) \equiv 0
$$

Remark: We do not assume that if there is a sequence $u_{i} \rightarrow 0$ such that

$$
z_{u_{i}}(t) \equiv 0 \text { for all } i
$$

then

$$
z_{0}(t) \equiv 0
$$

Although we do not know that (i)-(vi) give the equivalence relation $\equiv_{1^{\text {st }}}$ defined in section 5 above, we will show that this is indeed the case in a significant example. Namely, using the notation $(f, g)$ for $\operatorname{Var}(f, g)$ we let

$$
\begin{equation*}
z_{\alpha \beta}(t)=\left(x^{2}-\alpha y^{2}, x y-\beta t\right), \quad \alpha \neq 0 . \tag{6.1}
\end{equation*}
$$

Then the right hand side is the arc in the space of 0 -cycles in $\mathbb{C}^{2}$ defined by the ideal generated by $x^{2}-\alpha y^{2}$ and $x y-\beta t$. Denote by $F$ the free group generated by the 0 -cycles $z_{\alpha \beta}(t)-z_{1 \beta}(t)$ for all $\alpha \in \mathbb{C}^{*}, \beta \in \mathbb{C}$. We will prove the
Proposition: If $\equiv$ is the minimal equivalence relation satisfying (i)-(vi), then the map $F / \equiv \rightarrow \Omega_{\mathbb{C} / \mathbb{Q}}^{1}$ given by

$$
z_{\alpha \beta}(t) \rightarrow \beta \frac{d \alpha}{\alpha}
$$

is well defined and is an isomorphism.
Thus, the purely geometric axioms (i)-(v) force arithmetic considerations (we will not need (vi)). The proposition has the following

Corollary: For $\beta \neq 0, z_{\alpha \beta}(t) \equiv z_{1, \beta}(t)$ if and only if $\alpha \in \overline{\mathbb{Q}}$.
Of course, the point is that geometric condition that $z_{\alpha \beta}(t) \equiv z_{1 \beta}(t)$ is equivalent to the arithmetic condition $\alpha \in \overline{\mathbb{Q}}$.

The proof will be given in several steps. Remark that (i) and (iv) will be used in the form

$$
\begin{equation*}
\left(f_{1}, g\right)+\left(f_{2}, g\right) \equiv\left(f_{1} f_{2}, g\right) \tag{i}
\end{equation*}
$$

It will be seen that (i) ${ }^{\prime}$, (ii) and (v) are what force the arithmetic to enter.
The construction

$$
z_{\alpha \beta}(t) \mapsto \beta \frac{d \alpha}{\alpha}
$$

is a special case of a construction introduced in section 7.1. The properties (i)-(vi) are verified to hold for that general construction.

Step one: We will show that

$$
\begin{equation*}
\left(x^{2}-m^{2} y^{2}, x y-t\right) \equiv\left(x^{2}-y^{2}, x y-t\right), \quad m \in \mathbb{Z} \tag{6.2}
\end{equation*}
$$

By (i) and (iv)

$$
\begin{aligned}
& \left(x^{2}-m^{2} y^{2}, x y-t\right)-\left(x^{2}-y^{2}, x y-t\right) \\
& \equiv \\
& \equiv\left(x^{2}-m t, y-\frac{x}{m}\right)+\left(x^{2}+m t, y+\frac{x}{m}\right) \\
& \quad-\left(x^{2}-t, y-x\right)-\left(x^{2}+t, y+x\right)
\end{aligned}
$$

(when expanded as sums of Puiseaux series, both sides are the same), and by (iii) the right hand side is
$\equiv m\left(x^{2}-t, y-\frac{x}{m}\right)+m\left(x^{2}+t, y+\frac{x}{m}\right)+\left(x^{2}+t, y-x\right)+\left(x^{2}-t, y+x\right)$
which by (i) and (iv) again is

$$
\equiv\left(x^{2}-t,\left(y-\frac{x}{m}\right)^{m}(y+x)\right)+\left(x^{2}+t,\left(y+\frac{x}{m}\right)^{m}(y+x)\right)
$$

Now using (iii)

$$
\begin{aligned}
\left(x^{2}-t,\left(y-\frac{x}{m}\right)^{m}(y+x)\right) \equiv & \left(x^{2}-t, y^{m+1}+\left(\frac{\binom{m}{2}}{m^{2}}-1\right) y^{m-2} x^{2}\right. \\
& \left.+\left(\frac{\binom{m}{3}}{m^{3}}-\frac{\binom{m}{2}}{m^{2}}\right) y^{m-3} x^{3}\right)
\end{aligned}
$$

because $x^{4} \equiv t^{2} \equiv 0$, and by the same idea the right hand side is

$$
\equiv\left(x^{2}-t, y^{m+1}+\left(\left(\frac{\binom{m}{2}}{m^{2}}-1\right) y^{m-1}+\left(\frac{\binom{m}{3}}{m^{3}}-\frac{\binom{m}{2}}{m^{2}}\right) y^{m-2} x\right) t\right)
$$

which by (iii) and (iv) is

$$
\begin{aligned}
\equiv\left(x^{2}-t, y^{m-2}\right) & +\left(x^{2}-t, y^{3}+t\left(\frac{\binom{m}{2}}{m^{2}}-1\right) y\right) \\
& +\left(x^{2}-t, y^{3}+t\left(\frac{\binom{m}{3}}{m^{3}}-\frac{\binom{m}{2}}{m^{2}}\right) x\right)-\left(x^{2}-t, y^{3}\right)
\end{aligned}
$$

Similarly,

$$
\begin{aligned}
\left(x^{2}+t,(y+\right. & \left.\left.\frac{x}{m}\right)^{m}(y-x)\right) \\
\equiv & \left(x^{2}+t, y^{m-2}\right)+\left(x^{2}+t, y^{3}-t\left(\frac{\binom{m}{2}}{m^{2}}-1\right) y\right) \\
& +\left(x^{2}+t, y^{3}+t\left(\frac{\binom{m}{3}}{m^{3}}-\frac{\binom{m}{2}}{m^{2}}\right) x\right)-\left(x^{2}+t, y^{3}\right)
\end{aligned}
$$

Now by (ii)

$$
\begin{aligned}
\left(x^{2}-t, y^{m-2}\right) & \equiv-\left(x^{2}+t, y^{m-2}\right) \\
\left(x^{2}-t, y^{3}\right) & \equiv-\left(x^{2}+t, y^{3}\right)
\end{aligned}
$$

and

$$
\left(x-t, y^{3}+t\left(\frac{\binom{m}{2}}{m^{2}}-1\right) y\right) \equiv-\left(x+t, y^{3}-t\left(\frac{\binom{m}{2}}{m^{2}}-1\right) y\right)
$$

By (iii) and (iv)

$$
\begin{aligned}
\left(x^{2}-t, y^{3}+t\left(\frac{\binom{m}{3}}{m^{3}}-\frac{\binom{m}{2}}{m^{2}}\right) x\right) & +\left(x^{2}+t, y^{3}+t\left(\frac{\binom{m}{3}}{m^{3}}-\frac{\binom{m}{2}}{m^{2}}\right) x\right) \\
& \equiv\left(x^{4}, y^{3}+t\left(\frac{\binom{m}{3}}{m^{3}}-\frac{\binom{m}{2}}{m^{2}}\right) x\right)
\end{aligned}
$$

which by (ii) and (iv) is

$$
\begin{aligned}
& \equiv 4\left(x, y^{3}+t\left(\frac{\binom{m}{3}}{m^{3}}-\frac{\binom{m}{2}}{m^{2}} x\right)\right. \\
& \equiv 4\left(x, y^{3}\right) \quad(\text { by }(\mathrm{i})) \\
& \equiv 0
\end{aligned}
$$

since $\left(x, y^{3}\right)$ is a constant family. Thus all terms in the sum (6.3) cancel out and (6.2) is proved.

Step two: We will prove (2) with $m^{2}$ replaced by $m \in \mathbb{Z}$. We have

$$
\begin{aligned}
2\left(x^{2}-m y^{2}, x y-t\right) & \equiv\left(\left(x^{2}-m y^{2}\right)^{2}, x y-t\right) \\
& \equiv\left(x^{4}-2 m x^{2} y^{2}+m^{2} y^{4}, x y-t\right) \\
& \equiv\left(x^{4}-2 m t^{2}+m^{2} y^{2}, x y-t\right) \\
& \equiv\left(x^{4}+m^{2} y^{2}, x y-t\right) .
\end{aligned}
$$

Similarly,

$$
\left(x^{2}-m^{2} y^{2}, x y-t\right)+\left(x^{2}-y^{2}, x y-t\right) \equiv\left(x^{4}+m^{2} y^{2}, x y-t\right)
$$

so that

$$
2\left(x^{2}-m y^{2}, x y-t\right) \equiv\left(x^{2}-m^{2} y^{2}, x y-t\right)+\left(x^{2}-y^{2}, x y-t\right)
$$

which by step one is

$$
\equiv 2\left(x^{2}-y^{2}, x y-t\right)
$$

and then by (v) we get the result.
Step three: We will next establish (6.2) when $m^{2}$ is replaced by a rational number $q=m / n$ where $m$ and $n$ are integers. We have by a similar argument to the above

$$
\begin{aligned}
& \left(x^{2}-\left(\frac{m}{n}\right) y^{2}, x y-t\right)+\left(x^{2}-n y^{2}, x y-t\right) \\
& \quad \equiv\left(x^{2}-m y^{2}, x y-t\right)+\left(x^{2}-y^{2}, x y-t\right)
\end{aligned}
$$

By step two this gives
$\left(x^{2}-\left(\frac{m}{n}\right) y^{2}, x y-t\right)+\left(x^{2}-y^{2}, x y-t\right) \equiv\left(x^{2}-y^{2}, x y-t\right)+\left(x^{2}-y^{2}, x y-t\right)$,
which is what was to be proved.

The argument extends immediately to

$$
\begin{equation*}
q=q_{1} \cdots q_{k} \tag{6.4}
\end{equation*}
$$

where all $q_{i}^{n_{i}} \in \mathbb{Q}$. At this stage we have proved:
If $q \in \overline{\mathbb{Q}}$ is of the form (6.4), then

$$
\left(x^{2}-q y^{2}, x y-t\right) \equiv\left(x^{2}-y^{2}, x y-t\right)
$$

Step four: Changing notation slightly, we now set

$$
z_{\alpha \beta}(t)=\left(x^{2}-\alpha y^{2}, x y-\beta t\right)-\left(x^{2}-y^{2}, x y-\beta t\right)
$$

By arguments similar to above we have

$$
\begin{aligned}
& \left(x^{2}-\alpha_{1} y^{2}, x y-\beta t\right)+\left(x^{2}-\alpha_{2} y^{2}, x y-\beta t\right) \\
& \quad \equiv\left(x^{2}-\alpha_{1} \alpha_{2} y^{2} x y-\beta t\right)+\left(x^{2}-y^{2}, x y-\beta t\right)
\end{aligned}
$$

and

$$
\left(x^{2}-\alpha y^{2}, x y-\beta_{1} t\right)+\left(x^{2}-\alpha y^{2}, x y-\beta_{2} t\right) \equiv\left(x^{2}-\alpha y^{2}, x y-\left(\beta_{1}+\beta_{2}\right) t\right)
$$

It follows that the map of the free group of cycles of this form modulo the equivalence relation $\equiv$ to $\mathbb{C}^{*} \otimes_{\mathbb{Z}} \mathbb{C}$ qiven by

$$
z_{\alpha, \beta}(t) \rightarrow \alpha \otimes \beta
$$

is well-defined and surjective. Composing this with the map

$$
\mathbb{C}^{*} \otimes_{\mathbb{Z}} \mathbb{C} \rightarrow \Omega_{\mathbb{C} / \mathbb{Q}}^{1}
$$

given by

$$
\begin{equation*}
\alpha \otimes \beta \rightarrow \beta \frac{d \alpha}{\alpha} \tag{6.5}
\end{equation*}
$$

we obtain the map in the statement of the proposition. To establish that it is injective, we need to know that the defining relations for the Kähler differentials $\Omega_{\mathbb{C} / \mathbb{Q}}^{1}$ are satisfied by $\equiv$. We thus need to show that the relations
(i) $\alpha_{1} \alpha_{2} \otimes \alpha_{1} \alpha_{2}-\alpha_{1} \otimes \alpha_{1} \alpha_{2}-\alpha_{2} \otimes \alpha_{1} \alpha_{2} \equiv 0$
(ii) $\left(\alpha_{1}+\alpha_{2}\right) \otimes\left(\alpha_{1}+\alpha_{1}\right)-\alpha_{1} \otimes \alpha_{1}-\alpha_{2} \otimes \alpha_{2} \equiv 0$
(iii) $q \otimes \beta \equiv 0$ if $q \in \mathbb{Q}$
are satified. Here, for example, (i) is the Leibniz rule in the form

$$
\alpha_{1} \alpha_{2} \frac{d\left(\alpha_{1} \alpha_{2}\right)}{\alpha_{1} \alpha_{2}}-\alpha_{1} \alpha_{2} \frac{d \alpha_{1}}{\alpha_{1}}-\alpha_{1} \alpha_{2} \frac{d \alpha_{2}}{\alpha_{2}}=0
$$

and similarly (ii) is linearity. Now we have just proved (iii), and (i) has been proved above. We thus need to show:

$$
\begin{aligned}
\left(x^{2}-\right. & \left.(\alpha+\beta) y^{2}, x y-(\alpha+\beta) t\right)-\left(x^{2}-y^{2}, x y-(\alpha+\beta) t\right) \\
\equiv & \left(x^{2}-\alpha y^{2}, x y-\alpha t\right)+\left(x^{2}-\beta y^{2}, x y-\beta t\right) \\
& \quad\left(x^{2}-y^{2}, x y-\alpha t\right)-\left(x^{2}-y^{2}, x y-\beta t\right) .
\end{aligned}
$$

By simple manipulations this is equivalent to

$$
\begin{equation*}
\left(x^{4}+\left(\frac{\alpha+\beta}{\alpha}\right) y^{4}, x y-\alpha t\right)+\left(x^{4}+\left(\frac{\alpha+\beta}{\beta}\right) y^{4}, x y-\beta t\right) \equiv 0 \tag{6.6}
\end{equation*}
$$

Now

$$
\begin{aligned}
& 2\left(x^{2}-\left(\frac{\alpha+\beta}{\alpha}\right) y^{2}, x y-\alpha t\right) \\
& \quad \equiv\left(x^{2}-\left(\frac{\alpha+\beta}{\alpha}\right)^{2} y^{2}, x y-\alpha t\right)+\left(x^{2}-y^{2}, x y-\alpha t\right)
\end{aligned}
$$

so that

$$
\begin{aligned}
2 & {\left[\left(x^{2}-\left(\frac{\alpha+\beta}{\alpha}\right) y^{2}, x y-\alpha t\right)+\left(x^{2}-\left(\frac{\alpha+\beta}{\beta}\right) y^{2}, x y-\beta t\right)\right] } \\
\equiv & \left(x^{2}-\left(\frac{\alpha+\beta}{\alpha}\right)^{2} y^{2}, x y-\alpha t\right)+\left(x^{2}-y^{2}, x y-\alpha t\right) \\
& +\left(x^{2}-\left(\frac{\alpha+\beta}{\beta}\right)^{2} y^{2}, x y-\beta t\right)+\left(x^{2}-y^{2}, x y-\beta t\right)
\end{aligned}
$$

Now

$$
\begin{aligned}
& \left(x^{2}-\left(\frac{\alpha+\beta}{\alpha}\right)^{2} y^{2}, x y-\alpha t\right) \\
& \quad \equiv\left(x-\left(\frac{\alpha+\beta}{\alpha}\right) y, x^{2}-(\alpha+\beta) t\right) \\
& \quad+\left(x+\left(\frac{\alpha+\beta}{\alpha}\right) y, x^{2}+(\alpha+\beta) t\right)
\end{aligned}
$$

and

$$
\begin{aligned}
& \left(x^{2}-\left(\frac{\alpha+\beta}{\beta}\right)^{2} y^{2}, x y-\beta t\right) \\
& \quad \equiv\left(x-\left(\frac{\alpha+\beta}{\beta}\right) y, x^{2}-(\alpha+\beta) t\right) \\
& \quad+\left(x+\left(\frac{\alpha+\beta}{\beta}\right) y, x^{2}+(\alpha+\beta) t\right)
\end{aligned}
$$

Thus

$$
\begin{aligned}
& 2\left[\left(x^{2}-\left(\frac{\alpha+\beta}{\alpha}\right) y^{2}, x y-\alpha t\right)+\left(x^{2}-\left(\frac{\alpha+\beta}{\beta}\right) y^{2}, x y-\beta t\right)\right] \\
& \equiv \\
& \quad\left(x^{2}-(\alpha+\beta) t, y^{2}-x y+\left(\frac{\alpha \beta}{\alpha+\beta}\right) y^{2}\right) \\
& \\
& \quad+\left(x^{2}+(\alpha+\beta) t, y^{2}+x y+\left(\frac{\alpha \beta}{\alpha+\beta}\right) y^{2}\right)+2\left(x^{2}-y^{2}, x y-(\alpha+\beta) t\right) \\
& \equiv \\
& \equiv\left(x^{2}-(\alpha+\beta) t, y^{2}-x y+\left(\frac{\alpha \beta}{\alpha+\beta}\right) t\right) \\
& \\
& \quad+\left(x^{2}+(\alpha+\beta) t, y^{2}-x y-\left(\frac{\alpha \beta}{\alpha+\beta}\right) t\right)+2\left(x^{2}-y^{2}, x y-(\alpha+\beta) t\right) .
\end{aligned}
$$

Now

$$
\begin{aligned}
& \left(x^{2}-(\alpha+\beta) t, y^{2}-x y+\left(\frac{\alpha \beta}{\alpha+\beta}\right) t\right) \\
& \equiv-\left(x^{2}+(\alpha+\beta) t, y^{2}-x y-\left(\frac{\alpha \beta}{\alpha+\beta}\right) t\right)
\end{aligned}
$$

so

$$
\begin{aligned}
& 2\left[\left(x^{2}-\left(\frac{\alpha+\beta}{\alpha}\right) y^{2}, x y-\alpha t\right)+\left(x^{2}-\left(\frac{\alpha+\beta}{\beta}\right) y^{2}, x y-\beta t\right)\right] \\
& \quad \equiv 2\left(x^{2}-y^{2}, x y-(\alpha+\beta) t\right)
\end{aligned}
$$

and (6.6) follows after we cancel the 2's and substitute.

### 6.2 A NON-CLASSICAL CASE WHEN $n=1$

In the preceding section we have shown how purely geometric considerations from complex geometry force arithmetic considerations to enter. The example there was for 0 -cycles on a surface. However, similar considerations apply already for algebraic curves if we consider the tangent space to "divisors with values in $\mathbb{C}^{*}$. This will now be explained.

In the remainder of this section, $X$ is a smooth curve. For the sheaf

$$
\underline{\underline{Z}}^{1}(X)=\underset{x \in X}{\oplus} \underline{\underline{Z}}_{x}
$$

of divisors on a smooth curve, we have defined the tangent sheaf $\underline{\underline{T}} Z^{1}(X)$ and shown that it has the description

$$
\begin{equation*}
\underline{\underline{T}}^{1}(X)=\underset{x \in X}{\oplus}{\underline{\underline{\operatorname{Hom}^{c}}}}^{c}\left(\Omega_{X / \mathbb{C}, x}^{1}, \mathbb{C}\right) \tag{6.7}
\end{equation*}
$$

Here, $\underline{\underline{Z}}_{x}$ and $\underline{\underline{\operatorname{Hom}^{c}}}\left(\Omega_{X / \mathbb{C}, x}^{1}, \mathbb{C}\right)$ are skyscraper sheaves supported at $x \in X$. We now define

$$
\underline{\underline{Z}}_{1}^{1}(X)=\underset{x \in X}{\oplus} \underline{\underline{\mathbb{C}}}_{x}^{*}
$$

We will show that the natural analogue of (6.7) is

$$
\begin{equation*}
\underline{\underline{T}} Z_{1}^{1}(X)=\underset{x \in X}{\oplus} \underline{\underline{\operatorname{Hom}^{o}}}\left(\Omega_{X / \mathbb{Q}, x}^{1}, \Omega_{\mathbb{C} / \mathbb{Q}}^{1}\right) \tag{6.8}
\end{equation*}
$$

Here, $\operatorname{Hom}^{o}\left(\Omega_{X / \mathbb{Q}, x}^{1}, \Omega_{\mathbb{C} / \mathbb{Q}}^{1}\right)$ are the continuous $\mathbb{C}$-linear homomorphisms

$$
\varphi: \Omega_{X / \mathbb{Q}, x}^{1} \rightarrow \Omega_{\mathbb{C} / \mathbb{Q}}^{1}
$$

that satisfy

$$
\varphi(f \alpha)=\varphi_{0}(f) \alpha
$$

for $f \in \mathcal{O}_{X, x}$ and $\alpha \in \Omega_{\mathbb{C} / \mathbb{Q}}^{1}$ and where $\varphi_{0} \in \operatorname{Hom}_{\mathbb{C}}^{c}\left(\mathcal{O}_{X, x}, \mathbb{C}\right)$. The point of (6.8) will be:
(6.9) The condition that the tangent map

$$
\left\{\text { arcs in } Z_{1}^{1}(X)\right\} \rightarrow\{\text { vector space }\}
$$

be a homomorphism will imply that, with a natural geometric description of the first order equivalence relation $\equiv_{1^{\text {st }}}$ on arcs in $Z_{1}^{1}(X)$, we are led naturally to differentials over $\mathbb{Q}$.

Thus, in addition to spreads this will give another geometric interpretation of absolute differentials. Still another reason for the appearance of differentials over $\mathbb{Q}$ will be given below when we discuss van der Kallen's description of the formal tangent space to the Milnor $K$-groups.

The following discussion is heuristic. The intent is to motivate the formal definition. An arc in $Z_{1}^{1}(X)$ will be given by $(f(t), g(t))$ where $f(t)$ and $g(t)$ are arcs in $\mathbb{C}(X)^{*}$, and where it is understood that we consider $\left.g(t)\right|_{\operatorname{div} f(t)}$ and

$$
\operatorname{div} g(t) \cap \operatorname{div} f(t)=\phi
$$

Then if div $f(t)=\sum_{i} n_{i} x_{i}(t)$

$$
\left.\underset{i}{\oplus} g(t)^{n_{i}}\right|_{x_{i}(t)}
$$

will be an arc in $\underset{x \in X}{\oplus} \mathbb{C}_{x}^{*}$.
To obtain a harbinger of how the geometry and arithmetic will interact, let $\lambda \in \mathbb{C}^{*}$ be an $m^{\text {th }}$ root of unity and let us abbreviate by $\equiv$ the condition that an $\operatorname{arc}(f(t), g(t))$ be $1^{\text {st }}$ order equivalent to zero. Then since the tangent map is a homomorphism

$$
\begin{align*}
& m(f(t), \lambda)=(\underset{m}{f(t), \lambda)+\cdots+(f(t), \lambda}) \equiv\left(f(t), \lambda^{m}\right)  \tag{6.10}\\
&=(f(t), 1) \\
&=0 \\
& \Rightarrow m(f(t), \lambda) \equiv 0 \\
& \Rightarrow(f(t), \lambda) \equiv 0 \quad \text { if } \quad \lambda^{m}=1
\end{align*}
$$

since the stalks of the sheaf $\underline{\underline{T}} Z_{1}^{1}(X)$ are vector spaces.
Recall that we have not formally defined $\equiv$; we are just arguing heuristically. The conditions that $\equiv$ should satisfy are:
(i) $\left(f(t), g_{1}(t)\right)+\left(f(t), g_{2}(t)\right) \equiv\left(f(t), g_{1}(t) g_{2}(t)\right)$
(ii) $\left(f_{1}(t), g(t)\right)+\left(f_{2}(t), g(t)\right) \equiv\left(f_{1}(t) \cdot f_{2}(t), g(t)\right)$
(iii) $(f(m t), g(m t)) \equiv m(f(t), g(t)) \quad m \in \mathbb{Z}$
(iv) $(f(t), g(t)+h(t) f(t)) \equiv(f(t), g(t))$
(v) $(f(t), g) \equiv 0$ if $\dot{f} \in \mathcal{J}(f(0))$
(vi) $\left(\xi^{m}+t\left(g_{1}+g_{2}\right), g_{1}+g_{2}\right) \equiv\left(\xi^{m}+t g_{1}, g_{1}\right)+\left(\xi^{m}+t g_{2}, g_{2}\right)$

In (v), the function $g$ is constant in $t$ and $\dot{f} \in \mathcal{J}(f(0))$ means that to first order the divisor of $f$ does not move. In (vi), $\xi \in \mathcal{O}_{X, x} \subset \mathbb{C}(X)^{*}$ is a local uniformizing parameter. As to why (vi) should hold, we have by (iv)

$$
\begin{array}{rlrl}
\left(\xi^{m}+t\left(g_{1}+g_{2}\right), g_{1}+g_{2}\right) & \equiv\left(\xi^{m}+t\left(g_{1}+g_{2}\right),-\frac{\xi^{m}}{t}\right) & (t \neq 0) \\
\left(\xi^{m}+t g_{1}, g_{1}\right) & \equiv\left(\xi^{m}+t g_{1},-\frac{\xi^{m}}{t}\right) & (t \neq 0) \\
\left(\xi^{m}+t g_{2}, g_{2}\right) & \equiv\left(\xi^{m}+t g_{2},-\frac{\xi}{t}^{m}\right) & & (t \neq 0)
\end{array}
$$

Thus by (ii)

$$
\begin{array}{rlr}
\left(\xi^{m}+t g_{1},\right. & \left.g_{1}\right)+\left(\xi^{m}+t g_{2}, g_{2}\right) & (t \neq 0) \\
& \equiv\left(\left(\xi^{m}+t g_{1}\right)\left(\xi^{m}+t g_{2}\right),-\frac{\xi}{t}^{m}\right) & \\
& \equiv\left(\xi^{2 m}+t \xi^{m}\left(g_{1}+g_{2}\right),-\frac{\xi}{t}^{m}\right) & (t \neq 0) \\
& \equiv\left(\xi^{m},-\frac{\xi}{t}^{m}\right)+\left(\xi^{m}+t\left(g_{1}+g_{2}\right),-\frac{\xi}{t}^{m}\right) & \\
& \equiv\left(\xi^{m}+t\left(g_{1}+g_{2}\right),\left(g_{1}+g_{2}\right)\right) &
\end{array}
$$

by the first step above.
A similar argument shows that

$$
(\mathrm{vi})^{\prime} \quad\left(\xi+t f\left(g_{1}+g_{2}\right), g_{1}+g_{2}\right) \equiv\left(\xi+t f g_{1}, g_{1}\right)+\left(\xi+t f g_{2}, g_{2}\right)
$$

where $f \in \mathcal{O}_{X, x} \subset \mathbb{C}(X)$ and where we restrict attention to a Zariski neighborhood of $x$. From this we infer the

Proposition: For $f \in \mathcal{O}_{X, x}$
(a) $(\xi+t f, \lambda) \equiv 0$ if $\lambda \in \mathbb{Q}$
(b) $\left(\xi+t f\left(g_{1}+g_{2}\right), g_{1}+g_{2}\right) \equiv\left(\xi+t f g_{1}, g_{1}\right)+\left(\xi+t f g_{2}, g_{2}\right)$ where $g_{1}, g_{2} \in$ $\mathcal{O}_{X, x}^{*}$.
Proof: Assertion (b) is (vi) ${ }^{\prime}$ above. As for (a) we have

$$
\begin{aligned}
(\xi+t f, 2) & \equiv\left(\xi+t f\left(\frac{1}{2}(1+1)\right), 1+1\right) \\
& \equiv\left(\xi+\frac{t f}{2}, 1\right)+\left(\xi+\frac{t f}{2}, 1\right) \\
& \equiv 0
\end{aligned}
$$

A similar argument shows that

$$
\begin{equation*}
(\xi+t f, m) \equiv 0 \quad \text { for } m \in \mathbb{N} \tag{6.11}
\end{equation*}
$$

Using (6.10) we have

$$
(\xi+t f,-1) \equiv 0
$$

so that (6.11) holds for all integers $m$. For $q \neq 0$

$$
\begin{aligned}
q\left(\xi+t f, \frac{1}{q}\right) & \equiv(\xi+t \underbrace{\left.q f\left(\frac{1}{q}\right), \frac{1}{q}\right)+\cdots+\left(\xi+t q f\left(\frac{1}{q}\right), \frac{1}{q}\right)}_{q \text { times }} \\
& \equiv(\xi+t q f, 1) \quad\left(\mathrm{by}(\mathrm{vi})^{\prime}\right) \\
& \equiv 0 \\
& \Rightarrow\left(\xi+t f, \frac{1}{q}\right) \equiv 0
\end{aligned}
$$

This implies the proposition.
Using the proposition we see that for $f \in \mathcal{O}_{X, x}$ and $g \in \mathcal{O}_{X, x}^{*}$

$$
(\xi+t f, g) \rightarrow f \otimes g \in \mathcal{O}_{X, x} \otimes_{\mathbb{Z}} \mathcal{O}_{X, x}^{*}
$$

is well-defined on arcs modulo the above equivalence relation. It is obviously surjective, and with the obvious notations we have that

$$
\left\{\begin{array}{l}
f \otimes \lambda \equiv 0 \text { if } \lambda \in \mathbb{Q}^{*} \\
f\left(g_{1}+g_{2}\right) \otimes\left(g_{1}+g_{2}\right) \equiv f g_{1} \otimes g_{1}+f g_{2} \otimes g_{2}
\end{array}\right.
$$

From this we conclude that the tangent map from $\operatorname{arcs}$ in $Z^{1}(X, 1)$ factors through the map

$$
\mathcal{O}_{X, x} \otimes_{\mathbb{Z}} \mathcal{O}_{X, x}^{*} \rightarrow \Omega_{X / \mathbb{Q}, x}^{1}
$$

given by

$$
f \otimes g \rightarrow f \frac{d g}{g}
$$

In this way differentials over $\mathbb{Q}$ again appear from purely geometric considerations.

Finally we note the following result
(6.12) Proposition: The map to be defined from arcs in $Z_{1}^{1}(X)$ to $\underline{\underline{T}} Z_{1}^{1}(X)$ will be surjective.

We shall not prove this as the much more difficult analogue of this result for the case of surfaces will be given in section 8.2 below. We note that it is a geometric existence result, albeit one that is local (in the Zariski topology) and at the infinitesimal level.

### 6.3 THE DIFFERENTIAL OF THE TAME SYMBOL

The sheaf $\underline{\underline{Z}}_{1}^{1}(X)=\underset{x \in X}{\oplus} \underline{\mathbb{C}}_{x}^{*}$ arises by localizing the construction in the Weil reciprocity law, as follows: For $f, g \in \mathbb{C}(X)^{*}$ and a point $x \in X$, recall the
tame symbol given by

$$
\begin{equation*}
T_{x}(f, g)= \pm\left(\frac{f^{v_{g}(x)}}{g^{v_{f}(x)}}\right)(x) \tag{6.13}
\end{equation*}
$$

where the sign is

$$
(-1)^{v_{f}(x) v_{g}(x)} .
$$

The Weil reciprocity law states

$$
\begin{equation*}
\prod_{x \in X} T_{x}(f, g)=1 . \tag{6.14}
\end{equation*}
$$

It is of interest to compute the differential of the map (6.13) and, as an application, determine the infinitesimal form of (6.14).

We begin with a brief digression on residues.
If $X$ is a smooth curve and $x \in X$, then denoting by $\Omega_{X / \mathbb{Q}}^{q}(n x)$ the absolute $q$-forms with poles of order at most $n$ at $x$ there are residue maps

$$
\begin{aligned}
& \Omega_{X / \mathbb{Q}, x}^{1}(n x) \xrightarrow{\operatorname{Res}_{x}} \quad \mathbb{C} \\
& \Omega_{X / \mathbb{Q}, x}^{2}(n x) \xrightarrow{\operatorname{Res}_{x}} \Omega_{\mathbb{C} / \mathbb{Q}}^{1} \\
& \Omega_{X / \mathbb{Q}, x}^{3}(n x) \xrightarrow{\operatorname{Res}_{x}} \Omega_{\mathbb{C} / \mathbb{Q}}^{2},
\end{aligned}
$$

and the residue theorem

$$
\sum_{x \in X} \operatorname{Res}_{x}(\omega)=0, \quad \omega \in H^{0}\left(\Omega_{X / \mathbb{Q}}^{q+1}\right)
$$

holds.
The residues are defined by the sequences

$$
\begin{aligned}
& \Omega_{X / \mathbb{Q}, x}^{1}(n x) \rightarrow \quad \Omega_{X / \mathbb{C}, x}^{1}(n x) \\
& \Omega_{X / \mathbb{Q}, x}^{2}(n x) \rightarrow \Omega_{X / \mathbb{C}, x}^{1}(n x) \otimes \Omega_{\mathbb{C} / \mathbb{Q}}^{1} \xrightarrow{\text { Res } \otimes \text { identity }} \quad \mathbb{C} \\
& \Omega_{\mathbb{C} / \mathbb{Q}}^{1}
\end{aligned}
$$

and so forth.
We now consider an $\operatorname{arc}(1+t f, g)$ in $\mathbb{C}(X)^{*} \times \mathbb{C}(X)^{*}$ where $f \in \mathbb{C}(X)$ and $g \in \mathbb{C}(X)^{*}$. Denoting by $\tau$ the tangent to this arc we have for the differential of the tame symbol $d T_{x}$ applied to $\tau$ that

$$
d T_{x}(\tau) \in \operatorname{Hom}^{o}\left(\Omega_{X / \mathbb{Q}, x}^{1}, \Omega_{\mathbb{C} / \mathbb{Q}}^{1}\right) .
$$

Proposition: For $\varphi \in \Omega_{X / \mathbb{Q}, x}^{1}$,

$$
d T_{x}(\tau)(\varphi)=\operatorname{Res}_{x}\left(f \frac{d g}{g} \wedge \varphi\right)
$$

when $f d g / g \in \Omega_{\mathbb{C}(X) / \mathbb{Q}}^{1}$.

Proof: We will check the case where $\nu_{f}(x)=-1$ and $\nu_{g}(x)=0$; the general case is similar. Adjusting constants we may assume that

$$
\left\{\begin{array}{l}
f=-\frac{1}{\xi} \\
g=b_{0}\left(1+b_{1} \xi+\cdots\right) \quad b_{0} \neq 0
\end{array}\right.
$$

where $\xi \in \mathbb{C}(X)$ is a local uniformizing parameter centered at $x$. We may also assume that

$$
\varphi=c d \xi+\alpha+(\text { terms vanishing at } \xi=0)
$$

where $\alpha \in \Omega_{\mathbb{C} / \mathbb{Q}}^{1}$. Then

$$
\begin{equation*}
\operatorname{Res}_{x}\left(f \frac{d g}{g} \wedge \varphi\right)=-c \frac{d b_{0}}{b_{0}}+\frac{b_{1}}{b_{0}} \alpha \in \Omega_{\mathbb{C} / \mathbb{Q}}^{1} \tag{6.15}
\end{equation*}
$$

On the other hand, letting $x(t)$ be the point given by $\xi=t$

$$
T_{x(t)}(1+t f, g)
$$

is an arc in $\underset{x \in X}{\oplus} \underline{\mathbb{C}}_{x}^{*}$ whose tangent is equal to $d T_{x}(\tau)$. Now

$$
\begin{equation*}
T_{x(t)}(1+t f, g)=\left(t, b_{0}\left(1+b_{1} t+\cdots\right)\right) \in X \times \mathbb{C}^{*} \tag{6.16}
\end{equation*}
$$

From the discussion in section 8.2 below we have that the rule for evaluating the tangent to the arc (6.16) on $\varphi$ is as follows: Denote by $u$ the coordinate on $\mathbb{C}^{*}$. Then

$$
\Phi=: \varphi \wedge \frac{d u}{u} \in \Omega_{X \times \mathbb{P}^{1} / \mathbb{Q}}^{2}
$$

We restrict this form to the curve B given by the image of (6.16); then

$$
\left.\Phi\right|_{B} \in \Omega_{B / \mathbb{Q}, t_{0}}^{2}
$$

We then map $\Omega_{B / \mathbb{Q}, t_{0}}^{2}$ to $\Omega_{\mathbb{C} / \mathbb{Q}}^{1} \otimes \Omega_{B / \mathbb{C}, t_{0}}^{1}$ and evaluate the image of $\left.\Phi\right|_{B}$ on $\partial / \partial t$ in the second factor. Since

$$
\left.\Phi\right|_{B}=(c d t+\alpha+\cdots) \wedge \frac{d\left(b_{0}\left(1+b_{1} t+\cdots\right)\right)}{b_{0}\left(1+b_{1} t+\cdots\right)}
$$

we see that this procedure exactly gives (6.15).
What does the differential $d T_{x}$ of the tame symbol mean? Above we have taken it to mean the tangent to an arc $T(f(t), g(t))$ in $Z_{1}^{1}(X)$, where

$$
T=\underset{x \in X}{\oplus} T_{x}
$$

and $(f(t), g(t))$ is an arc in $\mathbb{C}(X)^{*} \times \mathbb{C}(X)^{*}$. But the differential should be a linear map

$$
d T_{x}: " ? " \rightarrow T_{\{x\}} Z_{1}^{1}(X),
$$

where $T_{\{x\}} Z_{1}^{1}(X)$ is the tangent to arcs $(z(t), a(t))$ in $Z_{1}^{1}(X)$ where $z(t)$ is an arc in $Z_{\{x\}}^{1}(X)$; the issue is what "?" should be?

To get some understanding of this, remark that we could of course take it to be something like

$$
T\left(\mathbb{C}(X)^{*} \times \mathbb{C}(X)^{*}\right) \cong \mathbb{C}(X) \oplus \mathbb{C}(X)
$$

But because of the easily verified relations

$$
\begin{cases}T_{x}\left(f^{n}, g\right)=T_{x}\left(f, g^{n}\right) & n \in \mathbb{Z}  \tag{6.17}\\ T_{x}\left(f_{1} f_{2}, g\right)=T_{x}\left(f_{1}, g\right) T_{x}\left(f_{2}, g\right) & \\ T_{x}\left(f, g_{1} g_{2}\right)=T_{x}\left(f, g_{1}\right) T_{x}\left(f, g_{2}\right) & \end{cases}
$$

we see that the tame symbol really should be defined on

$$
\mathbb{C}(X)^{*} \otimes_{\mathbb{Z}} \mathbb{C}(X)^{*}
$$

However, in addition to (6.17) one may directly check that

$$
T_{x}(f, 1-f)=0, \quad f \in \mathbb{C}(X)^{*} \backslash\{1\}
$$

At this point we recall the basic
Definition: For any field $F$ of characteristic zero, or a local ring whose residue field is of characteristic zero, the group $K_{2}(F)$ is defined by

$$
K_{2}(F)=F^{*} \otimes_{\mathbb{Z}} F^{*} / R
$$

where $R$ is the subgroup generated by the Steinberg relation

$$
a \otimes(1-a), \quad a \in F^{*} \backslash\{1\}
$$

The image of $a \otimes b \in F^{*} \otimes_{\mathbb{Z}} F^{*}$ in $K_{2}(F)$ is denoted by $\{a, b\}$. Our reference for $K$-theory is the book [35] by Milnor. We have taken as definition the identification given by the theorem of Matsumura. We note that the above definition will extend to define the higher Milnor $K$-groups

$$
K_{p}^{M}(F)=\overbrace{F^{*} \otimes \cdots \otimes F^{*}}^{p} / R, \quad p \geqq 2
$$

where $R$ is generated by elements $a_{1} \otimes \cdots \otimes a_{k} \otimes\left(1-a_{k}\right) \otimes \cdots \otimes a_{p-1}$ obtained by putting a Steinberg relation in adjacent positions.

Of particular importance for our work is the formal tangent space to $K_{2}(F)$. Letting $\epsilon$ be a formal indeterminate satisfying $\epsilon^{2}=0$ and $F^{*}[\epsilon]$ the set of expressions

$$
\left\{\begin{array}{l}
a+\epsilon b \\
a \in F^{*}, b \in F
\end{array}\right.
$$

we observe that we may define $K_{2}\left(F^{*}[\epsilon]\right)$ as above but now with $F^{*}[\epsilon]$ replacing $F^{*}$.

Definition: The formal tangent space $T K_{2}(F)$ is defined by

$$
T K_{2}(F)=\operatorname{ker}\left\{K_{2}(F[\epsilon]) \rightarrow K_{2}(F)\right\}
$$

Here the restriction map is obtained by setting $\epsilon=0$. A central result is the

Theorem (van der Kallen [12]): There is a natural identification

$$
\begin{equation*}
T K_{2}(F) \cong \Omega_{F / \mathbb{Q}}^{1} \tag{6.18}
\end{equation*}
$$

The map that induces (6.18) is

$$
\{1+\epsilon a, b\} \rightarrow \frac{a d b}{b}
$$

where $a \in F, b \in F^{*}$. Because of its central role in what follows, in the appendix to this section we have given a proof of the theorem of van der Kallen. Remark that the proof extends to the higher Milnor $K$-groups to give a natural identification

$$
T K_{p}^{M}(F) \cong \Omega_{F / \mathbb{Q}}^{p-1}
$$

where the map is

$$
\left\{1+\epsilon a, b_{1}, \ldots, b_{p-1}\right\} \rightarrow \frac{a d b_{1}}{b_{1}} \wedge \cdots \wedge \frac{d b_{p-1}}{b_{p-1}}
$$

Returning to the differential of the tame symbol, using (6.18) we should have

$$
\begin{equation*}
d T_{x}: \Omega_{\mathbb{C}(X) / \mathbb{Q}, x}^{1} \rightarrow \operatorname{Hom}^{o}\left(\Omega_{X / \mathbb{Q}, x}^{1}, \Omega_{\mathbb{C}, \mathbb{Q}}^{1}\right) \tag{6.19}
\end{equation*}
$$

Comparing (6.14) with the proposition above we infer the
Proposition: The differential (6.19) of the tame symbol is given by

$$
\begin{equation*}
d T_{x}(\psi)(\varphi)=\operatorname{Res}_{x}(\psi \wedge \varphi) \tag{6.20}
\end{equation*}
$$

where $\psi \in \Omega_{\mathbb{C}(X) / \mathbb{Q}}^{1}$ and $\varphi \in \Omega_{X / \mathbb{Q}, x}^{1}$.
We may now turn the discussion around. There is a sheaf mapping

$$
\underline{\underline{\Omega}}_{\mathbb{C}(X) / \mathbb{Q}}^{1} \xrightarrow{\rho} \underset{x \in X}{ }{\underline{\underline{\operatorname{Hom}^{2}}}}^{o}\left(\Omega_{X / \mathbb{Q}, x}^{1}, \Omega_{\mathbb{C} / \mathbb{Q}}^{1}\right)
$$

given on the stalk at a point $x$ by

$$
\rho(\psi)(\varphi)=\operatorname{Res}_{x}(\psi \wedge \varphi) \in \Omega_{\mathbb{C} / \mathbb{Q}}^{1}
$$

It is easy to check that this mapping is surjective and has kernel $\Omega_{X / \mathbb{Q}, x}^{1}$. Thus we have the exact sheaf sequence

$$
\begin{equation*}
0 \rightarrow \Omega_{X / \mathbb{Q}}^{1} \rightarrow \underline{=}_{\mathbb{C}(X) / \mathbb{Q}}^{1} \rightarrow \underset{x \in X}{\oplus} \underline{\underline{\operatorname{Hom}^{o}}}{ }^{o}\left(\Omega_{X / \mathbb{Q}, x}^{1}, \Omega_{\mathbb{C} / \mathbb{Q}}^{1}\right) \rightarrow 0 \tag{6.21}
\end{equation*}
$$

which gives a flasque resolution of $\Omega_{X / \mathbb{Q}}^{1}$. There is also the following special case of the Bloch-Gersten-Quillen flasque resolution of the sheaf $\mathcal{K}_{2}\left(\mathcal{O}_{X}\right)$

$$
\begin{equation*}
0 \rightarrow \mathcal{K}_{2}\left(\mathcal{O}_{X}\right) \rightarrow \underline{\underline{K}}_{2}(\mathbb{C}(X)) \xrightarrow{T} \underset{x \in X}{\oplus} \underline{\underline{\mathbb{C}}}_{x}^{*} \rightarrow 0 \tag{6.22}
\end{equation*}
$$

From the above discussion and proposition we infer that
The tangent sequence to (6.22) may be defined and it is then given by (6.21).

This is the "higher" analogue of the discussion in section 2 which identified

$$
0 \rightarrow \mathcal{O}_{X} \rightarrow \underline{\mathbb{C}}(X) \rightarrow \underset{x \in X}{\oplus}{\underline{\underline{\operatorname{Hom}^{c}}}}^{c}\left(\Omega_{X / \mathbb{C}, x}^{1}, \mathbb{C}\right) \rightarrow 0
$$

as the tangent sequence of

$$
0 \rightarrow \mathcal{O}_{X}^{*} \rightarrow \underline{\mathbb{C}}(X)^{*} \rightarrow \underset{x \in X}{\oplus} \underline{\underline{Z}}_{x} \rightarrow 0
$$

Turning now to the infinitesimal form of the Weil reciprocity law, we observe that there is a mapping of sheaves

$$
\begin{equation*}
\underset{x \in X}{\oplus} \mathbb{C}_{x}^{*} \rightarrow \underline{\underline{\mathbb{C}^{*}}} \tag{6.23}
\end{equation*}
$$

given by

$$
\underset{x \in X}{\oplus}\left(x, \lambda_{x}\right) \rightarrow \prod_{x \in X} \lambda_{x}
$$

where $\mathbb{C}^{*}$ is the constant Zariski sheaf with stalks $\mathbb{C}_{x}^{*}=\mathbb{C}^{*}$. The differential of $(6.2 \overline{3})$ is a mapping of sheaves

$$
\begin{equation*}
\underset{x \in X}{\oplus}{\underline{\underline{\operatorname{Hom}^{o}}}}^{o}\left(\Omega_{X / \mathbb{Q}, x}^{1}, \Omega_{\mathbb{C} / \mathbb{Q}}^{1}\right) \rightarrow \underline{\underline{\mathbb{C}}} \tag{6.24}
\end{equation*}
$$

that may be described as follows: An element $\tau_{x}$ of $\operatorname{Hom}^{o}\left(\Omega_{X / \mathbb{Q}, x}^{1}, \Omega_{\mathbb{C} / \mathbb{Q}}^{1}\right)$ satisfies

$$
\tau_{x}(h \alpha)=\tau_{x}^{o}(h) \alpha
$$

for $\alpha \in \Omega_{\mathbb{C} / \mathbb{Q}}^{1}, h \in \mathcal{O}_{X, x}$ and where $\tau_{x}^{o} \in \operatorname{Hom}^{c}\left(\mathcal{O}_{X, x}, \mathbb{C}\right)$. Then the differential of (6.23) at $\underset{x \in X}{\oplus}\left(x, \lambda_{x}\right)$ is given by sending $\tau=\underset{x \in X}{\oplus} \tau_{x}$, where $\tau_{x} \in \operatorname{Hom}^{o}\left(\Omega_{X / \mathbb{Q}, x}^{1}, \Omega_{\mathbb{C} / \mathbb{Q}}^{1}\right)$, to $\sum_{x \in X} \tau_{x}^{o}(1)$; i.e., we have

$$
\begin{equation*}
\tau \rightarrow \sum_{x \in X} \tau_{x}^{o}(1) \tag{6.25}
\end{equation*}
$$

Next, as noted above the differential of the tame symbol applied to the image of the arc $\{1+t f, g\}$ in $K_{2}(\mathbb{C}(X))$ is the tangent vector $\tau=\left\{\tau_{x}\right\}_{x \in X} \in$ $\underset{x \in X}{\oplus} \operatorname{Hom}^{o}\left(\Omega_{X / \mathbb{Q}, x}^{1}, \Omega_{\mathbb{C} / \mathbb{Q}}^{1}\right)$ given by

$$
\tau_{x}(\varphi)=\operatorname{Res}_{x}\left(f \frac{d g}{g} \wedge \varphi\right), \quad \varphi \in \Omega_{X / \mathbb{Q}, x}^{1}
$$

Taking $\varphi=h \alpha$ where $h \in \mathcal{O}_{X, x}$ we have

$$
\tau_{x}(h \alpha)=\operatorname{Res}_{x}\left(h f \frac{d g}{g}\right) \alpha
$$

i.e.

$$
\tau_{x}^{o}(h)=\operatorname{Res}_{x}\left(h f \frac{d g}{g}\right)
$$

Referring to (6.25) and taking $h=1$, we have the

Proposition: The infinitesimal form of the Weil reciprocity law is given by the residue theorem

$$
\sum_{x \in X} \operatorname{Res}_{x}\left(f \frac{d g}{g}\right)=0
$$

The Weil reciprocity law is the first of a series of reciprocity laws whose higher versions are due to Suslin. To state them above we have defined the higher Milnor $K$-groups are defined by

$$
K_{p}^{M}(F)=\overbrace{F^{*} \otimes_{\mathbb{Z}} \cdots \otimes_{\mathbb{Z}} F^{*}}^{p} / R
$$

where $R$ is generated by putting $a \otimes(1-a)\left(a \in F^{*} \backslash\{1\}\right)$ in adjacent positions. As noted there, the van der Kallen theorem generalizes in a straightforward way to give for the formal tangent space

$$
\begin{equation*}
T K_{p}^{M}(F) \cong \Omega_{F / \mathbb{Q}}^{p-1}, \quad p \geqq 1 \tag{6.26}
\end{equation*}
$$

Denoting the element of $K_{p}^{M}(F)$ that is the image of $a_{1} \otimes \cdots \otimes a_{p}$ by $\left\{a_{1}, \ldots, a_{p}\right\}$, the map that gives (6.26) is

$$
\left\{1+\epsilon a, b_{1}, \ldots, b_{p-1}\right\} \rightarrow a \frac{d b_{1}}{b_{1}} \wedge \cdots \wedge \frac{d b_{p-1}}{b_{p-1}}
$$

where $a \in F$ and $b_{1}, \ldots, b_{p-1} \in F^{*}$.
Returning to the consideration of an algebraic curve $X$, there is for each $x \in X$ a map

$$
K_{p}^{M}(\mathbb{C}(X)) \xrightarrow{\partial_{x}} K_{p-1}\left(\mathbb{C}_{x}\right)
$$

given by alternating the tame symbol as in the formula for a coboundary. The Suslin reciprocity formula states that the composite

$$
K_{p}^{M}(\mathbb{H}(X)) \stackrel{\partial}{\stackrel{\partial_{x}}{\longrightarrow} \underset{x \in X}{\oplus} K_{p-1}^{M}\left(\mathbb{C}_{x}\right)} \rightarrow K_{p-1}^{M}(\mathbb{C}),
$$

is the identity, where

$$
\partial=\prod_{x \in X} \partial_{x}
$$

The infinitesimal version of (6.27) states that the composite

$$
\frac{d(\partial)}{\Omega_{\mathbb{C}(X) / \mathbb{Q}}^{p-1} \rightarrow \underset{x \in X}{\oplus} \Omega_{\mathbb{C}_{x} / \mathbb{Q}}^{p-2} \rightarrow \Omega_{\mathbb{C} / \mathbb{Q}}^{p-2}}
$$

is zero, where $d(\partial)$ is the differential of $\partial$ using the identification (6.26). One may check that for $\varphi \in \Omega_{\mathbb{C}(X) / \mathbb{Q}}^{p-1}$

$$
d(\partial)(\varphi)=\sum_{x \in X} \operatorname{Res}_{x}(\varphi)
$$

Then as in the $p=2$ case of Weil reciprocity, we have the

Proposition: The infinitesimal form of the Suslin reciprocity law is given by the residue theorem

$$
\sum_{x \in X} \operatorname{Res}_{x}(\varphi)=0 \quad \text { in } \Omega_{\mathbb{C} / \mathbb{Q}}^{p-2}
$$

The higher reciprocity theorems are in some ways more subtle than Weil reciprocity. For example, when $p=3$ since

$$
d\left(\partial_{x}\right)\left(f \frac{d g_{1}}{g_{1}} \wedge \frac{d g_{2}}{g_{2}}\right)=\operatorname{Res}_{x}\left(f \frac{d g_{1}}{g_{1}} \wedge \frac{d g_{2}}{g_{2}}\right) \in \Omega_{\mathbb{C} / \mathbb{Q}}^{1}
$$

we see that

$$
\sum_{x \in X} d\left(\partial_{x}\right)\left(f \frac{d g_{1}}{g_{1}} \wedge \frac{d g_{2}}{g_{2}}\right)=0
$$

gives an arithmetic relation in the values of $g_{1}, g_{2}$ at the points of $|\operatorname{div} f| \cup$ $\left|\operatorname{div} g_{1}\right| \cup\left|\operatorname{div} g_{2}\right|$. As we will see below, this is very much the flavor of what happens for rational equivalence in higher codimension.

### 6.3.1 Appendix: On the theorem of van der Kallen

We want to discuss the natural isomorphism

$$
\begin{equation*}
T K_{2}(F) \cong \Omega_{F / \mathbb{Q}}^{1} \tag{6.29}
\end{equation*}
$$

due to van der Kallen [12]. Here, $F$ is either a field of characteristic zero or a local ring with residue field of characteristic zero. Following that we will discuss how geometric considerations inevitably lead into $K_{2}\left(\mathcal{O}_{X}\right)$.

We begin by recalling that

$$
K_{2}(F)=F^{*} \otimes_{\mathbb{Z}} F^{*} / R
$$

where $R$ is generated by the Steinberg relations

$$
\begin{equation*}
a \otimes(1-a) \sim 1, \quad a \in F^{*} \backslash\{1\} \tag{6.30}
\end{equation*}
$$

The following are non-trivial but elementary consequences of the defining relations for $\otimes_{\mathbb{Z}}$ and (6.30) (cf. Milnor [35])

$$
\left\{\begin{array}{l}
\{a, 1\}=1  \tag{6.31}\\
\{a, b\}=\{b, a\}^{-1} \\
\left\{a_{1} a_{2}, b\right\}=\left\{a_{1}, b\right\}\left\{a_{2}, b\right\} \\
\left\{a, b_{1} b_{2}\right\}=\left\{a, b_{1}\right\}\left\{a, b_{2}\right\} \\
\{a,-a\}=1
\end{array}\right.
$$

Recall also that by definition

$$
T K_{2}(F)=\operatorname{ker}\left\{K_{2}(F[\epsilon]) \xrightarrow{\epsilon=0} K_{2}(F)\right\} .
$$

Lemma: $T K_{2}(F)$ is generated by elements

$$
\begin{equation*}
\{1+\epsilon a, b\} \quad a \in F, b \in F^{*} \tag{6.32}
\end{equation*}
$$

Assuming for a moment the lemma, the mapping (6.30) is induced by

$$
\begin{equation*}
\{1+\epsilon a, b\} \rightarrow a \frac{d b}{b} \tag{6.33}
\end{equation*}
$$

Since (6.33) is clearly surjective, we have to show that it is well-defined and injective.

Proof of lemma: Suppose that $\left\{a_{1}+\epsilon b_{1}, a_{2}+\epsilon b_{2}\right\} \in K_{2}(F[\epsilon])$ and $\left\{a_{1}, a_{2}\right\}=1$. Then by (6.31)

$$
\begin{aligned}
\left\{a_{1}+\epsilon b_{1}, a_{2}+\epsilon b_{2}\right\} & =\left\{a_{1}, a_{2}+\epsilon b_{2}\right\}\left\{1+\epsilon \frac{b_{1}}{a_{1}}, a_{2}+\epsilon b_{2}\right\} \\
& =\left\{a_{1}, a_{2}\right\}\left\{a_{1}, 1+\epsilon \frac{b_{2}}{a_{2}}\right\}\left\{1+\epsilon \frac{b_{1}}{a_{1}}, a_{2}+\epsilon b_{2}\right\} \\
& =\left\{a_{1}, 1+\epsilon \frac{b_{2}}{a_{2}}\right\}\left\{1+\epsilon \frac{b_{1}}{a_{1}}, a_{2}\right\}\left\{1+\epsilon \frac{b_{1}}{a_{1}}, 1+\epsilon \frac{b_{2}}{a_{2}}\right\}
\end{aligned}
$$

We are reduced to proving: For $a, b \neq 0$

$$
\begin{align*}
& \{1+\epsilon a, 1+\epsilon b\} \text { is a product of elements of the form }  \tag{6.34}\\
& \{1+\epsilon f, g\} \text { where } f, g \in F^{*}
\end{align*}
$$

For $c \neq 0$

$$
\begin{aligned}
\{1+\epsilon a, 1+\epsilon b\} & =\left\{1+\epsilon a, \frac{1}{c}\right\}\{1+\epsilon a, c+\epsilon b c\} \\
& =\left\{1+\epsilon a, \frac{1}{c}\right\}\{1+\epsilon a, 1-(1-c-\epsilon b c)\} \\
& =\left\{1+\epsilon a, \frac{1}{c}\right\}\{(1+\epsilon a)(1-c-\epsilon b c), 1-(1-c-a b c)\}
\end{aligned}
$$

by using bilinearity and the Steinberg relation

$$
=\left\{1+\epsilon a, \frac{1}{c}\right\}\{1-c+\epsilon(a(1-c)-b c), c+\epsilon b c\} .
$$

Setting $c=a /(a+b)$ under the assumption $a+b \neq 0$, the term $a(1-c)-b c$ drops out and we have

$$
\begin{aligned}
& =\left\{1+\epsilon a, \frac{a+b}{a}\right\}\{1-c, c+\epsilon b c\} \\
& =\left\{1+\epsilon a, \frac{a+b}{a}\right\}\{1-c, 1+\epsilon b\} \\
& =\left\{1+\epsilon a, \frac{a+b}{a}\right\}\left\{\frac{-b}{a+b}, 1+\epsilon b\right\} \\
& =\{1+\epsilon a, a+b\}\{1+\epsilon a, b\}^{-1}\{-b, 1+\epsilon b\}\{1+\epsilon b, a+b\} \\
& =\{1+\epsilon(a+b), a+b\}\{1+\epsilon a, a\}^{-1}\{1+\epsilon b, b\}^{-1}\{-1,1+\epsilon b\}
\end{aligned}
$$

which using $\{-1,1+\epsilon b\}=\{1,1+\epsilon b / 2\}=1$ gives

$$
=\{1+\epsilon(a+b), a+b\}\{1+\epsilon a, a\}^{-1}\{1+\epsilon b, b\}^{-1}
$$

This proves (6.34) and therefore the lemma.
We note that under the mapping (6.33)

$$
\{1+\epsilon(a+b), a+b\}\{1+\epsilon a, a\}^{-1}\{1+\epsilon b, b\}^{-1} \rightarrow 0
$$

Since the relations

$$
\{1+\epsilon k a, b\}=\left\{1+\epsilon a, b^{k}\right\} \quad k \in \mathbb{Z}
$$

obviously also map to zero it follows that:

$$
\text { the mapping (6.28) defines } T K_{2}(F) \rightarrow \Omega_{F / \mathbb{Q}}^{1}
$$

We shall now prove the
Lemma: $\{1+\epsilon a, 1+\epsilon b\}=1$ in $K_{2}(F[\epsilon])$.
Proof: From the proof of the preceding lemma we have

$$
\begin{equation*}
\{1+\epsilon A, 1+\epsilon B\}=\frac{\{1+\epsilon(A+B), A+B\}}{\{1+\epsilon A, A\}\{1+\epsilon B, B\}} \tag{6.35}
\end{equation*}
$$

for any $A, B \in F^{*}$ such that also $A+B \in F^{*}$. Thus

$$
\begin{aligned}
\{1+\epsilon A, 1+\epsilon B\} & =\{(1+\epsilon(A-B))(1+\epsilon B), 1+\epsilon B\} \\
& =\{1+\epsilon(A-B), 1+\epsilon B\}\{1+\epsilon B, 1+\epsilon B\}
\end{aligned}
$$

which using

$$
\begin{aligned}
\{1+\epsilon B, 1+\epsilon B\} & =\{1+\epsilon B,-(1+\epsilon B)\}\{1+\epsilon B,-1\} \\
& =\{1+\epsilon B,-1\}=\{1+\epsilon B / 2,-1\}^{2}=\{1+\epsilon B / 2,1\}=1
\end{aligned}
$$

gives $\{1+\epsilon A, 1+\epsilon B\}=\{1+\epsilon(A-B), 1+\epsilon B\}$.
Applying (6.35) to both sides of the equation and assuming that $A-B \in$ $F^{*}$ gives

$$
\begin{aligned}
& \frac{\{1+\epsilon A, A\}}{\{1+\epsilon(A-B), A-B\}\{1+\epsilon B, B\}}=\frac{\{1+\epsilon(A+B), A+B\}}{\{1+\epsilon A, A\}\{1+\epsilon B, B\}} \\
& \Rightarrow\{1+\epsilon A, A\}^{2}=\{1+\epsilon(A+B), A+B\}\{1+\epsilon(A-B), A-B\}
\end{aligned}
$$

Setting $u=A+B$ and $v=A-B$ this becomes

$$
\left\{1+\epsilon \frac{(u+v)}{2}, \frac{u+v}{2}\right\}^{2}=\{1+\epsilon u, u\}\{1+\epsilon v, v\}
$$

The left hand side is

$$
\left\{1+\epsilon(u+v), \frac{u+v}{2}\right\}=\{1+\epsilon(u+v), u+v\}\left\{1+\epsilon(u+v), \frac{1}{2}\right\}
$$

By (iv) below the last term on the right is equal to 1 , so that we obtain

$$
\{1+\epsilon(u+v), u+v\}=\{1+\epsilon u, u\}\{1+\epsilon v, v\}
$$

Combining this with (6.35) gives

$$
\{1+\epsilon u, 1+\epsilon v\}=1 \text { if } u, v, u+v, u-v \in F^{*}
$$

Since for any $u, v$ we can write

$$
\{1+\epsilon u, 1+\epsilon v\}=\prod_{i, j}\left\{1+\epsilon u_{i}, 1+\epsilon v_{j}\right\}
$$

where $\sum_{i} u_{i}=u, \sum_{j} v_{j}=v$ and all $u_{i}, v_{j}, u_{i}+v_{j}, u_{i}-v_{j} \epsilon F^{*}$ we are done for the lemma.

To prove (6.29) we shall show that
(i) $\{1+\epsilon a c, a\}\{1+\epsilon b c, b\}=\{1+\epsilon c(a+b), a+b\}$
(ii) $\{1+\epsilon a b, a\}\{1+\epsilon a b, b\}=\{1+\epsilon a b, a b\}$
(iii) $\left\{1+\epsilon a_{1}, b\right\}\left\{1+\epsilon a_{2}, b\right\}=\left\{1+\epsilon\left(a_{1}+a_{2}\right), b\right\}$
(iv) $\{1+\epsilon a, \lambda\}=1$ for $\lambda \in \mathbb{Q}^{*}$.

Here it is understood that $a, b, c \in F$ and elements of $F$ are invertible when they need to be to make things well-defined.

Assuming (i)-(iv), we have that the mapping

$$
\operatorname{ker}\left\{K_{2}(F[\epsilon]) \rightarrow K_{2}(F)\right\} \rightarrow F \otimes_{\mathbb{Z}} F^{*}
$$

given by

$$
\{1+\epsilon a, b\} \rightarrow a \otimes b
$$

is well-defined and is injective, and (i)-(iv) generate exactly the relations that define the Kähler differentials; i.e., the kernel of the mapping

$$
F \otimes_{\mathbb{Z}} F^{*} \longrightarrow \Omega_{F / \mathbb{Q}}^{1}
$$

given by

$$
a \otimes b \longrightarrow a \frac{d b}{b}
$$

Thus the map induced by (6.33) is injective.
Since (ii) and (iii) are obvious it remains to prove (i) and (iv).
Let $A, A-1 \in F^{*}$ and $f \in F$. Then

$$
\begin{aligned}
1 & =\left\{1-\frac{A-1-\epsilon f}{A}, \frac{A-1-\epsilon f}{A}\right\} \\
& =\left\{\frac{1+\epsilon f}{A}, \frac{A-1-\epsilon f}{A}\right\} \\
& =\left\{\frac{1+\epsilon f}{A}, \frac{A-1}{A}\right\}\left\{\frac{1+\epsilon f}{A}, 1-\frac{\epsilon f}{A-1}\right\} \\
& =\left\{1+\epsilon f, \frac{A-1}{A}\right\}\left\{\frac{1}{A}, \frac{A-1}{A}\right\}\left\{\frac{1}{A}, 1-\frac{\epsilon f}{A-1}\right\}\left\{1+\epsilon f, 1-\frac{\epsilon f}{A-1}\right\}
\end{aligned}
$$

The second term is

$$
\left\{\frac{1}{A},-\frac{1}{A}\right\}\left\{\frac{1}{A}, 1-A\right\}=1
$$

and the fourth term is also 1 by the second lemma above. We thus have

$$
1=\left\{1+\epsilon f, \frac{A-1}{A}\right\}\left\{A, 1+\frac{\epsilon f}{A-1}\right\}
$$

where we have used $1+\frac{\epsilon f}{A-1}=\left(1-\frac{\epsilon f}{A-1}\right)^{-1}$.

Now set $A=(a+b) / b$ so that $A-1=a / b$, and set $f=c a$. Then $f /(A-1)=b c$ and

$$
1=\left\{1+\epsilon a c, \frac{a}{a+b}\right\}\left\{\frac{a+b}{b}, 1+\epsilon b c\right\}
$$

which gives

$$
\begin{aligned}
1 & =\{1+\epsilon a c, a\}\{1+\epsilon a c, a+b\}^{-1}\{a+b, 1+\epsilon b c\}\{b, 1+\epsilon b c\}^{-1} \\
& =\{1+\epsilon a c, a\}\{1+\epsilon a c, a+b\}^{-1}\{1+\epsilon b c, a+b\}^{-1}\{1+\epsilon b c, b\} \\
& =\{1+\epsilon a c, a\}\{1+\epsilon b c, b\}\{1+\epsilon c(a+b), a+b\}^{-1}
\end{aligned}
$$

and this is (ii).
Proof of (iv): Using

$$
\{1+\epsilon a, \lambda\}=\left\{1+\epsilon \frac{a}{m}, \lambda\right\}^{m}
$$

and (6.31) we are reduced to showing

$$
\begin{equation*}
\{1+\epsilon a, p\} \text { is torsion for } p \text { a prime. } \tag{6.36}
\end{equation*}
$$

Using that $\{\lambda, \mu\}$ is torsion for $\lambda, \mu \in \mathbb{Q}^{*}$ and computing modulo torsion, we have

$$
\begin{aligned}
\{1+\epsilon a, \mu\}^{k} & =\{\lambda, \mu\}^{-k}\{\lambda+\epsilon \lambda a, \mu\}^{k} \\
& =\{\lambda+\epsilon \lambda a, \mu(1-\lambda-\epsilon \lambda a)\}^{k}
\end{aligned}
$$

by the Steinberg relation

$$
=\left\{\lambda+\epsilon \lambda a, \mu^{k}(1-\lambda)^{k}-k \mu^{k-1}(1-\lambda)^{k-1} \epsilon \lambda a\right\} .
$$

Choosing $\lambda=1 /(1-k)$ gives

$$
\begin{aligned}
\{1+\epsilon a, \mu\}^{k} & =\left\{\lambda+\epsilon \lambda a, \mu^{k}(-k)^{k} \lambda^{k}-k \mu^{k-1}(-k)^{k-1} \lambda^{k} \epsilon a\right\} \\
& =\left\{\lambda+\epsilon \lambda a, \mu^{k}(-k)^{k} \lambda^{k}(1+\epsilon a)\right\} \\
& =\left\{\lambda, \mu^{k}(-k)^{k} \lambda^{k}\right\}\{\lambda, 1+\epsilon a\}\left\{1+\epsilon a, \mu^{k}(-k)^{k} \lambda^{k}\right\}\{1+\epsilon a, 1+\epsilon a\}
\end{aligned}
$$

The first term is torsion, and the last one is 1 by the second lemma above. Thus, modulo torsion

$$
\begin{aligned}
\{1+\epsilon a, \mu\}^{k} & =\left\{1+\epsilon a, \mu^{k}\right\}\left\{1+\epsilon a, \lambda^{k-1}\right\}\left\{1+\epsilon k,(-k)^{k}\right\} \\
& =\left\{1+\epsilon a, \mu^{k}\right\}\left\{1+\epsilon a,\left(\frac{1}{k-1}\right)\right\}^{k-1}\{1+\epsilon a, k\}^{k}
\end{aligned}
$$

by our choice of $\lambda$

$$
\Rightarrow\{1+\epsilon a, k\}^{k}=\{1+\epsilon a,(k-1)\}^{k-1}
$$

Now we may proceed inductively taking for $k$ the smallest prime $p$ for which $\{1+\epsilon a, p\}$ is not torsion. Using the prime power factorization of $p-1$ and bilinearity together with the induction assumption we arrive at a contradiction. This proves (6.36), and with it completes the proof of (6.29).

Remark: An important invariant of $K_{2}(F)$ is given by the map

$$
\begin{align*}
& \Lambda^{2} d \log : K_{2}(F) \longrightarrow \Omega_{F / \mathbb{Q}}^{2} \\
& \mathbb{U}  \tag{6.37}\\
&\{a, b\} \longrightarrow \frac{d a}{a} \wedge \frac{d b}{b} .
\end{align*}
$$

Replacing $F$ by $F[\epsilon]$ and noting that

$$
\operatorname{ker}\left\{\Omega_{F[\epsilon] / \mathbb{Q}}^{2} \rightarrow \Omega_{F / \mathbb{Q}}^{2}\right\} \cong d \epsilon \wedge \Omega_{F / \mathbb{Q}}^{1}
$$

we have a commutative diagram


This says that the tangent map factors through the $\Lambda^{2} d \log \operatorname{map}(6.37)$. Taking, e.g. $F=\mathbb{C}$ we have

$$
\Lambda^{2} d \log \{a, b\}=0 \Leftrightarrow a, b \text { are algebraically dependent over } \mathbb{Q} \text {. }
$$

This suggests that information is lost in the tangent map for arithmetic reasons. We will see this expressed more precisely when we discuss null curves in section 10 below.

We observe also that, unlike $T K_{2}(F), T\left(F^{*} \otimes_{\mathbb{Z}} F^{*}\right)$ does not seem to have a particularly nice description. In particular for $a, b$ non-zero

$$
(1+\epsilon a) \otimes(1+\epsilon b) \in \operatorname{ker}\left\{F^{*}[\epsilon] \otimes_{\mathbb{Z}} F^{*}[\epsilon] \rightarrow F^{*} \otimes_{\mathbb{Z}} F^{*}\right\}
$$

appears to be non-zero but in some sense to be of "order $\epsilon^{2}$ ".
We have given the above argument to bring out the following geometric point. Let $X$ be a smooth variety and

$$
X_{1}=X \times_{\mathbb{C}} \operatorname{Spec} \mathbb{C}[\epsilon]
$$

the variety whose points are $X$ and whose local rings are given by

$$
\begin{aligned}
\mathcal{O}_{X_{1}, x} & =\mathcal{O}_{X, x}[\epsilon] \\
& =\left\{f+\epsilon g: f, g \in \mathcal{O}_{X, x} \text { and } \epsilon^{2}=0\right\}
\end{aligned}
$$

Then, by definition the tangent sheaf is

$$
T \mathcal{K}_{2}\left(\mathcal{O}_{X}\right)=\operatorname{ker}\left\{\mathcal{K}_{2}\left(\mathcal{O}_{X_{1}}\right) \rightarrow \mathcal{K}_{2}\left(\mathcal{O}_{X}\right)\right\}
$$

and by the above argument

$$
T \mathcal{K}_{2}\left(\mathcal{O}_{X}\right) \cong \Omega_{X / \mathbb{Q}}^{1}
$$

Now suppose that $X$ is defined over a field $k$ that is finitely generated over $\mathbb{Q}$. The above argument works also for $X(k)$ and gives

$$
T \mathcal{K}_{2}\left(\mathcal{O}_{X(k)}\right) \cong \Omega_{X(k) / \mathbb{Q}}^{1} .
$$

On the other hand, in section 4 above we have given the interpretation (cf. (4.16d))

$$
\Omega_{X(k) / \mathbb{Q}, x}^{1} \cong \Omega_{\mathcal{X}(\mathbb{Q}) / \mathbb{Q},\left(x, s_{0}\right)}^{1}
$$

where $\mathcal{X} \rightarrow S$ is the $k$-spread of $X$. Combining these gives

$$
\begin{equation*}
T \mathcal{K}_{2}\left(\mathcal{O}_{X(k)}\right) \cong \Omega_{\mathcal{X}(\mathbb{Q}) / \mathbb{Q}}^{k}{ }_{k}^{\otimes} \mathcal{O}_{X} \tag{6.38}
\end{equation*}
$$

This will have the implication that
when considering algebraic cycles of higher codimension, the geometry of the spread necessarily enters.

More specifically, "vertical" variations of cycle classes within $X$ are measured by "horizontal" data in the spread of $X$ and the cycle class. In section 10 below we shall explain how this geometric interpretation allows us to in some sense "integrate" Abel's differential equations.

Finally, we want to summarize some of the points from above by discussing how $K_{2}$ and spreads inevitably arise from elementary geometric considerations, even if one is only interested in the geometry of complex varieties.
(a) The Weil reciprocity law, which is the exponentiated version of the residue theorem applied to the meromorphic differential

$$
\log f \frac{d g}{g}
$$

on the cut Riemannian surface, is expressed in terms of the tame symbol mappings

$$
\mathbb{C}(X)^{*} \times \mathbb{C}(X)^{*} \xrightarrow{T_{x}} \mathbb{C}^{*}
$$

The kernel of $T_{x}$ on

$$
\left(\mathbb{C}(X)^{*} / \mathcal{O}_{X, x}^{*}\right) \times\left(\mathbb{C}(X)^{*} / \mathcal{O}_{X, x}^{*}\right)
$$

is generated exactly by the relations that define $\mathbb{C}(X)^{*} \otimes_{\mathbb{Z}} \mathbb{C}(X)^{*}$ together with the Steinberg relation $T_{x}(f \otimes(1-f))=1$. Thus we have

$$
0 \rightarrow \mathcal{K}_{2}\left(\mathcal{O}_{X}\right) \rightarrow \underline{\underline{K}}_{2}(\mathbb{C}(X)) \rightarrow \underset{x \in X}{\oplus} \underline{\underline{\mathbb{C}}}_{x}^{*} \rightarrow 1
$$

and therefore once we consider the Weil reciprocity law $K_{2}$ is in the door;
(b) The above calculation shows that the Kähler differentials $\Omega_{X, x / \mathbb{Q}}^{1}$ arise when we "infinitesimalize" the relations that define $\mathcal{K}_{2}\left(\mathcal{O}_{X, x}[\epsilon]\right)$;
(c) As noted above, $\Omega_{\mathcal{O}_{X, x / \mathrm{C}}}^{1}$ is interpreted as ordinary differential forms on spreads, once we keep track of the the field of definition;
(d) Finally, as is well known and will be discussed further in section 8 below, when localized the very definition of rational equivalence of 0 -cycles on a surface $X$ gives

$$
\underset{\substack{\text { codimim } Y=1 \\ Y \text { irred }}}{\oplus} \mathbb{C}(Y)^{*} \xrightarrow{\text { div }} \underset{x \in X}{\oplus} \oplus_{x}^{\mathbb{Z}} \rightarrow 0
$$

where div is the map $f \rightarrow \operatorname{div}(f)$ for $f \in \mathbb{C}(Y)^{*}$. The 2-dimensional version of (a) is that, locally in the Zariski topology, the kernel of div - i.e., the only way in which cancellations can occur - is in the image of the tame symbol

$$
K_{2}(\underline{\underline{C}}(X)) \rightarrow \underset{Y}{\oplus} \underset{\underline{C}}{ }(Y)^{*}
$$

As in (a) the kernel of this map is $\mathcal{K}_{2}\left(\mathcal{O}_{X}\right)$, so that geometry inevitably leads to $K_{2}$. As in (b) and (c) this in turn inevitably leads to spreads.

## Chapter Seven

## The $\mathcal{E} x t$-definition of $T Z^{2}(X)$ for $X$ an algebraic surface

In Chapter 5 we have given the geometric description

$$
\begin{equation*}
\underline{\underline{T}} Z^{2}(X)=\underset{x \in X}{\oplus} \underline{\underline{\operatorname{Hom}^{o}}}{ }^{( }\left(\Omega_{X / \mathbb{Q}, x}^{2} / \Omega_{\mathbb{C} / \mathbb{Q}}^{2}, \Omega_{\mathbb{C} / \mathbb{Q}}^{1}\right) \tag{7.1}
\end{equation*}
$$

for the tangent space to the space of 0 -cycles on a smooth algebraic surface. ${ }^{1}$ This geometric description was in turn based on representing arcs in $Z^{2}(X)$ in local coordinates by Puiseaux series, taking the absolute differentials of these expressions and then extracting what is invariant when one changes local uniformizing parameters. In invariant terms, one represents an arc in $Z^{2}(X)$ by a diagram

$$
Z \subset X \times B, \quad \operatorname{dim} B=1
$$

and uses a pull-back, push-down construction to define the tangent map as a pairing

$$
T_{s_{0}} B \otimes\left(\Omega_{X / \mathbb{Q}, x}^{2} / \Omega_{\mathbb{C} / \mathbb{Q}}^{2}\right) \rightarrow \Omega_{\mathbb{C} / \mathbb{Q}}^{1} .
$$

In either case we are giving arcs in the space of 0 -cycles parametrically.
The other method to give such arcs is by their equations; i.e., by linear combinations of arcs in $\operatorname{Hilb}^{2}(X)$. This approach leads to what we feel is the proper definition of $T Z^{2}(X)$, one that although somewhat formal gives the better algebraic understanding of the tangent space and ties in more directly to duality theory. In subsection (i) we will then give the formal definition of $\underline{\underline{T}} Z^{2}(X)$ and show that it agrees with the geometric description (7.1). In subsection (ii) we will give the relation of $\underline{\underline{T}} Z^{2}(X)$ to $T \operatorname{Hilb}^{2}(X)$, and in subsection (iii) we will give the direct comparison between the parameter (i.e., Puiseaux series) and equations (i.e., $\mathcal{E} x t^{2}$ ) approaches. Finally, in (iv) we will give some concluding remarks dealing with the desirable - but not yet accomplished - axiomatic approach to $\underline{\underline{T}} Z^{2}(X)$.

### 7.1 THE DEFINITION OF $\underline{\underline{T}} Z^{2}(X)$

Throughout this section, $X$ will be a smooth algebraic surface, $x \in X$ a point and $Z$ a codimension- 2 subscheme of $X$ supported at $x$.

[^11]Definition: The stalk at $x$ of the tangent space to the space of 0-cycles is defined by

$$
\begin{equation*}
\underline{\underline{T}} Z^{2}(X)_{x}=\lim _{\substack{\text { sudim }^{2} \\ \text { subdine } \\ \text { supported at } x}} \operatorname{Ext}_{\mathcal{O}_{X}}^{2}\left(\mathcal{O}_{Z}, \Omega_{X / \mathbb{Q}}^{1}\right) . \tag{7.2}
\end{equation*}
$$

Proposition: We have the isomorphisms

$$
\begin{equation*}
\underline{\underline{T}} Z^{2}(X)_{x} \cong H_{x}^{2}\left(\Omega_{X / \mathbb{Q}}^{1}\right) \cong \operatorname{Hom}^{o}\left(\Omega_{X / \mathbb{Q}, x}^{2} / \Omega_{\mathbb{C} / \mathbb{Q}}^{2}, \Omega_{\mathbb{C} / \mathbb{Q}}^{1}\right) . \tag{7.3}
\end{equation*}
$$

It follows that the geometric description (7.1) and formal definition (7.2) agree as vector spaces. What remains to be done is to define the map

$$
\binom{\text { linear combinations }}{\text { of arcs in } \operatorname{Hilb}^{2}(X)} \rightarrow \underline{\underline{T}}^{2}(X)
$$

where the stalks of $\underline{\underline{T}} Z^{2}(X)$ are given by (7.2) and show that when arcs in $\operatorname{Hilb}^{2}(X)$ are represented by Puiseaux series we obtain the same tangent maps under the identification (7.3). This will be done in the next two subsections.

Before presenting the proof of the proposition, we remark that the limit in the RHS of (7.2) has the following meaning: If we have an inclusion

$$
\mathcal{J}_{Z_{1}} \subset \mathcal{J}_{Z_{2}} \quad\left(\text { in } \mathcal{O}_{X, x}\right)
$$

inducing

$$
\mathcal{O}_{Z_{1}} \rightarrow \mathcal{O}_{Z_{2}},
$$

then there is an induced map

$$
\varepsilon_{x t_{\mathcal{O}_{X}}}^{2}\left(\mathcal{O}_{Z_{2}}, \Omega_{X / \mathbb{Q}}^{1}\right) \rightarrow \varepsilon x t_{\mathcal{O}_{X}}^{2}\left(\mathcal{O}_{Z_{1}}, \Omega_{X / \mathbb{Q}}^{1}\right)
$$

and we use these maps to define the limit. If, as usual, $\mathfrak{m}_{x}$ denotes the maximal ideal in $\mathcal{O}_{X, x}$, then since $Z$ is supported at $x$

$$
\mathfrak{m}_{x}^{k} \subseteq \mathcal{J}_{Z} \quad \text { for } k \gg 0
$$

and consequently

$$
\begin{equation*}
\lim _{\substack{Z \text { codim } \\ \text { sub } \\ \text { supporteded at } x}} \varepsilon x t_{\mathcal{O}_{X}}^{2}\left(\mathcal{O}_{Z}, \Omega_{X / \mathbb{Q}}^{1}\right)=\lim _{k} \mathcal{E x} t_{\mathcal{O}_{X}}^{2}\left(\mathcal{O}_{X} / \mathfrak{m}_{x}^{k}, \Omega_{X / \mathbb{Q}}^{1}\right) . \tag{7.4}
\end{equation*}
$$

Proof of proposition: For any scheme $Z \subset X$ as above, we have by Grothendieck duality (cf. Appendix A to $\S 8(\mathrm{i})$ for a summary of this)

$$
\mathcal{E x t}_{\mathcal{O}_{X}}^{2}\left(\mathcal{O}_{Z}, \Omega_{X / \mathbb{C}}^{2}\right) \cong \operatorname{Hom}\left(\mathcal{O}_{Z}, \mathbb{C}\right) .
$$

From the exact sequence

$$
0 \rightarrow \mathcal{O}_{X} \otimes \Omega_{\mathbb{C} / \mathbb{Q}}^{1} \rightarrow \Omega_{X / \mathbb{Q}}^{1} \rightarrow \Omega_{X / \mathbb{C}}^{1} \rightarrow 0
$$

we then have

$$
\left\{\begin{array}{l}
\varepsilon x t_{\mathcal{O}_{X}}^{2}\left(\mathcal{O}_{Z}, \Omega_{X / \mathbb{C}}^{1}\right) \cong \operatorname{Hom}\left(\Omega_{X / \mathbb{C}}^{1} \otimes \mathcal{O}_{Z}, \mathbb{C}\right) \\
\varepsilon x t_{\mathcal{O}_{X}}^{2}\left(\mathcal{O}_{Z}, \mathcal{O}_{X} \otimes \Omega_{\mathbb{C} / \mathbb{Q}}^{1}\right) \cong \operatorname{Hom}\left(\Omega_{X / \mathbb{C}}^{2} \otimes \mathcal{O}_{Z}, \Omega_{\mathbb{C} / \mathbb{Q}}^{1}\right) .
\end{array}\right.
$$

From Section 5.1 we recall the exact sequence

$$
\begin{aligned}
0 \rightarrow \operatorname{Hom}\left(\Omega_{X / \mathbb{C}}^{2} \otimes \mathcal{O}_{Z}, \Omega_{\mathbb{C} / \mathbb{Q}}^{1}\right) & \rightarrow \operatorname{Hom}^{o}\left(\left(\Omega_{X / \mathbb{Q}}^{2} / \Omega_{\mathbb{C} / \mathbb{Q}}^{2}\right) \otimes \mathcal{O}_{Z}, \Omega_{\mathbb{C} / \mathbb{Q}}^{1}\right) \\
& \rightarrow \operatorname{Hom}\left(\Omega_{X / \mathbb{C}}^{1} \otimes \mathcal{O}_{Z}, \mathbb{C}\right) \rightarrow 0
\end{aligned}
$$

We thus have a diagram

$$
\begin{aligned}
& 0 \rightarrow \operatorname{Hom}\left(\Omega_{X / \mathbb{C}}^{2} \otimes \mathcal{O}_{Z}, \Omega_{\mathbb{C} / \mathbb{Q}}^{1}\right) \rightarrow \operatorname{Hom}^{o}\left(\left(\Omega_{X / \mathbb{Q}}^{2} / \Omega_{\mathbb{C} / \mathbb{Q}}^{2}\right) \otimes \mathcal{O}_{Z}, \Omega_{\mathbb{C} / \mathbb{Q}}^{1}\right) \rightarrow \operatorname{Hom}\left(\Omega_{X / \mathbb{C}}^{1} \otimes \mathcal{O}_{Z}, \mathbb{C}\right) \rightarrow 0 \\
& \imath \| \\
& 0 \rightarrow \varepsilon x t_{\mathcal{O}_{X}}^{2}\left(\mathcal{O}_{Z}, \mathcal{O}_{X} \otimes \Omega_{\mathbb{C} / \mathbb{Q}}^{1}\right) \longrightarrow \varepsilon_{x t}^{2}{ }_{\mathcal{O}_{X}}\left(\mathcal{O}_{Z}, \Omega_{X / \mathbb{Q}}^{1}\right) \longrightarrow \varepsilon_{x t}^{2}{ }_{\mathcal{O}_{X}}\left(\mathcal{O}_{Z}, \Omega_{X / \mathbb{Q}}^{1}\right) \longrightarrow 0 .
\end{aligned}
$$

If we can construct an upward vertical map in the middle compatible with the maps at the ends, then of necessity it is an isomorphism.

If

$$
0 \rightarrow F_{2} \rightarrow F_{1} \rightarrow F_{0} \rightarrow \mathcal{O}_{Z} \rightarrow 0
$$

is a minimal free resolution (locally defined), and

$$
F_{2} \xrightarrow{\phi} \Omega_{X / \mathbb{Q}}^{1}
$$

is an $\mathcal{O}_{X}$-linear map, then we have

$$
\Omega_{X / \mathbb{Q}}^{2} \otimes F_{2} \xrightarrow{\text { id } \otimes \phi} \Omega_{X / \mathbb{Q}}^{2} \otimes \Omega_{X / \mathbb{Q}}^{1} \xrightarrow{\wedge} \Omega_{X / \mathbb{Q}}^{3} \rightarrow \Omega_{X / \mathbb{C}}^{2} \otimes \Omega_{\mathbb{C} / \mathbb{Q}}^{1} .
$$

Thus $\phi$ gives a map

$$
\begin{gathered}
\Omega_{X / \mathbb{Q}}^{2} \rightarrow \operatorname{Hom}_{\mathcal{O}_{X}}\left(F_{2}, \Omega_{X / \mathbb{C}}^{2}\right) \otimes \Omega_{C / \mathbb{Q}}^{1} \\
\downarrow \\
\mathcal{E x t}_{\mathcal{O}_{X}}^{2}\left(\mathcal{O}_{Z}, \Omega_{X / \mathbb{C}}^{2}\right) \otimes \Omega_{\mathbb{C} / \mathbb{Q}}^{1}
\end{gathered}
$$

There is a natural trace map

$$
\mathcal{E x} t_{\mathcal{O}_{X}}^{2}\left(\mathcal{O}_{Z}, \Omega_{X / \mathbb{C}}^{2}\right) \rightarrow \operatorname{Hom}\left(\mathcal{O}_{Z}, \mathbb{C}\right) \rightarrow \mathbb{C}
$$

where the right arrow is given by "evaluation on 1 ", and consequently $\phi$ gives a map

$$
\Omega_{X / \mathbb{Q}}^{2} \longrightarrow \mathbb{C}
$$

One checks easily that this annihilates $\Omega_{\mathbb{C} / \mathbb{Q}}^{2}$, does not depend on the choice of represntative $\phi$ of the original class in $\mathcal{E x} t_{\mathcal{O}_{X}}^{2}\left(\mathcal{O}_{Z}, \Omega_{X / \mathbb{Q}}^{1}\right)$, and is compatible with the maps on the ends of the above diagram.

We conclude this section with some considerations that lead to the following conclusion:

If one assumes (i) some "evident" continuity properties, and (ii) that the construction of the tangent map to cycles is "of an algebraic character" (cf. below for explanation), then the Ext-definition (7.2) is uniquely determined.

To begin with we pose the question:
If we have a family

$$
z(t)=p_{1}(t)+\cdots+p_{N}(t)
$$

where $p_{1}(t), \ldots, p_{N}(t)$ are distinct for $0<|t|<\epsilon$, then one might ask:
How do we fill in over $t=0$ the family of vector spaces

$$
\left.\stackrel{N}{\oplus} \underset{i=1}{N} \Theta_{X / \mathbb{C}}\right|_{p_{i}(t)}=\oplus T_{p_{i}(t)} X
$$

so as to get a vector bundle over the parameter space in $t$ ?
If we note that for $0<|t|<\epsilon$,

$$
\left.\mathcal{E x t}_{\mathcal{O}_{X}}^{2}\left(\mathcal{O}_{z(t)}, \Omega_{X / \mathbb{C}}^{1}\right) \cong \stackrel{N}{i=1} \Theta_{X / \mathbb{C}}\right|_{p_{i}(t)}
$$

then we can answer the above question by filling in

$$
\mathcal{E} x t_{\mathcal{O}_{X}}^{2}\left(\mathcal{O}_{z(0)}, \Omega_{X / \mathbb{C}}^{1}\right) .
$$

Since the $1^{\text {st }}$ order derivative $z^{\prime}(t)$ for $0<|t|<\epsilon$ is certainly

$$
\left.\underset{i=1}{\stackrel{N}{\oplus}} p_{i}^{\prime}(t) \in \underset{i=1}{\stackrel{N}{\oplus}} \Theta_{X / \mathbb{C}}\right|_{p_{i}(t)},
$$

it is a matter of taking the correct limit of the left-hand side as $t \rightarrow 0$ to get an element of

$$
\mathcal{E} x t_{\mathcal{O}_{X}}^{2}\left(\mathcal{O}_{z(0)}, \Omega_{X / \mathbb{C}}^{1}\right) .
$$

This limit appears either in the Puiseaux construction or in the more algebraic construction of this section.

If, however, we take account of the fact that our variety $X$ and family of cycles $z(t)$ are defined over a finitely generated field of definition $k$, then any geometrically meaningful construction should also spread out over $k$, and we thus should consider the spread $\mathcal{Z}(t)$, a cycle on the spread $X \rightarrow S$ of $X$ over $k$. Now the first-order information lies in

$$
\mathcal{E x} t_{\mathcal{O}_{x}}^{2}\left(\mathcal{O}_{\mathcal{Z}(0)}, \Omega_{X / \mathbb{C}}^{1}\right)
$$

and this corresponds to

$$
\mathcal{E x} t_{\mathcal{O}_{X}}^{2}\left(\mathcal{O}_{z(0)}, \Omega_{X / \mathbb{Q}}^{1}\right)
$$

under the identification discussed previously.
This gives what we feel is a reasonably compelling explanation of why the formula for $\underline{\underline{T}} Z^{2}(X)$ takes the form that it does.
7.2 THE MAP $T \operatorname{Hilb}^{2}(X) \rightarrow T Z^{2}(X)$

In Chapter 5 we have used the differentials of Puiseaux series, expressed in terms of a set of local uniformizing parameters, to construct for each point $x \in X$ a map

$$
\begin{aligned}
\left\{\begin{aligned}
\operatorname{arcs} \text { in } Z^{2}(X) \\
\text { starting at } x
\end{aligned}\right\} \rightarrow & \operatorname{Hom}^{o}\left(\Omega_{X / \mathbb{Q}, x}^{2} / \Omega_{\mathbb{C} / \mathbb{Q}}^{2}, \Omega_{\mathbb{C} / \mathbb{Q}}^{1}\right) \\
& \lim _{k \rightarrow \infty} \varepsilon x t_{\mathcal{O}_{X}}^{2}\left(\mathcal{O}_{X} / \mathfrak{m}_{x}^{k}, \Omega_{X / \mathbb{Q}}^{1}\right) .
\end{aligned}
$$

This was essentially a geometric construction, one which does not tell us how to go from a set of generators for the ideal defining the 0-cycle $z(t)$ to an element of $\varepsilon x t^{2}$. However, as will now be explained, based on a very nice construction of Angeniol and Lejeune-Jalabert [19] there is a direct way of doing this. Then in the next section we shall show that this construction agrees with the Puiseaux series method when the identification (7.3) is made.
We think of a family $z(t)$ of 0 -dimensional subschemes as given by a subscheme

$$
Z \subset X \times B
$$

where $B$ is the parameter curve. We assume that $z(t)$ is supported in a neighborhood of $x \in X$ and that we have a family of free resolutions

$$
\begin{equation*}
0 \rightarrow F_{2} \xrightarrow{f_{2}(t)} F_{1} \xrightarrow{f_{1}(t)} F_{0} \rightarrow \mathcal{O}_{z(t)} \rightarrow 0 \tag{7.5}
\end{equation*}
$$

where if one wishes we may think of each $F_{i}$ as a direct sum of $\mathcal{O}_{X}$ 's and $f_{i}(t)$ as a matrix with entries in $\mathcal{O}_{X \times B}$. By the composition

$$
d f_{1}(t) \circ d f_{2}(t): F_{2} \rightarrow \Omega_{X \times B / \mathbb{Q}}^{2}
$$

we mean "compose the matrices of absolute differentials using exterior product". Assuming that the support of $z(0)$ is $x$ and letting $F_{i, x}$ be the stalk at $x$ of $F_{i}$, we have the
Definition: We define

$$
\begin{equation*}
z^{\prime}(0) \in \operatorname{Hom}_{\mathcal{O}_{X, x}}\left(F_{2, x}, \Omega_{X / \mathbb{Q}, x}^{1}\right) \tag{7.6}
\end{equation*}
$$

to be

$$
\left.z^{\prime}(0)=\frac{1}{2}\left(d f_{1}(t) \circ d f_{2}(t)\right)\right\rfloor\left.\frac{\partial}{\partial t}\right|_{t=0} .
$$

We will now show that this definition makes sense in

$$
\varepsilon_{x x}{\mathcal{O}_{X}}_{2}\left(\mathcal{O}_{Z}, \Omega_{X / \mathbb{Q}}^{1}\right) .
$$

First, if we write

$$
f_{1}(t)=f_{1}+t \dot{f}_{1}, \quad f_{2}=f_{2}+t \dot{f}_{2} \quad \bmod t^{2}
$$

then

$$
z^{\prime}(0)=\frac{1}{2}\left(d f_{1} \circ \dot{f}_{2}-\dot{f}_{1} \circ d f_{2}\right)
$$

so that $z^{\prime}(0)$ depends only on the $1^{\text {st }}$ order deformation of $z(0)$.
However, $z^{\prime}(0)$ does depend on the resolution (7.5). If we change resolutions according to a diagram

where $F_{0}=G_{0}=\mathcal{O}_{X}$, then denoting by $g_{i}(t)$ the maps on the bottom and using that the $u_{i}(t)$ are invertible we have

$$
\begin{aligned}
& d g_{1}(t) \circ d g_{2}(t)= d\left(f_{1}(t) \circ u_{1}(t)^{-1}\right) \circ\left(d u_{1}(t) \circ f_{2}(t) \circ u_{2}(t)^{-1}\right) \\
&=\left(d f_{1}(t) \circ u_{1}(t)^{-1}-f_{1}(t) \circ u_{1}(t)^{-1} \circ d u_{1}(t) \circ u_{1}(t)^{-1}\right) \\
& \circ\left(d u_{1}(t) \circ f_{2}(t) \circ u_{2}(t)^{-1}+u_{1}(t) \circ d f_{2}(t) \circ u_{2}(t)^{-1}\right. \\
&\left.\quad-u_{1}(t) \circ f_{2}(t) \circ u_{2}(t)^{-1} \circ d u_{2}(t) \circ u_{2}(t)^{-1}\right) .
\end{aligned}
$$

By passing to $\mathcal{E} x t^{2}$, these ambiguities will drop out. Indeed, it is a general fact that

$$
\mathcal{J}_{Z} \text { annihilates } \mathcal{E} x t_{\mathcal{O}_{X}}^{2}\left(\mathcal{O}_{Z}, \mathcal{F}\right)
$$

for any coherent sheaf of $\mathcal{O}_{X}$-modules $\mathcal{F}$, and applying this for $z(t)$, the

$$
f_{1}(t) \circ u_{1}(t)^{-1} \circ d u_{1}(t) \circ u_{1}(t)^{-1}
$$

term drops out. The

$$
d u_{1}(t) \circ f_{2}(t) \circ u_{2}(t)^{-1}
$$

term drops out by the definition of $\mathcal{E} x t^{2}$. So in $\mathcal{E} x t_{\mathcal{O}_{X}}^{2}\left(\mathcal{O}_{Z}, \Omega_{X \times B / \mathbb{Q}}^{1}\right)$ we are left with

$$
\begin{aligned}
d g_{1}(t) \circ d g_{2}(t)= & d f_{1}(t) \circ d f_{2}(t) \circ u_{2}(t)^{-1} \\
& -d f_{1}(t) \circ f_{2}(t) \circ u_{2}(t)^{-1} \circ d u_{2}(t) \circ u_{2}(t)^{-1} .
\end{aligned}
$$

The last term on the right drops out because, since from

$$
f_{1}(t) \circ f_{2}(t)=0
$$

we have

$$
f_{1}(t) \circ d f_{2}(t)=-d f_{1}(t) \circ f_{2}(t)
$$

Consequently the problem term becomes

$$
f_{1}(t) \circ d f_{2}(t) \circ u_{2}(t)^{-1} \circ d u_{2}(t) \circ u_{2}(t)^{-1}
$$

which drops out because $\mathcal{J}_{z(t)}$ annihilates the $\mathcal{E} x t$ group. Thus in $\mathcal{E} x t^{2}$

$$
d g_{1}(t) \circ d g_{2}(t)=d f_{1}(t) \circ d f_{2}(t) \circ u_{2}(t)^{-1}
$$

and we understand the definition (7.6) to be

$$
\begin{equation*}
\left.z^{\prime}(0)=\frac{1}{2}\left(d f_{1}(t) \circ d f_{2}(t)\right)\right\rfloor\left.\frac{\partial}{\partial t}\right|_{t=0} \in \mathcal{E} x t_{\mathcal{O}_{X}}^{2}\left(\mathcal{O}_{Z}, \Omega_{X / \mathbb{Q}}^{1}\right) \tag{7.7}
\end{equation*}
$$

where $Z=z(0)$.
We may view this construction as giving a map

$$
T \operatorname{Hilb}^{2}(X) \rightarrow \underline{\underline{T}} Z^{2}(X)
$$

Example: $z(t)=(a t, b t), \quad a, b \in \mathbb{C}$.
The resolution is just

$$
0 \rightarrow \mathcal{O}_{X} \xrightarrow{\begin{array}{c}
\binom{y-b t}{-(x-a t)}
\end{array} \mathcal{O}_{X}^{2} \xrightarrow{(x-a t, y-b t)} \mathcal{O}_{X} \rightarrow \mathcal{O}_{z(t)} \rightarrow 0}
$$

and

$$
\begin{aligned}
\frac{1}{2} d f_{1}(t) \circ d f_{2}(t) & =\frac{1}{2}(d x-a d t-t d a \quad d y-b d t-t d b) \circ\binom{d y-b d t-t d b}{-d x+a d t+t d a} \\
& =d x-d y+(a d y-b d x) \wedge d t \quad \bmod t
\end{aligned}
$$

So

$$
z^{\prime}(0)=a d y-b d x
$$

Here, upon choosing this resolution we have an isomorphism

$$
\mathcal{E x t}{\underset{\mathcal{O}_{X}}{2}\left(\mathcal{O}_{Z}, \Omega_{X / \mathbb{Q}}^{1}\right) \cong \Theta_{X / \mathbb{Q}} \otimes_{\mathcal{O}_{X}} \mathcal{O}_{Z} .}
$$

and $z^{\prime}(0)$ is the element corresponding to a lifting of the tangent vector $(a, b)$.
Example: $I_{z(t)}=\left(x^{2}, y+t x\right)$. Note that as a scheme $z(t)$ is varying, but as a cycle it is $2 \cdot(0,0)$ for all $t$. We thus expect to find $z^{\prime}(0)=0$.

The resolution is

$$
0 \rightarrow \mathcal{O}_{X} \xrightarrow{\binom{y+t x}{-x^{2}}} \mathcal{O}_{X}^{2} \xrightarrow{\left(x^{2} y+t x\right)} \mathcal{O}_{X} \rightarrow \mathcal{O}_{z(t)} \rightarrow 0
$$

and

$$
\begin{aligned}
\frac{1}{2} d f_{1}(t) \circ d f_{2}(t) & =2 x d x \wedge(d y+t d x+x d t) \\
& =2 x d x \wedge d y+2 x^{2} d x \wedge d t
\end{aligned}
$$

So,

$$
z^{\prime}(0)=x^{2} d x
$$

However, using this resolution,

$$
\mathcal{E x t}{ }_{\mathcal{O}_{X}}^{2}\left(\mathcal{O}_{Z}, \Omega_{X / \mathbb{Q}}^{1}\right)=\left(\mathcal{O}_{X} /(x, y)\right) \otimes \Omega_{X / \mathbb{Q}}^{1}
$$

and consequently

$$
x^{2} d x=0
$$

which gives

$$
z^{\prime}(0)=0
$$

as expected.
We are now ready for a more subtle example that illustrates one of the most novel elements of the construction, namely the use of differentials over $\mathbb{Q}$.

Example: $I_{z_{\alpha}(t)}=\left(x^{2}-\alpha y^{2}, x y-t\right), \quad \alpha \in \mathbb{C}^{*}$.
This example was discussed at length in section $6(\mathrm{i})$, and we want to recover its properties using $z^{\prime}(0)$. The resolution is

$$
0 \rightarrow \mathcal{O}_{X} \xrightarrow{\binom{x^{2}-\alpha 2^{2}}{-x y+t}} \mathcal{O}_{X} \xrightarrow{\left(x y-t, x^{2}-\alpha y^{2}\right)} \mathcal{O}_{X} \rightarrow \mathcal{O}_{z_{\alpha}(t)} \rightarrow 0
$$

and a computation as above gives

$$
z_{\alpha}^{\prime}(0)=2 x d x-2 \alpha y d y-y^{2} d \alpha
$$

In order to compare $z_{\alpha}^{\prime}(0)$ for different $\alpha$ 's, we go to the group

$$
\lim _{\substack{Z \text { supported } \\ \text { at }(0,0)}} \mathcal{E x} t_{\mathcal{O}_{X}}^{2}\left(\mathcal{O}_{Z}, \Omega_{X / \mathbb{Q}}^{1}\right) .
$$

We note that if $\mathfrak{m}$ is the maximal ideal at $(0,0)$, then

$$
I_{z_{\alpha}(0)} \supseteq \mathfrak{m}^{3} \quad \text { for all } \alpha
$$

We can thus lift $z_{\alpha}^{\prime}(0)$ to

$$
\mathcal{E x} t_{\mathcal{O}_{X}}^{2}\left(\mathcal{O}_{X} / \mathfrak{m}^{3}, \Omega_{X / \mathbb{Q}}^{1}\right)
$$

and then compare them for different $\alpha$ 's. We have the commutative diagram

$$
\begin{aligned}
& 0 \rightarrow \mathcal{O}_{X} \xrightarrow{\left(\begin{array}{ll}
\left.\alpha^{x}-x^{2}\right)
\end{array}\right.} \mathcal{O}_{X}^{2} \xrightarrow{\left(x^{2}-\alpha y^{2}-x y\right)} \mathcal{O}_{X} \rightarrow \mathcal{O}_{z_{\alpha}(0)} \rightarrow 0 \\
& \uparrow(11 / \alpha) \\
& \uparrow\left(\begin{array}{cccc}
x & 0 & 0 & -y / \alpha \\
\alpha y & x & y & x / \alpha
\end{array}\right) \| \\
& 0 \rightarrow\left.\mathcal{O}_{X}^{3} \xrightarrow{\left(\begin{array}{ccc}
y & 0 & 0 \\
-x & y & 0 \\
0 & -x & y \\
0 & 0 & -x
\end{array}\right)} \mathcal{O}_{X}^{4} \xrightarrow{\left(x^{3} x^{2} y\right.} x y^{2} y^{3}\right) \\
& \mathcal{O}_{X} \rightarrow \mathcal{O}_{X} / \mathfrak{m}^{3} \rightarrow 0
\end{aligned}
$$

So $z_{\alpha}^{\prime}(0)$ pulls back to

$$
\left(2 x d x-2 \alpha y d y-y^{2} d \alpha \quad 0 \quad \frac{2 x}{\alpha} d x-2 y d y-y^{2} \frac{d \alpha}{\alpha}\right)
$$

In

$$
\mathcal{E x} t_{\mathcal{O}_{X}}^{2}\left(\mathcal{O}_{X} / \mathfrak{m}^{3}, \Omega_{X / \mathbb{Q}}^{1}\right)
$$

we have the relations

$$
\left(\begin{array}{lll}
y & 0 & 0
\end{array}\right),(-x y 0),(0-x y),(00-x)
$$

Then $z_{\alpha}^{\prime}(0)$ is equivalent to

$$
\left(2 x d x \quad 0 \quad-2 y d y-y^{2} \frac{d \alpha}{\alpha}\right)
$$

Thus

$$
z_{\alpha}^{\prime}(0)-z_{1}^{\prime}(0)=\left(\begin{array}{lll}
0 & 0 & -y^{2} \frac{d \alpha}{\alpha}
\end{array}\right)
$$

Since

$$
\left(0,0, y^{2}\right) \neq 0 \text { in } \mathcal{E} x t_{\mathcal{O}_{X}}^{2}\left(\mathcal{O}_{X} / \mathfrak{m}^{3}, \mathcal{O}_{X}\right)
$$

we see that

$$
\begin{aligned}
z_{\alpha}^{\prime}(0)-z_{1}^{\prime}(0)=0 & \Leftrightarrow \frac{d \alpha}{\alpha}=0 \\
& \Leftrightarrow \alpha \text { is algebraic. }
\end{aligned}
$$

This is an exact fit for the discussion in section 6(i).
Remark: The construction given above makes sense in other dimensions and codimensions. For codimension $n=\operatorname{dim} X$, it goes through exactly, but for codimension $<n$ and $Z$ not locally Cohen-Macaulay, the resolution may have the wrong number of steps and the construction requires modification.

### 7.3 RELATION OF THE PUISEAUX AND ALGEBRAIC APPROACHES

In geometry a submanifold - or more generally a subvariety - may either be given "parametrically" by a map $f: M \rightarrow N$ or by the equations that define $f(M) \subset N$. The Puiseaux series and $\mathcal{E} x t^{2}$ approaches to $T Z^{2}(X)$ reflect these two perspectives. Each has its virtues and drawbacks. An obvious next issue for this study is to show that they coincide. Before doing this we mention that on the one hand the Puiseaux approach has the following desirable features:

- It is clearly additive
- It depends only on $z(t)$ as a cycle
- It depends on $z(t)$ only up to $1^{\text {st }}$ order in $t$
- It has clear geometric meaning

It has the undesirable feature:

- Two families of effective cycles might represent the same element of $T \operatorname{Hilb}^{2}(X)$ but not give the same tangent under the Puiseaux approach.
On the other hand the algebraic approach has the following desirable features:
- It clearly depends only on the element of $T \operatorname{Hilb}^{2}(X)$ determined by $z(t)$;
- It is easy to compute in examples,
while it has the undesirable features:
- Additivity does not make sense for arbitrary schemes.
- It is not clear that $z^{\prime}(0)$ depends only on the underlying cycle structure of $z(t)$.

In order to have the best of both approaches as well as, of course, for the development of the theory we need to know that the two maps coincide; i.e., that the diagram

commutes where the right hand vertical isomorphism is (7.2).
Proof that (7.8) commutes: The strategy is
Step 1: Verify equality in the case of a single moving point.
Step 2: Verify equality when $z(t)$ consists of distinct points.
Step 3: Pass from distinct points to arbitrary 0-dimensional schemes by taking limits.

We shall give the calculations in local coordinates $x, y$, which may be thought of as representatives of local uniformizing parameters in the completion of the local ring of the algebraic surface $X$ at a closed point.

Proof of Step 1: Let

$$
z(t)=\left(x_{0}+a t, y_{0}+b t\right)
$$

The Puiseaux expansion method has:

$$
d x \wedge d y=\left(d x_{0}+a d t+t d a\right) \wedge\left(d y_{0}+b d t+t d b\right)
$$

which, at $t=0$, has $d t$ coefficient $b d x_{0}-a d y_{0}$, so that

$$
d x \wedge d y \mapsto b d x_{0}-a d y_{0}
$$

Similarly

$$
\begin{aligned}
\left(x-x_{0}\right)^{i}\left(y-y_{0}\right)^{j} d x \wedge d y \mapsto 0 & \text { if } i>0 \text { or } j>0 \\
d x \wedge d \alpha \mapsto-a d \alpha & \text { all } \alpha \in \mathbb{C} \\
d y \wedge d \alpha \mapsto-b d \alpha & \text { all } \alpha \in \mathbb{C} \\
\left(x-x_{0}\right)^{i}\left(y-y_{0}\right)^{j} d x \wedge d \alpha \mapsto 0 & \text { if } i>0 \text { or } j>0 \\
\left(x-x_{0}\right)^{i}\left(y-y_{0}\right)^{j} d y \wedge d \alpha \mapsto 0 & \text { if } i>0 \text { or } j>0
\end{aligned}
$$

The algebraic construction gives

$$
0 \rightarrow \mathcal{O}_{X} \xrightarrow{\binom{y-y_{0}-b t}{-\left(x-x_{0}-a t\right)}} \mathcal{O}_{X}^{2} \xrightarrow{\left(x-x_{0}-a t \quad y-y_{0}-b t\right)} \mathcal{O}_{X} \rightarrow \mathcal{O}_{z(t)} \rightarrow 0
$$

and

$$
\frac{1}{2} d f_{1} \circ d f_{2}=\left(d x-d x_{0}-a d t-t d a\right) \wedge\left(d y-d y_{0}-b d t-t d b\right)
$$

THE $\varepsilon x t$-DEFINITION OF $T Z^{2}(X)$ FOR $X$ AN ALGEBRAIC SURFACE
consequently

$$
z^{\prime}(0)=-b\left(d x-d x_{0}\right)+a\left(d y-d y_{0}\right)
$$

The trace map

$$
\mathcal{E} x t_{\mathcal{O}_{X}}^{2}\left(\mathcal{O}_{Z}, \Omega_{X / \mathbb{C}}^{2}\right) \xrightarrow{\operatorname{Tr}} \mathbb{C}
$$

for this resolution is

$$
d x \wedge d y \mapsto 1
$$

To identify $z^{\prime}(0)$ with an element of

$$
\operatorname{Hom}^{o}\left(\left(\Omega_{X / \mathbb{Q}}^{2} / \Omega_{\mathbb{C} / \mathbb{Q}}^{2}\right) \otimes \mathcal{O}_{Z}, \Omega_{\mathbb{C} / \mathbb{Q}}^{1}\right)
$$

the prescription is that we send

$$
\left.\omega \mapsto\left(z^{\prime}(0) \wedge \omega\right)\right\rfloor \partial / \partial x \wedge \partial / \partial y \in \Omega_{\mathbb{C} / \mathbb{Q}}^{1}
$$

It follows that

$$
\begin{aligned}
d x \wedge d y \mapsto & \left.\left(\left(-b\left(d x-d x_{0}\right)+a\left(d y-d y_{0}\right)\right) \wedge d x \wedge d y\right)\right\rfloor \partial / \partial x \wedge \partial / \partial y \\
& =b d x_{0}-a d y_{0} \\
d x \wedge d \alpha \mapsto & \left.\left(\left(-b\left(d x-d x_{0}\right)+a\left(d y-d y_{0}\right)\right) \wedge d x \wedge d \alpha\right)\right\rfloor \partial / \partial x \wedge \partial / \partial y \\
& =-a d \alpha \\
d y \wedge d \alpha \mapsto & \left.\left(\left(-b\left(d x-d x_{0}\right)+a\left(d y-d y_{0}\right)\right) \wedge d y \wedge d \alpha\right)\right\rfloor \partial / \partial x \wedge \partial / \partial y \\
& =-b d \alpha
\end{aligned}
$$

All forms with an $x^{i} y^{j}, i>0$ or $j>0$, go to zero. So the two constructions agree in this case.

## Proof of Step 2:

Lemma: If we use a local free resolution of the form

$$
0 \rightarrow F_{2} \xrightarrow{f_{2}(t)} F_{1} \xrightarrow{f_{1}(t)} F_{0} \rightarrow \mathcal{O}_{z(t)} \rightarrow 0
$$

even if it is a non-minimal resolution, it gives the correct answer for the algebraic construction.
Proof of Lemma: If

$$
0 \rightarrow F_{2} \xrightarrow{f_{2}} F_{1} \xrightarrow{f_{1}} F_{0} \rightarrow \mathcal{O}_{Z} \rightarrow 0
$$

is a minimal local free resolution and

$$
0 \rightarrow F_{2} \oplus A \xrightarrow{\left(\begin{array}{cc}
f_{2} & 0 \\
0 & u_{2} \\
0 & 0
\end{array}\right)} F_{1} \oplus A \oplus B \xrightarrow{\left(\begin{array}{ccc}
f_{1} & 0 & 0 \\
0 & 0 & u_{1}
\end{array}\right)} F_{0} \oplus B \rightarrow \mathcal{O}_{Z} \rightarrow 0
$$

where $u_{1}, u_{2}$ have constant entries on $X$ (but possibly varying in $t$ ), then

$$
\begin{aligned}
& d\left(\begin{array}{ccc}
f_{1} & 0 & 0 \\
0 & 0 & u_{1}
\end{array}\right) \circ\left(\begin{array}{cc}
\dot{f}_{2} & 0 \\
0 & \dot{u}_{2} \\
0 & 0
\end{array}\right)-\left(\begin{array}{ccc}
\dot{f}_{1} & 0 & 0 \\
0 & 0 & \dot{u}_{1}
\end{array}\right) \circ d\left(\begin{array}{cc}
f_{2} & 0 \\
0 & u_{2} \\
0 & 0
\end{array}\right) \\
&=\left(\begin{array}{cc}
d f_{1} \circ \dot{f}_{2}-\dot{f}_{1} \circ d f_{2} & 0 \\
0 & 0
\end{array}\right)
\end{aligned}
$$

This proves the lemma.

If

$$
z(t)=p_{1}(t)+\cdots+p_{N}(t)
$$

with $p_{1}, \cdots p_{N}$ distinct, then

$$
\mathcal{E} x t_{\mathcal{O}_{X}}^{2}\left(\mathcal{O}_{z(t)}, \Omega_{X / \mathbb{Q}}^{1}\right) \cong \stackrel{N}{\oplus} \underset{p=1}{ } \mathcal{E} x t_{\mathcal{O}_{X}}^{2}\left(\mathcal{O}_{p_{i}(t)}, \Omega_{X / \mathbb{Q}}^{1}\right) .
$$

Since the sheaves on the right are supported at distinct points, there are canonical maps going both ways in this identification. Whatever local minimal free resolution is used for $\mathcal{O}_{z(t)}$, on a suitable neighborhood of $p_{i}(t)$ it becomes a (non-minimal) local free resolution of $\mathcal{O}_{p_{i}(t)}$. By the lemma, the algebraic construction still gives the correct answer.

Additivity is now automatic, since pulling back from each

$$
\mathcal{E} x t_{\mathcal{O}_{X}}^{2}\left(\mathcal{O}_{p_{i}(t)}, \Omega_{X / \mathbb{Q}}^{1}\right)
$$

to

$$
\mathcal{E} x t_{\mathcal{O}_{X}}^{2}\left(\mathcal{O}_{Z}, \Omega_{X / \mathbb{Q}}^{1}\right)
$$

and summing then commutes with summing in

$$
\stackrel{N}{\oplus} \underset{i=1}{N} \mathcal{E} x t_{\mathcal{O}_{X}}^{2}\left(\mathcal{O}_{p_{i}(t)}, \Omega_{X / \mathbb{Q}}^{1}\right)
$$

followed by the canonical map to $\mathcal{E x} t_{\mathcal{O}_{X}}^{2}\left(\mathcal{O}_{Z}, \Omega_{X / \mathbb{Q}}^{1}\right)$. This completes the proof of this step.
Proof of Step 3: We can make any family of 0-dimensional subschemes $z(t)$ part of a 2-parameter family $z(t, u)$ where

$$
z(t)=z(t, 0) \quad \text { for all } t
$$

and for some $\epsilon>0$,

$$
z(t, u) \text { consists of distinct points for } 0<|u|<\epsilon
$$

By flatness considerations, the dimensions of $F_{2}, F_{1}$ and $\varepsilon x t_{\mathcal{O}_{X}}^{2}\left(\mathcal{O}_{z(t, u)}, \mathcal{O}_{X}\right)$ are constant at $t, u$. If

$$
z_{u}(t)=z(t, u)
$$

then

$$
\lim _{u \rightarrow 0} z_{u}^{\prime}(0)=z^{\prime}(0)
$$

Also, for a fixed $\omega \in \Omega_{X / \mathbb{Q}}^{2}$, for the Puiseaux construction it is clear that

$$
\lim _{u \rightarrow 0}\left\langle\omega, z_{u}(t)\right\rangle=\langle\omega, z(t)\rangle
$$

We thus pass from equality of the two constructions for a family with distinct points to an arbitrary family.

To complete the argument we need to provide some clarification about taking limits in $\Omega_{X / \mathbb{Q}}^{1}$. In the above we want to have

$$
\lim _{u \rightarrow 0} d \alpha(u)=d \alpha(0)
$$

while avoiding the problem that in general for a sequence $\alpha_{i} \in \mathbb{C}$

$$
\lim _{i \rightarrow 0} d \alpha_{i} \neq d\left(\lim _{i \rightarrow 0} \alpha_{i}\right)
$$

The correct formalism here is to use spreads, as in section 4(ii). We let $k \subseteq \mathbb{C}$ be a finitely generated field over $\mathbb{Q}$ over which $x$ and $z(t)$ are defined, $S$ a smooth variety defined over $\mathbb{Q}$ and with $\mathbb{Q}(S) \cong k$, and $s_{0} \in S$ the point corresponding to the given embedding of $k$ in $\mathbb{C}$. Let
$x$
$\downarrow$
$S$
be the spread of $X$ over $S$. We may now use $\Omega_{X / \mathbb{C}}^{1}$ rather than $\Omega_{X / \mathbb{Q}}^{1}$ and take limits there in the usual sense.
Remark: We have remarked that there is no natural way to assign a scheme structure to a 0 -cycle. If, however, we have a family $z(t)$ of 0 -dimensional subschemes giving rise to family of cycles, then the assertion that the tangent map to cycles factors

$$
T \operatorname{Hilb}^{2}(X) \rightarrow T Z^{2}(X)
$$

asserts that $\mathcal{J}_{z(0)}$ together with

$$
\left.\dot{\mathcal{J}}_{z(0)} \stackrel{\operatorname{defn}}{=} \frac{d \mathcal{J}_{z(t)}}{d t}\right|_{t=0}: \mathcal{J}_{z(0)} \rightarrow \mathcal{O}_{X, z(0)}
$$

determine the tangent vector $z^{\prime}(0)$ to the space of cycles arising from $z(t)$ considered as an arc in $Z^{2}(X)$. In particular, $\mathcal{J}_{z(0)}$ and $\dot{\mathcal{J}}_{z(0)}$ determine how $z^{\prime}(0)$ acts on the 1 -forms $\Omega_{X / \mathbb{C}, x}^{1}$ and 2-forms $\Omega_{X / \mathbb{C}, x}^{2}$. At first this seemed surprising to us since it means that somehow some absolute differentials are determined by the geometric quantities $\mathcal{J}_{z(0)}$ and $\dot{J}_{z(0)}$.

For example, the family of cycles given by Puiseaux series

$$
z(t)=\left(a_{1} t^{1 / 2}+a_{2} t, b_{1} t^{1 / 2}+b_{2} t\right)+\left(-a_{1} t^{1 / 2}+a_{2} t,-b_{1} t^{1 / 2}+b_{2} t\right)
$$

lifts to the family of schemes

$$
z(t)=\operatorname{Var}\left(b_{1} x-a_{1} y+\left(a_{1} b_{2}-a_{2} b_{1}\right) t, x^{2}-2 a_{2} x t+a_{1}^{2} t\right) \bmod t^{3 / 2}
$$

Note that

$$
\mathcal{J}_{z(0)}=\left(b_{1} x-a_{1} y, x^{2}\right)
$$

determines

$$
a_{1} / b_{1}
$$

and $z^{\prime}(0)$ is the map

$$
\begin{aligned}
b_{1} x-a_{2} y & \mapsto a_{1} b_{2}-a_{2} b_{1} \\
x^{2} & \mapsto-2 a_{2} x+a_{1}^{2} .
\end{aligned}
$$

From this information, we can recover $\left(a_{1}^{2}, a_{1} b_{1}, b_{1}^{2}, a_{2}, b_{2}\right)$ and hence the original Puiseaux series - so, a fortiori, the information obtained by the action on differential forms.

Of course, for a sum of Puiseaux series of this type, one gets a much more complicated relationship between $\mathcal{J}_{z(0)}, \dot{J}_{z(0)}$ and the coefficients of the various Puiseaux series. What the factorization result asserts is that this information is always enough to allow us to recover the action of differential forms on the underlying sum of Puiseaux series. For example, for

$$
z(t)=\sum_{\nu=1}^{N}\left(\left(a_{1}^{\nu} t^{1 / 2}+a_{2}^{\nu} t, b_{1}^{\nu} t^{1 / 2}+b_{2}^{\nu} t\right)+\left(-a_{1}^{\nu} t^{1 / 2}+a_{2}^{\nu} t,-b_{1}^{\nu} t^{1 / 2}+b_{2}^{\nu}(t)\right)\right.
$$

then the action of $d x \wedge d y$ is

$$
z^{\prime}(0)(d x \wedge d y)=\sum_{\nu=1}^{N}\left(a_{1}^{\nu} d b_{1}^{\nu}-b_{1}^{\nu} d a_{1}^{\nu}\right) \in \Omega_{\mathbb{C} / \mathbb{Q}}^{1}
$$

The theorem asserts that one can recover this from knowing $\mathcal{J}_{z(0)}, \dot{J}_{z(0)}$, but because the formula for the ideal $\mathcal{J}_{z(t)}$ is difficult to write down the exact formula for how to recover this invariant will depend on $N$. The good aspect of the

$$
\frac{1}{2}\left(d f_{1} \cdot \dot{f}_{2}-\dot{f}_{1} \circ d f_{2}\right)
$$

formula is that it gives the correct answer without needing to know formulas for the relationship between the representation as an ideal and the representation as a Puiseaux series.

### 7.4 FURTHER REMARKS

Combining the virtues of the algebraic and Puiseaux constructions, we now have for a surface $X$ a well-defined group homomorphism
$\left\{\begin{array}{c}\begin{array}{c}\text { Free group on } \\ \text { 1-parameter families } \\ \text { of 0-dimensional } \\ \text { subschemes of } X\end{array}\end{array}\right\} \xrightarrow{\tau} \underset{\substack{Z \text { codim 2 } \\ \text { subschemes }}}{\left.\lim _{\substack{ }} \mathcal{E} t_{\mathcal{O}_{X}}^{2}\left(\mathcal{O}_{Z}, \Omega_{X / \mathbb{Q}}^{1}\right) \cong \underset{x \in X}{\oplus} H_{x}^{2}\left(\Omega_{X / \mathbb{Q}}^{1}\right), ~\right)}$ having the properties:
(i) $\tau$ depends only on the underlying cycle of $\sum_{i} z_{i}(t)$;
(ii) $\tau(z(t))$ depends only on the tangent vector to $z(t)$ in the Hilbert scheme; i.e., on $d I_{z(t)} /\left.d t\right|_{t=0} \bmod I_{z(0)}$;
(iii) $\tau$ kills torsion; i.e., if $\tau(n z(t))=0$ then $\tau(z(t))=0$;
(iv) $\tau$ is intrinsic and functorial, compatible with push-forward and pullback for maps of surfaces;
(v) $\tau$ behaves well under limits; i.e., if $z(t, u)$ is a 2-parameter family of 0 -cycles and $z_{u}(t)=z(t, u)$, then

$$
\lim _{u \rightarrow 0} \tau\left(z_{u}(t)\right)=\tau\left(z_{0}(t)\right)
$$

There is also the property that $\tau$ is functorial under maps to $Y \rightarrow X$ and $X \rightarrow Y$, where $Y$ is a curve and we use the tangent space to 0 -cycles on curves described in section 2.

We would expect that $\tau$ is universal in the sense that any group homomorphism satisfying properties (i)-(v) factors through $\tau$. In particular, we would expect $\operatorname{ker}(\tau)$ to be the smallest subgroup of the free group on 1-parameter families of 0 -dimensional subschemes of $X$ that satisfies the consequences of (i)-(v). We have been unable to prove this latter statement and consider it an important open problem - some evidence for how things might go is the result and argument from section 6(i) about the families $z_{\alpha \beta}(t)$ with

$$
I_{z_{\alpha, \beta}(t)}=\left(x^{2}-\alpha y^{2}, x y-\beta t\right),
$$

where the element

$$
\beta \frac{d \alpha}{\alpha} \in \Omega_{\mathbb{C} / \mathbb{Q}}^{1}
$$

completely controls the situation, and this fact can be reduced to basic geometric equivalences.

In concluding this section, we would like to make a direct connection between our original "computational" approach to tangents to arcs in $Z^{2}(X)$ by taking differentials of Puiseaux series, and the intrinsic Ext-approach just given. The first key observation is that, given a point $x \in X$ and local uniformizing parameters $\xi, \eta \in \mathbb{C}(X)$ centered at $x$, we have by Appendix A in section 8 below there is a well-known identification

$$
\lim _{k \rightarrow \infty} \varepsilon x t_{\mathcal{O}_{X}}^{2}\left(\mathcal{O}_{X} / \mathfrak{m}_{x}^{k}, \Omega_{X / \mathbb{Q}}^{1}\right) \cong\left\{\begin{array}{c}
4^{\text {th }} \text { quadrant Laurent }  \tag{7.9}\\
\text { tails } \sum_{i, j>0} \alpha_{i j} / \xi^{i} \eta^{j} \\
\text { where }\left.\alpha_{i j} \in \Omega_{X / \mathbb{Q}}^{1}\right|_{x}
\end{array}\right\} .
$$

Here the notation $\left.\Omega_{X / \mathbb{Q}}^{1}\right|_{x}$ means $\Omega_{X / \mathbb{Q}, x}^{1} / \mathfrak{m}_{x} \Omega_{X / \mathbb{Q}, x}^{1}$. Given an arc $z(t)$ in $Z_{\{x\}}^{1}(X)$ - i.e., with $\lim _{t \rightarrow \infty}|z(t)|=x$ - we want to identify its tangent $z^{\prime}(0)$ as given by a $4^{\text {th }}$ quadrant Laurent tail with coefficients in $\left.\Omega_{X / \mathbb{Q}}^{1}\right|_{x}$, as above. The key is to use the canonical element

$$
\begin{equation*}
\omega=\frac{d \xi \wedge d \eta}{\xi \eta} \in \mathcal{E} x t_{\mathcal{O}_{X}}^{2}\left(\mathcal{O}_{X} / \mathfrak{m}_{x}, \Omega_{X / \mathbb{C}}^{2}\right) \tag{7.10}
\end{equation*}
$$

(the sense in which this element is canonical will also be discussed below). Using the local uniformizing parameters $\xi, \eta$ we write (as in section 3)

$$
z(t)=x_{1}(t)+\cdots+x_{m}(t)
$$

as a sum of Puiseaux series

$$
x_{i}(t)=\left(\xi_{i}(t), \eta_{i}(t)\right) .
$$

Claim: If we write

$$
\begin{equation*}
\sum_{i} \frac{d\left(\xi-\xi_{i}(t)\right) \wedge d\left(\eta-\eta_{i}(t)\right)}{\left(\xi-\xi_{i}(t)\right)\left(\eta-\eta_{i}(t)\right)} \equiv \varphi \wedge d t+\gamma \quad \bmod t \tag{7.11}
\end{equation*}
$$

where $\gamma$ does not involve dt, then $\varphi$ is a $4^{\text {th }}$ quadrant Laurent series with coefficients in $\left.\Omega_{X / \mathbb{Q}}^{1}\right|_{x}$ whose coefficients are exactly the terms that arise as differentials of Puiseaux series as in section 3.

More precisely, if we consider

$$
z^{\prime}(0) \in \operatorname{Hom}^{o}\left(\Omega_{X / \mathbb{Q}, x}^{2} / \Omega_{\mathbb{C} / \mathbb{Q}}^{2}, \Omega_{\mathbb{C} / \mathbb{Q}}^{1}\right)
$$

as in the geometric description given in section 5 , then for $\psi \in \Omega_{X / \mathbb{Q}, x}^{2}$

$$
\begin{equation*}
z^{\prime}(0)(\psi)=\operatorname{Res}_{x}(\psi \wedge \varphi) \tag{7.12}
\end{equation*}
$$

where $\varphi$ is given in (7.11) above.
Conclusion: With the identification (7.9), we have

$$
z^{\prime}(0)=\varphi
$$

The proof of the claim is by direct computation. For example, if

$$
\begin{aligned}
z(t)= & \left(a_{1} t^{1 / 2}+a_{2} t+\cdots, b_{1} t^{1 / 2}+b_{2} t+\cdots\right) \\
& +\left(-a_{1} t^{1 / 2}+a_{2} t+\cdots,-b_{1} t^{1 / 2}+b_{2} t+\cdots\right)
\end{aligned}
$$

then

$$
\varphi=\frac{1}{\xi \eta}\left[\left(2 a_{2}+\frac{a_{1}^{2}}{\xi}+\frac{a_{1} b_{1}}{\eta}\right) d \eta-\left(2 b_{2}+\frac{a_{1} b_{1}}{\xi}+\frac{b_{1}^{2}}{\eta}\right) d \xi+\left(b_{1} d a_{1}-a_{1} d b_{1}\right)\right]
$$

and using (7.12)

$$
\begin{aligned}
z^{\prime}(0)(d \xi \wedge d \eta) & =b_{1} d a_{1}-a_{1} d b_{1} \\
z^{\prime}(0)(d \xi \wedge d \alpha) & =-2 a_{2} d \alpha \\
z^{\prime}(0)(d \eta \wedge d \alpha) & =-2 b_{2} d \alpha \\
z^{\prime}(0)(\eta d \eta \wedge d \alpha) & =-b_{1}^{2} d \alpha \\
z^{\prime}(0)(\xi d \eta \wedge d \alpha) & =z^{\prime}(0)(\eta d \xi \wedge d \alpha)=-a_{1} b_{1} \\
z^{\prime}(0)(\xi d \xi \wedge d \alpha) & =-a_{1}^{2}
\end{aligned}
$$

Finally, regarding the canonical element $\omega$ given by (7.10), we have that

$$
\omega \in \mathbb{H}_{x}^{4}\left(\Omega_{X / \mathbb{C}}^{\bullet}\right) \cong \mathbb{C}
$$

is a generator, which topologically may be thought of as the local fundamental class of the point $x$.

## Chapter Eight

## Tangents to related spaces

In the preceding section we have given the formal definition

$$
\begin{equation*}
\underline{\underline{T}} Z^{2}(X)=\lim _{\substack{Z \text { codim } \\ \text { subscheme }}} \varepsilon x t_{\mathcal{O}_{X}}^{2}\left(\mathcal{O}_{Z}, \Omega_{X / Q}^{1}\right) \tag{8.1}
\end{equation*}
$$

of the tangent sheaf to the space $Z^{2}(X)$ of 0 -cycles on a smooth algebraic surface $X$. For the study of the infinitesimal geometry of $Z^{2}(X)$ - especially the subspace $Z_{\mathrm{rat}}^{2}(X)$ of 0-cycles that are rationally equivalent to zero - it is important to define and study the tangent sheaf to several related spaces. This is the objective of the first two subsections of this section, and in the last subsection we will relate these to $\underline{\underline{T}} Z^{2}(X)$ and arrive at the main result of this work.

In the Appendix A to the first section we will recall the construction and some properties of the Cousin flasque resolution of a coherent sheaf on $X$, and in Appendix B we will use this material in dualized form to give a description of $\underline{\underline{T}} Z^{1}(X)$ in terms of differential forms.

### 8.1 DEFINITION OF $\underline{\underline{T}} Z^{1}(X)$ FOR A SURFACE $X$

For a $Y$ a smooth curve, based upon heuristic geometric considerations in Chapter 2 we gave the provisional definition

$$
\begin{equation*}
\underline{\underline{T}}^{1} Z^{1}(Y)=\mathcal{P} \mathcal{P}_{Y} \tag{8.2}
\end{equation*}
$$

for the tangent sheaf to the space of divisors on $Y$. In this case, divisors are the same as 0-cycles; in Chapter 2 and again in the preceding section we have noted that the analogue of the formal definition (8.1) when $n=1$ agrees with (8.2).

We begin by noting that the heuristic reasoning leading to (8.2) for curves works equally well for divisors in all dimensions: For any smooth variety $X$ and point $x$, given $f, g \in \mathcal{O}_{X, x}$ we have that one reasonable prescription is
tangent at $t=0$ and localized at $x$ corresponds to $\operatorname{div}(f+t g)=[g / f]_{x}$
where the RHS is the principal part at $x$ of $g / f$. This suggests that for the same geometric reason as in the case of curves we take as provisional definition

$$
\underline{T}^{\underline{1}}(X)=\mathcal{P P}_{X}
$$

where as usual the sheaf of principal parts is

$$
\begin{equation*}
\mathcal{P P}_{X}=\mathbb{C}(X) / \mathcal{O}_{X} \tag{8.3}
\end{equation*}
$$

We will now show that for $X$ a surface ${ }^{1}$

$$
\begin{equation*}
\mathcal{P P}_{X} \cong \lim _{\substack{Z \text { codim } \\ \text { subscheme }}} \mathcal{E x} t_{\mathcal{O}_{X}}^{1}\left(\mathcal{O}_{Z}, \mathcal{O}_{X}\right) \tag{8.4}
\end{equation*}
$$

This then leads to the formal
Definition: The tangent sheaf to the space of codimension 1 cycles on a smooth variety $X$ is

$$
\underline{\underline{T}} Z^{1}(X)=\lim _{\substack{Z \text { codim } 1 \\ \text { subscheme }}} \mathcal{E} x t_{\mathcal{O}_{X}}^{1}\left(\mathcal{O}_{Z}, \mathcal{O}_{X}\right)
$$

Proof of (8.4): From the Appendix to this section we recall the Cousin flasque resolution (the notations are explained there)

$$
0 \rightarrow \mathcal{O}_{X} \rightarrow \underset{\substack{\mathbb{C}}}{=} \underset{\substack{Y \\ Y \text { codim } 1 \\ \text { irred }}}{\oplus} \stackrel{H}{=}_{y}^{1}\left(\mathcal{O}_{X}\right) \rightarrow \underset{x \in X}{\oplus} \underline{\underline{H}}_{x}^{2}\left(\mathcal{O}_{X}\right) \rightarrow 0
$$

Thus we have to show that

$$
\lim _{\substack{Z \text { codim } 1  \tag{8.5}\\
\text { subscheme }}} \mathcal{E x} t_{\mathcal{O}_{X}}^{1}\left(\mathcal{O}_{Z}, \mathcal{O}_{X}\right) \cong \operatorname{ker}\left\{\underset{\substack{Y \\
\left\{\begin{array}{c}
\text { codim } 1 \\
Y \text { irred }
\end{array}\right.}}{\bigoplus_{y}^{H}}\left(\mathcal{O}_{X}\right) \rightarrow \underset{x \in X}{\oplus} \underline{\underline{H}}_{x}^{2}\left(\mathcal{O}_{X}\right)\right\}
$$

This is also proved in the Appendix. Briefly the idea is this: Working in the stalk at $x \in X$ we consider an element

$$
g / f \in \underline{\mathbb{C}}(X)_{x}
$$

where $f, g \in \mathcal{O}_{X, x}$ are relatively prime. This gives the element

$$
\left\{\begin{array}{l}
0 \rightarrow F_{1} \xrightarrow{f} F_{0} \rightarrow \mathcal{O}_{Z} \rightarrow 0  \tag{8.6}\\
F_{1} \xrightarrow{g} \mathcal{O}_{X}
\end{array} \quad\left(F_{1}, F_{0} \cong \mathcal{O}_{X}\right)\right.
$$

in $\operatorname{Ext}_{\mathcal{O}_{X}}^{1}\left(\mathcal{O}_{Z}, \mathcal{O}_{X}\right)_{x}$, where the top row is the free resolution of the codi-mension-1 subscheme Z defined by $(f)$ and the second row gives an element of Ext ${ }^{1}$, defined as usual to be the $1^{\text {st }}$ derived functor of $\operatorname{Hom}_{\mathcal{O}_{X}}\left(\mathcal{O}_{Z}, \mathcal{O}_{X}\right)$. This prescription annihilates $\mathcal{O}_{X, x} \subset \underset{\underline{C}}{ }(X)_{x}$ and behaves in a compatible way if we have an inclusion $Z \subseteq Z^{\prime}$ of subschemes. If

$$
f=f_{1}^{l_{1}} \cdots f_{k}^{l_{k}}
$$

where the $f_{i} \in \mathcal{O}_{X, x}$ are irreducible, relatively prime and with divisor $Y_{i}$, then we map (8.6) to

[^12]by sending (8.6) to $\sum_{i} \underline{\underline{H}}_{y_{i}}^{1}\left(\mathcal{O}_{X}\right)_{x}$, where the $i^{\text {th }}$ component is
\[

\left\{$$
\begin{array}{l}
F_{1} \xrightarrow{f_{i}^{l_{i}}} F_{0} \rightarrow \mathcal{O}_{X} / J_{Y_{i}}^{l_{i}} \\
F_{1} \xrightarrow{g / f_{1}^{l_{1} \ldots f_{i}^{l_{i} \cdots f_{k}^{l_{k}}}} \mathcal{O}_{X} .}
\end{array}
$$ \quad\left(F_{0}, F_{1} \cong \mathcal{O}_{X}\right)\right.
\]

This maps to zero in $H_{x}^{2}\left(\mathcal{O}_{X}\right)$ and by exactness of the Cousin flasque resolution has kernel $\mathbb{C}(X)_{x}$ (cf. the Appendix).

We thus have that for a surface $X$

$$
\underline{\underline{T}} Z^{1}(X) \cong \operatorname{ker}\left\{\underset{\left.\substack{Y  \tag{8.7}\\
\left\{\begin{array}{c}
\text { codim } \\
\text { irred } \\
\oplus
\end{array}\right.} \underset{=}{\underline{H}_{y}^{1}}\left(\mathcal{O}_{X}\right) \rightarrow \underset{x \in X}{\oplus} \underline{\underline{H}}_{x}^{2}\left(\mathcal{O}_{X}\right)\right\}}{ }\right.
$$

whereas for a smooth curve $Y$ we simply have

$$
\underline{\underline{T}}^{1}(Y) \cong \underset{y \in Y}{\oplus} \underline{\underline{H}}_{y}^{1}\left(\mathcal{O}_{Y}\right),
$$

and one question is:
What is the geometric meaning of being in the kernel in 8.7?
Later in this section we will discuss this using the interpretation of the last two terms in the Cousin flasque resolution by means of differential forms, which gives a particularly geometric way of understanding the situation. Here we shall give a more algebraic explanation.

The simplest interesting example is if

$$
\left\{\begin{array}{c}
Y_{1}=\operatorname{div} f_{1}, Y_{2}=\operatorname{div} f_{2} \\
Y_{1} \cap Y_{2}=x
\end{array}\right.
$$

where the intersection is transverse


If we consider $g / f_{1} f_{2} \in \mathbb{C}(X)_{x}$, then there exist $h_{1}, h_{2} \in \mathcal{O}_{X, x}$ such that

$$
g=h_{1} f_{1}+h_{2} f_{2} \Leftrightarrow g(x)=0 .
$$

Such $g$ 's correspond to deforming $Y_{1}$ and $Y_{2}$ independently. The more interesting case when $g(x) \neq 0$ corresponds to smoothing the singularity and deforming $Y_{1}+Y_{2}$ into an irreducible curve (all of this is local)


In this case, on $Y_{1}$ we have the element

$$
\left\{\begin{array}{ll}
F_{1} \xrightarrow{f_{1}} F_{0} \rightarrow \mathcal{O}_{Y_{1}} \\
F_{1} \xrightarrow{g / f_{2}} \mathcal{O}_{X}
\end{array} \quad\left(F_{1}, F_{0} \cong \mathcal{O}_{X}\right)\right.
$$

in $H_{y_{1}}^{1}\left(\mathcal{O}_{X}\right)$ (the reason that poles are allowed in the $2^{\text {nd }}$ term is explained in the Appendix), and in $H_{y_{2}}^{1}\left(\mathcal{O}_{X}\right)$ the element

$$
\left\{\begin{array}{ll}
F_{1} \xrightarrow{f_{2}} F_{0} \rightarrow \mathcal{O}_{Y_{2}} \\
F_{1} \xrightarrow{g / f_{1}} \mathcal{O}_{X} .
\end{array} \quad\left(F_{1}, F_{0} \cong \mathcal{O}_{X}\right)\right.
$$

The first element maps in $H_{x}^{2}\left(\mathcal{O}_{X}\right)$ to

$$
\left\{\begin{array}{l}
F_{2} \xrightarrow{\binom{f_{2}}{-f_{1}}} F_{2} \xrightarrow{\left(f_{1}, f_{2}\right)} F_{0} \rightarrow \mathcal{O}_{x} \rightarrow 0 \quad F_{2}, F_{0} \cong \mathcal{O}_{X}, F_{1} \cong \mathcal{O}_{X} \oplus \mathcal{O}_{X} \\
F_{2} \xrightarrow{g} \mathcal{O}_{X}
\end{array}\right.
$$

where the top row is the Koszul resolution of $\mathcal{O}_{x}$ with $x=\left\{f_{1}=f_{2}=0\right\}$. The second element maps similarly, and because of the commutative diagram

$$
\begin{aligned}
& 0 \rightarrow \mathcal{O}_{X} \xrightarrow{\binom{f_{2}}{-f_{1}}} \mathcal{O}_{X}^{2} \xrightarrow{\left(f_{1}, f_{2}\right)} \mathcal{O}_{X} \rightarrow \mathcal{O}_{x} \rightarrow 0 \\
& \downarrow-1 \quad \downarrow\left(\begin{array}{ll}
0 & 1 \\
1 & 0
\end{array}\right) \quad \downarrow 1 \quad \| \\
& \rightarrow \mathcal{O}_{X} \xrightarrow{\binom{f_{1}}{-f_{2}}} \mathcal{O}_{X}^{2} \xrightarrow{\left(f_{2}, f_{1}\right)} \mathcal{O}_{X} \rightarrow \mathcal{O}_{x} \rightarrow 0
\end{aligned}
$$

we see that these determine classes in

$$
\operatorname{Ext}_{\mathcal{O}_{X}}^{2}\left(\mathcal{O}_{x}, \mathcal{O}_{X}\right)
$$

that are negatives of each other and hence cancel. We thus map to 0 in $H_{x}^{2}\left(\mathcal{O}_{X}\right)$, as must be the case.

More sophisticated examples that illustrate the various aspects of the geometric significance of being in the kernel in (8.7) may be especially easily computed using differential forms; this will be done in Appendix 2 to this subsection.

The simplest example of a tangent vector to a codimension-1 cycle is given by a normal vector field

$$
\nu \in H^{0}\left(N_{Y / X}\right)
$$

to a smooth curve $Y \subset X$. If locally $Y$ is the divisor of a function $f$, then

$$
\nu=g \partial / \partial f
$$

for some function $g$. (This expression is well-defined as a normal vector field along $Y$ - its value on a 1 -form $\varphi$ is given by

$$
\nu\rfloor \varphi=\operatorname{Res}_{Y}\left(\frac{g \varphi \wedge d f}{f}\right)
$$

where the $\operatorname{Res}_{Y}$ is the Poincaré residue.) The corresponding element of Ext ${ }^{1}$ is given by

$$
\left\{\begin{array}{lll}
F_{1} & \xrightarrow{f} & F_{0} \rightarrow \mathcal{O}_{Y} \\
F_{1} & \xrightarrow{g} & \mathcal{O}_{X}
\end{array}\right.
$$

One interesting point that arises when we consider $T Z^{1}(X)$ rather than $T \operatorname{Hilb}^{1}(X)$ is the following question:
(8.8) Can $\nu$ be extended to a $2^{\text {nd }}$ order arc in $Z^{1}(X)$ ?

It is well known that this may not be possible in $\operatorname{Hilb}^{1}(X)$ - i.e., $\nu$ may be obstructed. In [ ] Ting Fei Ng has proved that if we allow $Y$ to deform as a 1-cycle then this obstruction vanishes, so that (8.8) has an affirmative answer. In fact, Ng has shown that $Z^{1}(X)$ is formally unobstructed; i.e., any $\tau \in T Z^{1}(X)$ is tangent to an infinite order arc in $Z^{1}(X)$ (this is always true locally). The heurestic reason why (8.8) should be true will be discussed in section 10.

Finally, the differential of the Abel-Jacobi map

$$
Z^{1}(X) \rightarrow \operatorname{Pic}(X)
$$

is a map

$$
T Z^{1}(X) \xrightarrow{d A J_{X}^{1}} H^{1}\left(\mathcal{O}_{X}\right)
$$

that may be expressed using Serre duality and the pairing
induced by globalizing the pairing

$$
\begin{gathered}
\mathcal{E x}{\underset{\mathcal{O}_{X}}{1}\left(\mathcal{O}_{Z}, \mathcal{O}_{X}\right) \otimes \Omega_{X / \mathbb{C}}^{2} \rightarrow \mathcal{E} x t_{\mathcal{O}_{X}}^{1}\left(\mathcal{O}_{X}, \Omega_{X / \mathbb{C}}^{2}\right)}_{\imath \|}^{\omega_{Z}}
\end{gathered}
$$

and composing with the trace mapping

$$
H^{1}\left(\omega_{Z}\right) \xrightarrow{\operatorname{Tr}} \mathbb{C}
$$

### 8.1.1 Appendix A: The Cousin flasque resolution; duality

 (cf. [13], [14] and [15])Let $X$ be a smooth $n$-dimensional quasi-projective algebraic variety and denote by $V^{p}(X)$ the set of all irreducible, codimension- $p$ subvarieties of $X$. The Cousin flasque resolution for the sheaf $\mathcal{O}_{X}$ is

$$
\begin{align*}
& 0 \rightarrow \mathcal{O}_{X} \rightarrow \mathbb{C}(X) \rightarrow \underset{Y \in V^{1}(X)}{\oplus} \underline{\underline{H}}_{y}^{1}\left(\mathcal{O}_{X}\right) \rightarrow \underset{Z \in V^{2}(X)}{\oplus} \underline{\underline{H}}_{z}^{2}\left(\mathcal{O}_{X}\right) \rightarrow \cdots  \tag{A.1}\\
& \cdots \rightarrow{\underset{x \in X}{ } \underline{\underline{H}}_{x}^{n}\left(\mathcal{O}_{X}\right) \rightarrow 0}^{\cdots}
\end{align*}
$$

Here, $y \in Y, z \in Z \ldots$, are generic points, $\underline{\underline{H}}_{y}^{1}\left(\mathcal{O}_{X}\right), \underline{\underline{H}}_{z}^{2}\left(\mathcal{O}_{X}\right) \ldots$ denote the Zariski sheaves $\left(j_{Y}\right)_{*} H_{y}^{1}\left(\mathcal{O}_{X}\right),\left(j_{Z}\right)_{*} H_{z}^{2}\left(\mathcal{O}_{X}\right)$, and we identify $X$ with $V^{n}(X)$. The objectives of this appendix are (i) to give procedures for calculating in practice the terms in (A.1), and (ii) to give ways of interpreting the terms in (A.1) using differential forms. This latter will be used in Appendix B to give an effective computational method for understanding the question below (8.7) above. We will do this in the cases $n=1,2$ as this is all that is needed for the present work (in any case, most of the essential features of the general case already appear here).

We first describe the procedure for computing the stalk at $x \in X$ of $\underline{\underline{H}}_{y}^{1}\left(\mathcal{O}_{X}\right)$ where $Y$ is an irreducible divisor in $X$. We may assume that $x \in Y$ and let $f \in \mathcal{O}_{X, x}$ give a local defining equation for $Y$. We then have

$$
\begin{equation*}
F_{1} \xrightarrow{f^{l}} F_{0} \rightarrow \mathcal{O}_{X, x} / f^{l} \mathcal{O}_{X, x} \tag{A.2}
\end{equation*}
$$

where $F_{1}, F_{0}$ are copies of $\mathcal{O}_{X, x}$. We shall denote by

$$
\operatorname{Hom}\left(F_{1}, \mathcal{O}_{X}\right)
$$

the homomorphisms given by rational functions $h / g \in \mathbb{C}(X)$ where $h, g \in$ $\mathcal{O}_{X, x}$ and $g$ is relatively prime to $f$. The diagrams (A.2) $l_{l}$ and (A.2) $)_{l+1}$ are related by

which induces a map

$$
\operatorname{Hom}\left(F_{1}, \mathcal{O}_{X}\right) / \operatorname{Hom}\left(F_{0}, \mathcal{O}_{X}\right) \xrightarrow{\alpha} \rightarrow \operatorname{Hom}\left(F_{1}^{\prime}, \mathcal{O}_{X}\right) / \operatorname{Hom}\left(F_{0}^{\prime}, \mathcal{O}_{X}\right)
$$

If we identify $h / g \in \operatorname{Hom}\left(F_{1}, \mathcal{O}_{X}\right)$ with the function $h / g f^{l}$, then $\alpha(h / g)=$ $h^{\prime} / g^{\prime}$ where $h^{\prime}=f h, g^{\prime}=g$, then we have consistency:

$$
h / g f^{l}=h^{\prime} / g^{\prime} f^{l+1}
$$

The prescription for the stalk at $x$ of the sheaf $\underline{\underline{H}}_{y}^{1}\left(\mathcal{O}_{X}\right)$ is

$$
\begin{equation*}
\underline{\underline{H}}_{y}^{1}\left(\mathcal{O}_{X}\right)_{x}=\lim _{l} \operatorname{Hom}\left(F_{1}, \mathcal{O}_{X}\right) / \operatorname{Hom}\left(F_{0}, \mathcal{O}_{X}\right) \tag{A.3}
\end{equation*}
$$

By what was just said, there is a map

$$
\mathcal{P P}_{X, x} \rightarrow\left(\underset{Y \in V^{1}(X)}{\oplus} \underline{\underline{H}}_{y}^{1}\left(\mathcal{O}_{X}\right)\right)_{x}
$$

as follows: Write $f \in \mathbb{C}(X)$ as

$$
f=h / f_{1}^{l_{1}} \cdots f_{k}^{l_{k}}
$$

where $f_{1}, \cdots, f_{k}, h \in \mathcal{O}_{X, x}$ are relatively prime and the $f_{i}$ are irreducible. Set $Y_{i}=\left\{f_{i}=0\right\}$. Then

$$
f \rightarrow \sum_{i} h / f_{1}^{l_{1}} \cdots \hat{f}_{i}^{l_{i}} \cdots f_{k}^{l_{k}}
$$

where the $\hat{f}_{i}^{l_{i}}$ means to omit the $i^{\text {th }}$ term and $h / f_{1}^{l_{1}} \cdots \hat{f}_{i}^{l_{i}} \cdots f_{k}^{l_{k}}$ is considered as an element of $\underline{\underline{H}}_{y_{i}}^{1}\left(\mathcal{O}_{X}\right)_{x}$ by the procedure given above.

When $n=1$ we obviously have

$$
\mathcal{P P}_{X, x} \cong H_{x}^{1}\left(\mathcal{O}_{X}\right)
$$

When $n=2$ the map

$$
\stackrel{\mathbb{C}}{=}(X)_{x} \rightarrow\left(\underset{Y \in V^{1}(X)}{\oplus} \underline{\underline{H}}_{y}^{1}\left(\mathcal{O}_{X}\right)\right)_{x}
$$

clearly has kernel $\mathcal{O}_{X, x}$, and hence it gives an injection

$$
\mathcal{P P}_{X, x} \hookrightarrow\left(\underset{Y \in V^{1}(X)}{\oplus} \underline{\underline{H}}_{y}^{1}\left(\mathcal{O}_{X}\right)\right)_{x}
$$

We shall give the prescription for computing $H_{x}^{2}\left(\mathcal{O}_{X}\right)$ and then observe that from the general theory it follows that the exact sequence

$$
\begin{equation*}
\mathcal{P P}_{X, x} \rightarrow\left(\underset{Y \in V^{1}(X)}{\oplus} \underline{\underline{H}}_{y}^{1}\left(\mathcal{O}_{X}\right)\right)_{x} \rightarrow H_{x}^{2}\left(\mathcal{O}_{X}\right) \rightarrow 0 \tag{A.4}
\end{equation*}
$$

is exact.
For $X$ a surface and $Z \subset X$ any subscheme with $\operatorname{supp} Z=x$ and ideal $\mathcal{J}_{Z} \subset \mathcal{O}_{X, x}$, we take a minimal resolution

$$
0 \rightarrow E_{2} \rightarrow E_{1} \rightarrow E_{0} \rightarrow \mathcal{O}_{Z} \rightarrow 0
$$

where $E_{0} \cong \mathcal{O}_{X, x}$ and $E_{i}$ is isomorphic to the direct sum of $\mathcal{O}_{X, x}$ 's for $i=1,2$. We then consider the quotient

$$
\operatorname{Hom}\left(E_{2}, \mathcal{O}_{X, x}\right) / \operatorname{Hom}\left(E_{1}, \mathcal{O}_{X, x}\right)
$$

where the matrix elements in $\operatorname{Hom}\left(E_{i}, \mathcal{O}_{X, x}\right)$ are in $\mathcal{O}_{X, x}$. If $Z^{\prime}$ is another subscheme with $\mathcal{J}_{Z^{\prime}} \subset \mathcal{J}_{Z}$, then there is a commutative diagram

inducing a map

$$
\operatorname{Hom}\left(E_{2}, \mathcal{O}_{X, x}\right) / \operatorname{Hom}\left(E_{1}, \mathcal{O}_{X, x}\right) \rightarrow \operatorname{Hom}\left(E_{2}^{\prime}, \mathcal{O}_{X, x}\right) / \operatorname{Hom}\left(E_{1}^{\prime}, \mathcal{O}_{X, x}\right)
$$

The prescription is

$$
\begin{equation*}
H_{x}^{2}\left(\mathcal{O}_{X}\right)=\lim _{\substack{\text { subschemes } Z \\ \text { supp } Z=x}} \operatorname{Hom}\left(E_{2}, \mathcal{O}_{X, x}\right) / \operatorname{Hom}\left(E_{1}, \mathcal{O}_{X, x}\right) \tag{A.5}
\end{equation*}
$$

It is well-known that we may take the limit only over the subschemes with ideal $\mathfrak{m}_{x}^{l}$ and obtain the same result.

If $X$ is a curve and $\xi$ is a local uniformizing parameter centered at $x$, then we have

$$
\mathcal{P P}_{X, x} \cong H_{x}^{1}\left(\mathcal{O}_{X}\right) \cong\left\{\begin{array}{l}
\text { finite Laurent tails } \\
\sum_{k>0} a_{k} / \xi^{k}
\end{array}\right\}
$$

For $X$ a surface with local uniformizing parameters $\xi, \eta$ centered at $x$, we have similarly (cf. f)) below

$$
H_{x}^{2}\left(\mathcal{O}_{X}\right) \cong\left\{\begin{array}{c}
\text { finite } 4^{\text {th }} \text { quadrant Laurent } \\
\text { tails } \tau=\sum_{k, l>0} a_{k l} / \xi^{k} \eta^{l}
\end{array}\right\}
$$

The map

$$
\left(\underset{Y \in V^{1}(X)}{\oplus} \underline{\underline{H}}_{y}^{1}\left(\mathcal{O}_{X}\right)\right)_{x} \rightarrow H_{x}^{2}\left(\mathcal{O}_{X}\right)
$$

may be described as follows: Represent an element of $H_{y}^{1}\left(\mathcal{O}_{Y}\right)$ by

$$
\left\{\begin{array}{c}
F_{1} \xrightarrow{f^{k}} F_{0} \rightarrow \mathcal{O}_{X, x} / f^{k} \mathcal{O}_{X, x} \\
h / g^{l} \text { where } h, g \in \mathcal{O}_{X, x}
\end{array}\right.
$$

and we assume for the moment that $f$ and $g$ are relatively prime and irreducible. Then $f^{k}$ and $g^{l}$ generate an ideal $\mathcal{J}_{Z}$ with $\operatorname{supp} Z=x$, and we may consider the corresponding Koszul complex

$$
0 \rightarrow E_{2} \xrightarrow{\binom{g^{l}}{-f^{k}}} E_{1} \xrightarrow{\left(f^{k}, g^{l}\right)} E_{0} \rightarrow \mathcal{O}_{Z} \rightarrow 0
$$

where $E_{2} \cong \mathcal{O}_{X, x}, E_{1} \cong \mathcal{O}_{X, x} \oplus \mathcal{O}_{X, x}, E_{0} \cong \mathcal{O}_{X, x}$, and the map $E_{2} \rightarrow E_{1}$ is given by $1 \rightarrow\left(-g^{l}, f^{k}\right)$. Then the above element of $H_{y}^{1}\left(\mathcal{O}_{X}\right)$ maps to

$$
h \in \operatorname{Hom}\left(E_{2}, \mathcal{O}_{X, x}\right) / \operatorname{Hom}\left(E_{1}, \mathcal{O}_{X, x}\right)
$$

In general, $h / g^{l}$ will be of the form $h / g_{1}^{l_{1}} \cdots g_{k}^{l_{k}}$ where $f, g_{1}, \ldots, g_{k}$ are irreducible and pairwise relatively prime. We then sum up the above construction with $\left(f^{k}, g_{i}^{l_{i}}\right)$ replacing $\left(f^{k}, g^{l}\right)$.

By our sign conventions, the sequence (A.4) is a complex and it is a nontrivial result that it is exact. The surjectivity on the right is easy to check using the Laurent series interpretation of $H_{x}^{2}\left(\mathcal{O}_{X}\right)$. The issue is to show that given the data

$$
\left\{\begin{array}{l}
F_{1, i} \xrightarrow{f_{i}^{l_{i}}} F_{0, i} \rightarrow \mathcal{O}_{X, x} / f_{i}^{l_{i}} \mathcal{O}_{X, x} \\
h_{i} / g_{i} \in \operatorname{Hom}\left(F_{1, i}, \mathcal{O}_{X, x}\right) / \operatorname{Hom}\left(F_{0, i}, \mathcal{O}_{X, x}\right)
\end{array}\right.
$$

where $1 \leqq i \leqq k$ and the $Y_{i}=\left\{f_{i}=0\right\}$ are irreducible curves passing through $x$, then the condition that the sum of this data in $\underset{Y_{i}}{\rightarrow} \oplus H_{y_{i}}^{1}\left(\mathcal{O}_{X}\right)$ map to zero in $H_{x}^{2}\left(\mathcal{O}_{X}\right)$ gives the compatibility condition that the (equivalence classes of) the $h_{i} / g_{i}$ come from a single rational function in $\mathbb{C}(X)$.

We conclude this section by drawing global consequences of the relation between the Cousin flasque resolution

$$
0 \rightarrow \mathcal{O}_{X} \rightarrow \underset{\mathbb{C}}{=}(X) \rightarrow \underset{\substack{Y \\
\left\{\begin{array}{r}
\text { irred } \\
Y \text { codim } 1
\end{array}\right.} \underset{y}{H^{1}}\left(\mathcal{O}_{X}\right) \rightarrow \underset{x \in X}{\oplus} \underline{\underline{H}}_{x}^{2}\left(\mathcal{O}_{X}\right) \rightarrow 0}{ }
$$

and the global tangent space

$$
T Z^{1}(X)=: H^{0}\left(\underline{\underline{T}} Z^{1}(X)\right)
$$

as defined above. Namely from the acyclicity of the Zariski sheaves in the above resolution and standard identification

$$
H^{1}\left(\mathcal{O}_{X}\right) \cong T \operatorname{Pic}(X)
$$

we have the exact sequence

$$
0 \rightarrow \mathbb{C}(X) \rightarrow T Z^{1}(X) \rightarrow T \operatorname{Pic}(X) \rightarrow 0
$$

The geomertric interpretation of this is clear.
Before turning to the interpretation of the terms in the Cousin flasque resolution via differential forms, we want to give the
Summary of Grothendieck local duality: Let $X$ be an $n$-dimensional smooth variety and $Z$ a subscheme with $\operatorname{supp} Z=x$. Then
a) There is a natural map

$$
\mathcal{E x} t_{\mathcal{O}_{X}}^{n}\left(\mathcal{O}_{Z}, \Omega_{X / \mathbb{C}}^{n}\right) \xrightarrow{\operatorname{Tr}} \longrightarrow \mathbb{C}
$$

b) The $\mathcal{O}_{X}$-modules $\mathcal{E} x t_{\mathcal{O}_{X}}^{n}\left(\mathcal{O}_{Z}, \mathcal{O}_{X}\right)$ and $\mathcal{E} x t_{\mathcal{O}_{X}}^{n}\left(\mathcal{O}_{Z}, \Omega_{X / \mathbb{C}}^{n}\right)$ annihilate $\mathcal{J}_{Z}$; i.e., they are $\mathcal{O}_{Z}$-modules;
c) The pairing

is a perfect pairing (local duality);
d) Given a regular sequence $f_{1}, \ldots, f_{n}$ with $\mathcal{J}_{Z}=\left(f_{1}, \ldots, f_{n}\right)$, there is an identification $\mathcal{E} x t_{\mathcal{O}_{X}}^{n}\left(\mathcal{O}_{Z}, \Omega_{X / \mathbb{C}}^{n}\right) \cong \Omega_{X / \mathbb{C}, x}^{n} \otimes \mathcal{O}_{Z}$ and the pairing

$$
\mathcal{O}_{Z} \otimes\left(\Omega_{X / \mathbb{C}, x}^{n} \otimes \mathcal{O}_{Z}\right) \rightarrow \mathbb{C}
$$

is given by

$$
g \otimes(\omega \otimes h) \rightarrow \operatorname{Res}_{x}\left\{\frac{g h \omega}{f_{1} \cdots f_{n}}\right\}
$$

where the term in brackets is the Grothendieck residue symbol;
e) In general, given a minimal free resolution

$$
0 \rightarrow E_{n} \rightarrow E_{n-1} \rightarrow \cdots \rightarrow E_{0} \rightarrow \mathcal{O}_{Z} \rightarrow 0
$$

there is a recipe for computing the pairing (A.6) in terms of Grothendieck residue symbols;
f) Local duality for subschemes $Z$ with $\operatorname{supp} Z=x$ together with the isomorphism

$$
\lim _{\left\{\begin{array}{l}
Z \text { codim } n \\
\text { subscheme }
\end{array}\right.} \mathcal{E x} t_{\mathcal{O}_{X}}^{n}\left(\mathcal{O}_{Z}, \mathcal{O}_{X}\right) \cong H_{x}^{n}\left(\mathcal{O}_{X}\right)
$$

give an isomorphism

$$
\begin{equation*}
H_{x}^{n}\left(\mathcal{O}_{X}\right) \cong \operatorname{Hom}_{\mathbb{C}}^{c}\left(\Omega_{X / \mathbb{C}, x}^{n}, \mathbb{C}\right) \tag{A.7}
\end{equation*}
$$

When $n=2$, if we make the identification of $H_{x}^{2}\left(\mathcal{O}_{X}\right)$ with $4^{\text {th }}$ quadrant Laurent tails $\tau$ as above, then (A.7) is given by

$$
\tau(\omega)=\operatorname{Res}(\tau \omega)
$$

where the residue is the usual interated 1-variable residue.
Proof: If $\xi, \eta$ are local coordinates at $x$, and $\xi^{*}, \eta^{*}$ are the dual variables, then we may naturally identify

$$
\operatorname{Ext}_{\mathcal{O}_{X}}^{2}\left(\mathcal{O}_{X} / \mathfrak{m}_{x}^{k+1}, \mathcal{O}_{X}\right)=\left\{\sum_{\substack{i+j \leq k \\ i, j \geq 0}} a_{i j} \xi^{* i} \eta^{* j}\right\}
$$

To see this, we have the minimal free resolution

$$
0 \rightarrow \mathcal{O}_{X}^{k+1} \xrightarrow{\left(\begin{array}{cccc}
\eta & 0 & \cdots & 0 \\
-\xi & \eta & \cdots & 0 \\
0 & -\xi & \cdots & 0 \\
\vdots & \vdots & & \vdots \\
0 & 0 & \cdots & -\xi
\end{array}\right)} \mathcal{O}_{X}^{k+2} \xrightarrow{\left(\xi^{k+1}, \xi^{k} \eta, \cdots, \eta^{k+1}\right)} \mathcal{O}_{X}
$$

If we let $e_{1}, \ldots, e_{k+1}$ be a basis for $\mathcal{O}_{X}^{k+1}$, then if we identify

$$
e_{1}^{*} \leftrightarrow \xi^{* k}, e_{2}^{*} \leftrightarrow \xi^{* k-1} \eta^{*}, \ldots, e_{k+1}^{*} \leftrightarrow \eta^{* k}
$$

then the relations in $\operatorname{Ext}_{\mathcal{O}_{X}}^{2}\left(\mathcal{O}_{X} / \mathfrak{m}_{x}^{k+1}, \mathcal{O}_{X}\right)$

$$
\begin{gathered}
\eta e_{2}^{*}=\xi e_{1}^{*} \\
\vdots \\
\eta e_{k+1}^{*}=\xi e_{k}^{*} \\
0=\xi e_{k+1}^{*}
\end{gathered}
$$

translate into the relations

$$
\begin{aligned}
\eta\rfloor \xi^{* k} & =0 \\
\eta\rfloor \xi^{* k-1} \eta^{*} & =\xi\rfloor \xi^{* k} \\
& \vdots \\
\eta\rfloor \eta^{* k} & =\xi\rfloor \xi^{*} \eta^{* k-1} \\
0 & =\xi\rfloor \eta^{* k}
\end{aligned}
$$

Consequently

$$
\begin{aligned}
&{\mathcal{E} x t_{\mathcal{O}_{X}}^{2}\left(\mathcal{O}_{X} / \mathfrak{m}_{x}^{k+1}, \mathcal{O}_{X}\right)}=\operatorname{Hom}_{\mathcal{O}_{X}}\left(\mathcal{O}_{X}^{k+1}, \mathcal{O}_{X}\right) / \operatorname{Hom}_{\mathcal{O}_{X}}\left(\mathcal{O}_{X}^{k+2}, \mathcal{O}_{X}\right) \\
&\left.\cong\left\{\sum_{l=0}^{k} p_{l}(\xi, \eta)\right\rfloor \xi^{* k-l} \eta^{* l}: p_{l}(\xi, \eta) \in \mathcal{O}_{X}\right\} \\
&=\left\{\sum_{\substack{i+j \leq k \\
i, j \geq 0}} a_{i j} \xi^{* i} \eta^{* j}\right\} .
\end{aligned}
$$

Here 」means

$$
\left.\xi^{a} \eta^{b}\right\rfloor \xi^{* i} \eta^{* j}= \begin{cases}\xi^{* i-a} \eta^{* j-b} & \text { if } a \leq i, b \leq j \\ 0 & \text { otherwise }\end{cases}
$$

Under the above isomorphism, Grothendieck local duality is the non-degenerate pairing

$$
\operatorname{Ext}_{\mathcal{O}_{X}}^{2}\left(\mathcal{O}_{X} / \mathfrak{m}_{x}^{k+1}, \mathcal{O}_{X}\right) \otimes\left(\Omega_{X / \mathbb{C}}^{2} \otimes \mathcal{O}_{X} / \mathfrak{m}_{x}^{k+1}\right) \rightarrow \mathbb{C}
$$

where

$$
\sum_{\substack{i+j \leq k \\ i, j \geq 0}} a_{i j} \xi^{* i} \eta^{* j} \otimes \sum_{\substack{i+j \leq k \\ i, j \geq 0}} b_{i j} \xi^{i} \eta^{j} d \xi \wedge d \eta \mapsto \sum_{\substack{i+j \leq k \\ i, j \geq 0}} a_{i j} b_{i j}
$$

If we make the identification with Laurent tails

$$
\sum a_{i j} \xi^{* i} \eta^{* j} \leftrightarrow \sum a_{i j} \xi^{-i-1} \eta^{-j-1}
$$

then the duality becomes

$$
\tau \otimes \omega \mapsto \operatorname{Res}_{x}(\tau \omega)
$$

since $\xi^{* i} \eta^{* j} \leftrightarrow \frac{1}{\xi^{i+1} \eta^{j+1}}$ under the residue mapping.
If we pass to the limit,

$$
\begin{aligned}
H_{x}^{2}\left(\mathcal{O}_{X}\right) & =\left\{\sum_{\substack{i, j \geq 0 \\
\{\text { finite sum }}} a_{i j} \xi^{* i} \eta^{* j}\right\} \\
& \cong\left\{\sum_{\substack{i, j<0 \\
\text { finite sum }}} b_{i j} \xi^{i} \eta^{j}\right\}
\end{aligned}
$$

and Grothendieck local duality is the non-degenerate pairing

$$
\begin{aligned}
H_{x}^{2}\left(\mathcal{O}_{X}\right) \otimes \Omega_{X / \mathbb{C}, x}^{2} & \rightarrow \mathbb{C} \\
\tau \otimes \omega & \mapsto \operatorname{Res}_{x}(\tau \omega)
\end{aligned}
$$

Thus

$$
H_{x}^{2}\left(\mathcal{O}_{X}\right) \cong\{4 \text { th quadrant finite Laurent tails at } x\}
$$

with Grothendieck duality being given by residue.
We note that

$$
H_{x}^{2}\left(\Omega_{X / \mathbb{Q}}^{1}\right)=\left\{\sum_{\substack{i, j<0 \\ \text { finite sum }}} \alpha_{i j} \xi^{i} \eta^{j}:\left.\alpha_{i j} \in \Omega_{X / \mathbb{Q}}^{1}\right|_{x}\right\}
$$

In conclusion,
for $X$ a surface we have a natural isomorphism

$$
H_{x}^{2}\left(\mathcal{O}_{X}\right) \cong \operatorname{Hom}_{\mathbb{C}}^{c}\left(\Omega_{X / \mathbb{C}, x}^{2}, \mathbb{C}\right)
$$

This expresses the last term in the Cousin flasque resolution

$$
0 \rightarrow \mathcal{O}_{X} \rightarrow \underset{=}{\mathbb{C}}(X) \rightarrow \underset{Y}{\oplus} H_{y}^{1}\left(\mathcal{O}_{X}\right) \rightarrow \underset{x}{\oplus} H_{x}^{2}\left(\mathcal{O}_{X}\right) \rightarrow 0
$$

in terms of differentials.
It remains to so express the third term, to which we will turn after a side discussion of the local arithmetic fundamental class.

Local arithmetic cycle class of a 0-dimensional subscheme: Angeniol and Lejeune-Jalabert [19] have given a definition - referred to in section 7 (ii) above - of the local fundamental class

$$
[Z]_{\mathrm{loc}} \in H_{x}^{n}\left(\Omega_{X / \mathbb{C}}^{n}\right)
$$

of a 0 -dimensional subscheme $Z$ with support $Z=x$. Recall that if

$$
0 \rightarrow F_{n} \xrightarrow{f_{n}} F_{n-1} \rightarrow \cdots \rightarrow F_{1} \xrightarrow{f_{1}} \mathcal{O}_{X} \rightarrow \mathcal{O}_{Z} \rightarrow 0
$$

is a free resolution of $\mathcal{O}_{Z}$ where each $F_{i} \cong \mathcal{O}_{X}^{r_{i}}$, so that the $f_{i}$ are matrices with entries in $\mathcal{O}_{X}$, then

$$
\frac{1}{n!} d f_{1} \circ \cdots \circ d f_{n} \in \operatorname{Hom}\left(F_{n}, \Omega_{X / \mathbb{C}}^{n}\right)
$$

defines an element in

$$
\begin{aligned}
\lim _{k} \mathcal{E} x t_{\mathcal{O}_{X}}^{n}\left(\mathcal{O}_{X} / \mathcal{J}_{Z}^{k}, \Omega_{X / \mathbb{C}}^{n}\right) & \cong \lim _{k} \mathcal{E} x t_{\mathcal{O}_{X}}^{n}\left(\mathcal{O}_{X} / \mathfrak{m}_{x}^{k}, \Omega_{X / \mathbb{C}}^{n}\right) \\
& \cong H_{x}^{n}\left(\Omega_{X / \mathbb{C}}^{n}\right)
\end{aligned}
$$

which does not depend on the choice of resolution and local trivializations. By definition this is the class $[Z]_{\text {loc }}$.

Now by (A.6)

$$
H_{x}^{n}\left(\Omega_{X / \mathbb{C}}^{n}\right) \cong \text { dual of } \lim _{k}\left(\mathcal{O}_{X} / \mathfrak{m}_{x}^{i}\right)
$$

For $Z$ the subscheme $x$ defined by $\mathfrak{m}_{x}$, using the above identification the standard Koszul resolution of $\mathfrak{m}_{x}$ gives the interpretation of $[x]_{\text {loc }}$ as the evaluation map

$$
[x]_{\operatorname{loc}}(f)=f(x), \quad f \in \mathcal{O}_{X}
$$

More generally, by an argument similar to step 3 in the proof of (7.8) in section 7(ii), we have for any 0-dimensional subscheme $Z$ supported at $x$ that

$$
[Z]_{\mathrm{loc}}(f)=l(Z) f(x)
$$

where $l(Z)$ is the length of $Z$.
Now the Angeniol and Lejeune-Jalabert construction may be adapted to define the local arithmetic fundamental class

$$
[Z]_{a, \mathrm{loc}} \in H_{x}^{n}\left(\Omega_{X / \mathbb{Q}}^{n}\right)
$$

as follows: Given a free resolution of $\mathcal{O}_{Z}$ as above, we consider

$$
d f_{i} \in \operatorname{Hom}\left(F_{i}, F_{i-1} \otimes \Omega_{X / \mathbb{Q}}^{1}\right)
$$

as matrices of absolute differentials and proceed as before. Now, as explained in section 7(ii) and just above,

$$
\begin{aligned}
H_{x}^{n}\left(\Omega_{X / \mathbb{Q}}^{n}\right) & \cong \lim _{i} \mathcal{E} x t_{\mathcal{O}_{X}}^{n}\left(\mathcal{O}_{X} / \mathfrak{m}_{x}^{i}, \Omega_{X / \mathbb{Q}}^{n}\right) \\
& \cong \lim _{i} \operatorname{Hom}_{\mathcal{O}_{X}}^{o}\left(\Omega_{X / \mathbb{Q}}^{n} \otimes \mathcal{O}_{X} / \mathfrak{m}_{x}^{i}, \Omega_{\mathbb{C} / \mathbb{Q}}^{n}\right)
\end{aligned}
$$

and we claim that for $\omega \in \Omega_{X / \mathbb{Q}}^{n}$

$$
[Z]_{a, \operatorname{loc}}(\omega)=l(Z) \omega(x) \in \Omega_{\mathbb{C} / \mathbb{Q}}^{n}
$$

where $\omega \rightarrow \mathrm{ev}_{x}(\omega)$ is the evaluation map. Explicitly,

$$
\frac{1}{n!} d f_{1} \circ \cdots \circ d f_{n} \wedge \omega \in \operatorname{Hom}\left(F_{n}, \Omega_{X / \mathbb{Q}}^{2 n}\right)
$$

and combining this with the natural map

$$
\Omega_{X / \mathbb{Q}}^{2 n} \rightarrow \Omega_{\mathbb{C} / \mathbb{Q}}^{n} \otimes \Omega_{X / \mathbb{C}}^{n}
$$

we get a class

$$
\left[\frac{1}{n!} d f_{1} \circ \cdots \circ d f_{n} \wedge \omega\right] \in \Omega_{\mathbb{C} / \mathbb{Q}}^{n} \otimes \mathcal{E} x t_{\mathcal{O}_{X}}^{n}\left(\mathcal{O}_{Z}, \Omega_{X / \mathbb{C}}^{n}\right) .
$$

Then our claim is

$$
\operatorname{Tr}\left[\frac{1}{n!} d f_{1} \circ \cdots \circ d f_{n} \wedge \omega\right]=l(Z) \operatorname{ev}_{x}(\omega)
$$

To prove this result, one first verifies it directly when $\mathcal{J}_{Z}=\mathfrak{m}_{x}$. In general, one perturbs the above resolution to get a flat family $Z(t)$ given by data $f_{1}(t), \ldots, f_{n}(t)$ and where

$$
Z(t)=\sum_{i=1}^{l(Z)} x_{i}(t)
$$

with the $x_{i}(t)$ distinct for $t \neq 0$. The result is true for each $x_{i}(t), t \neq 0$, and by taking the limit we obtain the desired statement (cf. section 7(ii) for similar argument).

For $n=2$ the extra information in $[Z]_{a, \text { loc }}$ is the difference between

$$
\Omega_{X / \mathbb{Q}}^{2} \xrightarrow{\mathrm{ev}_{x}} \Omega_{\mathbb{C} / \mathbb{Q}}^{2}
$$

and

$$
\mathcal{O}_{X} \xrightarrow{\mathrm{ev}_{x}} \mathbb{C} .
$$

Local duality along an irreducible curve: Let $Y \subset X$ be an irreducible curve, and let $\omega$ be a rational 2-form on $X$ whose polar locus includes $Y$. We want to define a rational 1-form $Y$

$$
\begin{equation*}
\operatorname{Res}_{Y}(\omega) \in \Omega_{\mathbb{C}(Y) / \mathbb{C}}^{1} \tag{A.8}
\end{equation*}
$$

If $\omega$ has a $1^{\text {st }}$-order pole on $Y$, then we can take $\operatorname{Res}_{Y}(\omega)$ to simply be the Poincaré residue of $\omega$ along $Y$. (Even if $\omega$ has poles only on $Y, \operatorname{Res}_{Y}(\omega)$ may have singularities at the singular points of $Y$.) In general, to be able to define (A.8) we need to introduce auxilary data in the form of a retraction $U \longrightarrow Y$ of a Zariski open set $U$ such that $U \cap Y$ is a Zariski open in $Y$. We will not get into the formal definition here, but will just explain how the process works in practice. At a general point $y$ of $Y$, we may choose rational functions $\xi, \eta \in \mathbb{C}(X)$ that are regular at $y$ and such that $\eta=0$ on $Y$. Geometrically, we have a rational mapping

$$
X--\rightarrow \mathbb{P}^{2}
$$

which is regular near $y$ and such that $Y$ maps to a line. Using $\xi, \eta$ as local holomorphic coordinates we may define $\operatorname{Res}_{Y}(\omega)$ in an analytic neighborhood of $y$ in the usual way. Thus writing

$$
\omega=\left(\frac{f_{k}(\xi)}{\eta^{k}}+\cdots+\frac{f_{1}(\xi)}{\eta}+f_{0}(\xi, \eta)\right) d \xi \wedge d \eta
$$

where $f_{0}(\xi, \eta)$ is regular near $y$, we set

$$
\operatorname{Res}_{Y}(\omega)=-f_{1}(\xi) d \xi
$$

We may cover a Zariski open subset $Y^{0}$ of $Y$ with analytic neighborhoods in which this process works, and we observe that (i) the definition agrees in intersections, ${ }^{2}$ and (ii) the resulting regular 1-form on $Y^{0}$ has at most poles on $Y$ and therefore defines a rational 1-form on $Y$.

[^13]We also observe that the map $\omega \rightarrow \operatorname{Res}_{Y}(\omega)$ is $\mathcal{O}_{Y}$-linear in the following sense: At a general point $y \in Y$ the retraction gives an inclusion

$$
\begin{equation*}
\mathcal{O}_{Y, y} \hookrightarrow \mathcal{O}_{X, y} \tag{A.9}
\end{equation*}
$$

such that the composition $\mathcal{O}_{Y, y} \rightarrow \mathcal{O}_{X, y} \xrightarrow{\text { restriction }} \mathcal{O}_{Y, y}$ is the identity. Using (A.9), a rational function $f$ on $Y$ induces a rational function $\tilde{f}$ on $X$ and

$$
\operatorname{Res}_{Y}(\tilde{f} \omega)=f \operatorname{Res}_{Y}(\omega)
$$

Denoting by $\Omega_{X / \mathbb{C}, Y}^{2}$ the restriction of $\Omega_{X / \mathbb{C}}^{2}$ to $Y$ (thus the stalk of $\Omega_{X / \mathbb{C}, Y}^{2}$ at $x$ is zero if $x \notin Y, \Omega_{X / \mathbb{C}, x}^{2}$ if $x \in Y$ ), we may define the sheaf

$$
\operatorname{Hom}_{\mathcal{O}_{Y}}\left(\Omega_{X / \mathbb{C}, Y}^{2}, \Omega_{\mathbb{C}(Y) / \mathbb{C}}^{1}\right)
$$

By the preceeding discussion, using the retraction we may define a sheaf mapping

$$
\begin{equation*}
\underset{\underline{\mathbb{C}}}{ }(X) \rightarrow \operatorname{Hom}_{\mathcal{O}_{Y}}\left(\Omega_{X / \mathbb{C}, Y}^{2}, \Omega_{\mathbb{C}(Y) / \mathbb{C}}^{1}\right) \tag{A.10}
\end{equation*}
$$

In fact, given a retraction as above we may define a mapping

$$
\begin{equation*}
H_{y}^{1}\left(\mathcal{O}_{X}\right) \longrightarrow \operatorname{Hom}_{\mathcal{O}_{Y}}\left(\Omega_{X / \mathbb{C}, Y}^{2}, \mathcal{O}_{\mathbb{C}(Y)}^{1}\right) \tag{A.11}
\end{equation*}
$$

as follows: Given $x \in Y$ and the data

$$
\left\{\begin{array}{l}
\stackrel{f^{l}}{F_{1} \operatorname{lrar}_{0} \longrightarrow} \mathcal{O}_{X, x} / f^{l} \mathcal{O}_{X, x} \\
F_{1} \xrightarrow{g} \mathcal{O}_{X, x}
\end{array}\right.
$$

defining an element of stalk at $x$ of the sheaf $H_{y}^{1}\left(\mathcal{O}_{X}\right)$, then for $\omega \in \Omega_{X / \mathbb{C}, x}^{2}$

$$
\omega \longrightarrow \operatorname{Res}_{Y}\left(\frac{g \omega}{f^{l}}\right)
$$

defines the map (A.11). Moreover, (A.10) and (A.11) are compatible in the sense that the diagram

is commutative (the two slanted arrows both being defined by the same retraction). The basic fact in local duality along an irreducible curve is that the mapping (A.11) is an isomorphism.

We will not prove this here as our interest is in the geometric interpretations of the Cousin flasque resolution and its relation to $\underline{\underline{T}} Z^{1}(X)$. However, in order to complete the story we shall define, for $x \in Y$, a map

$$
\begin{equation*}
\operatorname{Hom}_{\mathcal{O}_{Y}}\left(\Omega_{X / \mathbb{C}, x}^{2}, \Omega_{\mathbb{C}(Y) / \mathbb{C}}^{1}\right) \xrightarrow{\rho_{x}} \operatorname{Hom}_{\mathbb{C}}^{c}\left(\operatorname{Hom}_{X / \mathbb{C}, x}^{2}, \mathbb{C}\right) \tag{A.12}
\end{equation*}
$$

such that the diagram

is commutative, where for each $Y$ we have chosen a retraction as above. In fact, (A.12) is simply the usual residue: Given

$$
\alpha \in \operatorname{Hom}_{\mathcal{O}_{Y}}\left(\Omega_{X / \mathbb{C}, x}^{2}, \Omega_{\mathbb{C}(Y) / \mathbb{C}}^{1}\right),
$$

then for $\omega \in \Omega_{X / \mathbb{C}, x}^{2}$

$$
\rho_{x}(\alpha)(\omega)=\operatorname{Res}_{x}(\alpha(\omega))
$$

where the RHS is the residue at $x \in Y$ of the rational 1-form $\alpha(\omega) \in \Omega_{\mathbb{C}(Y) / \mathbb{C}}^{1}$ (with the usual conventions if $x$ is a singular point of $Y$ ).

In summary then, for $X$ a smooth surface the usual Cousin flasque resolution

$$
\left.0 \rightarrow \mathcal{O}_{X} \rightarrow \underset{\underline{\mathbb{C}}}{=}(X) \rightarrow \underset{Y}{\underset{\underline{H}}{\underline{H}}} y=\mathcal{O}_{X}\right) \rightarrow \underset{x}{\underset{\underline{H^{\prime}}}{2}} \underset{x}{ }\left(\mathcal{O}_{X}\right) \rightarrow 0
$$

may, upon choice of retractions, be interpreted as

$$
\begin{align*}
0 \rightarrow \mathcal{O}_{X} \rightarrow \mathbb{C}(X) & \rightarrow \underset{Y}{\oplus \underline{\underline{\operatorname{Hom}}}_{\mathcal{O}}^{Y}}\left(\Omega_{X / \mathbb{C}, Y}^{2}, \Omega_{\mathbb{C}(Y) / \mathbb{C}}^{1}\right)  \tag{A.14}\\
& \rightarrow \underset{x}{{\underline{\underline{\operatorname{Hom}^{c}}}}^{c}\left(\Omega_{X / \mathbb{C}, x}^{2}, \mathbb{C}\right) \rightarrow 0 .}
\end{align*}
$$

### 8.2 APPENDIX B: DUALITY AND THE DESCRIPTION OF $\underline{\underline{T}} Z^{1}(X)$ USING DIFFERENTIAL FORMS

In some ways the use of differential forms appropriately evaluated on tangent vectors to the space of cycles gives an especially good geometric picture. We have seen this for the case of 0-cycles, and we shall now discuss it for divisors on surfaces. Again we shall focus on the question of the geometric meaning of the kernel in (8.7).

Referring to Appendix A, upon choices of retractions for each irreducible curve $Y$ in $X$ there is defined a residue map

$$
\begin{equation*}
\left.\mathcal{P P}_{X} \xrightarrow{r} \underset{Y}{{\underset{\underline{\operatorname{Hom}}}{\mathcal{O}_{Y}}}\left(\Omega_{X / \mathbb{C}, Y}^{2}, \Omega_{\mathbb{C}(Y) / \mathbb{C})}^{1}\right)}\right) \tag{B.1}
\end{equation*}
$$

by setting for each $x \in Y \subset X, f \in \underset{\underline{\mathbb{C}}}{(X)}$ and $\omega \in \Omega_{X, \mathbb{C}, x}^{2}$

$$
\begin{equation*}
r(f)(\omega)=\underset{Y}{\oplus} \operatorname{Res}_{Y}(f \omega) \tag{B.2}
\end{equation*}
$$

where $\operatorname{Res}_{Y}(f \omega) \in \underline{\underline{\Omega}}_{\underline{C}(Y), x}^{1}$. Thinking of $\mathcal{P P}_{X}$ as $\underline{\underline{T}} Z^{1}(X)$, in simplest geometric terms the map (B.1) has the following interpretation: For the special
case of an irreducible curve $Y$ one way of giving a $1^{\text {st }}$ order deformation of $Y$ in $X$ is by a global section $\nu \in H^{0}\left(\operatorname{Hom}\left(\mathcal{J}_{Y} / \mathcal{J}_{Y}^{2}, \mathcal{O}_{Y}\right)\right)$. We may think of $\nu$ as a normal vector field to $Y$ over a Zariski open set, and then thinking also of $\nu$ as being the tangent to a $1^{\text {st }}$ order variation of $Y$ we have simply that

$$
\begin{equation*}
r(\nu)(\omega)=\nu\rfloor\left.\omega\right|_{Y} \tag{B.3}
\end{equation*}
$$

This is the case where under the provisional definition

$$
\mathcal{P P}_{X}=\underline{\underline{T}} Z^{1}(X)
$$

the principal part $[f]_{x} \in \mathbb{C}(X) / \mathcal{O}_{X, x}$ has only a $1^{\text {st }}$ order pole along $Y$ and $\operatorname{Res}_{Y}(f \omega)$ is the usual Poincaré residue. The (non-trivial) geometric content of (B.3) is that when we identify $\nu$ with the $1^{\text {st }}$-order variation of $Y$ given by $\operatorname{div}\left(g_{0}+t g_{1}\right)$ where $g_{0}$ is a local defining equation for $Y$ and $f=g_{1} / g_{0}$

$$
\nu\rfloor\left.\omega\right|_{Y}=\operatorname{Res}_{Y}(f \omega)
$$

The case where we have an $\operatorname{arc} Z_{t}$ in $Z^{1}(X)$ with

$$
\left\{\begin{array}{l}
Z_{0}=k Y_{0} \\
Z_{t}=Y_{1}(t)+\cdots+Y_{k}(t)
\end{array}\right.
$$

with the $Y_{i}(t)$ and $Y_{0}$ being irreducible curves stands in relation to the case just considered of one irreducible curve varying on the surface much as the situation of an irreducible Puiseaux series $z(t)=x_{1}(t)+\cdots+x_{k}(t)$ with $z(0)=k x$ stands in relation to a single point moving on a algebraic curve. Here, of course, higher order poles arise and for surfaces the use of retractions is necessary. The geometry underlying this is the following: In a Zariski open neighborhood $U$ of $Y_{0}$ there will be a rational vector field that in a smaller neighborhood $U^{*}$ is regular and induces a non-zero normal vector field along $Y^{*}=U^{*} \cap Y_{0}$. Thus $U^{*}$ is foliated and the leaves give locally in the analytic topology a map $U^{*} \rightarrow Y^{*}$. (This is generally not a rational map, since the integral curves of a rational vector field do not close up to algebraic curves.) Following an arc $\gamma$ on $Y_{0}$ as $t$ varies along an arc in the $t$-disc gives a 2-chain $\Gamma(t)$ in $U^{*}$. For $\omega \in \Omega_{X / \mathbb{C}, x}^{2}$ assumed to be regular in $U^{*}$, we may consider the "Abelian sum"

$$
\int_{\Gamma(t)} \omega
$$

Taking the derivative at $t=0$ gives an integral along $\gamma$

$$
\int_{\gamma} \tau(\omega)
$$

where $\tau(\omega)=\Omega_{\mathbb{C}(Y) / \mathbb{C}}^{1}$ is the value of the tangent vector

$$
\tau \in \operatorname{Hom}_{\mathcal{O}_{Y}}\left(\Omega_{X / \mathbb{C}, Y}^{2}, \Omega_{\mathbb{C}(Y) / \mathbb{C}}^{1}\right)
$$

applied to $\omega$ and restricted to the above arc in $Z^{1}(X)$. The point here is that in this case the map

$$
\underline{\underline{T}} Z^{1}(X) \rightarrow \underset{Y}{{\underset{\underline{H o m}}{ }}^{\mathcal{O}_{Y}}}\left(\Omega_{X / \mathbb{C}, Y}^{2}, \Omega_{\mathbb{C}(Y) / \mathbb{C}}^{1}\right)
$$

may be interpreted geometrically using calculus as "being basically like the case of points on a curve with dependence on an auxilary parameter." ${ }^{3}$ Thus, in a sense geometrically there is nothing essentially new beyond 0 -cycles on a curve. (Of course the use of retractions introduces non-intrinsic data, and it is instructive to check that the various descriptions of $\underline{T} Z^{1}(X)$ change in the same way when the non-intrinsic data is changed - cf. the "Afterword" to this section.)

Essentially new phenomena arise when for example we have an arc $Z_{t}$ in $Z^{1}(X)$ with

$$
\left\{\begin{array}{l}
Z_{t}=Y_{t} \text { an irreducible curve for } t \neq 0 \\
Z_{0}=Y_{0}^{\prime}+Y_{0}^{\prime \prime} \text { is a reducible curve }
\end{array}\right.
$$

Locally in the analytic topology, this is a special case of when we have a family of smooth curves acquiring a singularity. We shall discuss this by analyzing several examples. This will show the tangent $\tau$ always lies in

$$
\begin{equation*}
\operatorname{ker}\left\{\underset{Y}{\oplus \underline{\operatorname{Hom}}_{\mathcal{O}_{Y}}}\left(\Omega_{X / \mathbb{C}, Y}^{2}, \Omega_{\mathbb{C}(Y) / \mathbb{C}}^{1}\right) \rightarrow \underset{x}{\oplus \underline{\operatorname{Hom}}^{c}} \mathbb{C}\left(\Omega_{X / \mathbb{C}, x}^{2}, \mathbb{C}\right)\right\} \tag{B.4}
\end{equation*}
$$

and being in the kernel reflects limiting infinitesimal compatibility conditions (cf. the question below (8.7) above; this is what we are investigating using differential forms).

Suppose we have an $\operatorname{arc} Z_{t}$ in $Z^{1}(X)$ with tangent vector $\tau$. What does it mean that $\tau$ should be in the kernel (B.4)? Locally in the analytic topology, given $x \in X$ the 1-cycle $Z_{0}$ - assumed to be effective for this discussion will have several different irreducible analytic branches $Y_{i}$ passing through $x$, and some of the $Y_{i}$ may be singular at $x$. Given $\omega \in \Omega_{X / \mathbb{C}, x}^{2}$ and denoting by $\widetilde{Y}_{i} \rightarrow Y_{i}$ the normalization, the condition is

$$
\begin{equation*}
\sum \operatorname{Res}_{\widetilde{Y}_{i, x}}(\tau(\omega))=0 \tag{B.5}
\end{equation*}
$$

where the sum is over all of the inverse images on all the $\tilde{Y}_{i}$ of the point $x$. We shall first illustrate this for the two families

$$
\begin{equation*}
\xi \eta=t \tag{B.6a}
\end{equation*}
$$

and

$$
\begin{equation*}
\eta^{2}=\xi^{3}+t \tag{B.6b}
\end{equation*}
$$

which together with a third example given below illustrate the essential aspects of the phenomena that can arise.

The family (B.6a) may be pictured as


[^14]Here, $Y_{1}$ and $Y_{2}$ are the coordinate axes $\eta=0$ and $\xi=0$, and the arrows represent the normal vectors $\nu_{i}$ to the $Y_{i}$ that give the tangent to the family. Explicitly

$$
\begin{aligned}
\nu_{1} & =\frac{1}{\xi} \frac{\partial}{\partial \eta} \\
\nu_{2} & =\frac{1}{\eta} \frac{\partial}{\partial \xi}
\end{aligned}
$$

By our prescription (B.3), for $\omega=f(\xi, \eta) d \xi \wedge d \eta$ we have

$$
\left\{\begin{array}{l}
\left.\tau(\omega)\right|_{Y_{1}}=f(\xi, 0) \frac{d \xi}{\xi} \\
\left.\tau(\omega)\right|_{Y_{2}}=-f(0, \eta) \frac{d \eta}{\eta}
\end{array}\right.
$$

from which (B.3) is clear. Note that the singularity acquired by $Z_{t}$ produces a pole in $\tau(\omega)$. This is a geometrically distinct phenomenon from the poles produced by the singularities of the retraction when $k Y_{0}$ deforms into $Y_{1}(t)+$ $\cdots+Y_{k}(t)$ as above, when as in the curve case discussed in $\S 2$ we must take the residue of a rational form with a pole of order $k$ along $Y$.

For the family (B.6b), we shall use the alternate prescription discussed in earlier sections for computing $\tau .{ }^{4}$ Namely, in $\mathbb{C}^{3}$ with coordinates $(\xi, \eta, t)$ we consider the surface $S$ given by (B.6b). Then for $\omega=d \xi \wedge d \eta$ we have on $S$

$$
\left\{\begin{array}{l}
2 d \xi=3 \eta^{2} d \eta+d t \\
\omega=\frac{1}{2} \frac{d \eta}{\xi} \wedge d t
\end{array}\right.
$$

and this implies that

$$
\tau(\omega)=\frac{1}{2} \frac{d \eta}{\xi}
$$

Uniformizing the cusp in the usual way with parameter $\zeta$ gives

$$
\tau(\omega)=\frac{d \zeta}{\zeta^{2}}
$$

For $\omega=f(\xi, \eta) d \xi \wedge d \eta$ we have

$$
\tau(\omega)=\frac{f\left(\zeta^{3}, \zeta^{2}\right) d \zeta}{\zeta^{2}}
$$

Thus (B.3) is satisfied.
A final interesting example is when the variation smooths a reducible curve with a multiple component; e.g.

$$
\begin{equation*}
\xi^{2} \eta=t \tag{B.6c}
\end{equation*}
$$

Here, to find the answer one may replace the curve with a multiple component by one without such and take a limit

$$
\xi(\xi+\lambda) \eta=t
$$

[^15]Then as above, on $S$ and taking on the component $\eta=0$ the limit as $\lambda \rightarrow 0$ we have

$$
d \xi \wedge d \eta=\frac{d \xi \wedge d t}{\xi(\xi+\lambda)} \rightarrow \frac{d \xi}{\xi^{2}}
$$

The other component is more interesting: From

$$
\xi^{2}+\lambda \xi-\frac{1}{\eta}=0
$$

we have

$$
\xi=\frac{\lambda \pm \sqrt{\lambda^{2}-4 / \eta}}{2}
$$

and thus on $S$

$$
d \xi \wedge d \eta=\frac{ \pm d t \wedge d \eta}{\eta \sqrt{\lambda^{2} \eta^{2}-4 t}}
$$

and when we sum over the two values of the square root we get zero; i.e.,

$$
\tau(d \xi \wedge d \eta)=0
$$

However, by a similar computation

$$
\tau(\xi d \xi \wedge d \eta)=\left\{\begin{array}{c}
-\frac{d \xi}{\xi} \text { on } \eta=0 \\
\frac{d \eta}{\eta} \text { on } \xi=0
\end{array}\right.
$$

and again (B.3) is satisfied.
Summary: Upon choices of retractions for each irreducible curve $Y$ in $X$, and with the provisional definition (8.2) for $\underline{\underline{T}} Z^{1}(X)$, we have

$$
\begin{equation*}
\underline{\underline{T}} Z^{1}(X) \cong \operatorname{ker}\left\{\underset{Y}{\oplus \underline{\operatorname{Hom}}^{\mathcal{O}}}{ }_{Y}\left(\Omega_{X / \mathbb{C}, Y}^{2}, \Omega_{\mathbb{C}(Y) / \mathbb{C}}^{1}\right) \rightarrow \underset{x}{{\underset{\underline{\operatorname{Hom}}}{ }}_{c}^{C}}\left(\Omega_{X / \mathbb{C}, x}^{1}, \mathbb{C}\right)\right\} \tag{B.7}
\end{equation*}
$$

If $f \in \mathbb{C}(X)$ represents an element in $\underline{\underline{T}} Z^{1}(X)_{x}$, then the corresponding tangent vector has as image in the RHS of (B.7) the map

$$
\omega \rightarrow \operatorname{Res}_{Y}(f \omega), \quad \omega \in \Omega_{X / \mathbb{C}, x}^{2}
$$

Being in the kernel on the RHS represents compatibility conditions of the form $\sum$ Res $=0$ that arise when the local geometry of a family of divisors changes in the limit as $t \rightarrow 0$.

Afterword (not essential for what follows)
We will discuss the behaviour of the residue map under two sample changes of retraction and verify that the maps in (i) and (ii) below transform correctly.

Let $Y \subset X$ be an irreducible curve. Upon choice of a retraction of a Zariski neighborhood of $Y$, we have defined a mapping

$$
\underline{\underline{T}} Z^{1}(X) \rightarrow \operatorname{Hom}_{\mathcal{O}_{Y}}\left(\Omega_{X / \mathbb{C}, Y}^{2}, \Omega_{\mathbb{C}(Y) / \mathbb{C}}^{1}\right)
$$

In simplest terms this map goes as follows: There is the map

$$
\begin{equation*}
\underline{\mathbb{C}}(X) \rightarrow \underline{\underline{T}}^{1}(X) \tag{i}
\end{equation*}
$$

given in the provisional definition of $\underline{\underline{T}} Z^{1}(X)$, and composite of this and the above map

$$
\stackrel{\mathbb{C}}{=}(X) \rightarrow \operatorname{Hom}_{\mathcal{O}_{Y}}\left(\Omega_{X / \mathbb{C}, Y}^{2}, \Omega_{\mathbb{C}(X) / \mathbb{C}}^{1}\right)
$$

is given by

$$
f(\omega)=\operatorname{Res}_{Y}(f \omega), \quad \omega \in \Omega_{X / \mathbb{C}, x}^{2} .
$$

On the other hand, an arc $Z_{t}$ in $Z^{1}(X)$ with $Z_{0}=k Y$ may be though of as given by a divisor

$$
z \in X \times B
$$

with $\mathcal{Z} \cdot(X \times\{t\})=Z_{t}$. We may pull $\omega$ back to $X \times B$, restrict it to $z$ and write

$$
\left.\omega\right|_{z}=\varphi \wedge d t
$$

where $\varphi \in \Omega_{\mathbb{C}(Y) / \mathbb{C}}^{1} \cdot{ }^{5}$ This gives another map

$$
\begin{equation*}
\underline{\underline{T}} Z^{1}(X) \rightarrow \operatorname{Hom}_{\mathcal{O}_{Y}}\left(\Omega_{X / \mathbb{C}, Y}^{2}, \Omega_{\mathbb{C}(Y) / \mathbb{C}}^{1}\right), \tag{ii}
\end{equation*}
$$

and these maps agree after suitable identifications are made. However, it is instructive and a good consistency check to verify that they transform the same way when we change retractions.

Assume that we have local uniformizing parameters $\xi, \eta$ such that $Y$ is given locally by $\xi=0$. Since the case of $f \in \mathbb{C}(X)$ with a $1^{\text {st }}$ order pole along $Y$ corresponds to a Poincaré residue where no retraction is necessary, we consider

$$
f=\frac{A_{2}(\eta)}{\xi^{2}}+\frac{A_{1}(\eta)}{\xi}+\cdots
$$

(this is the case $k=2$ above). We take the family $Y_{t}$ to be given by

$$
\left\{\begin{array}{l}
\xi(t)=a_{1}(\eta) t^{1 / 2}+a_{2}(\eta) t \\
\eta(t)=\eta
\end{array}\right.
$$

For $\omega=\left(B_{0}(\eta)+B_{1}(\eta) \xi+\cdots\right) d \xi \wedge d \eta$
(iii) $\operatorname{Res} f \omega=\left(A_{2} B_{1}+A_{1} B_{0}\right) d \eta$.

On the other hand, the mapping (ii) above is given by substituting $\xi(t), \eta(t)$ in $\omega$ and taking the coefficient of $d t$. Denoting by $\dot{Y}$ the image in $\operatorname{Hom}_{\mathcal{O}_{Y}}\left(\Omega_{X / \mathbb{C}, Y}^{2}, \Omega_{\mathbb{C}(Y) / \mathbb{C}}^{1}\right)$ of the $1^{\text {st }}$-order variation of $Y$, this gives along $\xi=0$
(iv) $\quad \dot{Y}(\omega)=\left(2 B_{0} a_{2}+B_{1} a_{1}^{2}\right) d \eta$.

Comparing (iii) and (iv) we find, for the given retraction,

$$
\left\{\begin{array}{l}
A_{2}=a_{1}^{2}  \tag{v}\\
A_{1}=2 a_{2} .
\end{array}\right.
$$

We will consider two cases of a change of retraction.

[^16]
## Case 1:

$$
\begin{aligned}
& \xi=\xi^{\#} \\
& \eta=\eta^{\#}+e_{1}(\eta) \xi+\cdots .
\end{aligned}
$$

Computation gives

$$
\begin{align*}
& A_{2}^{\#}=A_{2} \\
& A_{1}^{\#}=A_{1}+e_{1} A_{2}^{\prime}, \tag{vi}
\end{align*}
$$

where both sides are considered as functions of $\eta^{\#}$ and ' denotes the derivative with respect to $\eta$, and also

$$
\omega=\left(B_{0}+\left(B_{0}^{\prime}+B_{1}+e_{1}^{\prime} B_{0}\right) \xi^{\#}\right) d \xi^{\#} \wedge d \eta^{\#}
$$

Then

$$
\operatorname{Res}_{Y} f^{\#} \omega^{\#}=\left[A_{2}\left(B_{1}+B_{0}^{\prime}-e_{1}^{\prime} B_{0}\right)+\left(e_{1} A_{2}^{\prime}+A_{1}\right) B_{0}\right] d \eta^{\#} .
$$

Another computation gives

$$
\begin{align*}
\xi^{\#}(t) & =a_{1} t^{1 / 2}+\left(a_{1} a_{1}^{\prime} e_{1}+a_{2}\right) t \\
a_{1}^{\#} & =a_{1}  \tag{viii}\\
a_{2}^{\#} & =a_{2}+a_{1} a_{1}^{\prime} e_{1} .
\end{align*}
$$

Comparing (v)-(vii) gives $A_{2}^{\#}=\left(a_{1}^{\#}\right)^{2}$ and

$$
\begin{aligned}
& A_{1}^{\#}=2 a_{2}^{\#}=2\left(a_{2}+a_{1} a_{1}^{\prime} e_{1}\right) \\
& A_{1}^{\#}=A_{1}+e_{1} A_{2}^{\prime}=2 a_{2}+2 e_{1} a_{1} a_{1}^{\prime}
\end{aligned}
$$

and we have agreement.
Case 2: For this we take

$$
\begin{aligned}
& \eta=\eta^{\#} \\
& \xi=c_{1} \xi^{\#}+c_{2} \xi^{\# 2}+\cdots, \quad c_{i}=c_{i}\left(\eta^{\#}\right) \text { and } c_{1} \neq 0 .
\end{aligned}
$$

Then computation gives

$$
\left\{\begin{array}{l}
A_{2}^{\#}=\frac{A_{2}}{c_{1}^{2}} \\
A_{1}^{\#}=\frac{A_{1}}{c_{1}}-2 \frac{c_{2} A_{2}}{c_{1}^{2}}
\end{array}\right.
$$

and

$$
\left\{\begin{array}{l}
a_{1}^{\#}=\frac{a_{1}}{c_{1}} \\
a_{2}^{\#}=\frac{a_{2}}{c_{1}}-\frac{c_{2} a_{1}^{2}}{c_{1}^{3}} .
\end{array}\right.
$$

As before, one verifies directly that we have agreement.
Conclusion: The use of a choice of retraction to give the identification (i), (ii) above transforms in such a way as to give a well-defined map

$$
\underline{\underline{T}} Z^{1}(X) \rightarrow \underset{Y}{\oplus \underline{\underline{H o m}}_{\mathcal{O}_{Y}}^{o}\left(\Omega_{X / \mathbb{C}, Y}^{2}, \Omega_{\mathbb{C}(Y) / \mathbb{C}}^{1}\right) . . . . .}
$$

Finally, we want to observe that the above discussion implies global existence result concerning the mapping (B.7). Namely, we have that
(B.8) The map

$$
\begin{aligned}
\underline{\underline{T}} Z^{1}(X) \rightarrow \operatorname{ker}\left\{\underset{Y \text { irred }}{\oplus} \stackrel{\text { Hom }_{\mathcal{O}_{Y}}}{ }\left(\Omega_{X / \mathbb{C}, Y}^{2}, \Omega_{\mathbb{C}(Y) / \mathbb{C}}^{1}\right)\right. \\
\left.\rightarrow \underset{x \in X}{\oplus}{\underline{\underline{\operatorname{Hom}^{c}}}}^{c}\left(\Omega_{X / \mathbb{C}, x_{i}}^{2}, \mathbb{C}\right)\right\}
\end{aligned}
$$

is surjective.
Again, we know this to be the case if we assume results from general duality theory. The geometric existence result is the surjectivity locally in the Zariski topology of the map

$$
\left\{\operatorname{arcs} \text { in } Z^{1}(X)\right\} \rightarrow \mathcal{P P}_{X}
$$

So the issue is not so much as to whether or not (B.8) is true as to understand it geometrically, which we now shall discuss. Concretely what is needed is to produce homomorphisms

$$
\begin{equation*}
\varphi_{i}: \Omega_{X, \mathbb{C}, x}^{2} \rightarrow \Omega_{\mathbb{C}\left(Y_{i}\right) / \mathbb{C}}^{1} \quad i=1, \cdots n \tag{B.9}
\end{equation*}
$$

where the $Y_{i}$ are algebraic curves passing through $x$ and where the images

$$
\varphi_{i}\left(\Omega_{X / \mathbb{C}, x_{i}}^{2}\right)
$$

have arbitrary poles subject only to the constraint in (B.8). Since poles can only be produced by families of curves acquiring "additional singularities" at $x,{ }^{6}$ the issue is one of having "sufficiently many degenerations".

Let $\xi, \eta \in \mathbb{C}(X)$ give local uniformizing parameters at $x$. We consider the family

$$
\xi^{k} \eta^{l}=t
$$

and the resulting homomorphisms (B.9) on the components $\xi=0$ and $\eta=0$ of the limit 1-cycle. To compute these maps we give the above family by

$$
z \subset X \times B
$$

and for $\omega \in \Omega_{X / \mathbb{C}, x}^{2}$ we map

$$
\left.\omega \longrightarrow \frac{\partial}{\partial t}\right\rfloor\left(\pi_{X}^{*} \omega \mid z\right)
$$

restricted to $t=0$. Up to irrelevant constants this gives

$$
\xi^{a} \eta^{b} d \xi \wedge d \eta \mapsto\left\{\begin{array}{l}
\eta^{b-l} d \eta \text { on } \xi=0 \text { if } a=k-1,0 \text { otherwise } \\
\xi^{a-k} d \xi \text { on } \eta=0 \text { if } b=l-1,0 \text { otherwise }
\end{array}\right.
$$

It follows that we can get arbitrary poles on $\xi=0$ and zero on $\eta=0$, and this implies the surjectivity of (B.8).

[^17]
### 8.3 DEFINITIONS OF $\underline{\underline{T}} Z_{1}^{1}(X)$ FOR $X$ A CURVE AND A SURFACE

To understand geometrically the space of divisors on an algebraic curve, one introduces the relation of linear equivalence $\sim$ and then the quotient Divisors modulo $\sim$ is the Jacobian variety of the curve. Infinitesimally, letting " $T$ " denote "passing to tangents", the subspace $T(\sim) \subset T$ (Divisors) is defined by the equations

$$
\begin{equation*}
\omega=0 \tag{8.9}
\end{equation*}
$$

where $\omega$ varies over the regular 1-forms on the curve.
To extend this picture to 0 -cycles on a surface $X$, we have defined $T Z^{2}(X)$ and now must define the subspace

$$
T Z_{\mathrm{rat}}^{2}(X) \subset T Z^{2}(X)
$$

of tangents to rational equivalences. By a rational equivalence on the surface $X$, we mean the following: Setting

$$
Z_{1}^{1}(X)=\underset{\substack{Y \\ Y \text { codim } 1 \\ Y \\ \text { irred }}}{\oplus} \mathbb{C}(Y)^{*}
$$

there is a natural map

$$
\begin{equation*}
Z_{1}^{1}(X) \xrightarrow{\text { div }} Z^{2}(X) \tag{8.10}
\end{equation*}
$$

given by

$$
\sum_{\nu}\left(Y_{\nu}, f_{\nu}\right) \rightarrow \sum_{\nu} \operatorname{div} f_{\nu}
$$

where $Y_{\nu}$ is an irreducible curve on $X$ and $f_{\nu} \in \mathbb{C}\left(Y_{\nu}\right)^{*}$ is a rational function on $Y_{\nu}$. The image of the map (8.10) will be denoted by $Z_{\text {rat }}^{2}(X)$, the subgroup of 0 -cycles that are rationally equivalent to zero. We will define the tangent space $T Z_{1}^{1}(X)$ and compute the differential

$$
\begin{equation*}
T Z_{1}^{1}(X) \rightarrow T Z^{2}(X) \tag{8.11}
\end{equation*}
$$

of the map (8.10). In section 8(iii) below, we will give the extension of (8.9) to 0 -cycles on surfaces thereby giving Hodge-theoretically the equations that define

$$
T Z_{\mathrm{rat}}^{2}(X)=\{\text { image of }(8.11)\}
$$

This latter point is important, because in contrast to the case of divisors on curves the map (8.10) is not injective. Its kernel, which we may think of as the irrelevant rational equivalences, enters into the definition of the higher Chow groups $C H^{2}(X, 1)$ and is the factor most likely responsible for the difficulty in proving some of the conjectures about rational equivalence in higher codimension, for the usual reason that it is hard to prove existence without a way to control the lack of uniqueness.

The main result of this paper will follow from the global consequences of the Cousin flasque resolution of $\Omega_{X / \mathbb{Q}}^{1}$ together with the following theorem, whose proof will be given below following the discussion of a number of examples that will show what is going on.
(8.12) Theorem: With the formal definition (8.14) below of the tangent sheaf $\underline{\underline{T}} Z_{1}^{1}(X)$, the maps that assign to an arc its tangent

$$
\left\{\operatorname{arcs} \text { in } \underset{\substack{Y(\underset{y}{Y} \text { codim } 1 \\ Y \text { irred }}}{\oplus} \xlongequal[C]{\mathbb{C}}(Y)^{*}\right\} \rightarrow \underline{T} Z_{1}^{1}(X)
$$

is surjective.
We emphasize that this is a geometric existence result, albeit one that is local in the Zariski topology and at the infinitesimal level.

We begin with the following
Definition: For $X$ a smooth algebraic variety of dimension n, we denote by $V^{p}(X)$ the set of irreducible codimension-p subvarieties of $X$ and define the sheaf

$$
\underline{\underline{Z}}_{q}^{p}(X)=\underset{Y \in V^{p}(X)}{\oplus} \underline{\underline{K}}_{q}(\mathbb{C}(Y)) .
$$

Here, $\underline{\underline{K}}_{q}(\mathbb{C}(Y))$ is the $q^{\text {th }} K$-group of the field $\mathbb{C}(Y)$ considered as a constant sheaf on $Y$ and extended to zero outside $Y$ (the proper notation would be $\left.\left(j_{Y}\right)_{*} \underline{\underline{K}}_{q}(\mathbb{C}(Y))\right)$. We also set

$$
Z_{q}^{p}(X)=H^{0}\left(\underline{\underline{Z}}_{q}^{p}(X)\right)
$$

As special cases we have

$$
\begin{equation*}
Z_{0}^{p}(X)=Z^{p}(X) \tag{i}
\end{equation*}
$$

$$
\begin{equation*}
\underline{\underline{Z}}_{1}^{1}(X)=\underset{x \in X}{\oplus} \underline{\underline{C}}_{x}^{*} \quad(\operatorname{dim} X=1) \tag{ii}
\end{equation*}
$$

and for any $n$

$$
\begin{equation*}
\underline{\underline{Z}}_{1}^{1}(X)=\underset{\substack{\underset{\begin{subarray}{c}{\text { codim } \\
Y \text { irred }} }}{\oplus}} \end{subarray} \underset{=}{\mathbb{C}}(Y)^{*} . . . . ~}{\text {. }} \tag{iii}
\end{equation*}
$$

Note that

$$
\begin{aligned}
Z_{1}^{1}(X) & =H^{0}\left(\underline{\underline{Z}}_{1}^{1}(X)\right) \\
& =\{\text { rational equivalences on } X \text { of codimension } 2 \text { cycles }\}
\end{aligned}
$$

Finally, we will denote by

$$
\underline{\underline{T}} Z_{q}^{p}(X)=: T \underline{\underline{Z}}_{q}^{p}(X)
$$

the tangent sheaf - to be defined below when $p=q=1$. By (i) above we have already defined $\underline{\underline{T}} Z_{0}^{1}(X)$ for any $n$ and $\underline{\underline{T}} Z_{0}^{2}$ for $n=2$.

We have also given in section 6(ii) a geometric definition of $\underline{\underline{T}} Z_{1}^{1}(X)$ when $X$ is a smooth algebraic curve. There we have explained how a set of geometric axioms for $1^{\text {st }}$ order equivalence of $\operatorname{arcs}$ in $Z_{1}^{1}(X)$ led to the defining relations for absolute Kähler differentials, thereby introducing $\Omega_{X / \mathbb{Q}}^{1}=\Omega_{\mathcal{O}(X) / \mathbb{Q}}^{1}$ into the picture (cf. (6.9)). The definition (6.8) of $\underline{\underline{T}} Z_{1}^{1}(X)$ may be expressed by (see below)

$$
\begin{equation*}
\underline{\underline{T}} Z_{1}^{1}(X)=\underset{x \in X}{\oplus} H_{x}^{1}\left(\Omega_{X / \mathbb{Q}}^{1}\right) \tag{8.13}
\end{equation*}
$$

and for a smooth algebraic surface $X$ we give the analogue

Definition: The tangent sheaf $\underline{\underline{T}} Z_{1}^{1}(X)$ is defined by

$$
\begin{equation*}
\underline{\underline{T}} Z_{1}^{1}(X)=\underset{\substack{Y \text { cooim 1 } \\ Y \text { irred }}}{\oplus} H_{y}^{1}\left(\Omega_{X / \mathbb{Q}}^{1}\right) \tag{8.14}
\end{equation*}
$$

where $y$ is the generic point of $Y$.
To justify this definition we check that (8.13) coincides with (6.8) in the curve case. The stalk at $x$ of (8.13) is

$$
\lim _{k} \mathcal{E} x t_{\mathcal{O}_{X}}^{1}\left(\mathcal{O}_{X} / \mathfrak{m}_{x}^{k}, \Omega_{X / \mathbb{Q}}^{1}\right)
$$

If $\xi$ is a local uniformizing parameter centered at $x$, then an element of this group is given by

$$
\left\{\begin{array}{l}
F_{1} \xrightarrow{\xi^{k}} F_{0} \longrightarrow \mathcal{O}_{X} / \mathfrak{m}_{x}^{k} \\
F^{1} \xrightarrow{\psi} \Omega_{X / \mathbb{Q}, x}^{1}
\end{array} \quad\left(F_{1}, F_{0} \cong \mathcal{O}_{X, x}\right)\right.
$$

This maps to $\operatorname{Hom}^{o}\left(\Omega_{X / \mathbb{Q}, x}^{1}, \Omega_{\mathbb{C} / \mathbb{Q}}^{1}\right)$ by

$$
\varphi \mapsto \operatorname{Res}_{x}\left(\frac{\psi \wedge \varphi}{\xi^{k}}\right)
$$

Here the residue of a form in $\mathbb{C}(X) \otimes \Omega_{X / \mathbb{Q}, x}^{2}$ is defined as in section 6 (iii). If $\varphi=f \alpha$ where $f \in \mathcal{O}_{X, x}$, then clearly

$$
f \alpha \mapsto \operatorname{Res}_{x}\left(\frac{f \psi}{\xi^{k}}\right) \alpha=\varphi_{0}(f) \alpha
$$

where $\varphi_{0}(f)$ is defined by the term in the parentheses, and so we have a well-defined map

$$
\begin{equation*}
\lim _{k} \mathcal{E} x t_{\mathcal{O}_{X}}^{1}\left(\mathcal{O}_{X} / \mathfrak{m}_{x}^{k}, \Omega_{X / \mathbb{Q}}^{1}\right) \rightarrow \operatorname{Hom}^{o}\left(\Omega_{X / \mathbb{Q}, x}^{1}, \Omega_{\mathbb{C} / \mathbb{Q}}^{1}\right) \tag{8.15}
\end{equation*}
$$

We may see that (8.15) is an isomorphism as follows: Using the exact sequence

$$
0 \rightarrow \mathcal{O}_{X, x} \otimes \Omega_{\mathbb{C} / \mathbb{Q}}^{1} \xrightarrow{i} \Omega_{X / \mathbb{Q}, x}^{1} \rightarrow \Omega_{X / \mathbb{C}, x}^{1} \rightarrow 0
$$

and the fact that, by definition, the inclusion $i$ induces the map

$$
\operatorname{Hom}^{o}\left(\Omega_{X / \mathbb{Q}, x}^{1}, \Omega_{\mathbb{C} / \mathbb{Q}}^{1}\right) \rightarrow \operatorname{Hom}^{c}\left(\mathcal{O}_{X, x}, \mathcal{O}_{X, x}\right) \otimes \operatorname{Id}_{\Omega_{\mathbb{C} / \mathbb{Q}}}
$$

we are reduced to showing that

$$
\lim _{k} \mathcal{E} x t_{\mathcal{O}_{X}}^{1}\left(\mathcal{O}_{X} / \mathfrak{m}_{x}^{k}, \mathcal{O}_{X}\right) \otimes \Omega_{\mathbb{C} / \mathbb{Q}}^{1} \cong \operatorname{Hom}^{c}\left(\Omega_{X / \mathbb{C}, x}^{1}, \mathbb{C}\right) \otimes \Omega_{\mathbb{C} / \mathbb{Q}}^{1}
$$

and

$$
\lim _{k} \varepsilon x t_{\mathcal{O}_{X}}^{1}\left(\Omega_{X / \mathbb{C}}^{1} / \mathfrak{m}_{x}^{k} \Omega_{X / \mathbb{C}}^{1}, \mathcal{O}_{X}\right) \cong \operatorname{Hom}^{c}\left(\mathcal{O}_{X, x}, \mathbb{C}\right)
$$

both of which follow from local duality (and of course may be checked directly). Thus for curves the definition (8.13) agrees with the definition (6.8) given earlier.

To justify the definition (8.14) we need to discuss the geometry behind it. One very interesting point is that based on the discussion in section 8(i) above, one might think that the general analogue of

$$
\begin{equation*}
\underline{\underline{T}} Z_{0}^{1}(X)=\lim _{\substack{Z \text { codim } \\ \text { subscheme }}} \mathcal{E x} t_{\mathcal{O}_{X}}^{1}\left(\mathcal{O}_{Z}, \mathcal{O}_{X}\right) \tag{8.16}
\end{equation*}
$$

would be to define

$$
\begin{equation*}
\underline{\underline{T}} Z_{1}^{1}(X)=\lim _{\substack{Z \text { codim } 1 \\ \text { subscheme }}} \mathcal{E} x t_{\mathcal{O}_{X}}^{1}\left(\mathcal{O}_{Z}, \Omega_{X / \mathbb{Q}}^{1}\right) . \tag{8.17}
\end{equation*}
$$

But for interesting geometric reasons this is not correct. As discussed above in section 8(i) and in Appendix B, definition (8.16) reflects compatibility conditions that arise when a reducible curve smooths to an irreducible one. However, such compatibility conditions do not arise for $\operatorname{arcs}$ in $Z_{1}^{1}(X)$. For example, consider the arc

$$
\left(\xi \eta=t,\left.\frac{\xi^{2}+\eta^{2}}{\xi^{2}-\eta^{2}}\right|_{\xi \eta=t}\right)
$$

in $\underset{Y}{\oplus} \mathbb{C}(Y)^{*}$. We are working locally in the Zariski topology where $\xi, \eta \in \mathcal{O}_{X, x}$ give local uniformizing parameters. The $1^{\text {st }}$ component is the irreducible curve $Y_{t}$ (or sum of curves at $t=0$ ) given by $\xi \eta=t$, and the second component is the designated function in $\mathbb{C}\left(Y_{t}\right)^{*}$. At $t=0$ we get the sum

$$
(\xi=0,-1)+(\eta=0,+1)
$$

in $\underset{Y}{\oplus} \mathbb{C}(Y)^{*}$. At the point of intersection the limit functions do not agree, and hence there are no compatibility conditions. Below, this point will be further discussed and illustrated by differential form calculations. Remark that the RHS of (8.17) is equal to

$$
T\left(\operatorname{ker}\left(\underline{\underline{Z}}_{1}^{1}(X) \xrightarrow{\text { div }} \underline{\underline{Z}}^{2}(X)\right)\right) .
$$

Thus

$$
\lim _{\substack{Z \\
\left\{\begin{array}{c}
\text { codim } \\
Z \text { subscheme }
\end{array}\right.}} \mathcal{E} x t_{\mathcal{O}_{X}}^{1}\left(\mathcal{O}_{Z}, \Omega_{X / \mathbb{Q}}^{1}\right)
$$

turns up naturally when one is trying to understand geometrically the tangent spaces to the higher Chow groups.

Before turning to the differential form calculations we shall amplify the definition (8.14) and give a useful expression for calculating the tangent to an arc in $Z_{1}^{1}(X)$ which is given by equations.

By definition of local cohomology, we may alternatively give (8.14) as

$$
\underline{\underline{T}} Z_{1}^{1}(X)=\underset{\substack{Y \text { codim 1 }  \tag{8.18}\\
Y \text { irred }}}{\oplus} \lim _{\left\{\begin{array}{c}
U \text { a Zariski } \\
\text { open with } U \cap Y \neq \phi
\end{array}\right.} \lim _{k \rightarrow \infty} \mathcal{E x} t_{\mathcal{O}_{U}}^{1}\left(\mathcal{O}_{U} / \mathcal{J}_{Y}^{k}, \Omega_{U / \mathbb{Q}}^{1}\right)
$$

An element in the stalk at $x \in X$ of the term corresponding to an irreducible curve $Y$ passing through $x$ and with $f \in \mathcal{O}_{X, x}$ generating $\mathcal{J}_{Y, x}$ may be described by the data

$$
\left\{\begin{array}{l}
F_{1} \xrightarrow{f^{k}} F_{0} \rightarrow \mathcal{O}_{X} / \mathcal{J}_{Y}^{k}  \tag{8.19}\\
F_{1} \xrightarrow{g} \Omega_{X / \mathbb{Q}}^{1}
\end{array} \quad F_{0}, F_{1} \cong \mathcal{O}_{X}\right.
$$

where $g \in \mathbb{C}(X)_{x}$ does not have $Y$ as a component of its polar locus - this is entirely analogous to the description of $H_{y}^{1}\left(\mathcal{O}_{Y}\right)$ used in $\underline{\underline{T}} Z^{1}(X)$.

We now turn to the description of the tangent map. For this we give an arc in $Z_{1}^{1}(X)$ by

$$
\left(\operatorname{div}(f+t \dot{f}),\left.(g+t \dot{g})\right|_{\operatorname{div}(f+t \dot{f})}\right)
$$

The first factor describes an arc in the space of 1-cycles, and the second factor gives rational functions on the irreducible components of div $(f+t \dot{f})$. Suppose now that $f \in \mathcal{O}_{X, x}$ with div $f=k Y$ where $Y$ is an irreducible curve. Then an element of $\mathcal{E x} t_{\mathcal{O}_{X}}^{1}\left(\mathcal{O}_{X} / \mathcal{J}_{Y}^{k}, \Omega_{X / \mathbb{Q}}^{1}\right)_{x}$ is given by the data (8.19)

$$
\left\{\begin{array}{l}
F_{1} \xrightarrow{f} F_{0} \longrightarrow \mathcal{O}_{X} / \mathcal{J}_{Y}^{k}  \tag{8.20}\\
F_{1} \xrightarrow{\frac{\dot{g}}{g} d f-\dot{f} \frac{d g}{g}} \Omega_{X / \mathbb{Q}}^{1}
\end{array}\right.
$$

where $\frac{\dot{g}}{g} d f-\dot{f} \frac{d g}{g} \in \Omega_{\mathbb{C}(X) / \mathbb{Q}}^{1}$ has polar locus not containing $Y$. This description of the tangent map will agree with the one using differential forms when the appropriate identifications are made.

We now explain what is necessary to show that, on the sheaf level and with the definition (8.14), what is necessary to establish the surjectivity of the tangent map

$$
\begin{equation*}
\left\{\operatorname{arcs} \text { in } Z_{1}^{1}(X)\right\} \rightarrow \underline{\underline{T}} Z_{1}^{1}(X) \tag{8.21}
\end{equation*}
$$

Namely, let $x \in X$ and set

$$
\left.\Omega_{X / \mathbb{Q}}^{1}\right|_{x}=\Omega_{X / \mathbb{Q}, x}^{1} / \mathfrak{m}_{x} \Omega_{X / \mathbb{Q}, x}^{1}
$$

Let $Y$ be an irreducible curve with $x \in Y$. Then in (8.20) the differential form $(\dot{g} d f-\dot{f} d g) / g$ gives by restriction along $Y$ and evaluation at $x$ an element

$$
\left.\left.\frac{1}{g}(\dot{g} d f-\dot{f} d g)\right|_{x} \in \mathbb{C}(Y) \otimes \Omega_{X / \mathbb{Q}}^{1}\right|_{x}
$$

After an illustrative discussion we shall give a proof of the
(8.22) Theorem: The mapping

$$
\underset{Y}{\oplus}\left\{\left.(\dot{f}, \dot{g}) \mapsto \frac{1}{g}(\dot{g} d f-\dot{f} d g)\right|_{x}\right\} \in \underset{Y}{\oplus}\left\{\left.\mathbb{C}(Y) \otimes \Omega_{X / \mathbb{Q}}^{1}\right|_{x}\right\}
$$

is surjective.
Here there is a crucial geometric subtlety:
In (8.22) one must use the direct sum over all irreducible curves $Y$ to have surjectivity; for a fixed $Y$ the map fails to be surjective.

Concretely, for smooth $Y$ if we only deform $Y$ to nearly smooth curves we will end up only in part of $\left.\mathbb{C}(Y) \otimes \Omega_{Y / \mathbb{Q}, x}^{1}\right|_{x}$; to produce forms whose restriction to $Y$ have poles at $x$ we must deform $Y$ into a reducible curve (see below for the proof). When this happens the notation

$$
(\dot{f}, \dot{g}) \rightarrow \underset{Y}{\oplus}\left\{\left.\frac{1}{g}(\dot{g} d f-\dot{f} d g)\right|_{x}\right\}
$$

needs explanation, which also will be given in equation (vii) below.
Before turning to the formal proof of (8.22), we will continue in our discussion of the geometry behind the definition (8.14)
 using differential forms gives a good way of understanding this. W individual terms in (8.14) as $H_{y}^{1}\left(\Omega_{X / \mathbb{Q}}^{1}\right)$ and, after choosing for each $Y$ a retraction as explained in Appendix A, use local duality to re-express these terms as

$$
\begin{equation*}
\operatorname{Hom}_{{O_{Y}}^{o}}\left(\Omega_{X / \mathbb{Q}, Y}^{2} / \Omega_{\mathbb{C} / \mathbb{Q}}^{2}, \Omega_{\mathbb{C}(Y) / \mathbb{C}}^{1} \otimes \Omega_{\mathbb{C} / \mathbb{Q}}^{1}\right) . \tag{8.23}
\end{equation*}
$$

Here, $\operatorname{Hom}_{\mathcal{O}_{Y}}^{o}(\cdot, \cdot)$ has the following meaning: There is an inclusion

$$
\Omega_{X / \mathbb{C}, Y}^{1} \otimes \Omega_{\mathbb{C} / \mathbb{Q}}^{1} \hookrightarrow \Omega_{X / \mathbb{Q}, Y}^{2} / \Omega_{\mathbb{C} / \mathbb{Q}}^{2}
$$

arising from the exact sequence

$$
0 \rightarrow \Omega_{\mathbb{C} / \mathbb{Q}}^{1} \otimes \mathcal{O}_{X} \rightarrow \Omega_{X / \mathbb{Q}}^{1} \rightarrow \Omega_{X / \mathbb{C}}^{1} \rightarrow 0 .
$$

Then

$$
\varphi: \Omega_{X / \mathbb{Q}, Y}^{2} / \Omega_{\mathbb{C}, \mathbb{Q}}^{2} \rightarrow \Omega_{\mathbb{C}(Y) / \mathbb{C}}^{1} \otimes \Omega_{\mathbb{C} / \mathbb{Q}}^{1}
$$

is in $\operatorname{Hom}_{\mathcal{O}_{Y}}^{o}(\cdot, \cdot)$ if it is $\mathcal{O}_{Y}$-linear and if for $\omega \in \Omega_{X / \mathbb{C}, Y}^{1}$ and $\alpha \in \Omega_{\mathbb{C} / \mathbb{Q}}^{1}$

$$
\varphi(\omega \otimes \alpha)=\varphi^{0}(\omega) \otimes \alpha
$$

for some $\mathcal{O}_{Y}$-linear map

$$
\begin{equation*}
\varphi^{0}: \Omega_{X / \mathbb{C}, Y}^{1} \rightarrow \Omega_{\mathbb{C}(Y) / \mathbb{C}}^{1} . \tag{8.24}
\end{equation*}
$$

Using (8.23) in (8.14) we thus have, upon choice of retractions,

Although the notation is a bit complicated, this identification contains a lot of geometry. We shall illustrate this through several examples and special cases.
(a) One of the equivalent prescriptions for computing the tangent map

$$
\begin{equation*}
\operatorname{arcs} \text { in } Z_{1}^{1}(X) \rightarrow \underline{\underline{T}} Z_{1}^{1}(X) \tag{8.26}
\end{equation*}
$$

is the following: Let $B$ denote the parameter curve with parameter $t \in B$ and represent an arc in $Z_{1}^{1}(X)$ by a codimension-two cycle

$$
Z \subset X \times \mathbb{P}^{1} \times B
$$

where

$$
z \cdot\left(X \times \mathbb{P}^{1} \times\{t\}\right)=\sum_{i} n_{i}\left(Y_{i, t}, f_{i, t}\right)
$$

with the $Y_{i, t}$ being irreducible curves, and $f_{i, t} \in \mathbb{C}\left(Y_{i, t}\right)^{*}$, and where $\left(Y_{i, t}, f_{i, t}\right)$ is the graph of $f_{i, t}$ in $X \times \mathbb{P}^{1}$. To compute the image of this curve in the stalk at $x \in X$ of this arc in $Z_{1}^{1}(X)$, we let $u \in \mathbb{C}^{*} \subset \mathbb{P}^{1}$ be a standard coordinate and $\omega \in \Omega_{X / \mathbb{Q}, x}^{2}$. We then write

$$
\left.\omega \wedge \frac{d u}{u}\right|_{z}=\tau(\omega) \wedge d t
$$

and the map (8.26) is given by

$$
\begin{equation*}
\left.\omega \rightarrow \tau(\omega)\right|_{t=0} \tag{8.27}
\end{equation*}
$$

Here, the notation $\left.\tau(\omega)\right|_{t=0}$ is understood as follows: If $Y_{i}$ are the components in $X$ of $\mathcal{Z} \cdot\left(X \times \mathbb{P}^{1} \times\{0\}\right)$, then the restriction of $\tau(\omega)$ to $Y_{i}$ is in $\Omega_{\mathbb{C}\left(Y_{i}\right) / \mathbb{Q}}^{2}$. Since $Y_{i}$ is an algebraic curve, there is for dimension reasons a natural map

$$
\Omega_{\mathbb{C}\left(Y_{i}\right) / \mathbb{Q}}^{2} \rightarrow \Omega_{\mathbb{C}\left(Y_{i}\right) / \mathbb{C}}^{1} \otimes \Omega_{\mathbb{C} / \mathbb{Q}}^{1}
$$

and the image of $\tau(\omega)$ under this map is what is meant by (8.27).
There is one caveat to this prescription. Namely, we may have $d t=0$ along some of the components of $Z \cdot\left(X \times \mathbb{P}^{1} \times\{0\}\right)$. When this happens

$$
\partial / \partial t\rfloor\left(\left.\omega \wedge \frac{d u}{u}\right|_{z}\right)
$$

will have a pole on the projection to $X$ of that component, so that (8.27) is not defined. What one does in this case is to perturb $Z$ to a family $\mathcal{Z}_{\lambda}$ where $z_{0}=z$ and where (8.27) is well-defined for $\lambda \neq 0$, and then one takes the limit of (8.27) as $\lambda \rightarrow 0$ (essentially this is l'Hospital's rule). This procedure will be illustrated by example below.

Remark that this last phenomenon corresponds (also see below) to the case of taking the residue of a form with a higher order pole along a curve. It is here that the retraction is used and this corresponds to making a perturbation as described above. All of this will be quite clear in the example below.
(b) We may define a map

$$
\begin{equation*}
\Omega_{\mathbb{C}(X) / \mathbb{Q}}^{1} \xrightarrow{d T} \underset{Y}{\oplus \text { Hom }_{\mathcal{O}_{Y}}^{o}}\left(\Omega_{X / \mathbb{Q}, Y}^{2} / \Omega_{\mathbb{C} / \mathbb{Q}}^{2}, \Omega_{\mathbb{C}(Y)}^{1} \otimes \Omega_{\mathbb{C} / \mathbb{Q}}^{1}\right) \tag{8.28}
\end{equation*}
$$

by sending, for $\psi \in \Omega_{\mathbb{C}(X) / \mathbb{Q}}^{1}$ and $\omega \in \Omega_{X / \mathbb{Q}, Y}^{2}$,

$$
\psi \otimes \omega \longrightarrow \operatorname{Res}_{Y}(\psi \wedge \omega)
$$

Here the residue is defined as in $\S 6$ (iii) extended one dimension up and using the retraction as in $\S 8(\mathrm{i})$ above.
(8.29) Proposition: Using the identification (8.25) and (cf. the Appendix to section 6)

$$
\underline{\underline{T}} K_{2}(\mathbb{C}(X)) \cong \Omega_{\mathbb{C}(X) / \mathbb{Q}}^{1}
$$

the map (8.28) may be identified with the differential of the tame symbol.
We have in §6(iii) given a proof of this one dimension down. We shall give a different argument based upon (8.20) and shall then illustrate it in an example that exhibits phenomena not encountered in the curve case. From this the result should be clear.

An arc in $K_{2}(\mathbb{C}(X))$ is given by $\{f+t \dot{f}, g+t \dot{g}\}$ where $f, \dot{f}, g, \dot{g} \in \mathbb{C}(X)$, and where we assume that the divisors of $f+t \dot{f}$ and $g+t \dot{g}$ have no curve components in common. Then the tame symbol is given by

$$
\{f+t \dot{f}, g+t \dot{g}\} \rightarrow g+\left.t \dot{g}\right|_{\operatorname{div}(f+t \dot{f})}-f+\left.t \dot{f}\right|_{\operatorname{div}(g+t \dot{g})}
$$

From (6.10), the tangent to this arc in

$$
\underset{\{\substack{Y \text { codim 1 } \\ Y \text { irred }}}{\oplus} H_{y}^{1}\left(\Omega_{X / \mathbb{Q}}^{1}\right)
$$

is the sum of

$$
\left\{\begin{array}{l}
F_{1} \xrightarrow{f} F_{0} \rightarrow \mathcal{O}_{X} /(f) \\
F_{1} \xrightarrow{\frac{\dot{g}}{g} d f-\dot{f} \frac{d g}{g}} \Omega_{X / \mathbb{Q}}^{1}
\end{array} \quad\left(F_{1}, F_{0} \cong \mathcal{O}_{X}\right)\right.
$$

and

$$
\left\{\begin{array}{l}
F_{1}^{\prime} \xrightarrow{g} F_{0}^{\prime} \rightarrow \mathcal{O}_{X} /(g) \\
F_{1}^{\prime} \xrightarrow{-\frac{f}{f} d g+\dot{g} \frac{d f}{f}} \Omega_{X / \mathbb{Q}}^{1}
\end{array}\right.
$$

Here, to be precise we should work in a Zariski neighborhood of a point $x \in X$, factor $f, g$ into irreducible factors in $\mathcal{O}_{X, x}$ and by the methods used in the Appendix to section 6 write the symbol $\{f+t \dot{f}, g+t \dot{g}\}$ as a product of symbols with constant $t$-terms in $\mathcal{O}_{X, x}$.

On the other hand, from the discussion in that Appendix the tangent to the arc $\{f+t \dot{f}, g+t \dot{g}\}$ in $K_{2}(\mathbb{C}(X))$ is

$$
\frac{\dot{g}}{g} \frac{d f}{f}-\frac{\dot{f}}{f} \frac{d g}{g} \in \Omega_{\mathbb{C}(X) / \mathbb{Q}}^{1}
$$

Under the map

$$
\underline{\underline{\Omega}}_{\mathbb{C}(X) / \mathbb{Q}}^{1} \rightarrow \underset{\substack{Y \text { codim } \\ Y \text { irred }}}{\oplus} \underline{H}_{y}^{1}\left(\Omega_{X / \mathbb{Q}}^{1}\right)
$$

this maps to the same element as given above.
Before turning to the example, it is useful to compute in this notation the differential of

$$
\left\{\underset{\substack{Y \text { codim } 1 \\ Y \text { irred }}}{\oplus} \mathbb{C}(Y)^{*} \rightarrow \underset{x \in X}{\oplus} \underset{=}{\mathbb{Z}},\right.
$$

which maps the $\operatorname{arc} g+\left.t \dot{g}\right|_{\operatorname{div}(f+t \dot{f})}$ in the $1^{\text {st }}$ term to the $\operatorname{arc} \operatorname{Var}(g+t \dot{g}, f+t \dot{f})$ in the second. Again, localizing at $x \in X$ and assuming that $f, g \in \mathcal{O}_{X, x}$ are relatively prime, the tangent to the $1^{\text {st }}$ arc in $\underset{Y}{\oplus} H_{y}^{1}\left(\Omega_{X / \mathbb{Q}}^{1}\right)_{x}$ is

$$
\left\{\begin{array}{l}
F_{1} \xrightarrow{f} F_{0} \rightarrow \mathcal{O}_{X} /(f) \\
F_{1} \xrightarrow{\frac{\dot{g}}{g} d f-\frac{\dot{f} d g}{g}} \Omega_{X / \mathbb{Q}}^{1}
\end{array}\right.
$$

Under the natural map

$$
\underset{Y}{\oplus} \underline{\underline{H}}_{y}^{1}\left(\Omega_{X / \mathbb{Q}}^{1}\right) \rightarrow \underset{x \in X}{\oplus} \underline{\underline{H}}_{x}^{2}\left(\Omega_{X / \mathbb{Q}}^{1}\right)
$$

in the Cousin flasque resolution, this maps to

$$
\left\{\begin{array}{l}
E_{2} \xrightarrow{\left({ }_{-f}^{g}\right)} E_{1} \xrightarrow{(f g)} E_{0} \rightarrow \mathcal{O}_{X} /(f, g) \quad\left(E_{2}, E_{0} \cong \mathcal{O}_{X}, E_{1} \cong \mathcal{O}_{X}^{2}\right) \\
E_{2} \xrightarrow{\dot{g} d f-\dot{f} d g} \Omega_{X / \mathbb{Q}}^{1} .
\end{array}\right.
$$

On the other hand, the family

$$
z_{t}=\operatorname{Var}(f+t \dot{f}, g+t \dot{g})
$$

has a minimal free resolution

$$
E_{2}^{\prime} \xrightarrow{\binom{g+t \dot{g}}{-f-t \dot{f}}} E_{1}^{\prime} \xrightarrow{(f+t \dot{f}, g+t \dot{g})} E_{0}^{\prime} \rightarrow \mathcal{O}_{z_{t}} \quad\left(E_{2}^{\prime}, E_{0}^{\prime} \cong \mathcal{O}_{X}, E_{1}^{\prime} \cong \mathcal{O}_{X}^{2}\right)
$$

By the prescription in section 7, its tangent is the $d t$ coefficient of

$$
\frac{1}{2}(d(f+t \dot{f}), d(g+t \dot{f}))\binom{d(g+t \dot{g})}{-d(f+t \dot{f})}
$$

which is

$$
E_{2}^{\prime} \xrightarrow{\dot{g} d f-\dot{f} d y} \Omega_{X / \mathbb{Q}}^{1}
$$

in agreement with the above.
Summary: These calculations show that the differentials of the maps in the Bloch-Gersten-Quillen sequence

$$
\underline{\underline{K}}_{2}(\mathbb{C}(X)) \xrightarrow{T} \underset{Y}{\oplus} \underline{\mathbb{C}}(Y)^{*} \rightarrow \underset{x \in X}{\oplus} \underline{\underline{Z}}_{x}
$$

are the maps in the Cousin flasque sequence

$$
\underline{\underline{\Omega}}_{\underline{C}(X) / \mathbb{Q}}^{1} \rightarrow \underset{Y}{\oplus} \underline{\underline{H}}_{y}^{1}\left(\Omega_{X / \mathbb{Q}}^{1}\right) \rightarrow \underset{x \in X}{\oplus} \underline{\underline{H}}_{x}^{2}\left(\Omega_{X / \mathbb{Q}}^{1}\right)
$$

Proposition: The tangent sequence to the Bloch-Gersten-Quillen sequence

$$
0 \rightarrow K_{2}\left(\mathcal{O}_{X}\right) \rightarrow \underline{\underline{K}}_{2}(\mathbb{C}(X)) \rightarrow \underset{Y}{\oplus} \underline{\underline{\mathbb{C}}}(Y)^{*} \rightarrow \underset{x \in X}{\oplus} \underline{\underline{Z}}_{x} \rightarrow 0
$$

is the Cousin flasque resolution of $\Omega_{X / \mathbb{Q}}^{1}$

$$
0 \rightarrow \Omega_{X / \mathbb{Q}}^{1} \rightarrow \underline{\underline{\Omega}}_{\mathbb{C}(X) / \mathbb{Q}}^{1} \rightarrow \underset{Y}{\oplus} \underline{\underline{H}}_{y}^{1}\left(\Omega_{X / \mathbb{Q}}^{1}\right) \rightarrow \underset{x \in X}{\oplus} \underline{\underline{H}}_{x}^{2}\left(\Omega_{X / \mathbb{Q}}^{1}\right) \rightarrow 0
$$

Here, we have defined the tangent sheaf to each of the terms in the top sequence, and the proposition states that these may be naturally identified with the terms in the bottom sequence.

We now turn to an example that illustrates phenomena that do not occur in the curve case.

Example: We consider the curve

$$
\left\{\xi^{2}+t, \eta\right\}
$$

in $K_{2}(\mathbb{C}(X))$ where $\xi, \eta \in \mathbb{C}(X)$ give local uniformizing parameters on a Zariski open set in $X$. From the discussion in the Appendix to section 6, the tangent to this curve is

$$
\frac{d \eta}{\xi^{2} \eta} \in \Omega_{\mathbb{C}(X) / \mathbb{Q}}^{1}
$$

We first compute

$$
\operatorname{Res}_{Y_{i}}\left(\frac{d \eta}{\xi^{2} \eta} \wedge \omega\right)
$$

on the components $Y_{0}=\{\eta=0\}$ and $Y_{1}=\{\xi=0\}$ of the polar locus of the form in parenthesis. We will only get something non-zero in case

$$
\omega=f(\xi, \eta) d \xi \wedge d \alpha
$$

where $d \alpha \in \Omega_{\mathbb{C} / \mathbb{Q}}^{1}$. Then

$$
\left\{\begin{array}{l}
\operatorname{Res}_{Y_{0}}\left(\frac{d \eta}{\eta} \wedge \frac{f(\xi, \eta) d \xi \wedge d \alpha}{\xi^{2}}\right)=\frac{f(\xi, 0)}{\xi^{2}} d \xi \wedge d \alpha \\
\operatorname{Res}_{Y_{1}}\left(\frac{d \xi}{\xi^{2}} \wedge \frac{f(\xi, \eta) d \eta \wedge d \alpha}{\eta}\right)=\frac{f_{\xi}(0, \eta)}{\eta} d \eta \wedge d \alpha
\end{array}\right.
$$

Taking into acocunt signs the final result is

$$
\begin{equation*}
\frac{f(\xi, 0)}{\xi^{2}} d \xi \wedge d \alpha-\frac{f_{\xi}(0, \eta)}{\eta} d \eta \wedge d \alpha \tag{8.30}
\end{equation*}
$$

On the other hand, applying the tame symbol $T$ to the above arc in $K_{2}(\mathbb{C}(X))$ we obtain

$$
\begin{equation*}
\left(\eta=0, \xi^{2}+t\right)-\left(\xi^{2}+t, \eta\right) \tag{8.31}
\end{equation*}
$$

To compute the tangent to this arc in $Z_{1}^{1}(X)$ we shall use (a) above. For this we let the curve $B$ have parameter $t$ and consider at the codimension- 2 cycle

$$
\mathcal{Z} \subset X \times \mathbb{P}^{1} \times B
$$

given by (8.31). As before we need only consider $\omega$ 's of the form $\omega=$ $f(\xi, \eta) d \xi \wedge d \alpha$ where $d \alpha \in \Omega_{\mathbb{C} / \mathbb{Q}}^{1}$. The prescription in (a) is to take $u \in$ $\mathbb{C}^{*} \subset \mathbb{P}^{1}$ as coordinate and then take the restriction to $t=0$ of

$$
\left.\frac{\partial}{\partial t}\right\rfloor\left(\left.\omega \wedge \frac{d u}{u}\right|_{\mathcal{Z}}\right) .
$$

For the first term in (8.31) this gives

$$
\begin{equation*}
f(\xi, 0) \frac{d \xi}{\xi^{2}} \wedge d \alpha \tag{8.32}
\end{equation*}
$$

on the curve $\eta=0$. For the second term in (8.31), if we use the relation

$$
\begin{equation*}
2 \xi d \xi+d t=0 \tag{8.33}
\end{equation*}
$$

on $Z$ we have

$$
\left.\frac{\partial}{\partial t}\right\rfloor\left(\left.\omega \wedge \frac{d u}{u}\right|_{\mathcal{Z}}\right)=-\frac{f(\xi, \eta)}{2 \xi} \frac{d \eta}{\eta} \wedge d \alpha
$$

which blows up if we try to set $\xi=0$. The trouble is that $d t$ vanishes on the component $Z \cap\{\xi=0\}$ of $Z \cdot\left(X \times \mathbb{P}^{1} \times\{0\}\right)$, and so we cannot divide by it.

To resolve this problem, as explained above we peturb our family to one where this does not happen and then take a limit. Thus we consider the curve

$$
\{\xi(\xi+\lambda)+t, \eta\}
$$

in $K_{2}(\mathbb{C}(X))$. The first term in the analogue of (8.31) is as before, and the second is now

$$
(\xi(\xi+\lambda)+t, \eta)
$$

Here we have in place of (8.33)

$$
(2 \xi+\lambda) d \xi+d t=0
$$

There are two components of $z$ over $t=0$; they are given by $\xi=0$ and $\xi+\lambda=0$. On the first and second respectively of these components

$$
\begin{aligned}
& \partial / \partial t\rfloor\left(\left.\omega \wedge \frac{d u}{u}\right|_{z}\right)=-\frac{f(0, \eta)}{\lambda} \frac{d \eta}{\eta} \wedge d \alpha \\
& \partial / \partial t\rfloor\left(\left.\omega \wedge \frac{d u}{u}\right|_{z}\right)=+\frac{f(-\lambda, \eta)}{\lambda} \frac{d \eta}{\eta} \wedge d \alpha
\end{aligned}
$$

Adding these and taking the limit as $\lambda \rightarrow 0$ gives

$$
-f_{\xi}(0, \eta) \frac{d \eta}{\eta} \wedge d \alpha
$$

Adding this to (8.32) we find agreement with (8.30).
Remark: If we use the relation (8.33), then as noted above

$$
\begin{equation*}
\partial / \partial t\rfloor\left(\left.\omega \wedge \frac{d u}{u}\right|_{\mathcal{Z}}\right)=-\frac{f(\xi, \eta)}{2 \xi} \frac{d \eta}{\eta} \wedge d \alpha \tag{8.34}
\end{equation*}
$$

We write

$$
f(\xi, \eta)=f(0, \eta)+\xi f_{\xi}(0, \eta)+\cdots
$$

and substitute in (8.34) and sum up over the two branches of $\xi^{2}+t=0$. Then the constant term in the Taylor expansion cancels out and the linear term gives

$$
-f_{\xi}(0, \eta) \frac{d \eta}{\eta} \wedge d \alpha
$$

Taking the limit as $t \rightarrow 0$ we find agreement with the calculation above.
(c) We shall examine the tangents to a number of special kinds of arcs in $Z_{1}^{1}(X)$.

The first is an $\operatorname{arc}\left(z_{t}, \lambda\right)$ where $z_{t}$ is an arc in $Z^{1}(X)$ and $\lambda \in \mathbb{C}^{*}$ is a constant. Recalling that for the tangent $\dot{z}$ to $z_{t}$ we have, upon choices of retractions,

$$
\dot{z} \in \underset{Y \text { irred }}{\oplus} \operatorname{Hom}_{\mathcal{O}_{Y}}^{o}\left(\Omega_{X / \mathbb{C}, Y}^{2}, \Omega_{\mathbb{C}(Y) / \mathbb{C}}^{1}\right)
$$

Denoting by

$$
\tau \in \underset{Y \text { irred }}{\oplus} \operatorname{Hom}_{\mathcal{O}_{Y}}^{o}\left(\Omega_{X / \mathbb{Q}, Y}^{2} / \Omega_{\mathbb{C} / \mathbb{Q}}^{2}, \Omega_{\mathbb{C}(Y) / \mathbb{C}}^{1} \otimes \Omega_{\mathbb{C} / \mathbb{Q}}^{1}\right)
$$

the tangent to $\left(z_{t}, \lambda\right)$ we have

$$
\begin{equation*}
\tau=\dot{z} \otimes \frac{d \lambda}{\lambda} \tag{8.35}
\end{equation*}
$$

where we are using the natural mapping

$$
\operatorname{Hom}_{Y}^{o}\left(\Omega_{X / \mathbb{C}, Y}^{2}, \Omega_{\mathbb{C}(Y) / \mathbb{C}}^{1}\right) \rightarrow \operatorname{Hom}_{Y}^{o}\left(\Omega_{X / \mathbb{Q}, Y}^{2} / \Omega_{\mathbb{C} / \mathbb{Q}}^{2}, \Omega_{\mathbb{C}(Y) / \mathbb{C}}^{1}\right)
$$

applied to $\dot{z}$. We note that the fact that

$$
\dot{z} \in \operatorname{ker}\left\{\underset{Y}{\oplus} \operatorname{Hom}_{\mathcal{O}_{Y}}^{o}\left(\Omega_{X / \mathbb{C}, Y}^{2}, \Omega_{\mathbb{C}(Y) / \mathbb{C}}^{1}\right) \rightarrow \underset{x \in X}{\oplus} \operatorname{Hom}_{\mathbb{C}}^{o}\left(\Omega_{X / \mathbb{C}, x}^{2}, \mathbb{C}\right)\right\}
$$

is reflected by the obvious fact that under the map

$$
Z_{1}^{1}(X) \xrightarrow{\text { div }} Z^{2}(X)
$$

the arc $\left(z_{t}, \lambda\right)$ maps to zero. The geometric reason why the arithmetic properties of $\lambda$ enter into the definition of the tangent to $\left(z_{t}, \lambda\right)$ were discussed in section 6(ii).

A second special type of arc in $Z_{1}^{1}(X)$ is given by $\left(z, f_{t}\right)$ where $f_{t}$ is an arc in $\mathbb{C}(X)^{*}$ and where no component of the divisors of the $f_{t}$ contains a component of the 1-cycle $z$. Now there is a natural map
$\operatorname{Hom}_{\mathcal{O}_{X}}\left(\Omega_{X / \mathbb{C}, Y}^{1}, \Omega_{\mathbb{C}(Y) / \mathbb{C}}^{1}\right) \xrightarrow{j} \operatorname{Hom}_{\mathcal{O}_{Y}}^{o}\left(\Omega_{X / \mathbb{Q}, Y}^{2} / \Omega_{\mathbb{C} / \mathbb{Q}}^{2}, \Omega_{\mathbb{C}(Y) / \mathbb{C}}^{1} \otimes \Omega_{\mathbb{C} / \mathbb{Q}}^{1}\right)$
given by using the natural map

and sending $\tau \in \operatorname{Hom}_{\mathcal{O}_{X}}\left(\Omega_{X / \mathbb{C}, Y}^{1}, \Omega_{\mathbb{C}(Y) / \mathbb{C}}^{1}\right)$ to the map given by

$$
j(\tau)(\omega)=\tau(\alpha(\omega)) \otimes \beta(\omega)
$$

Then the tangent to $\left(z, f_{t}\right)$ is given by

$$
j(\text { restriction to } Y) \frac{\dot{f}}{f}
$$

where

$$
(\text { restriction to } Y) \in \operatorname{Hom}_{\mathcal{O}_{X}}\left(\Omega_{X / \mathbb{C}, Y}^{1}, \Omega_{\mathbb{C}(Y) / \mathbb{C}}^{1}\right)
$$

is just the usual restriction mapping. More simply, the map is

$$
\begin{equation*}
\omega \longrightarrow\left(\frac{\dot{f}}{f} \alpha(\omega)\right) \otimes \beta(\omega) \in \Omega_{\mathbb{C}(Y) / \mathbb{C}}^{1} \otimes \Omega_{\mathbb{C} / \mathbb{Q}}^{1} \tag{8.36}
\end{equation*}
$$

(d) From the exact sequence

$$
0 \rightarrow \Omega_{X / \mathbb{C}}^{1} \otimes \Omega_{\mathbb{C} / \mathbb{Q}}^{1} \rightarrow \Omega_{X / \mathbb{Q}}^{2} / \Omega_{X / \mathbb{C}}^{2} \rightarrow \Omega_{X / \mathbb{C}}^{2} \rightarrow 0
$$

we infer the sequence

$$
\begin{aligned}
(8.37) 0 \rightarrow & {\underset{Y}{\oplus}}_{\underline{\operatorname{Hom}^{( }}}^{\mathcal{O}_{Y}} \\
& \rightarrow \Omega_{X / \mathbb{C}, Y}^{2}, \Omega_{\mathbb{C}(Y) / \mathbb{C}}^{1} \otimes \Omega_{\mathbb{C} / \mathbb{Q}}^{1} Z_{1}^{1}(X) \xrightarrow{\pi} \underset{Y}{\oplus} \underline{\underline{\operatorname{Hom}}}_{\mathcal{O}_{Y}}\left(\Omega_{X / \mathbb{C}, Y}^{1}, \Omega_{\mathbb{C}(Y) / \mathbb{C}}^{1}\right) \otimes \operatorname{Id}_{\Omega_{\mathbb{C} / \mathbb{Q}}^{1}} \rightarrow 0
\end{aligned}
$$

The mapping $\pi$ may be thought of as follows: Ignore any arithmetic aspect of an arc in $Z_{1}^{1}(X)$. For example, by (8.36) above tangents to arcs of the form $\left(z, f_{t}\right)$ are sent under $\pi$ to the map

$$
\left(\frac{\dot{f}}{f}\right)(\text { restriction to } Y) \operatorname{Id}_{\Omega_{\mathbb{C} / \mathbb{Q}}^{1}}
$$

In general we may describe $\pi$ as follows: Represent an $\operatorname{arc}$ in $Z_{1}^{1}(X)$ by

$$
\mathcal{Z} \subset X \times \mathbb{P}^{1} \times B
$$

Then for $\varphi \in \Omega_{X / \mathbb{C}, x}^{1}$ we map

$$
\begin{equation*}
\left.\left.\varphi \mapsto \sum_{i} n_{i}(\partial / \partial t\rfloor\left(\left.\varphi \wedge \frac{d u}{u}\right|_{z}\right)\right|_{Y_{i}}\right) \tag{8.38}
\end{equation*}
$$

where $Z \cdot\left(X \times \mathbb{P}^{1} \times t_{0}\right)=\sum_{i} n_{i}\left(Y_{i}, f_{i}\right)$.
The kernel of $\pi$ in (8.37) is the subspace

$$
\begin{gather*}
{\underset{Y}{ }{\underline{\underline{\operatorname{Hom}^{( }}}}^{c}}_{\mathcal{O}_{Y}}\left(\Omega_{X / \mathbb{C}, Y}^{2}, \Omega_{\mathbb{C}(Y) / \mathbb{C}}^{1}\right) \otimes \Omega_{\mathbb{C} / \mathbb{Q}}^{1} \subset \underline{\underline{T}} Z_{1}^{1}(X) \\
\underline{\underline{T}} Z^{1}(X) \otimes \Omega_{\mathbb{C} / \mathbb{Q}}^{1} \tag{8.39}
\end{gather*}
$$

Here, the dotted vertical arrow refers to the map

$$
\underline{\underline{T}} Z^{1}(X) \otimes \Omega_{\mathbb{C} / \mathbb{Q}}^{1} \rightarrow \underline{\underline{T}} Z_{1}^{1}(X)
$$

given as the differential of the map

$$
\left(\operatorname{arc} z_{t} \text { in } Z^{1}(X)\right) \otimes d \alpha \longrightarrow \operatorname{arc}\left(z_{t}, e^{\alpha}\right) \text { in } Z_{1}^{1}(X)
$$

encountered earlier.
We do not know a geometric interpretation of the full subspace (8.39).
(e) In section 8(i) we discussed two properties that $\underline{\underline{T}} Z^{1}(X)$ might have. Here we shall discuss the analogues for $\underline{\underline{T}} Z_{1}^{1}(X)$.

Using local duality and theorem (8.22), the map

$$
\begin{equation*}
\left\{\operatorname{arcs} \text { in } Z_{1}^{1}(X)\right\} \rightarrow \underset{Y}{\oplus}{\underline{\underline{\operatorname{Hom}^{2}}}}^{o}{ }_{Y}\left(\Omega_{X / \mathbb{C}, Y}^{2} / \Omega_{\mathbb{C} / \mathbb{Q}}^{2}, \Omega_{\mathbb{C}(Y) / \mathbb{C}}^{1} \otimes \Omega_{\mathbb{C} / \mathbb{Q}}^{1}\right) \tag{8.40}
\end{equation*}
$$

should be surjective. The proof of (8.22) given below emerged from understanding the following types of examples. As was the case for the surjectivity of the analogous map in $\S 8(\mathrm{i})$, the issue is to produce poles. In these illustrative examples we shall let $\xi, \eta$ be local uniformizing parameters.
(i) For the family given by

$$
\left(\xi+\alpha t^{1 / 2}=0, \eta+\beta t^{1 / 2}\right)
$$

we have

$$
d \xi \wedge d \eta \mapsto \frac{d \eta}{\eta} \otimes(\alpha d \beta-\beta d \alpha) \in \Omega_{\mathbb{C}(Y) / \mathbb{C}}^{1} \otimes \Omega_{\mathbb{C} / \mathbb{Q}}^{1}
$$

where $Y$ is given by $\xi=0$. Here the notation means the following: For each of the two choices of $\sqrt{t}$ we may define a curve $Y_{t}^{ \pm}$by $\xi \pm \alpha t^{1 / 2}=0$, and on $Y_{t}^{ \pm}$a function given by $\eta \pm \beta t^{1 / 2}$ using the same value of $\sqrt{t}$. Adding these gives an arc in $Z_{1}^{1}(X)$. To compute the tangent to this arc interpreted as an element on the RHS in (8.40), we have used the prescription (8.28). Similar considerations apply also to the following examples.
(ii) An example that illustrates the absence of compatibility conditions in $\underline{\underline{T}} Z_{1}^{1}(X)$ is given by the arc

$$
(\xi \eta-t=0, \alpha \xi+\beta \eta), \quad \alpha \beta \in \mathbb{C}
$$

For its tangent we have

$$
d \xi \wedge d \eta \rightarrow\left\{\begin{array}{l}
-\frac{d \eta}{\eta} \wedge \frac{d \beta}{\beta} \text { on } \xi=0 \\
+\frac{d \xi}{\xi} \wedge \frac{d \alpha}{\alpha} \text { on } \eta=0
\end{array}\right.
$$

(iii) For the next example we take the arc

$$
\left(\xi^{m} \eta-t=0, e^{\alpha}\right) \quad(\alpha \in \mathbb{C})
$$

in $Z_{1}^{1}(X)$. A similar argument to that which gave (8.31) gives for

$$
\omega=g(\xi) \eta d \xi \wedge d \eta
$$

that the tangent to the above arc is

$$
\omega \mapsto \begin{cases}\frac{g(\xi)}{\xi^{m}} d \xi \wedge d \alpha & \text { on } \eta=0 \\ \left(\frac{1}{m}\right) g^{(m-1)}(0) d \eta \wedge d \alpha & \text { on } \xi=0\end{cases}
$$

By taking linear combinations of this together with examples (i) and (ii) above we have produced an arbitrary linear combination

$$
\sum_{k=m}^{0} \frac{c_{k}}{\xi^{k}} d \alpha_{k} \wedge d \xi, \quad c_{k} \in \mathbb{C} \text { and } d \alpha_{k} \in \Omega_{\mathbb{C} / \mathbb{Q}}^{1}
$$

Proof of theorem 8.22: The proof will proceed in three steps.

Step one: For $x \in Y$ a smooth point we will show that

$$
\begin{equation*}
\left\{\operatorname{arcs} \text { in } Z_{1}^{1}(X)\right\} \rightarrow \mathcal{O}_{Y, x} \underset{\mathbb{C}}{\otimes}\left(\left.\Omega_{X / \mathbb{Q}, x}^{1}\right|_{x}\right) \tag{i}
\end{equation*}
$$

is surjective. (Actually we will prove more - that we can reach $1^{\text {st }}$ order poles along $Y$ and arbitrary poles in directions normal to $Y$.)
Step two: For $x \in Y$ a smooth point with local uniformizing parameter $\xi$, for each $n$ we will produce arcs in $Z_{1}^{1}(X)$ whose polar part reaches

$$
\begin{equation*}
\left.\left(\frac{1}{\xi^{n}}\right) \otimes \Omega_{X / \mathbb{Q}, x}^{1}\right|_{x}+\text { lower order terms. } \tag{ii}
\end{equation*}
$$

Step three: From the first two steps we have surjectivity in the stalk at $x$ in (8.22) for all those $Y$ for which $x \in Y$ is a smooth point. Using this we will deduce (i) and (ii) above when $x \in Y$ may be a singular point and $\xi$ is a local uniformizing paramater on a point of the normalization $\widetilde{Y} \xrightarrow{\pi} Y$ lying over $x$.

Step one is easy: If $x \in Y$ is a smooth point then expression

$$
\left.\frac{1}{g}(\dot{g} d f-\dot{f} d g)\right|_{x}
$$

where $\dot{f}, \dot{g} \in \mathcal{O}_{X, x}$ clearly reach all of $\mathcal{O}_{X, x} \otimes \mathbb{C}\left(\left.\Omega_{X / \mathbb{Q}, x}^{1}\right|_{x}\right)$. Here taking, e.g., $g=e^{\alpha}$ gives

$$
\left(-\left.\dot{f}\right|_{Y}\right) \otimes d \alpha \in \mathcal{O}_{Y, x} \otimes_{\mathbb{C}} \Omega_{\mathbb{C}, \mathbb{Q}}^{1}
$$

which reaches the $\Omega_{\mathbb{C} / \mathbb{Q}^{-}}^{1}$-part of $\left.\Omega_{X / \mathbb{Q}, x}^{1}\right|_{x}$. Actually, as will be seen by explicit computation below, using $\dot{g} d f / g$ 's we may reach arbitrary poles in co-normal direction to $Y$ and $\dot{f} d g / g$ 's to reach $1^{\text {st }}$ order poles along $Y$.

Step two is more interesting and involves one fundamental new point. Thinking of $\underline{\underline{H}}_{y}^{1}\left(\Omega_{X / \mathbb{Q}}^{1}\right)_{x}$ in terms of $\mathcal{E} x t^{\prime}$ 's, for $\varphi \in \Omega_{X / \mathbb{Q}, x}^{1}$ we will let

$$
\frac{\varphi}{\overline{\mathcal{O}_{X} \xrightarrow{f} \mathcal{O}_{X}}}
$$

denote the element that sends $1 \in \mathcal{O}_{X, x} \cong E_{1}$ to $\varphi$. The denominator means that we impose the equivalence relation

$$
\varphi \sim \varphi+f \psi .
$$

Working in $\underline{\underline{H}}_{y}^{1}\left(\Omega_{X / \mathbb{Q}}^{1}\right)_{x}$ where $y$ is a generic point of $Y$ means that we may allow $\varphi$ to be a rational 1 -form on $X$ whose polar locus does not include $Y$ as a component, and similarly for $\psi$. Thus the map

$$
\left.\left.\xlongequal[{\overline{\mathcal{O}_{X} \xrightarrow{f} \mathcal{O}_{X}}}]{\varphi} \mapsto \varphi\right|_{x} \in \mathbb{C}(Y) \otimes \mathbb{C} \Omega_{X / \mathbb{Q}, x}^{1}\right|_{x}
$$

is well-defined. This map means: Write $\varphi$ a linear combination of 1-forms in $\Omega_{X / \mathbb{Q}, x}^{1}$ with coefficients in $\mathbb{C}(X)$ not having poles on $Y$ and then restrict the coefficient functions to $Y$ ending up in $\mathbb{C}(Y)$. Since the tensor product is over $\mathbb{C}$ this mapping is well-defined, and essentially we have to show that it is surjective for those $\varphi$ 's that arise from tangents to arcs in $Z_{1}^{1}(X)$.

We will first work on the image of the map

$$
\left.\left.\mathbb{C}(Y) \otimes_{\mathbb{C}} \Omega_{X / \mathbb{Q}, x}^{1}\right|_{x} \rightarrow \mathbb{C}(Y) \otimes_{\mathbb{C}} \Omega_{X / \mathbb{C}, x}^{1}\right|_{x}
$$

The remaining $\mathbb{C}(Y) \otimes_{\mathbb{C}} \Omega_{\mathbb{C} / \mathbb{Q}}^{1}$-part may then be treated similarly using considerations as in step one.

Let now $\xi, \eta \in \mathcal{O}_{X, x} \subset \mathbb{C}(X)$ be local uniformizing parameters centered at $x$ and with $\eta=0$ being a local defining equation for $Y$. Then for $h \in \mathcal{O}_{X, x}$

$$
(\eta-t h, g) \rightarrow \frac{h \frac{d g}{g}}{\overline{\mathcal{O}_{X} \xrightarrow{\eta} \mathcal{O}_{X}} .}
$$

The notation means: The arc $(\eta-t h, g)$ in $\oplus \mathbb{C}(Y)^{*}$ maps to the expression on the right in $\underline{\underline{H}}_{y}^{1}\left(\Omega_{X / \mathbb{C}}^{1}\right)_{x}$. Taking $h=1$ and $g=\alpha \xi$ we have

$$
\begin{equation*}
\alpha \frac{d \xi}{\xi} . \tag{iii}
\end{equation*}
$$

Taking $h=1$ and $g=\eta+\xi^{k}$ we have

$$
\begin{equation*}
\frac{d \eta}{\xi^{k}}+\frac{k d \xi}{\xi} \tag{iv}
\end{equation*}
$$

Taking linear combinations of (iii) and (iv) we see that we can reach all of

$$
\begin{equation*}
\mathcal{O}_{Y, x} \frac{d \xi}{\xi}, \mathcal{O}_{Y, x} \frac{d \eta}{\xi^{k}} \tag{v}
\end{equation*}
$$

for any $k$. It remains to show that we can reach

$$
\frac{\frac{d \xi}{\xi^{a+1}}}{\mathcal{O}_{X} \xrightarrow{\eta} \mathcal{O}_{X}}
$$

and

$$
\frac{\frac{d \xi}{\xi^{a+1}}}{\overline{\mathcal{O}_{X} \xrightarrow{\eta^{b}} \mathcal{O}_{X}}}
$$

for all positive integers $a, b$.
Now we come to the essential point, which is to consider arcs in the space of cycles. Thus, suppose we have an arc

$$
\begin{equation*}
(f k-t h, g) \tag{vi}
\end{equation*}
$$

in $\left(\underset{Y}{\oplus} \underline{\underline{\mathbb{C}}}(Y)^{*}\right)_{x}$. Here, $f$ and $k$ are relatively prime in $\mathcal{O}_{X, x}, h \in \mathcal{O}_{X, x}$, and $g \in \mathbb{C}(X)$ does not have polar locus containing any component of $f k-$ th $=0$. All of this is local in the Zariski topology. What is the tangent in
$\underset{Y}{\oplus} H_{y}^{1}\left(\Omega_{X / \mathbb{Q}}^{1}\right)_{x}$ to the $\operatorname{arc}(\mathrm{vi})$ ? Letting $Y_{1}=\{f=0\}, Y_{2}=\{k=0\}$, on the face of it our prescription above gives something like

$$
\frac{h d g / g}{\overline{\mathcal{O}_{X} \xrightarrow{f k} \mathcal{O}_{X}}} .
$$

But we need to have something in the direct sum

$$
\underline{\underline{H}}_{y_{1}}^{1}\left(\Omega_{X / \mathbb{Q}}^{1}\right)_{x} \oplus \underline{\underline{H}}_{y_{2}}^{1}\left(\Omega_{X / \mathbb{Q}}^{1}\right)_{x} .
$$

We define this to be

$$
\begin{equation*}
\frac{\frac{h}{k} \frac{d g}{g}}{\underset{\mathcal{O}_{X} \xrightarrow{f} \mathcal{O}_{X}}{ }}+\frac{\frac{h}{f} \frac{d g}{g}}{\mathcal{O}_{X} \xrightarrow{k} \mathcal{O}_{X}} . \tag{vii}
\end{equation*}
$$

It is necessary to verify that this definition makes sense. For example, if $h=k u$ then as arcs in $Z_{1}^{1}(X)$

$$
\begin{aligned}
(f k-t h, g) & =(f k-t u k, g) \\
& =(f-t u, g)+(k, g)
\end{aligned}
$$

and the second term is constant so that (vii) reduces to

$$
\frac{\frac{h}{k} \frac{d g}{g}}{\mathcal{O}_{X} \xrightarrow{f} \mathcal{O}_{X}} .
$$

We can also check that this definition is compatible with the description above using differential forms.

With this understood we have

$$
\begin{equation*}
(\xi \eta-t, g) \rightarrow \frac{\frac{d g}{g}}{\mathcal{O}_{X} \xrightarrow{\eta} \mathcal{O}_{X}}+\frac{\frac{d g}{\eta g}}{\mathcal{O}_{X} \xrightarrow{\xi} \mathcal{O}_{X}} . \tag{viii}
\end{equation*}
$$

Now take $g=\xi^{m}+\eta^{n}$. Then the first term is

$$
\xlongequal[{\mathcal{O}_{X} \xrightarrow{\eta} \mathcal{O}_{X}}]{\frac{m \xi^{m-1} d \xi}{\xi\left(\xi^{m}+\eta^{n}\right)}}+\frac{\frac{n \eta^{n-1} d \eta}{\xi\left(\xi^{m}+\eta^{n}\right)}}{\mathcal{O}_{X} \xrightarrow{\eta} \mathcal{O}_{X}}
$$

Write

$$
\frac{1}{\xi^{m}+\eta^{n}}-\frac{1}{\xi^{m}}=\frac{-\eta^{n}}{\xi^{m}+\eta^{n}}=\left(\frac{-\eta^{n-1}}{\xi^{m}+\eta^{n}}\right) \eta
$$

Since we mod out by $\eta \psi$ 's where $\psi$ does not have polar locus containing $Y$ we may replace the expression above by

$$
\frac{m d \xi}{\xi^{2}}
$$

and then in (viii)

$$
\left(\xi \eta-t, \xi^{m}+\eta^{n}\right) \rightarrow \frac{\frac{m d \xi}{\xi^{2}}}{\mathcal{O}_{X} \xrightarrow{\eta} \mathcal{O}_{X}}+\frac{\frac{n d \eta}{\eta^{2}}}{\underset{\mathcal{O}_{X} \xrightarrow{\xi} \mathcal{O}_{X}}{ }}
$$

Taking linear combinations with different $m$ and $n$ we may reach

$$
\frac{\frac{d \xi}{\xi^{2}}}{\mathcal{O}_{X} \xrightarrow{\eta} \mathcal{O}_{X}}
$$

Replacing $\xi \eta-t$ by $\xi \eta-t h$ we may then reach $\mathcal{O}_{Y, x}$ times this form in the numerator.

Similar considerations give

$$
\left(\xi^{a} \eta-t, \xi^{a n}+\eta^{n}\right) \rightarrow \frac{\frac{a m d \xi}{\xi^{a+1}}}{\overline{\mathcal{O}_{X} \xrightarrow{\eta} \mathcal{O}_{X}}}+\frac{\frac{n d \eta}{\eta^{2}}}{\mathcal{O}_{X} \xrightarrow{\xi^{a}} \mathcal{O}_{X}}
$$

modulo terms already reached. Recalling that we are taking the limit over powers of the defining equations, and that by the previous step we may reach $\xlongequal[{\mathcal{O}_{X} \xrightarrow{\xi} \mathcal{O}_{X}}]{n d \eta / \eta^{2}}$, we may reach the second term, and again taking linear combinations we may reach

$$
\frac{\frac{d \xi}{\xi^{a+1}}}{\overline{\mathcal{O}_{X} \xrightarrow{\eta} \mathcal{O}_{X}}}
$$

Finally, working modulo terms already reached we have

$$
\left(\xi^{a} \eta^{b}-t, \xi^{a m}+\eta^{b n}\right) \sim \frac{\frac{d \xi}{\xi^{a+1}}}{\overline{\mathcal{O}_{X} \xrightarrow{\eta^{b}} \mathcal{O}_{X}}}
$$

Throughout we may replace $t$ by $h t$ with the effect of multiplying everything by $\mathcal{O}_{Y, x}$. This completes the proof of step two.

For step three we let $\widetilde{Y} \xrightarrow{\pi} Y \subset X$ be the normalization of the irreducible curve $Y$, and we let $\xi, \eta$ be local uniformizing parameters centered at $x$ and such that the projection $\xi, \eta \rightarrow \xi$ realizes $Y$ as a branched covering over the curve $\eta=0$ (all of this being local in the Zariski topology). The essential observation is this:
(iv) the map

$$
k \rightarrow \pi^{*}\left(\frac{k}{\xi^{a}}\right) \in \mathbb{C}(\tilde{Y}), k \in \mathcal{O}_{X, x} \text { and } a \in \mathbb{Z}
$$

is surjective.
We now consider arcs of the form $\left(f^{a} \xi^{b}-t h, g\right)$ with tangent

$$
\xlongequal[{\mathcal{O}_{X} \xrightarrow{\frac{f^{a}}{g}\left(\frac{d g}{\xi} b\right)} \mathcal{O}_{X}}]{\frac{\frac{h}{g}\left(\frac{d g}{f^{a}}\right)}{\mathcal{O}_{X} \xrightarrow{\xi^{b}} \mathcal{O}_{X}}}
$$

By step two the second term may be reached by an arc in $\underset{Y}{\oplus}(Y)^{*}$. Subtracting this off and using (iv) above we may reach all of

$$
\left.\mathbb{C}(\tilde{Y}) \otimes_{\mathbb{C}} \Omega_{X / \mathbb{Q}, x}^{1}\right|_{x}
$$

### 8.4 IDENTIFICATION OF THE GEOMETRIC AND FORMAL TANGENT SPACES TO $C H^{2}(X)$ FOR $X$ A SURFACE

Above we have defined

$$
\begin{equation*}
T Z^{2}(X)=H^{0}\left(\underset{x \in X}{\oplus} \underline{\underline{H}}_{x}^{2}\left(\Omega_{X / \mathbb{Q}}^{1}\right)\right) \tag{8.41}
\end{equation*}
$$

and

$$
T Z_{1}^{1}(X)=H^{0}\left(\underset{\substack{Y \text { irred }  \tag{8.42}\\
\left\{\begin{array}{c}
\text { corim } \\
\text { col }
\end{array}\right.}}{\underline{H}_{y}^{1}}\left(\Omega_{X / \mathbb{Q}}^{1}\right)\right)
$$

Moreover, there are maps

$$
\begin{array}{cl}
Z_{1}^{1}(X) & \longrightarrow Z^{2}(X)  \tag{8.43}\\
\| & \| \\
\substack{\text { irired ed } \\
\text { codim } Y=1} \\
\text { codim }(Y)^{*} \\
\\
\text { div }
\end{array} \oplus_{x \in X} \mathbb{Z}_{x}
$$

and

$$
\begin{equation*}
T Z_{1}^{1}(X) \xrightarrow{\text { res }} T Z^{2}(X) \tag{8.44}
\end{equation*}
$$

where using the isomorphisms in (8.41) and (8.42) the map (8.44) is given by the map in the Cousin flasque resolution of $\Omega_{X / \mathbb{Q}}^{1}$. Moreover, and this is a central point,
(8.45) the mapping (8.44) is the differential of (8.43).

We set

$$
Z_{\text {rat }}^{2}(X)=\text { image of }\left\{Z_{1}^{1}(X) \rightarrow Z^{2}(X)\right\}
$$

and recall that the Chow group is defined by

$$
C H^{2}(X)=Z^{2}(X) / Z_{\mathrm{rat}}^{2}(X) .
$$

Definition: The geometric tangent space to $C H^{2}(X)$ is defined by

$$
\begin{equation*}
T_{\mathrm{geom}} C H^{2}(X)=T Z^{2}(X) / \text { image }\left\{T Z_{1}^{1}(X) \xrightarrow{\text { res }} T Z^{2}(X)\right\} . \tag{8.46}
\end{equation*}
$$

The word "geometric" refers to the fact that the RHS is given by geometric data; i.e., the numerator by tangents to arcs in $Z^{2}(X)$ and the denominator by the tangents to image of arcs in $Z_{1}^{1}(X)$ under the map "div".

A tangent vector in $T_{\text {geom }} C H^{2}(X)$ is thus represented by data

$$
\tau=\sum_{i} \tau_{i}
$$

where there are points $x_{i} \in X$ and where, using duality to express local cohomology by differential forms,

$$
\tau_{i} \in \operatorname{Hom}^{o}\left(\Omega_{X / \mathbb{Q}, x_{i}}^{2} / \Omega_{\mathbb{C} / \mathbb{Q}}^{2}, \Omega_{\mathbb{C} / \mathbb{Q}}^{1}\right) .
$$

A vector in the subspace image $\left\{T Z_{1}^{1}(X) \rightarrow T Z^{2}(X)\right\}$ is represented by the residue of data

$$
\varphi=\sum_{\nu} \varphi_{\nu}
$$

where there are irreducible curves $Y_{\nu} \subset X$ and

$$
\varphi_{\nu} \in \operatorname{Hom}_{\mathcal{O}_{Y}}\left(\Omega_{X / \mathbb{Q}, Y_{\nu}}^{2} / \Omega_{\mathbb{C} / \mathbb{Q}}^{2}, \Omega_{\mathbb{C}\left(Y_{\nu}\right) / \mathbb{C}}^{1} \otimes \Omega_{\mathbb{C} / \mathbb{Q}}^{1}\right)
$$

Both the data $\left\{\tau_{i}\right\}$ and $\left\{\varphi_{\nu}\right\}$ are geometric in character.
Remark that although (8.46) is geometric it is definitely "non-classical." For example, as will be discussed in section 10 below there are algebraic arcs $z(t)$ in $Z^{2}(X)$ such that for all $t$

$$
z^{\prime}(t) \in T Z_{\mathrm{rat}}^{2}(X)
$$

where $T Z_{\text {rat }}^{2}(X)$ denotes the denominator on the RHS of (8.46), but where

$$
z(t) \text { is non-constant in } C H^{2}(X)
$$

Thus, for what will seem to be arithmetic reasons, $Z_{\text {rat }}^{2}(X)$ is definitely not a "subvariety" of $Z^{2}(X)$ in anything resembling the usual sense.

Now many years ago, Spencer Bloch established the identification

$$
C H^{2}(X) \cong H^{2}\left(\mathcal{K}_{2}\left(\mathcal{O}_{X}\right)\right)
$$

and, on the basis of this together with the van der Kallen isomorphism

$$
T \mathcal{K}_{2}\left(\mathcal{O}_{X}\right) \cong \Omega_{X / \mathbb{Q}}^{1}
$$

defined what we shall call the formal tangent space

$$
T_{\text {formal }} C H^{2}(X)=H^{2}\left(\Omega_{X / \mathbb{Q}}^{1}\right)
$$

The main result in this work is the following
Theorem: There is a natural isomorphism

$$
\begin{equation*}
T_{\text {formal }} C H^{2}(X) \cong T_{\text {geom }} C H^{2}(X) \tag{8.47}
\end{equation*}
$$

The proof of this result is a consequence of Theorem (8.22) above together with the Cousin flasque resolution

$$
\begin{equation*}
0 \rightarrow \Omega_{X / \mathbb{Q}}^{1} \rightarrow \Omega_{\mathbb{C}(X) / \mathbb{Q}}^{1} \rightarrow \underset{\substack{Y \text { irred } \\ \operatorname{codim} Y=1}}{\oplus} \underline{\underline{H}}_{y}^{1}\left(\Omega_{X / \mathbb{Q}}^{1}\right) \rightarrow \underset{x \in X}{\oplus_{x} \underline{\underline{H}}_{x}^{2}\left(\Omega_{X / \mathbb{Q}}^{1}\right) \rightarrow 0} \tag{8.48}
\end{equation*}
$$

discussed in the Appendix to section 8(i).
Remarks: (i) The result (8.47) implies an existence theorem, albeit at the infinitesimal level. Namely, given data $\tau \in \sum_{i} \tau_{i}$ as above, we may consider that

$$
\tau \in T_{\text {formal }} C H^{2}(X)=H^{2}\left(\Omega_{X / \mathbb{Q}}^{1}\right)
$$

If in this interpretation $\tau=0$, then there exists a global configuration $\left\{Y_{\nu}, \varphi_{\nu}\right\}$ consisting of irreducible curves $Y_{\nu}$ and data $\varphi_{\nu}$ on $Y_{\nu}$ that under the residue construction maps to $\tau$.

This may be thought of as somewhat analogous to a 2 -dimensional version of the following result for a smooth curve $Y$ : Let $y_{i} \in Y$ and $\tau_{i} \in \mathcal{P P}_{Y, y_{i}}$ be Laurent tails that satisfiy

$$
\sum_{i} \operatorname{Res}_{y_{i}}\left(\tau_{i} \omega\right)=0
$$

for all $\omega \in H^{0}\left(\Omega_{Y / \mathbb{C}}^{1}\right)$. Then there exists a global rational function $f \in$ $\mathbb{C}(Y)^{*}$ with

$$
\text { principal part of } f \text { at } y_{i}=\tau_{i} \text {. }
$$

(ii) The above theorem has the following consequence, which is an infinitesimal analogue of a conjecture of Bloch and Beilinson:
(8.49) Corollary: Let $X$ be an algebraic surface defined over a number field, and assume given tangent vectors

$$
\tau_{i} \in T_{x_{i}} X
$$

such that (a) for all $\varphi \in H^{0}\left(\Omega_{X / \mathbb{C}}^{1}\right)$

$$
\sum_{i}\left\langle\varphi, \tau_{i}\right\rangle=0
$$

and (b) the points $x_{i} \in X(\overline{\mathbb{Q}})$. Then there exists an infinitesimal rational equivalence given by irreducible curves $Y_{\nu}$ and data $\varphi_{\nu}$ on $Y_{\nu}$ that cuts out $\tau=\sum_{i} \tau_{i}$ in the sense that

$$
\sum_{\nu} \operatorname{Res}\left(\varphi_{\nu}\right)=\sum_{i} \tau_{i} .
$$

We may also take the $\left(Y_{\nu}, \varphi_{\nu}\right)$ to be defined over $\overline{\mathbb{Q}}$.
Condition (a) is equivalent to $\sum_{i}\left(X_{i}, \tau_{i}\right) \in T X$ being in the kernel of the differential of the Albanese map.

A variant of this is the following
(8.50) Corollary: Let $X$ be as above and assume that $X$ is regular. Assume that the $x_{i} \in X(k)$ are defined over a field $k$ and let

$$
\begin{aligned}
& X=X \times S \\
& \cup \\
& X_{i}=k \text {-spread of } x_{i}
\end{aligned}
$$

where $\mathbb{Q}(S) \cong k$ (cf. section 4 (ii) for the notations). Each $\omega \in H^{0}\left(\Omega_{X(\mathbb{Q}) / \mathbb{Q}}^{2}\right)$ defines a 2 -form $\widetilde{\omega}$ on $X$ and we assume that

$$
\left.\sum_{i} \tau_{i}\right\rfloor \widetilde{\omega} \in \oplus_{i} T^{*} x_{i}
$$

is zero. Then $\tau=\sum_{i} \tau_{i}$ is tangent to an infinitesimal rational equivalence as in the preceding corollary.
(iii) As suggested earlier, it is reasonable to hope that it will be possible to define $T Z^{p}(X)$ in general and that the analogue of Theorem (8.47) will be valid. However, the analogue of the following consequence of (8.47)

$$
\text { every } \tau \in T_{\text {formal }} C H^{2}(X) \text { is tangent to an arc in } Z^{2}(X)
$$

will in general be false. This phenomenon, which may be related to the phenomenon noted above that $Z_{\mathrm{rat}}^{2}(X)$ is not a "subvariety" of $Z^{2}(X)$, will be discussed in section 10 below. Remark that the principal seems to be the following:

There are formal constructions of compatible maps

$$
\left\{\begin{array}{l}
\varphi_{n}: \mathbb{C}[t] / t^{n+1} \rightarrow Z^{p}(X) \\
\varphi_{n}: \mathbb{C}[t] / t^{n+1} \rightarrow Z_{\mathrm{rat}}^{p}(X)
\end{array}\right.
$$

for $n=1,2 \ldots$ for which no convergent constructions exist with a given tangent $\varphi_{1}$.

This is in contrast to classical algebraic geometry, where the principal

$$
\text { formal } \Rightarrow \text { actual }
$$

holds. The reason for this non-classical phenomena seems to be a subtle mix of Hodge-theory and/or arithmetic (cf. section 10).

To conclude this section we will discuss how to calculate the differential of the map

$$
\begin{equation*}
C H^{1}(Y) \xrightarrow{i} C H^{2}(X) \tag{8.51}
\end{equation*}
$$

where $Y \subset X$ is a curve with normal crossings. In fact, the exact cohomology sequence of the exact sheaf sequence

$$
\begin{equation*}
0 \rightarrow \Omega_{X / \mathbb{Q}}^{1} \rightarrow \Omega_{X / \mathbb{Q}}^{1}(\log Y) \xrightarrow{\text { Res }} \mathcal{O}_{Y} \rightarrow 0 \tag{8.52}
\end{equation*}
$$

gives a map

$$
H^{1}\left(\mathcal{O}_{Y}\right) \xrightarrow{\delta} H^{2}\left(\Omega_{X / \mathbb{Q}}^{1}\right)
$$

Observation: The diagram

commutes, where the vertical isomorphisms are the natural identifications discussed above and $i_{*}$ is the differential of the map (8.51).
In fact, we can say a little more. The extension class of (8.51) lies in

$$
\mathcal{E} x t_{\mathcal{O}_{X}}^{1}\left(\mathcal{O}_{Y}, \Omega_{X / \mathbb{Q}}^{1}\right)
$$

and maps to $H_{Y}^{1}\left(\Omega_{X / \mathbb{Q}}^{1}\right)$ to define the local arithmetic cycle class

$$
[Y]_{a, \text { loc }} \in H_{Y}^{1}\left(\Omega_{X / \mathbb{Q}}^{1}\right)
$$

In this sense we have that

$$
[Y]_{a, \text { loc }} \text { determines } T C H^{1}(Y) \xrightarrow{i_{*}} T C H^{2}(X)
$$

### 8.5 CANONICAL FILTRATION ON $T C H^{n}(X)$

## AND ITS RELATION TO THE CONJECTURAL

## FILTRATION ON $C H^{n}(X)$

Beilinson has conjectured the existence of a canonical filtration $F^{m} C H^{p}(X)$ on the Chow groups $C H^{p}(X)$ of a smooth projective variety and, assuming the existence of the category of mixed motives, has proposed a Hodgetheoretic interpretation of the associated graded of this filtration. ${ }^{7}$ H. SaitoJannsen [25] and [28] and Murre [29] have proposed definitions for $F^{m} C H^{p}(X)$. In this section we shall show that
(i) there is a canonical filtration $F^{m} T C H^{n}(X)$ such that $G r^{m} T C H(S)$ has a Hodge-theoretic description; and
(ii) both the H. Saito-Jannsen and Murre definitions satisfy

$$
T F^{m} C H^{n}(X) \subseteq F^{m-1} T C H^{n}(X) ;{ }^{8}
$$

and
(iii) there is a geometric interpretation of $F^{m} T C H^{n}(X)$ in terms of the transcendence level of cycles representing a class in $T C H^{n}(X)$.

We begin with step (i). It is based on the extension of the identification (8.47) to $n$-dimensional smooth varieties to give the isomorphism

$$
\begin{equation*}
T C H^{p}(X) \cong H^{p}\left(\Omega_{X / \mathbb{Q}}^{p-1}\right) \tag{8.53}
\end{equation*}
$$

For all $p$ there is a canonical filtration on $\Omega_{X / \mathbb{Q}}^{p}$ given by

$$
\begin{equation*}
F^{m} \Omega_{X / \mathbb{Q}}^{p}=\text { image of }\left\{\Omega_{\mathbb{C} / \mathbb{Q}}^{m} \otimes \Omega_{X / \mathbb{Q}}^{p-m} \rightarrow \Omega_{X / \mathbb{Q}}^{p}\right\} \tag{8.54}
\end{equation*}
$$

The associated graded of (8.54) is

$$
G r^{m} \Omega_{X / \mathbb{Q}}^{p}=\Omega_{\mathbb{C} / \mathbb{Q}}^{m} \otimes \Omega_{X / \mathbb{C}}^{p-m}
$$

Geometrically, we may think of this filtration as reflecting the Leray filtration along $X$ in the spread

$$
x \rightarrow S
$$

of $X$ (cf. section 4(ii)). The arithmetic Gauss Manin connection

$$
\begin{equation*}
\nabla_{X / \mathbb{Q}}: \Omega_{\mathbb{C} / \mathbb{Q}}^{m} \otimes H^{q}\left(\Omega_{X / \mathbb{C}}^{p-m}\right) \rightarrow \Omega_{\mathbb{C} / \mathbb{Q}}^{m+1} \otimes H^{q+1}\left(\Omega_{X / \mathbb{C}}^{p-m-1}\right) \tag{8.55}
\end{equation*}
$$

is induced from the extension classes of the filtration (8.54); it may be thought of as the usual Gauss-Manin connection for the spread looked at along $X$. With this interpretation it was proved by Esnault-Paranjape [18]

[^18]that the spectral sequence associated to (8.54) degenerates at $E_{2}$. From this it follows that the induced filtration on $H^{q}\left(\Omega_{X / \mathbb{Q}}^{p}\right)$ is given by
\[

$$
\begin{equation*}
F^{m} H^{q}\left(\Omega_{X / \mathbb{Q}}^{p}\right)=\text { image of }\left\{H^{q}\left(F^{m} \Omega_{X / \mathbb{Q}}^{p}\right) \rightarrow H^{q}\left(\Omega_{X / \mathbb{Q}}^{p}\right)\right\} \tag{8.56}
\end{equation*}
$$

\]

and the associated graded is

$$
\begin{equation*}
G r^{m} H^{q}\left(\Omega_{X / \mathbb{Q}}^{p}\right)=\left(\Omega_{\mathbb{C} / \mathbb{Q}}^{m} \otimes H^{q}\left(\Omega_{X / \mathbb{C}}^{p-m}\right)\right)_{\nabla} \tag{8.57}
\end{equation*}
$$

where $\nabla$ is $\nabla_{X / \mathbb{Q}}$ and the RHS is the cohomology of the complex arising from (8.55) at the indicated spot.

Definition. With the identification (8.53), the canonical filtration on $T C H^{p}(X)$ is defined by

$$
\begin{equation*}
F^{m} T C H^{p}(X)=F^{m-1} H^{n}\left(\Omega_{X / \mathbb{Q}}^{p-1}\right) \tag{8.58}
\end{equation*}
$$

Remarks: For the conjectural filtration on $C H^{n}(X)$, there is agreement that

$$
\begin{align*}
& F^{1} C H^{p}(X)=\operatorname{ker}\left\{C H^{p}(X) \rightarrow H^{2 p}(X, \mathbb{Z})\right\}  \tag{8.59}\\
& F^{2} C H^{p}(X)=\operatorname{ker}\left\{F^{1} C H^{p}(X) \xrightarrow{A J_{X}^{p}} J^{p}(X)\right\}
\end{align*}
$$

where $J^{p}(X)$ is the intermediate Jacobian variety of $X$ and $A J_{X}^{p}$ is the AbelJacobi mapping. Since $H^{2 p}(X, \mathbb{Z})$ is discrete and therefore does not show up in infinitesimal considerations, the filtration (8.58) is shifted by one in order to have the possibility that

$$
F^{m} T C H^{p}(X)=T F^{m} C H^{p}(X)
$$

We note that by (8.59)

$$
\begin{aligned}
F^{2} T C H^{p}(X) & =\operatorname{ker} d A J_{X}^{p} \\
& =T F^{2} C H^{p}(X)
\end{aligned}
$$

where $d A J_{X}^{p}$ is the differential of the Albanese mapping.
We now turn to (ii).
Proposition: Denoting by $F^{m} C H^{p}(X)$ the filtration on $C H^{p}(X)$ defined by H. Saito-Jannsen or by Murre, we have

$$
\begin{equation*}
T F^{m} C H^{p}(X) \subseteq F^{m} T C H^{p}(X) \tag{8.60}
\end{equation*}
$$

Proof: The H. Saito-Jannsen definition of $F^{m} C H^{p}(X)_{\mathbb{Q}}$ is as follows: ${ }^{9}$
$F^{m} C H^{n}(X)_{\mathbb{Q}}$ is generated by cycles of the form

$$
\left(p_{X}\right)_{*}\left(Z_{1} \cdots Z_{m}\right)
$$

where, for some parameter variety $T$,

$$
\left\{\begin{array}{l}
Z_{i} \in C H^{q_{i}}(X \times T) \\
Z_{i} \equiv \text { hom } 0
\end{array}\right.
$$

[^19]To obtain the tangent to an arc in $F^{m} C H^{p}(X)$, using the evident notation we have

$$
\dot{Z}_{1} \in H^{q_{1}}\left(\Omega_{X \times T / \mathbb{Q}}^{q_{1}-1}\right)
$$

and

$$
\left[Z_{i}\right]_{a} \in \text { image }\left\{H^{q_{i}}\left(F^{1} \Omega_{X \times T / \mathbb{Q}}^{q_{i}}\right) \rightarrow H^{q_{i}}\left(\Omega_{X \times T / \mathbb{Q}}^{q_{i}}\right)\right\}
$$

Consequently

$$
\begin{aligned}
\dot{Z}_{1} \cup\left[Z_{2}\right]_{a} \cup \cdots \cup\left[Z_{m}\right]_{a} & \in \operatorname{image}\left\{H^{q_{1}+\cdots+q_{m}}\left(F^{m-1} \Omega_{X \times T / \mathbb{Q}}^{q_{1}+\cdots+q_{m}-1}\right)\right. \\
& \left.\rightarrow H^{q_{1}+\cdots+q_{m}}\left(\Omega_{X \times T / \mathbb{Q}}^{q_{1}+\cdots+q_{m}-1}\right)\right\} .
\end{aligned}
$$

Applying $\left(p_{X}\right)_{*}$ we end up in

$$
\text { image }\left\{H^{p}\left(F^{m-1} \Omega_{X / \mathbb{Q}}^{n-1}\right) \rightarrow H^{p}\left(\Omega_{X / \mathbb{Q}}^{n-1}\right)\right\}
$$

as desired.
Murre's conjectural filtration on $C H^{p}(X)_{\mathbb{Q}}$ is constructed inductively as follows (again his construction works for all $\left.C H^{p}(X)_{\mathbb{Q}}\right)$ : Denoting, as usual, the diagonal by $\Delta \subset X \times X$ with fundamental class

$$
[\Delta] \in H^{2 p}(X \times X)_{\mathbb{Q}} \cong \underset{k=0}{2 p} \operatorname{Hom}\left(H^{k}(X)_{\mathbb{Q}}, H^{k}(X)_{\mathbb{Q}}\right)
$$

The $k^{\text {th }}$ Künnuth component is a Hodge class in $H^{2 p}(X \times X)_{\mathbb{Q}}$, and assuming the Hodge conjecture - is represented by a cycle $\Delta_{k}$ which induces a map

$$
\Delta_{k}: C H^{p}(X)_{\mathbb{Q}} \rightarrow C H^{p}(X)_{\mathbb{Q}}
$$

Now

$$
\Delta_{2 p}=\text { identity on } G r^{0} C H^{p}(X)_{\mathbb{Q}}
$$

and we set

$$
F^{1} C H^{p}(X)_{\mathbb{Q}}=\operatorname{ker} \Delta_{2 p}
$$

Next,

$$
\Delta_{2 p-1}=\text { identity on } G r^{1} C H^{p}(X)_{\mathbb{Q}}
$$

and we set

$$
F^{2} C H^{p}(X)_{\mathbb{Q}}=\operatorname{ker}\left(\left.\Delta_{2 p-1}\right|_{\operatorname{ker}\left(\Delta_{2 p}\right)}\right)
$$

and so forth.
To prove (8.60) for the Murre filtration, we assume that we have an arc $z(t)$ in $Z^{n}(X)$ given by

$$
z \subset X \times B
$$

We assume that

$$
\left(p_{2}\right)_{*}\left(p_{1}^{*} z(t) \cdot\left[\Delta_{k}\right]\right) \equiv_{\mathrm{rat}} 0
$$

for $t \in B$, where $p_{i}(i=1,2)$ are the coordinate projections $X \times X \rightarrow X_{i}$. Now

$$
\begin{array}{r}
{[Z]_{a} \in H^{k}\left(\Omega_{X \times B / \mathbb{Q}}^{n}\right)} \\
{[\Delta]_{a} \in H^{n}\left(\Omega_{X \times X / \mathbb{Q}}^{n}\right)}
\end{array}
$$

and, as explained in section 7,

$$
z^{\prime}(0) \in H^{n}\left(\Omega_{X / \mathbb{Q}}^{n-1}\right) \otimes \Omega_{B / \mathbb{C}}^{1}
$$

represents part of $[z]_{a}$. Thus

$$
\left(p_{2}\right)_{*}\left(p_{1}^{*}\left(z^{\prime}(0)\right) \cdot\left[\Delta_{k}\right]\right)=0
$$

Now the topological part of $\left[\Delta_{k}\right]$ is

$$
\operatorname{id}_{H^{k}(X)} \in H^{n}\left(\Omega_{X \times X / \mathbb{C}}^{n}\right)
$$

and

$$
\alpha \rightarrow\left(p_{2}\right)_{*}\left(p_{1}^{*} \alpha \cdot\left[\Delta_{k}\right]\right)
$$

induces the identity on

$$
G r^{2 n-1-k} H^{n}\left(\Omega_{X / \mathbb{Q}}^{n-1}\right) \cong\left(\Omega_{\mathbb{C} / \mathbb{Q}}^{2 n-1-k} \otimes H^{n}\left(\Omega^{n-k}\right)\right)_{\Delta}
$$

Thus we can tell which $F^{m} H^{n}\left(\Omega_{X / \mathbb{Q}}^{n-1}\right)$ the class $z^{\prime}(0)$ belongs to by which $\Delta_{k}$ annihilates it. The indices work out to give (8.60).

Turning to the third point, in order to illustrate the essential geometric idea we shall assume that $X$ is defined over $\mathbb{Q}$ (or over a number field). For $w=x_{1}+\cdots+x_{d} \in X^{(d)}$ where the $x_{i}$ are assumed distinct, we shall denote by

$$
T_{w} Z^{n}(X) \subset T Z^{n}(X)
$$

the tangents to $\operatorname{arcs} z(t)$ in $Z^{n}(X)$ with

$$
\lim _{t \rightarrow 0}|z(t)|=w
$$

There is then a natural mapping

$$
T_{w} Z^{n}(X) \rightarrow T C H^{n}(X)
$$

induced from the geometric mapping

$$
T Z^{n}(X) \rightarrow T C H^{n}(X)
$$

discussed in section 8(iii). From that discussion follows a proof of the
Proposition: If $\operatorname{tr} \operatorname{deg} w \leqq m$ and $\dot{z}(0) \in F^{m+1} T C H^{n}(X)$, then $\dot{z}(0)=0$ in $T C H^{n}(X)$. For example, if $X$ and $w$ are defined over $\overline{\mathbb{Q}}$ and $\dot{z}(0) \in$ $F^{1} T C H^{n}(X)$, i.e. $\dot{z}(0)=0$ in $H^{n}\left(\Omega_{X / \mathbb{C}}^{n-1}\right)$, then $\dot{z}(0)=0$ in $H^{n}\left(\Omega_{X / \mathbb{Q}}^{n-1}\right)$.

In other words, infinitesimally the filtration on $C H^{n}(X)$ reflects the transcendence level of cycles representing classes in the Chow groups. In [32] we have proposed yet another definition of $F^{m} C H^{p}(X)$ for all $p$, together with a set of Hodge-theoretic invariants of $G r^{m} C H^{p}(X)$ that will - assuming the conjectures of Bloch-Beilinson - capture rational equivalence modulo torsion. Our proposed definition of $F^{m} C H^{p}(X)$ will be compatible with those of H. Saito-Jannsen and Murre, but will differ from theirs in that our condition on a cycle $Z$ that

$$
[Z] \in F^{m} C H^{p}(X)
$$

will be testable in finite terms. Its infinitesimal description is given by (8.61).

## Chapter Nine

## Applications and examples

### 9.1 THE GENERALIZATION OF ABEL'S <br> DIFFERENTIAL EQUATIONS (CF. [36])

Let $X$ be a smooth algebraic curve and

$$
\tau=\sum_{i=1}^{d}\left(x_{i}, \tau_{i}\right)
$$

a configuration of points $x_{i} \in X$ (assumed for simplicity of exposition to be distinct) and tangent vectors $\tau_{i} \in T_{x_{i}} X$. Classically Abel's differential equations dealt with the question

### 9.1. When is $\tau$ tangent to a rational equivalence?

The answer, which emerged from the work of Abel, Jacobi, Riemann and others in the $19^{\text {th }}$ century is:

The necessary and sufficient condition that $\tau$ be tangent to a rational equivalence is that for every regular differential $\omega \in H^{0}\left(\Omega_{X / \mathbb{C}}^{1}\right)$

$$
\begin{equation*}
\langle\omega, \tau\rangle=: \sum_{i=1}^{d}\left\langle\omega\left(x_{i}\right), \tau_{i}\right\rangle=0 . \tag{9.2}
\end{equation*}
$$

It is the higher dimensional analogue of this statement that we shall be discussing, focusing on the case of configurations of points on a surface.

We first reformulate (9.2). On the symmetric product $X^{(d)}$ we have the regular 1-forms

$$
\operatorname{Tr} \omega \in H^{0}\left(\Omega_{X^{(d)} / \mathbb{C}}^{1}\right)
$$

defined for $\omega \in H^{0}\left(\Omega_{X / \mathbb{C}}^{1}\right)$, and (4.1) is equivalent to

$$
\langle\operatorname{Tr} \omega, \tau\rangle=0 \text { for } \tau \in T_{z} X^{(d)}
$$

where $z=x_{1}+\cdots+x_{d}$, and the $x_{i}$ need not be distinct. The equations

$$
\begin{equation*}
\operatorname{Tr} \omega=0 \text { on } X^{(d)} \tag{9.3}
\end{equation*}
$$

define an exterior differential system on $X^{(d)}$ which we call Abel's differential equations on $X^{(d)}$. Referring to [30] for explanation of the terminology, it is a consequence of the theorems of Abel, Jacobi and Riemann-Roch that:

Abel's differential equations constitute an involutive exterior differential system. The maximal integral manifold through $z \in X^{(d)}$ is given by the complete linear system

$$
|z|=\left\{z^{\prime} \in X^{(d)}: z^{\prime}-z=(f) \text { for some } f \in \mathbb{C}(X)^{*}\right\}
$$

and

$$
\operatorname{dim}|z|=g-d+i(z)
$$

where $g=\operatorname{dim} H^{0}\left(\Omega_{X / \mathbb{C}}^{1}\right)$ and

$$
i(z)=\operatorname{dim}\left\{\tau \in T_{z} X^{(d)}:\langle\operatorname{Tr} \omega, \tau\rangle=0 \text { for all } \omega \in H^{o}\left(\Omega_{X / \mathbb{C}}^{1}\right)\right\} .
$$

Before taking up the situation of 0 -cycles on a surface we want to relate (9.4) to the topic of this paper, which is the tangent space to the space of cycles. Namely, we have

$$
T Z^{1}(X) \cong \underset{x \in X}{\oplus} \operatorname{Hom}_{\mathbb{C}}^{c}\left(\Omega_{X / \mathbb{C}, x}^{1}, \mathbb{C}\right)
$$

Each regular differential $\omega \in H^{0}\left(\Omega_{X / \mathbb{C}}^{1}\right)$ gives in the obvious way

$$
\operatorname{Tr} \omega \in T^{*} Z^{1}(X)
$$

By definition, Abel's differential equations are given by

$$
\begin{equation*}
\operatorname{Tr} \omega=0 \text { on } Z^{1}(X) . \tag{9.5}
\end{equation*}
$$

The difference between (9.3) and (9.5) is that in (9.5) creation and annihilation are allowed. That is, for $z$ and $z^{\prime} \in X^{(d)}$ a rational equivalence between $z$ and $z^{\prime}$ will in principal allow the existence of $w \in X^{\left(d^{\prime}\right)}$ and a map

$$
\mathbb{P}^{1} \xrightarrow{f} X^{\left(d+d^{\prime}\right)}
$$

with

$$
\left\{\begin{array}{l}
f(0)=z+w \\
f(\infty)=z^{\prime}+w
\end{array}\right.
$$

For curves, this is of course not necessary, which we may formulate by considering the obvious map

$$
X^{(d)} \xrightarrow{\pi} Z^{1}(X)
$$

and saying that for $z \in X^{(d)}$ the integral manifold of (9.5) through $\pi(z)$ lies in $\pi\left(X^{(d)}\right)$. In this sense, for algebraic curves there is no real need to consider $Z^{1}(X)$, other than of course that it makes the formalism neater. This situation will change completely when considering higher codimension cycles.

We now turn to (9.1) on an algebraic surface. For reasons to be discussed below the question needs to be refined into three parts:
(9.6) (a) When is $\tau$ tangent to a first order rational equivalence?
(b) When is $\tau$ tangent to a formal rational equivalence?
(9.6) (c) When is $\tau$ tangent to a geometric rational equivalence?

Here, (a) has the following meaning: $\tau$ defines a tangent vector, still denoted by $\tau$, in

$$
\begin{aligned}
\underline{\underline{T}} Z^{2}(X) & =: \underset{x \in X}{\oplus} \lim _{k \rightarrow \infty} \mathcal{E x} t_{\mathcal{O}_{X}}^{2}\left(\mathcal{O}_{X} / \mathfrak{m}_{x}^{k}, \Omega_{X / \mathbb{Q}}^{1}\right) \\
& \cong \underset{x \in X}{\oplus} \operatorname{Hom}^{o}\left(\Omega_{X / \mathbb{Q}, x}^{2}, / \Omega_{\mathbb{C} / \mathbb{Q}}^{2}, \Omega_{\mathbb{C} / \mathbb{Q}}^{1}\right)
\end{aligned}
$$

From section 8 we have a natural map

$$
T\left(\underset{\substack{Y \text { codim } 1 \\ Y \text { irred }}}{\oplus} \mathbb{C}(Y)^{*}\right) \xrightarrow{\rho} T Z^{2}(X),
$$

and (a) means that $\tau$ should be in the image of $\rho$. As for (b), there should be a formal arc $z(t)$ in $Z^{2}(X)$ and a formal $\operatorname{arc} \xi(t)$ in $\underset{Y}{\oplus} \mathbb{C}(Y)^{*}$ such that
and

$$
\rho\left(\xi^{\prime}(0)\right)=z^{\prime}(0)=\tau
$$

$$
(\xi(t))=z(t)-z(0)
$$

(A formal arc in $\underset{Y}{\oplus} \mathbb{C}(Y)^{*}$ means a map from $\lim _{k} \operatorname{Spec}\left(\mathbb{C}[\epsilon] / \epsilon^{k}\right)$ into thin space.) Finally, (c) means the same statement dropping the "formal" there should be a geometric cycle in $B \times X \times \mathbb{P}^{1}$ and $t_{0} \in B$ such that the induced map $T_{t_{0}} B \rightarrow T Z_{1}^{1}(X)$ has $\tau$ in its image. From the discussion in section 8 , (a) is a linear cohomological question which we shall now discuss, postponing (b) and (c) to the next section.

Turning to question (a) above, we will first discuss (a) informally without complete proofs emphasizing some consequences of the result. Then we shall discuss (a) more formally, giving proofs and tying the situation into the interpretation of $\mathcal{E} x t^{2}$ in terms of $4^{\text {th }}$ quarter Laurent tails that was given at the end of section 7 .

Let us first assume that $X$ is defined over $\mathbb{Q}$. For $\tau \in T Z^{2}(X)$ and $\omega \in H^{0}\left(\Omega_{X / \mathbb{Q}}^{2}\right)$ we have in section 5 defined

$$
\langle\omega, \tau\rangle \in \Omega_{\mathbb{C} / \mathbb{Q}}^{1}
$$

with the property that if $\omega=\varphi \wedge \alpha$ where $\varphi \in H^{0}\left(\Omega_{X / \mathbb{Q}}^{1}\right)$ and $\alpha \in \Omega_{\mathbb{C} / \mathbb{Q}}^{1}$

$$
\langle\varphi \wedge \alpha, \tau\rangle=\langle\varphi, \tau\rangle \alpha
$$

where $\langle\varphi, \tau\rangle$ is the usual pairing of 1 -forms against tangent vectors. We observe that this expression depends only on the image of $\varphi$ in $H^{0}\left(\Omega_{X / \mathbb{C}}^{1}\right)$, so that we may intuitively think of $\varphi \in H^{0}\left(\Omega_{X / \mathbb{C}}^{1}\right)$. From section 8 we know that $T Z_{\text {rat }}^{2}(X) \subset T Z^{2}(X)$ is defined by the conditions

$$
\begin{equation*}
\langle\omega, \tau\rangle=0 \text { for all } \omega \in H^{0}\left(\Omega_{X / \mathbb{Q}}^{2}\right) \tag{9.7}
\end{equation*}
$$

which we shall call Abel's differential equations and write as

$$
\begin{equation*}
\operatorname{Tr} \omega=0 \tag{9.8}
\end{equation*}
$$

in analogy to (9.5).

To get some feeling for these equations, suppose that $\tau=\sum_{i=1}^{d}\left(x_{i}, \tau_{i}\right)$ where the $x_{i}$ are distinct and $\tau_{i} \in T_{x_{i}} X$. Let $\xi, \eta \in \mathbb{Q}(X)$ give local uniformizing parameters around each $x_{i}$. If $\omega=f(\xi, \eta) d \xi \wedge d \eta$ where $f(\xi, \eta)$ is an algebraic function of $\xi, \eta$, then equation (9.7) is

$$
\begin{equation*}
\sum_{i} f\left(\xi_{i}, \eta_{i}\right)\left(d \xi_{i} \mu_{i}-d \eta_{i} \lambda_{i}\right)=0 \tag{9.9}
\end{equation*}
$$

where

$$
\left\{\begin{array}{l}
\tau_{i}=\lambda_{i} \partial / \partial \xi+\mu_{i} \partial / \partial \eta \\
\xi_{i}=\xi\left(x_{i}\right), \eta_{i}=\eta\left(x_{i}\right)
\end{array}\right.
$$

Varying $\tau_{i}$ we see that the rank of the equations (9.9) depends on the geometric position of the points $x_{i}$ and on the field of definition of the $x_{i}$. This mixture of geometry and arithmetic is characteristic of higher codimensional cycles.

To give a simply stated corollary, we set $z=x_{1}+\cdots+x_{d}$ and define

$$
\operatorname{Tr} \operatorname{deg} z=\operatorname{dim} \operatorname{span}\left\{d \xi_{i}, d \eta_{i}\right\}
$$

where $d=d_{\mathbb{C} / \mathbb{Q}}$. Then

$$
0 \leqq \operatorname{Tr} \operatorname{deg} z \leqq 2 d
$$

with $\operatorname{Tr} \operatorname{deg} z=0$ if, and only if, all the $x_{i} \in X(\overline{\mathbb{Q}})$ while $\operatorname{Tr} \operatorname{deg} z=2 d$ may be taken as a definition of $z$ being generic.
Corollary: For a surface $X$ with $K_{X} \cong \mathcal{O}_{X}$ the rank of the equations (9.9) is equal to $\operatorname{Tr} z$ where $\omega \in H^{0}\left(\Omega_{X / \mathbb{Q}}^{2}\right)$ is a generator.

It follows easily from the obvious extension of this corollary to the case when $H^{0}\left(\Omega_{X / \mathbb{C}}^{2}\right) \neq 0$ that there is no finite dimensional algebraic variety $W$ together with a map $W \rightarrow Z^{2}(X)$ such that the induced mapping $W \rightarrow$ $C H^{2}(X)$ is surjective. This type of result is due to Mumford, Roitman and others; in all of their arguments the word "generic" is used to mean in the complement of a countable union of proper subvarieties. The above discussions gives a somewhat precise arithmetic-geometric meaning to what generic should mean (cf. the appendix to section 10.1 below).

At the other extreme, if all the $x_{i} \in X(\overline{\mathbb{Q}})$ then the rank of the equations (9.9) is zero. As explained in section 8.2 this result that is an infinitesimal version of conjectures of Bloch and Beilinson. Namely, assuming that $X$ is a regular surface, to say that the equations (9.9) are zero means that given any set of tangent vectors $\tau_{i}^{\prime} \in T_{x_{i}} X$, there exists an $\operatorname{arc}\left\{Y_{\lambda}(\epsilon), f_{\lambda}(\epsilon)\right\}_{*}\left(\epsilon^{2}=0\right)$ where $Y_{\lambda}(\epsilon)$ is a family of irreducible curves and $f_{\lambda}(\epsilon) \in \mathbb{C}\left(Y_{\lambda}(\epsilon)\right)^{*}$ with

$$
\frac{d}{d \epsilon}\left(\sum_{\lambda} \operatorname{div} f_{\lambda}(\epsilon)\right)=\sum_{i} \tau_{i}
$$

The infinitesimal picture that we have developed has the following implications (here, $X$ is still an algebraic surface defined over $\mathbb{Q}$ with $\left.h^{2,0}(X) \neq 0\right)$ :
(i) If $z=\sum_{i=1}^{d} x_{i}$ is generic, then it does not move in a rational equivalence.

Here, "generic" means something both geometric and arithmetic. The geometric part is relative to the canonical linear system $\left|K_{X}\right|$, in analogy with non-special divisors in the theory of algebraic curves. The arithmetic part is that $\operatorname{tr} \operatorname{deg} z \operatorname{should}$ be sufficiently large - e.g., $\operatorname{tr} \operatorname{deg} z=2 d$ will do.
(ii) At the other extreme, if the $x_{i} \in X(\overline{\mathbb{Q}})$ then any infinitesimal motion of $z$ is covered by a rational equivalence.
The conjecture of Bloch-Beilinson implies that for any other $\widetilde{z}=\sum_{i=1}^{0} \widetilde{x}_{i}$ with $\widetilde{x}_{i} \in X(\mathbb{Q})$ there is a rational equivalence

$$
z \equiv_{\mathrm{rat}} \widetilde{z}
$$

We may rephrase this by saying that on $X(\overline{\mathbb{Q}})$ the 0 -cycle $z$ moves in a rational equivalence class $|z|_{\bar{Q}}$ where

$$
\operatorname{dim}|z|_{\overline{\mathbb{Q}}}=2 d
$$

Intermediate between (i) and (ii) we consider a fixed field $k$ of transcendence degree $d(k)$. Then the infinitesimal theory suggests
(iii) Any $z=\sum_{i=1}^{d} x_{i}$ where $x_{i} \in X(k)$ will move on $X(k)$ in a rational equivalence class $|z|_{k}$ where asymptotically

$$
\operatorname{dim}|z|_{k} \sim 2(d-d(k)) .
$$

Comparing (i)-(iii) what is suggested is behaviour analogous to linear equivalence on curves but where $\operatorname{tr} \operatorname{deg} k$ replaces the genus.
Thus, for curves we have

$$
\operatorname{dim}|z| \sim d-g
$$

where $z=\sum_{i=1}^{d} x_{i}$ is a divisor of degree $d$ with complete linear system $|z|$ and $g$ is the genus. The correction term $i(z)$ in this formula is the index of speciality, which for $d \geq g$ measures the failure of the $x_{i}$ to impose independent conditions on the canonical series. Geometrically, we have the canonical mapping

$$
\varphi_{K}: X \rightarrow \mathbb{P}\left(H^{1}\left(\mathcal{O}_{X}\right)\right)
$$

and $i(z)$ measures the failure of the $\varphi_{K}\left(x_{i}\right)$ to be in general position.
For a surface $X$ as above we may define the arithmetic canonical mapping

$$
\varphi_{K_{a}}: X(k) \rightarrow \mathbb{P}\left(H^{2}\left(\mathcal{O}_{X(k)}\right) \otimes \Omega_{k / \mathbb{Q}}^{1}\right),
$$

and what is suggested is that

$$
\operatorname{dim}|z|_{k}=2 d-2 d(k)-i(z)
$$

where $i(z)$ is expressible in terms of the geometry of the points $\varphi_{K_{a}}\left(x_{i}\right)$.
We will now reformulate (9.7) in a way that will enable the extension of those equations to the case when $X$ is not defined over $\mathbb{Q}$. Again the formal proof will be given later. First, remembering that we are still assuming that $X$ is defined over $\mathbb{Q}$ the equations (9.7) include the equations

$$
\begin{equation*}
\langle\varphi, \tau\rangle=0 \text { for } \varphi \in H^{0}\left(\Omega_{X / \mathbb{C}}^{1}\right) \tag{9.7}
\end{equation*}
$$

Next, since

$$
H^{0}\left(\Omega_{X(\mathbb{Q}) / \mathbb{Q}}^{2}\right) \otimes \mathbb{C} \cong H^{0}\left(\Omega_{X(\mathbb{C}) / \mathbb{C}}^{2}\right)
$$

we may lift every $\omega \in H^{0}\left(\Omega_{X / \mathbb{C}}^{2}\right)$ to $\widetilde{\omega} \in H^{0}\left(\Omega_{X / \mathbb{Q}}^{2}\right)$; the lifting is unique up to $\Omega_{\mathbb{C} / \mathbb{Q}}^{1} \otimes H^{0}\left(\Omega_{X / \mathbb{C}}^{1}\right)$. Thus, if $(9.7)_{1}$ is satisfied then we may unambiguously set

$$
\langle\omega, \tau\rangle=\langle\widetilde{\omega}, \tau\rangle
$$

and the equations

$$
\langle\omega, \tau\rangle=0 \text { for } \omega \in H^{0}\left(\Omega_{X / \mathbb{C}}^{2}\right)
$$

are well-defined. If for $\partial / \partial \alpha \in \Omega_{\mathbb{C} / \mathbb{Q}}^{1 *}$ we set

$$
\langle\omega \otimes \partial / \partial \alpha, \tau\rangle=\{\langle\omega, \tau\rangle, \partial / \partial \alpha\}
$$

where the curly brackets are the right hand side is the pairing $\Omega_{\mathbb{C} / \mathbb{Q}}^{1} \otimes \Omega_{\mathbb{C} / \mathbb{Q}}^{1 *} \rightarrow$ $\mathbb{C}$, then the equations (9.7) are equivalent to $(9.7)_{1}$ together with

$$
(9.7)_{2} \quad\langle\omega \otimes \partial / \partial \alpha, \tau\rangle=0 \text { for all } \omega \in H^{0}\left(\Omega_{X / \mathbb{C}}^{2}\right) \text { and } \partial / \partial \alpha \in \Omega_{\mathbb{C} / \mathbb{Q}}^{1 *}
$$

Finally, since $\omega$ is in the image of $H^{0}\left(\Omega_{X / \mathbb{Q}}^{2}\right) \rightarrow H^{0}\left(\Omega_{X / \mathbb{C}}^{2}\right)$ we have

$$
\begin{equation*}
\nabla(\omega \otimes \partial / \partial \alpha)=0 \text { in } H^{1}\left(\Omega_{X / \mathbb{C}}^{1}\right) \tag{9.10}
\end{equation*}
$$

where $\nabla$ is the arithmetic Gauss-Manin connection.
For $X$ defined over a general field

$$
\operatorname{ker}\left\{H^{0}\left(\Omega_{X / \mathbb{C}}^{2}\right) \otimes \Omega_{\mathbb{C} / \mathbb{Q}}^{1 *} \xrightarrow{\nabla} H^{1}\left(\Omega_{X / \mathbb{C}}^{1}\right)\right\}
$$

is by [18] the image of

$$
H^{0}\left(\Omega_{X / \mathbb{Q}}^{2}\right) \otimes \Omega_{\mathbb{C} / \mathbb{Q}}^{1 *} \rightarrow H^{0}\left(\Omega_{X / \mathbb{C}}^{2}\right) \otimes \Omega_{\mathbb{C} / \mathbb{Q}}^{1 *}
$$

The equations

$$
\begin{equation*}
\langle\varphi, \tau\rangle=0 \text { for all } \varphi \in H^{0}\left(\Omega_{X / \mathbb{C}}^{1}\right) \tag{9.11}
\end{equation*}
$$

$$
\begin{equation*}
\langle\xi, \tau\rangle=0 \text { for all } \xi \in \operatorname{ker}\left\{H^{0}\left(\Omega_{X / \mathbb{C}}^{2}\right) \otimes \Omega_{\mathbb{C} / \mathbb{Q}}^{1 *} \rightarrow H^{1}\left(\Omega_{X / \mathbb{C}}^{1}\right)\right\} \tag{9.11}
\end{equation*}
$$

are well-defined, and when $X$ is defined over $\mathbb{Q}$ they reduce to $(9.7)_{1}$ and $(9.7)_{2}$. One may write them out in coordinates as was done in (9.9) above. This involves choosing an open covering $\left\{U_{\alpha}\right\}$ and writing

$$
(\nabla \xi)_{\alpha \beta}=\delta\left\{\sigma_{\alpha}\right\}
$$

for $\sigma=\left\{\sigma_{\alpha}\right\} \in C^{1}\left(\left\{U_{\alpha}\right\}, \Omega_{X / \mathbb{C}}^{1}\right)$. Then the analogue of (9.9) will involve $\xi$ and $\sigma$. We refer to the following discussion for a proof and to section 9.3 below where explicit computations of this will be given for general surfaces in $\mathbb{P}^{3}$.

We now re-look at Abel's differential equations from a different, more formal perspective and give proofs of the interpretations stated above. For this we consider the Cousin flasque resolution

$$
0 \rightarrow \Omega_{X / \mathbb{Q}}^{1} \rightarrow \Omega_{\underline{\underline{\mathbb{C}}}(X) / \mathbb{Q}}^{1} \rightarrow \underline{\underline{T}} Z_{1}^{1}(X) \rightarrow \underline{\underline{T}} Z^{2}(X) \rightarrow 0
$$

Taking the hypercohomology spectral sequence of this and noting that all but the leftmost sheaf are flasque, we have an exact sequence

$$
H^{0}\left(\underline{\underline{T}} Z_{1}^{1}(X)\right) \rightarrow H^{0}\left(\underline{\underline{T}} Z^{2}(X)\right) \rightarrow H^{2}\left(\Omega_{X / \mathbb{Q}}^{1}\right) \rightarrow 0
$$

or in other words

$$
T Z_{1}^{1}(X) \rightarrow T Z^{2}(X) \rightarrow H^{2}\left(\Omega_{X / \mathbb{Q}}^{1}\right) \rightarrow 0
$$

We may thus say:
In terms of 9.6(a), Abel's differential equations for a surface are the map

$$
T Z^{2}(X) \rightarrow H^{2}\left(\Omega_{X / \mathbb{Q}}^{1}\right)
$$

From the exact sequence

$$
0 \rightarrow \Omega_{\mathbb{C} / \mathbb{Q}}^{1} \otimes \mathcal{O}_{X} \rightarrow \Omega_{X / \mathbb{Q}}^{1} \rightarrow \Omega_{X / \mathbb{C}}^{1} \rightarrow 0
$$

we have an exact sequence

$$
\begin{aligned}
0 \rightarrow \frac{\Omega_{\mathbb{C} / \mathbb{Q}}^{1} \otimes H^{2}\left(\mathcal{O}_{X}\right)}{\nabla_{X / \mathbb{Q}} H^{1}\left(\Omega_{X / \mathbb{C}}^{1}\right)} \rightarrow H^{2}\left(\Omega_{X / \mathbb{Q}}^{1}\right) \rightarrow & \operatorname{ker}\left(H^{2} / \Omega_{X / \mathbb{C}}^{1}\right) \\
& \xrightarrow{\nabla_{X / \mathbb{Q}}} \Omega_{\mathbb{C} / \mathbb{Q}}^{1} \otimes H^{3}\left(\mathcal{O}_{X}\right) \rightarrow 0
\end{aligned}
$$

Here $\nabla_{X / \mathbb{Q}}$ is the arithmetic Gauss-Manin connection, and since $X$ is a surface we have $H^{3}\left(\mathcal{O}_{X}\right)=0$. For a regular surface,

$$
H^{2}\left(\Omega_{X / \mathbb{Q}}^{1}\right) \cong \frac{\Omega_{\mathbb{C} / \mathbb{Q}}^{1} \otimes H^{2}\left(\mathcal{O}_{X}\right)}{\nabla_{X / \mathbb{Q}} H^{1}\left(\Omega_{X / \mathbb{C}}^{1}\right)}
$$

When $X$ is defined over $\overline{\mathbb{Q}}, \nabla_{X / \mathbb{Q}}$ is zero in the above expression and then

$$
\begin{aligned}
H^{2}\left(\Omega_{X / \mathbb{Q}}^{1}\right) & \cong \Omega_{\mathbb{C} / \mathbb{Q}}^{1} \otimes H^{2}\left(\mathcal{O}_{X}\right) \\
& \cong \operatorname{Hom}_{\mathbb{C}}\left(H^{0}\left(\Omega_{X / \mathbb{C}}^{2}\right), \Omega_{\mathbb{C} / \mathbb{Q}}^{1}\right)
\end{aligned}
$$

For such an $X$,

$$
H^{0}\left(\Omega_{X(\overline{\mathbb{Q}}) / \mathbb{Q}}^{2}\right) \otimes \mathbb{C} \rightarrow H^{0}\left(\Omega_{X / \mathbb{C}}^{2}\right)
$$

so we may choose a basis of the holomorphic 2-forms that come from absolute Kähler differentials defined over $\overline{\mathbb{Q}}$.

We now explain how to associate to

$$
\omega \in H^{0}\left(\Omega_{X(\overline{\mathbb{Q}}) / \mathbb{Q}}^{2}\right)
$$

an Abel's differential equation. If $\xi, \eta \in \overline{\mathbb{Q}}(X)$ give local uniformizing parameters around each point $x_{i}$,

$$
x=(\xi, \eta) \in X
$$

and if at $x_{i}$

$$
\omega=h_{i} d \xi \wedge d \eta
$$

then for tangent vectors

$$
v_{i} \in T_{x_{i}} X, \quad v_{i}\left(\lambda_{i}, \mu_{i}\right)
$$

the associated Abel's differential equation is

$$
\sum_{i} h_{i}(x)\left(\mu_{i} d \xi_{i}-\lambda_{i} d \eta_{i}\right)=0 \quad \text { in } \Omega_{\mathbb{C} / \mathbb{Q}}^{1}
$$

where $\xi_{i}=\xi\left(x_{i}\right), \eta_{i}=\eta\left(x_{i}\right)$. More generally, if $\tau_{i}$ is a finite $4^{\text {th }}$ quadrant Laurent tail at $x_{i}$ with $\left.\Omega_{X / \mathbb{Q}}^{1}\right|_{x_{i}}$ coefficients, then the associated Abel's differential equation is

$$
\sum_{i} \operatorname{Res}_{x_{i}}(\omega \tau)=0 \quad \text { in } \Omega_{\mathbb{C} / \mathbb{Q}}^{1}
$$

In the above, $\omega \tau_{i}$ is a Laurent tail with coefficients in the image of

$$
\left.\left.\Omega_{X / \mathbb{Q}}^{3}\right|_{x_{i}} \rightarrow \Omega_{X / \mathbb{C}}^{2}\right|_{x_{i}} \otimes \Omega_{\mathbb{C} / \mathbb{Q}}^{1}
$$

and we pull out the $\Omega_{\mathbb{C} / \mathbb{Q}}^{1}$ and then take the residue.
If $X$ is regular and not defined over $\overline{\mathbb{Q}}$, but only over a field $k$ (which we may take to be finitely generated over $\mathbb{Q}$ ), then letting

$$
\operatorname{Der}_{k / \mathbb{Q}}=\left(\Omega_{k / \mathbb{Q}}^{1}\right)^{*}
$$

we get an Abel's differential equation associated to each element of

$$
\operatorname{ker}\left(H^{0}\left(\Omega_{X(k) / k}^{2}\right) \otimes \operatorname{Der}_{k / \mathbb{Q}} \xrightarrow{\nabla_{X / Q}} H^{1}\left(\Omega_{X(k) / k}^{1}\right)\right)
$$

If $\phi$ belongs to this kernel, then on an open cover $\left\{U_{\alpha}\right\}$ of $X$, we may lift $\phi$ to

$$
\widetilde{\phi}_{\alpha} \in H^{0}\left(U_{\alpha}, \Omega_{X(k) / \mathbb{Q}}^{2} / \Omega_{k / \mathbb{Q}}^{2}\right) \otimes \operatorname{Der}_{k / \mathbb{Q}}
$$

Now

$$
\widetilde{\phi}_{\alpha}-\widetilde{\phi}_{\beta} \in H^{0}\left(U_{\alpha} \cap U_{\beta}, \Omega_{X(k) / k}^{1} \otimes \Omega_{k / \mathbb{Q}}^{1}\right) \otimes \operatorname{Der}_{k / \mathbb{Q}}
$$

If we let

$$
\pi\left(\widetilde{\phi}_{\alpha}-\widetilde{\phi}_{\beta}\right) \in H^{0}\left(U_{\alpha} \cap U_{\beta}, \Omega_{X(k) / k}^{1}\right)
$$

be obtained by contracting

$$
\Omega_{k / \mathbb{Q}}^{1} \otimes \operatorname{Der}_{k / \mathbb{Q}} \rightarrow k
$$

then

$$
\left[\pi\left(\widetilde{\phi}_{\alpha}-\widetilde{\phi}_{\beta}\right)\right]=0 \quad \text { in } H^{1}\left(\Omega_{X(k) / k}^{1}\right)
$$

Consequently we can find

$$
\psi_{\alpha} \in H^{0}\left(U_{\alpha}, \Omega_{X(k) / k}^{1}\right)
$$

with

$$
\pi\left(\widetilde{\phi}_{\alpha}-\widetilde{\phi}_{\beta}\right)=\psi_{\alpha}-\psi_{\beta} \quad \text { for all } \alpha, \beta
$$

With these preliminaries:
The Abel's differential equation associated to $\phi$ is, if $x_{i} \in U_{\alpha_{i}}$,

$$
\sum_{i} \operatorname{Res}_{x_{i}}\left(\pi\left(\widetilde{\phi}_{\alpha_{i}} \tau_{i}\right)-\psi_{\alpha_{i}} \tau_{i}\right)=0 \quad \text { in } \mathbb{C}
$$

Summary: We may give parallel formulations of Abel's DE's for a curve and a surface as follows:

X a curve: For

$$
\omega \in H^{0}\left(\Omega_{X / \mathbb{C}}^{1}\right), \quad \tau_{i} \in \mathcal{P} \mathcal{P}_{X, x_{i}}
$$

Abel's DE's are

$$
\sum_{i} \operatorname{Res}_{x_{i}}\left(\omega \tau_{i}\right)=0
$$

X a surface: There are two sets of DE's, one for 1-forms and one for 2 -forms. We shall use the notations

$$
L T_{X, x}=\left\{\text { finite } 4^{\text {th }} \text { quadrant Laurent tails at } x\right\} .{ }^{1}
$$

Then for

$$
\varphi \in H^{0}\left(\Omega_{X / \mathbb{C}}^{1}\right), \quad \tau_{i} \in L T_{X, x_{i}} \otimes \Omega_{X / \mathbb{Q}, x_{i}}^{1}
$$

Abel's DE's for 1-forms are

$$
\sum_{i} \operatorname{Res}_{x_{i}}\left(\varphi \wedge \tau_{i}\right)=0 .^{2}
$$

[^20]Turning to 2-forms, first if $X$ is defined over $\overline{\mathbb{Q}}$, then for

$$
\omega \in H^{0}\left(\Omega_{X(\overline{\mathbb{Q}}) / \mathbb{Q}}^{2}\right)
$$

Abel's DE's for 2-forms are

$$
\sum_{i} \operatorname{Res}_{x_{i}}\left(\omega \wedge \tau_{i}\right)=0 \quad \text { in } \Omega_{\mathbb{C} / \mathbb{Q}}^{2}
$$

If $X$ is not defined over $\mathbb{Q}$, then there is a formulation using the arithmetic Gauss-Manin along the lines discussed above.

### 9.1.1 Appendix to section 9.1: Remarks on Mumford's argument and its extensions

Above we have discussed the result
(i) If $X$ is an algebraic surface with $h^{2,0}(X) \neq 0$, then a generic $z \in X^{(d)}$ does not move in a rational equivalence.

As noted there, this result which has a number of formulations and is due to Mumford, Roitman, Bloch-Srinivas, and Voisin also follows from our infinitesimal theory. However, the term "generic" has somewhat different meanings in the different approaches, and here we want to briefly explain this.

The essential observation in Mumford's argument is the following: Let $\omega \in H^{0}\left(\Omega_{X / \mathbb{C}}^{2}\right)$ and

$$
f: \mathbb{P}^{r} \rightarrow X^{(d)}
$$

be a holomorphic mapping that has rank $r$ at some point and where $f\left(\mathbb{P}^{r}\right)$ contains a general point of $X^{(d)}$. Then

$$
\begin{equation*}
r \leq d \tag{ii}
\end{equation*}
$$

Here "general" has geometric meaning; we should have

$$
\left\{\begin{array}{l}
z=x_{1}+\cdots+x_{d} \in f\left(\mathbb{P}^{r}\right) \\
x_{i} \neq x_{j} \text { for } i \neq j \text { and all } \omega\left(x_{i}\right) \neq 0
\end{array}\right.
$$

Under these circumstances, by moving $z$ slightly we may assume that $z=$ $f(p)$ where $d f(p)$ has rank $r$. Then $\operatorname{Tr} \omega$ is a symplectic form in $T_{z}^{*} X^{(d)}$, and since

$$
f^{*}(\operatorname{Tr} \omega)=0
$$

it follows that

$$
d f\left(T_{p} \mathbb{P}^{r}\right) \subset T_{z} X^{(d)}
$$

is a null plane for $\operatorname{Tr} \omega$ and (ii) follows. ${ }^{3}$

[^21]We note that $X$ need only be a complex surface for this argument to work. The estimate (ii) is asymptotically sharp, as follows by considering linear series on hypersurface sections of algebraic $K 3$ surfaces.

The proof that a generic $z \in X^{(d)}$ does not move in a rational equivalence is based upon (ii) together with the following consideration: Let $S$ be a smooth variety and

$$
Z \subset X \times S
$$

an algebraic cycle such that for a general point $s \in S$ the intersection

$$
z_{s}=Z \cdot(X \times\{s\})
$$

is a 0 -cycle on $X$. Then we may define

$$
\begin{equation*}
\operatorname{Tr}_{Z}: H^{0}\left(\Omega_{X / \mathbb{C}}^{2}\right) \rightarrow H^{0}\left(\Omega_{S / \mathbb{C}}^{2}\right) \tag{ii}
\end{equation*}
$$

One definition is by using linearity in $Z$ to reduce to the case where $Z$ is an irreducible subvariety, which then gives a rational map

$$
Z: S \rightarrow X^{(d)}
$$

where $d=\operatorname{deg} z_{s}$. We may then set

$$
\operatorname{Tr}_{Z}(\omega)=Z^{*}(\operatorname{Tr} \omega)
$$

for $\omega \in H^{0}\left(\Omega_{X / \mathbb{C}}^{2}\right)$. Another definition, to be used below, uses the Künneth components

$$
[Z]_{p, q} \in H^{p}(X) \otimes H^{q}(S), \quad p+q=4
$$

of the fundamental class of $[Z]$ of $Z$. Since $[Z]$ is a Hodge class, $[Z]_{2,2}$ has a component in

$$
H^{0,2}(X) \otimes H^{2,0}(S) \simeq \operatorname{Hom}\left(H^{0}\left(\Omega_{X / \mathbb{C}}^{2}\right), H^{0}\left(\Omega_{S / \mathbb{C}}^{2}\right)\right)
$$

and this component is the map $\operatorname{Tr}_{Z} X$ in (ii).
Using this map we have
(iii) Let $Z_{1}, Z_{2}$ be two algebraic cycles in $X \times S$ as above, and assume that for every point $s \in S$

$$
z_{1, s} \equiv_{\text {rat }} z_{2, s}
$$

Then, for $\omega \in H^{0}\left(\Omega_{X / \mathbb{C}}^{2}\right)$.

$$
\operatorname{Tr}_{Z_{1}}(\omega)=\operatorname{Tr}_{Z_{2}}(\omega)
$$

For the proof, standard algebro-geometric arguments reduce us to the following situation: Replacing $S$ by a finite covering if necessary, we will have maps

$$
\left\{\begin{array}{l}
S \xrightarrow{f} X^{(k)} \\
\mathbb{P}^{1} \times S \xrightarrow{g} X^{(d+k)}
\end{array}\right.
$$

such that

$$
\begin{gathered}
g(0, s)=z_{1, s}+f(s) \\
g(\infty, s)=z_{2, s}+f(s)
\end{gathered}
$$

Then since

$$
g^{*}(\operatorname{Tr} \omega)=\pi_{S}^{*} \varphi
$$

for some $\varphi \in H^{0}\left(\Omega_{S / \mathbb{C}}^{2}\right)$ we infer (iii).
Mumford then used (i) and (ii) to show that for the evident map

$$
X^{(d)} \rightarrow C H^{2}(X)
$$

we have

$$
\operatorname{dim}\left(\operatorname{Im} X^{(d)}\right) \geqq d
$$

Roitman refined the argument to show

$$
\operatorname{dim}\left(\operatorname{Im} X^{(d)}\right)=2 d
$$

This implies (i), where "generic" means "outside of a countable union of proper subvarieties". One may contrast this geometric meaning of generic with the more precise arithmetic/geometric meaning given by the infinitesimal theory above.

Remark: An easy observation is that
(iv) If $h^{0}\left(K_{X}\right) \neq 0$, then any dominant holomorphic mapping

$$
f: \mathbb{P}^{1} \times S \rightarrow X^{(d)}
$$

is constant in the $\mathbb{P}^{1}$-factor.
It is of interest to note that
(iv) remains true if we only assume that

$$
\begin{gathered}
h^{0}\left(n K_{X}\right) \neq 0 \\
\text { for some } n \geqq 1
\end{gathered}
$$

Example: If $X$ is an Enriques surface then Bloch, Kas and Lieberman proved that

$$
C H^{2}(X) \cong \mathbb{Z}
$$

Here, $h^{0}\left(K_{X}\right)=0$ but $h^{0}\left(2 K_{X}\right) \neq 0$, so that (iv) applies. Thus for $z_{1}, z_{2} \in$ $X^{(d)}$ we have that there exists $w \in X^{(k)}$ and

$$
f: \mathbb{P}^{1} \rightarrow X^{(d+k)}
$$

such that

$$
\begin{aligned}
& f(0)=z_{1}+w \\
& f(\infty)=z_{2}+w
\end{aligned}
$$

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but in general we cannot take $w=0$. In other words, the equivalence

$$
z_{1} \equiv_{\mathrm{rat}} z_{2}
$$

cannot be taken to be given by a linear equivalence on an irreducible curve on $X$, but rather a configuration of linear equivalences where cancellations are necessary.

For the proof we will show that $h^{0}\left(n K_{X}\right) \neq 0 \Rightarrow h^{0}\left(n K_{X^{(d)}}\right) \neq 0$. The case $n=2$ will illustrate the idea. In local coordinates $x, y$ on $X$ let

$$
\varphi=g(x, y)(d x \wedge d y)^{2}
$$

be a quadratic differential. Then it is easy to see that the trace

$$
\operatorname{Tr} \varphi=g\left(x_{1}, y_{1}\right)\left(d x_{1} \wedge d y_{1}\right)^{2}+\cdots+g\left(x_{d}, y_{d}\right)\left(d x_{d} \wedge d y_{d}\right)^{2}
$$

is single-valued but has poles along the diagonals. On other other hand

$$
\operatorname{Tr} \varphi^{1 / 2}=g\left(x_{1}, y_{1}\right)^{1 / 2} d x_{1} \wedge d y_{1}+\cdots+g\left(x_{d}, y_{d}\right)^{1 / 2} d x_{d} \wedge d y_{d}
$$

is holomorphic but not single-valued. But then

$$
\begin{aligned}
\Phi & =\left(\frac{1}{d!}\right)^{2}(\underbrace{\operatorname{Tr} \varphi^{1 / 2} \wedge \ldots \wedge \operatorname{Tr}} \varphi^{1 / 2})^{2} \\
& =g\left(x_{1}, y_{1}\right) \cdots g\left(x_{d}, y_{d}\right)\left(d x_{1} \wedge y_{1} \wedge \ldots \wedge d x_{d} \wedge d y_{d}\right)^{2}
\end{aligned}
$$

is holomorphic and single-valued, and therefore gives a non-zero section of $2 K_{X^{(d)}}$.

Turning to the proof of (iv), if $f$ is not constant in the $\mathbb{P}^{1}$ factor we may assume that $\operatorname{dim} S=2 d-1$. For $\Phi$ as above we have that for local reasons

$$
f^{*} \Phi \neq 0
$$

but for global reasons $h^{0}\left(2 d K_{\mathbb{P}^{1} \times S}\right)=0$, which is a contradiction.

### 9.2 ON THE INTEGRATION OF ABEL'S

## DIFFERENTIAL EQUATIONS

Above we have expressed in differential form the condition for infinitesimal rational motion of a 0 -cycle on a curve or on a surface. Now we will discuss how one may "integrate" Abel's differential equations.
Definition: By integration of Abel's differential equations we mean defining a Hodge-theoretic object $\mathcal{H}$ and constructing a map

$$
\begin{equation*}
\psi: Z^{n}(X) \rightarrow \mathcal{H} \tag{9.12}
\end{equation*}
$$

whose fibers are the rational equivalence classes of 0 -cycles.
Two caveats: First, we shall always work modulo torsion. Secondly, what will be constructed is a sequence of such maps

$$
\psi_{i}: \operatorname{ker} \psi_{i-1} \rightarrow \mathcal{H}_{i} \quad i=0,1, \ldots, n
$$

(where $\psi_{-1}$ is the trivial map) such that the intersection of the kernel is rational equivalence.

For $n=1$ the construction of (9.12) is classical. Here we shall briefly review this, and then we shall introduce a Hodge-theoretic construction of a $\psi$ in the case $n=2$ for surfaces defined over $\mathbb{Q}$ whose fibers are exactly rational equivalence classes provided that one assumes the conjecture of Bloch and Beilinson. In [32] we shall give this construction in general.

We shall use the notation

$$
Z^{n}(X)_{i}=\operatorname{ker} \psi_{i}
$$

In the case $n=1$ of a smooth algebraic curve we have the classical maps

$$
\begin{aligned}
& \psi_{0}: Z^{1}(X) \rightarrow \mathbb{Z} \\
& \psi_{1}: Z^{1}(X)_{0} \rightarrow J(X)
\end{aligned}
$$

where $J(X)$ is the Jacobian variety of $X$. Here for $z=\sum_{i} n_{i} x_{i}$

$$
\psi_{0}(z)=\sum_{i} n_{i}=\operatorname{deg} z
$$

and if $\psi_{0}(z)=0$ so that $z=\partial \gamma$ for some 1-chain $\gamma$

$$
\psi_{1}(z)=\left(\int_{\gamma} \varphi_{1}, \ldots, \int_{\gamma} \varphi_{g}\right) \bmod \text { periods }
$$

where $\varphi_{1}, \ldots, \varphi_{g}$ is a basis for $H^{o}\left(\Omega_{X / \mathbb{C}}^{1}\right)$. We may think of $\psi_{0}$ as a bilinear map

$$
Z^{1}(X) \otimes H^{0}\left(\Omega_{X / \mathbb{C}}^{0}\right) \xrightarrow{\psi_{0}} \mathbb{C}
$$

given by

$$
\begin{equation*}
\psi_{0}(z, 1)=\int_{z} 1 \tag{9.13}
\end{equation*}
$$

and of $\psi_{1}$ as a bilinear map

$$
Z^{1}(X)_{0} \otimes H^{0}\left(\Omega_{X / \mathbb{C}}^{1}\right) \xrightarrow{\psi_{1}} \mathbb{C} \text { mod periods }
$$

given by

$$
\begin{equation*}
\psi_{1}(z, \varphi)=\int_{\gamma} \varphi, \quad \partial \gamma=z \tag{9.13}
\end{equation*}
$$

Let now $X$ be an algebraic surface. Then we may define $\psi_{0}$ and $\psi_{1}$ exactly as in the curve case, where now $\psi_{1}$ maps to the Albanese variety. The issue has always been how to define $\psi_{2}$.

From $(9.13)_{0}$ and $(9.13)_{1}$ we want to define something like a bilinear map

$$
Z^{2}(X)_{1} \otimes H^{0}\left(\Omega_{X / \mathbb{C}}^{2}\right) \xrightarrow{\psi_{2}} \mathbb{C} \text { mod periods }
$$

given by

$$
\begin{equation*}
\psi_{2}(z, \omega)=\int_{\Gamma} \omega \tag{9.13}
\end{equation*}
$$

Here, $\Gamma$ should be a 2-chain that can only be constructed if $\psi_{0}(z)=\psi_{1}(z)$ $=0$.

A first hint of how to proceed comes if we think of $H^{0}\left(\Omega_{X / \mathbb{C}}^{1}\right)$ as a subspace of $T^{*} C H^{n}(X)$. When $n=1$ obviously $H^{0}\left(\Omega_{X / \mathbb{C}}^{1}\right)$ is equal to $T^{*} C H^{1}(X)$. However, when $n=2$

$$
T^{*} C H^{2}(X) / H^{0}\left(\Omega_{X / \mathbb{C}}^{1}\right) \cong \operatorname{ker}\left\{H^{0}\left(\Omega_{X / \mathbb{C}}^{2}\right) \otimes \Omega_{\mathbb{C} / \mathbb{Q}}^{1 *} \xrightarrow{\nabla} H^{1}\left(\Omega_{X / \mathbb{C}}^{1}\right)\right\}
$$

where $\nabla$ is the arithmetic Gauss-Manin connection. The right hand side has to do with the obstruction to lifting differentials defined over $\mathbb{C}$ to differentials defined over $\mathbb{Q}$. Thus, $H^{0}\left(\Omega_{X / \mathbb{Q}}^{2}\right)$ should enter the picture.

Suppose then that $X$ is a regular surface defined over $\mathbb{Q}$, so that by base change

$$
H^{0}\left(\Omega_{X(\mathbb{Q}) / \mathbb{Q}}^{2}\right) \otimes \mathbb{C} \cong H^{0}\left(\Omega_{X(\mathbb{C}) / \mathbb{C}}^{2}\right)
$$

We want to define something like $(9.13)_{2}$ when $\omega \in H^{0}\left(\Omega_{X / \mathbb{Q}}^{2}\right)$. Referring to the preceding section, for

$$
\tau=\sum_{i}\left(x_{i}, \tau_{i}\right) \in T Z^{2}(X)
$$

where $\tau_{i} \in T_{x_{i}} X$ and, for the sake of simplicity the $x_{i}$ are assumed to be distinct, the condition that $\tau$ be tangent to infinitesimal rational motion is

$$
\begin{equation*}
\langle\omega, \tau\rangle=: \sum_{i}\left\langle\omega\left(x_{i}\right), \tau_{i}\right\rangle=0 \quad \text { in } \Omega_{\mathbb{C} / \mathbb{Q}}^{1} \tag{9.14}
\end{equation*}
$$

for all $\omega$. Thinking of $\Omega_{\mathbb{C} / \mathbb{Q}}^{1}$ geometrically as reflecting cotangent vectors to spreads, this relation suggests how to proceed to construct $(9.13)_{2}$.

Namely, suppose that $z \in Z^{2}(X(k))_{0}$; set $\mathcal{X}=X \times S$ where $\mathbb{Q}(S) \cong k$ and let

be the spread of $z$. The form $\omega$ defines a form, denoted by $\widetilde{\omega}$, in $H^{0}\left(\Omega_{\mathcal{X}(\mathbb{Q}) / \mathbb{Q}}^{2}\right)$. As shown by the calculations in section 4 , using the evaluation mappings in (9.14) above we may think of

$$
\left\langle\omega\left(x_{i}\right), \tau_{i}\right\rangle \in \pi^{*} T_{s_{0}} S \subset T_{\left(x_{i}, s_{0}\right)}^{*} \mathcal{X}
$$

i.e. along $\mathcal{Z}$ we may think of $\widetilde{\omega}$ as having one "vertical" and one "horizontal" foot. This suggests that the 2 -chain $\Gamma$ in $(9.13)_{2}$ should be traced out by 1-chains $\gamma_{s}$ in $X$ parametrized by a 1-chain $\lambda$ in $S$.

Thus, let $\lambda \in \Omega S$ be a closed loop in $S$. For each $s \in \lambda$ we have

$$
z_{s}=\partial \gamma_{s}
$$

for some 1-chain $\gamma_{s}$ in $X$. Using that $H_{1}(X, \mathbb{Q})=0$ and that we are working modulo torsion, we will have

$$
\gamma_{1}=\gamma_{0}+\partial \Lambda
$$

for some 2-chain $\Lambda$. If we set

$$
\Gamma=\bigcup_{s \in \lambda} \gamma_{s}+\Lambda
$$

then

$$
\partial \Gamma=\bigcup_{s \in \lambda} z_{s}
$$

and we define

$$
\begin{equation*}
I(z, \omega, \lambda)=\int_{\Gamma} \omega \quad \bmod \text { periods. } \tag{9.15}
\end{equation*}
$$

Again elementary considerations show that a different choice of paths $\gamma_{s}$ changes $(9.15)$ by a period $\int_{\sigma} \omega$ where

$$
\sigma \in H_{2}(X, \mathbb{Z})
$$

Now recall that on a manifold $M$ a differential character is given by a function on the loop space

$$
\chi: \Omega M \rightarrow R
$$

mapping to some abelian group $R$ which is a quotient of $\mathbb{C}$ by a subgroup and which satisfies

$$
\chi(\partial \Delta) \equiv \int_{\Delta} \varphi
$$

where $\Delta$ is a 2 -chain and $\varphi$ is a 2 -form on $M$.
Proposition: (i) If $\lambda=\partial \Delta$ then

$$
I(z, \omega, \lambda)=\int_{\Delta} \operatorname{Tr}_{\mathcal{Z}}(\widetilde{\omega})
$$

where $\operatorname{Tr}_{\mathcal{Z}}$ is the trace of the generically finite $\operatorname{map} \mathcal{Z} \rightarrow S$. Thus, (9.15) defines a differential character on $S$.
(ii) $I(z, w, \lambda)$ depends only on the $k$-rational equivalence class $[z] \in$ $C H^{2}(X(k))$.
Proof: (i) Let $\Sigma=\bigcup_{s \in \Delta} \gamma_{s}$ and $\mathcal{Z}_{\Delta}=\bigcup_{s \in \Delta} z_{s}$. Then

$$
\partial \Sigma=\Gamma-\mathcal{Z}_{\Delta}
$$

and the result follows from Stokes' theorem, noting that

$$
\int_{\mathcal{Z}_{\Delta}} \widetilde{\omega}=\int_{\Delta} \operatorname{Tr}_{\mathcal{Z}}(\widetilde{\omega})
$$

(ii) Let $z_{t}$, for $t \in \mathbb{P}^{1}$, be a rational equivalence defined over $k$ given by a cycle

$$
\mathfrak{Z} \subset \mathcal{X} \times \mathbb{P}^{1}
$$

Then

$$
\frac{d}{d t} I\left(z_{t}, \omega, \lambda\right)=\int_{\lambda}\left\langle\omega, z_{t}^{\prime}\right\rangle
$$

where $z_{t}^{\prime}$ is the tangent to the family of 0 -cycles $z_{t}$ and

$$
\left\langle\omega, z_{t}^{\prime}\right\rangle \in T_{s}^{*} S
$$

when we use the evaluation maps $\Omega_{\mathbb{C} / \mathbb{Q}}^{1} \rightarrow T_{s}^{*} S$. Since $z_{t}^{\prime} \in T Z^{2}(X)_{\text {rat }}$, we have

$$
\left\langle\omega, z_{t}^{\prime}\right\rangle=0
$$

by the results in part (i) of this section (cf. (9.14) above).
This argument shows how one may think of $I(z, \omega, \lambda)$ as "integrating" Abel's differential equations. Actually, as explained in [32] there is an extension of the construction of $I(z, \omega, \lambda)$ to all $\omega \in H^{2}(X)_{\text {tr }}$ - the transcendental part of $H^{2}(X, \mathbb{C})$ - that does not show up infinitesimally. We will not go into this here, but rather shall note the following consequence which will also be established in the work referred to above:

Assuming the conjecture of Bloch-Beilinson, if $I(z, \omega, \lambda)=0$ for all $\omega$ and $\lambda$, then

$$
z \equiv_{\text {rat }} 0
$$

(modulo torsion).
This result has the following
Corollary: If $h^{1,0}(S)=h^{2,0}(S)=0$, then $z$ is rationally equivalent to zero.
We note that the conditions in the corollary are birationally invariant and thus depend only on the field $k$.

Addendum: For later reference we want to give the extension of the above construction to the case when $X$ is defined over $\mathbb{Q}$ but may not be regular. Let $z \in Z^{2}(X(k))$ be a 0 -cycle of degree zero and satisfying

$$
\psi_{1}(z)=: \operatorname{Alb}_{X} z=0
$$

Since $\operatorname{Alb}(X)$ is defined over a finite extension field of $\mathbb{Q}$ and (i) is an algebraic condition, it follows that

$$
\psi_{1}\left(z_{s}\right)=\operatorname{Alb} z_{s}=0
$$

for the spread $\left\{z_{s}\right\}_{s \in S}$. Put differently, given the spread picture

$$
\begin{aligned}
& \mathcal{Z} \subset \mathcal{X}=X \times S \\
& \downarrow \quad \downarrow \\
& S=S
\end{aligned}
$$

where we assume $S$ is smooth and complete, we have that the maps induced from the Künneth component of the fundamental class of $\mathcal{Z}$

$$
\mathcal{Z}_{*, 0}: H_{0}(S, \mathbb{Q}) \rightarrow H_{0}(X, \mathbb{Q})
$$

and

$$
\mathcal{Z}_{x, 1}: H_{1}(S, \mathbb{Q}) \rightarrow H_{1}(X, \mathbb{Q})
$$

are both zero. Working modulo torsion, if $\lambda$ is a closed curve on $S$, then

$$
\mathcal{Z}(\lambda)=\left\{z_{s}\right\}_{s \in \lambda}
$$

traces out a 1-cycle on $X$ that is the boundary of a 2 -chain $\Gamma$

$$
\mathcal{Z}(\lambda)=\partial \Gamma
$$

Since $\Gamma$ is determined up to a 2 -cycle on $X$, we may set as before

$$
I(z, \omega, \lambda)=\int_{\Gamma} \omega \bmod \text { periods }
$$

Here, $\omega \in H^{0}\left(\Omega_{X / \mathbb{C}}^{2}\right)$ is all that is needed to make the definition. Again as before, if $\lambda=\partial \Delta$ then

$$
I(z, \omega, \lambda)=\int_{\Delta} \operatorname{Trace}_{\mathcal{Z}} \omega
$$

To show that $I(z, \omega, \cdot)$ depends only on the $k$-rational equivalence class of $z$, we may argue as before using the description of the pairing

$$
H^{0}\left(\Omega_{X / \mathbb{Q}}^{2}\right) \otimes T Z^{2}(X) \rightarrow \Omega_{\mathbb{C} / \mathbb{Q}}^{1}
$$

satisfying

$$
H^{0}\left(\Omega_{X / \mathbb{Q}}^{2}\right) \otimes T Z_{\mathrm{rat}}^{2}(X) \rightarrow 0
$$

For this argument we need that $\omega$ is the image in $H^{0}\left(\Omega_{X / \mathbb{C}}^{2}\right)$ of some $\widetilde{\omega} \in$ $H^{0}\left(\Omega_{X / \mathbb{Q}}^{2}\right)$.

The relation between this construction and the preceding is that, when $X$ is regular, we may take

$$
\Gamma=\bigcup_{s \in \lambda} \gamma_{s}
$$

### 9.3 SURFACES IN $\mathbb{P}^{3}$

We shall prove the following
Proposition 9.16: Let $X$ be a general surface of degree $d \geq 5$ in $\mathbb{P}^{3}$. Then

$$
T X \cap T Z_{\mathrm{rat}}^{2}(X)=0
$$

This means that for any point $p \in X$ and non-zero $v \in T_{p} X$, the image of $\tau=(p, v)$ in $T Z^{2}(X)$ is not tangent to rational equivalence.

We intend Proposition 9.16 as an illustration of how the spread perspective suggests geometric approaches, rather than as a "state of art" result. In fact, the following corollary due to Herb Clemens is well known and can be improved into a lower bound on the genus - see [10] and [11] for this result and for references to earlier work.

Corollary: A generic surface of degree $d \geqq 5$ in $\mathbb{P}^{3}$ contains no rational curves. ${ }^{4}$

Suppose the proposition is false. Then for a general $X$ there is a point $p \in X$ such that

$$
T_{p} X \cap T Z_{\mathrm{rat}}^{2}(X) \neq 0 .
$$

Let

be the spread of $(X, p)$ and set $k=\mathbb{Q}(S)$. Throughout the argument we shall allow ourselves to shrink $S$ and to pass to finite coverings $S^{\prime} \rightarrow S$; i.e., to pass to finite algebraic extensions $k^{\prime}$ of $k$. Thus we may assume that $\mathcal{X}=\left\{X_{s}\right\}_{s \in S}$ is a smooth family of smooth surfaces in $\mathbb{P}^{3}$ and $\mathcal{P}=\{p(s)\}_{s \in S}$ with $p(s) \in X$ is a cross-section of $\mathcal{X} \rightarrow S$. We denote by $(X, p)=\left(X_{s_{0}}, p\left(s_{0}\right)\right)$ the data corresponding to a generic point $s_{0} \in S$. We then have

$$
\begin{equation*}
\Omega_{k / \mathbb{Q}}^{1} \cong T_{s_{0}}^{*} S \tag{9.18}
\end{equation*}
$$

as $k$-vector spaces. By our assumption of genericity and since $d \geqq 5$, the Kodaira-Spencer mapping

$$
\rho: T_{s_{0}} S \rightarrow H^{1}\left(\Theta_{X}\right)
$$

is surjective. Using the identification (9.18) it follows that the extension class

$$
\begin{equation*}
e \in \operatorname{Hom}\left(\Omega_{k / \mathbb{Q}}^{1 *}, H^{1}\left(\Theta_{X}\right)\right) \tag{9.19}
\end{equation*}
$$

of

$$
0 \rightarrow \Omega_{k / \mathbb{Q}}^{1} \otimes \mathcal{O}_{X(k)} \rightarrow \Omega_{X(k) / \mathbb{Q}}^{1} \rightarrow \Omega_{X(k) / k}^{1} \rightarrow 0
$$

is surjective.
In first approximation, we may think of our situation in coordinates as follows: The surface $X$ is defined by

$$
F(x)=\sum_{I} a_{I} x^{I}=0,
$$

where we are using multi-index notation, the $a_{I}$ are independent transcendentals, and

$$
p(a)=\left[p_{0}(a), p_{1}(a), p_{2}(a), p_{3}(a)\right]
$$

where $a=\left(\cdots, a_{I}, \cdots\right)$. More precisely, $k$ will be a finite algebraic extension of $\mathbb{Q}\left(\cdots, a_{I}, \cdots\right)$ and are working over an open set in $S$ where the $a_{I}$ are local uniformizing parameters, so that expressions such as

$$
\frac{\partial p_{i}(a)}{\partial a_{I}}
$$

[^22]are defined. If $V^{*}=H^{0}\left(\mathcal{O}_{\mathbb{P}^{3}}(1)\right)$, then $\Omega_{k / \mathbb{Q}}^{1}$ has basis $d a_{I}$ and
$$
\Omega_{k / \mathbb{Q}}^{1 *} \cong V^{d}
$$
where $V^{d}=\operatorname{Sym}^{d} V$. The idea is that the cohomology groups $H^{0}\left(\Omega_{X(k) / k}^{2}\right)$ and $H^{1}\left(\Omega_{X(k) / k}^{1}\right)$ and the arithmetic Gauss-Manin connection $\nabla$ have polynomial descriptions, and that consequently the calculation of the pairing
$$
\langle\xi, \tau\rangle
$$
where
$$
\xi \in T Z_{\mathrm{rat}}^{2}(X(k))^{\perp} \cong \operatorname{ker}\left\{H^{0}\left(\Omega_{X(k) / k}^{2} \otimes \Omega_{k / \mathbb{Q}}^{1 *} \rightarrow H^{1}\left(\Omega_{X(k) / k}^{1}\right)\right\}\right.
$$
can be reduced to algebra.
We shall now explain the main computational step in the proof. Set
$$
I=\operatorname{ker}\left\{H^{0}\left(\Omega_{X(k) / k}^{2}\right) \otimes \Omega_{k / \mathbb{Q}}^{1 *} \rightarrow H^{1}\left(\Omega_{X(k) / k}^{1}\right)\right\} .
$$

Let $F_{i}=F_{x_{i}}$ and let

$$
J=\underset{k \geqq d-1}{\oplus} J^{k}=\left\{F_{0}, F_{1}, F_{2}, F_{2}\right\}
$$

be the Jacobi ideal. Then it is well known that

$$
\begin{gathered}
H^{0}\left(\Omega_{X(k) / k}^{2}\right) \cong V^{d-4} \\
H^{1}\left(\Omega_{X(k) / k}^{1}\right)_{\text {prim }} \cong V^{2 d-4} / J^{2 d-4}
\end{gathered}
$$

where $H^{1}\left(\Omega_{X^{(k) / k}}^{1}\right)_{\text {prim }}$ is the primitive part of the cohomology,

$$
H^{1}\left(\Theta_{X(k)}\right) \cong V^{d} / J^{d}
$$

and by our choice of $k$

$$
\Omega_{k / Q}^{1 *} \cong V^{d} .
$$

Moreover the Kodaira-Spencer map $\rho$ and arithmetic Gauss-Manin connection $\nabla$ are given, using these identifications, by

$$
\left\{\begin{array}{l}
V^{d} \xrightarrow{\rho} V^{d} / J^{d} \\
V^{d-4} \otimes V^{d} \xrightarrow{\nabla} V^{2 d-4} / J^{2 d-4}
\end{array}\right.
$$

where the second map is just polynomial multiplication. We set

$$
K=\operatorname{ker}\left\{V^{d-4} \otimes V^{d} \rightarrow V^{2 d-4} / J^{2 d-4}\right\}
$$

Then

$$
\begin{equation*}
K=\left\{\xi=\sum_{I} H_{I} \otimes x^{I}: \sum_{I} H_{I} x^{I}=\sum_{i} R_{i} F_{i}\right\} \tag{9.20}
\end{equation*}
$$

where $H_{I} \in V^{d-4}$ and $R_{i} \in V^{d-3}$. Recalling that $p=p\left(\ldots, a_{I}, \ldots\right)$ is a cross-section of $\mathcal{X} \rightarrow S$ we define

$$
W_{\xi}(p)=\left(W_{\xi, 0}(p), W_{\xi, 1}(p), W_{\xi, 2}(p), W_{\xi, 3}(p)\right)
$$

where

$$
\begin{equation*}
W_{\xi, i}(p)=\sum_{I} H_{I}(p(a)) \frac{\partial p_{i}(a)}{\partial a_{I}}+R_{i}(p(a)) \tag{9.21}
\end{equation*}
$$

Lemma 1: $W_{\xi} \in T_{p} X$, and up to a non-zero scale factor

$$
\langle\xi, \tau\rangle=\left|\begin{array}{cccc}
p_{0} & p_{1} & p_{2} & p_{3}  \tag{9.22}\\
v_{0} & v_{1} & v_{2} & v_{3} \\
W_{\xi, 0}(p) & W_{\xi, 1}(p) & W_{\xi, 2}(p) & W_{\xi, 3}(p)
\end{array}\right|
$$

Here, $T_{p} X$ is being identified with $V / k \cdot p$, so that $k \cdot p+T_{p} X$ is given by

$$
\left\{w=\left(w_{0}, w_{1}, w_{2}, w_{3}\right): \sum_{i} F_{i}(p) w_{i}=0\right\}
$$

and $\tau=(p, v) \in T_{p} X$ where $v=\left(v_{0}, v_{1}, v_{2}, v_{3}\right)$ in (9.22) above.
The proof of the proposition will follow from (9.22) together with
Lemma 2: If $d \geq 5$, then for every $p \in X$

$$
W: K \rightarrow T_{p} X
$$

given by $\xi \rightarrow W_{\xi}(p)$, is surjective.
Proof of Lemma 1: We will compute in affine coordinates and then express the result in homogeneous coordinates. Thus, let $\mathcal{U} \subset \mathbb{P}^{3}$ be one of the standard affine open sets with coordinates $x_{1}, x_{2}, x_{3}$ obtained by setting one of the homogeneous coordinates, say $x_{0}$, equal to one. Denote by $f, h$ the affine versions obtained from $F, H$ by setting $x_{0}=1$. Then we have on $X$

$$
f_{1} d x_{1}+f_{2} d x_{2}+f_{3} d x_{3}=-\sum_{I} f_{a_{I}} d a_{I}=-\sum_{I} x^{I} d a_{I}
$$

since $f=\sum_{I} a_{I} x^{I}$. This gives the equality

$$
f_{1} d x_{1} \wedge d x_{3}+f_{2} d x_{2} \wedge d x_{3}=-\sum_{I} x^{I} d a_{I} \wedge d x_{3}
$$

of absolute differentials on $X$. On the open set where $f_{1} \neq 0, f_{2} \neq 0$ this gives

$$
\begin{equation*}
\frac{h d x_{2} \wedge d x_{3}}{f_{1}}=\frac{h d x_{3} \wedge d x_{1}}{f_{2}}-\frac{\sum_{I} h x^{I} d a_{I} \wedge d x_{3}}{f_{1} f_{2}} \tag{i}
\end{equation*}
$$

where $\operatorname{deg} h \leqq d-4$. If we are considering ordinary differential forms - i.e., sections of $\Omega_{X(k) / k}^{2}$ - then the right hand term drops out and the equality expresses the fact that the Poincaré residue of $\Omega=\left(h d x_{1} \wedge d x_{2} \wedge d x_{3}\right) / f$ may be computed in a well-defined manner by writing

$$
\Omega=\omega \wedge \frac{d f}{f}
$$

and mapping

$$
\left.\Omega \rightarrow \omega\right|_{X}
$$

However, as expressed by (i) the Poincaré residue operator is not well-defined for absolute differentials, and this is the central point of the computation.

Suppose now that

$$
\xi=\sum_{I} h_{I} \otimes x^{I} \in I
$$

so that we have

$$
\begin{equation*}
\sum_{I} h_{I} x^{I}=\sum_{i} r_{i} f_{i} \tag{ii}
\end{equation*}
$$

Then using

$$
v_{1} f_{1}(p)+v_{2} f_{2}(p)+v_{3} f_{3}(p)=0
$$

for $v=\left(v_{1}, v_{2}, v_{3}\right) \in T_{p} X$ we obtain from (i) and (ii) that

$$
\text { (iii) } \begin{aligned}
\left.\sum_{I} \frac{\partial}{\partial a_{I}}\right\rfloor & \left.\left(\frac{h_{I}\left(v_{2} d p_{3}-v_{3} d p_{2}\right)}{f_{1}(p)}\right)-\sum_{I} \frac{\partial}{\partial a_{I}}\right\rfloor\left(\frac{h_{I}\left(v_{3} d p_{1}-v_{1} d p_{3}\right)}{f_{2}(p)}\right) \\
= & -\sum_{I} \frac{h_{I} x^{I} v_{3}}{f_{1}(p) f_{2}(p)} \\
& =-\frac{r_{1} f_{1}(p) v_{3}-r_{2} f_{2}(p) v_{3}+r_{3} f_{1}(p) v_{1}+r_{3} f_{2}(p) v_{2}}{f_{1}(p) f_{2}(p)} \\
& =\frac{r_{3} v_{2}-r_{2} v_{3}}{f_{1}(p)}-\frac{r_{1} v_{3}-r_{3} v_{1}}{f_{2}(p)}
\end{aligned}
$$

Expressing this in homogeneous coordinates we find that the expression (iv)

$$
\left.\sum_{I} \frac{\partial}{\partial a_{I}}\right\rfloor H_{I}(p) \frac{\left|\begin{array}{cccc}
p_{0} & p_{1} & p_{2} & p_{3} \\
v_{0} & v_{1} & v_{2} & v_{3} \\
d p_{0} & d p_{1} & d p_{2} & d p_{3}
\end{array}\right|}{F_{1}(p)}+\frac{\left|\begin{array}{cccc}
p_{0} & p_{1} & p_{2} & p_{3} \\
v_{0} & v_{1} & v_{2} & v_{3} \\
R_{0}(p) & R_{1}(p) & R_{2}(p) & R_{3}(p)
\end{array}\right|}{F_{1}(p)}
$$

which is defined and regular in the open set $U_{1}=\left\{F_{1}=0\right\}$, is equal to the same expression with $F_{1}(p)$ replaced by $F_{2}(p)$ when we consider it in $U_{2}$.

Now we are essentially done. Set $\Omega_{I}=\left(h_{I} d x_{1} \wedge d x_{2} \wedge d x_{3}\right) / f$ and denote by $\omega_{I} \in H^{o}\left(\Omega_{X(k) / k}^{2}\right)$ the usual Poincaré residue of $\Omega_{I}$. Denote by

$$
\widetilde{\omega}_{I, 1}=h_{I} \frac{d x_{2} \wedge d x_{3}}{f_{1}}
$$

the above lifting of $\omega_{I}$ to an absolute differential in $U_{1}$, and similarly for $U_{2}$ and $U_{3}$. Our hypothesis is that

$$
\begin{equation*}
\sum_{I} \rho\left(\partial / \partial a_{I}\right) \omega_{I}=0 \text { in } H^{1}\left(\Omega_{X(k) / k}^{1}\right) . \tag{v}
\end{equation*}
$$

The left hand side of this equation is computed, relative to the covering $U_{i}$, by lifting $\omega_{I} \mid U_{i}$ to an absolute differential as above, and then taking in $U_{1} \cap U_{2}$

$$
\left.\sum_{I} \frac{\partial}{\partial a_{I}}\right\rfloor\left(\widetilde{\omega}_{I, 2}-\widetilde{\omega}_{I, 2}\right)
$$

By assumption this is a coboundary $\sigma_{1}-\sigma_{2}$, and equation (iv) above gives an explicit expression for this coboundary. Over $U_{1} \cap U_{2}$ we thus have

$$
\begin{equation*}
\left.\left.\sum_{I} \frac{\partial}{\partial a_{I}}\right\rfloor \widetilde{\omega}_{I, 1}+\sigma_{1}=\sum_{I} \frac{\partial}{\partial a_{I}}\right\rfloor \widetilde{\omega}_{I, 2}+\sigma_{2} \tag{vi}
\end{equation*}
$$

We now follow the prescription in section 10.1 for evaluating an absolute 2-form on $v \in T_{p} X$ to obtain an element of $\Omega_{k / \mathbb{Q}}^{1}$, given over $U_{1}$ by the expression in (iv) above.

To complete the proof of the lemma we differentiate $0=F(p)=\sum_{I} a_{I} p^{I}$ to obtain

$$
\frac{\partial F}{\partial a_{I}}(p)+\sum_{j} \frac{\partial p_{j}}{\partial a_{I}} F_{j}(p)=0
$$

This gives

$$
\sum_{I} H_{I}(p) \frac{\partial F}{\partial a_{I}}(p)+\sum H_{I}(p) \frac{\partial p_{j}}{\partial a_{I}} F_{j}(p)=0
$$

Using $\sum_{I} H_{I}(x) x^{I}=\sum_{j} R_{j}(x) F_{j}(x)$ at $x=p$ gives

$$
\begin{gathered}
\sum_{I} H_{I}(p) p^{I}=\sum_{j} R_{j}(p) F_{j}(p) \\
\Rightarrow \sum_{j}\left(\sum_{I} H_{I}(p) \frac{\partial p_{j}}{\partial a_{I}}+R_{j}(p)\right) F_{j}(p)=0 .
\end{gathered}
$$

The term in the parenthesis is just $W_{\xi, j}(p)$, which is also the $j^{\text {th }}$ component in the bottom row of the determinants in (iv).
Proof of Lemma 2: Suppose that there exist $c_{j}$ such that

$$
\sum_{j} c_{j} W_{\xi, j}(p)=0
$$

for all $\xi \in K$. We will show that

$$
\begin{equation*}
c_{j}=\lambda F_{j}(p) \tag{9.23}
\end{equation*}
$$

for some $\lambda$. The proof will be done in two steps.
Step one: Let

$$
K_{0}=\operatorname{ker}\left\{V^{d-4} \otimes V^{d} \rightarrow V^{2 d-4}\right\}
$$

We will show that

$$
\begin{equation*}
W_{\xi}(p)=0 \text { for all } \xi \in K_{0} \Leftrightarrow \frac{\partial p_{j}}{\partial a_{I}}=\lambda_{j} p^{I} \tag{9.24}
\end{equation*}
$$

for some $\lambda_{0}, \lambda_{1}, \lambda_{2}, \lambda_{3}$.
For this we have that $K_{0}$ is generated by relations of the form

$$
\begin{equation*}
x_{i} R \otimes x_{j} S-x_{j} R \otimes x_{i} S \tag{9.25}
\end{equation*}
$$

In fact, any relation of the form

$$
x^{I} \otimes x^{J}-x^{I^{\prime}} \otimes x^{J^{\prime}}
$$

where $|I|=\left|I^{\prime}\right|=d-4,|J|=\left|J^{\prime}\right|=d$ and $I+J=I^{\prime}+J^{\prime}$ is generated by relations (9.25) as they allow us to "trade" $x_{i}$ and $x_{j}$ across the tensor product.

We now define the sheaf $\mathcal{R}$ over $\mathbb{P}^{3}$ by

$$
0 \rightarrow \mathcal{R} \rightarrow V^{d} \otimes \mathcal{O}_{\mathbb{P}^{3}} \rightarrow \mathcal{O}_{\mathbb{P}^{3}}(d) \rightarrow 0
$$

We claim that

$$
\begin{equation*}
H^{o}(\mathcal{R}(1)) \otimes \mathcal{O}_{\mathbb{P}^{3}} \rightarrow \mathcal{R}(1) \rightarrow 0 \tag{9.26}
\end{equation*}
$$

is surjective. For this we first observe that

$$
\text { image }\left\{V^{d-1} \otimes \Lambda^{2} V \rightarrow V^{d} \otimes V\right\} \subseteq H^{o}(\mathcal{R}(1))
$$

Since we are dealing with vector bundles it is enough to check (9.26) pointwise. Since the entire question is $G L(V)$ equivariant it is enough to check that, in homogeneous coordinates $x_{0}, x_{1}, x_{2}, x_{3}$ at $p=[1,0,0,0]$,

$$
\text { Image }\left\{V^{d-1} \otimes \Lambda^{2} V \rightarrow V^{d} \otimes V\right\}_{p}=\mathcal{R}(1)_{p}
$$

Now

$$
\mathcal{R}(1)_{p}=\oplus \mathcal{O}_{\mathbb{P}^{3}}(1)_{p}
$$

when the direct sum is over all monomials except $x_{0}^{d}$. Since the map $V^{d-1} \otimes$ $\Lambda^{2} V \rightarrow V^{d} \otimes V \rightarrow \mathcal{R}(1)_{p}$ is given by

$$
x^{I} \otimes x_{j} \wedge x_{k} \rightarrow x^{I+j} \otimes \delta_{0 k}-x^{I+k} \otimes \delta_{0 j}
$$

we see that

$$
x^{I} \otimes x_{j} \wedge x_{0} \rightarrow x^{I+j} \otimes 1
$$

if $j \neq 0$. Thus we hit every monomial except $x_{0}^{d}$ and this establishes (9.26).
We now observe that, for $d \geqq 5$

$$
\begin{equation*}
H^{o}(\mathcal{R}(d-4)) \otimes \mathcal{O}_{\mathbb{P}^{3}} \rightarrow \mathcal{R}(d-4) \rightarrow 0 \tag{9.27}
\end{equation*}
$$

is surjective. This follows from (9.26), since for $d \geqq 5$

$$
H^{o}\left(\mathcal{O}_{\mathbb{P}^{3}}(d-5)\right) \otimes \mathcal{O}_{\mathbb{P}^{3}} \rightarrow \mathcal{O}_{\mathbb{P}^{3}}(d-5) \rightarrow 0
$$

is surjective.
We will now prove (9.24). The composite map

$$
\begin{equation*}
K_{0}=H^{o}(\mathcal{R}(d-4)) \rightarrow \mathcal{R}(d-4)_{p} \rightarrow V^{d} \otimes \mathcal{O}_{\mathbb{P}^{3}}(d-4)_{p} \tag{9.28}
\end{equation*}
$$

is

$$
\xi=\sum_{I} H_{I} \otimes x^{I} \rightarrow \sum_{I} x^{I} \otimes H_{I}(p)
$$

where $\sum_{I} H_{I}(x) x^{I}=0$. If

$$
c=\sum_{I}\left(x^{I}\right)^{*} \otimes c_{I} \in\left(V^{d}\right)^{*}
$$

annihilates the image of (9.28), so that

$$
\begin{equation*}
\sum_{I} H_{I}(p) c_{I}=0 \text { for all } \xi \in K_{0} \tag{9.29}
\end{equation*}
$$

then since by (9.27)

$$
\begin{gathered}
\left(\operatorname{Im} K_{0}\right)^{\perp}=\mathcal{R}(d-4)_{p}^{\perp} \\
\mathcal{R}(d-4)_{p} \subset V^{d} \otimes \mathcal{O}_{\mathbb{P}^{3}}(d-4)_{p}
\end{gathered}
$$

has codimension one, and

$$
\sum_{i}\left(x^{I}\right)^{*} \otimes p^{I} \in V^{d *} \otimes \mathcal{O}_{\mathbb{P}^{3}}(d)_{p}
$$

is a generator of $\mathcal{R}(d-4)_{p}^{\perp}$, we infer from (9.29) that

$$
c_{I}=\lambda p^{I}
$$

for some constant $\lambda$. Applying this to $c_{I}=\frac{\partial p_{j}}{\partial a_{I}}$ for each $j$ gives (9.24).
Step two: Now suppose that

$$
\begin{equation*}
\sum_{j} \sum_{I} H_{I}(p) c_{j} \frac{\partial p_{j}}{\partial a_{I}}+\sum_{j} c_{j} R_{j}(p)=0 \tag{9.30}
\end{equation*}
$$

for all $\xi \in K$. Using only $K_{0}$ we have (9.24). Substituting in the left hand side of (9.30) we obtain for $\lambda=\sum_{j} c_{j} \lambda_{j}$

$$
\begin{aligned}
0 & =\lambda\left(\sum_{I} H_{I}(p) p^{I}\right)+\sum_{j} c_{j} R_{j}(p) \\
& =\lambda\left(\sum_{j} R_{j}(p) F_{j}(p)\right)+\sum_{j} c_{j} R_{j}(p) \\
& =\sum_{j} R_{j}(p)\left(\lambda F_{j}(p)+c_{j}\right)
\end{aligned}
$$

Since this holds for all $R_{j}$ of degree $d-3$ we have

$$
\lambda F_{j}(p)+c_{j}=0 \quad j=0,1,2,3
$$

as desired.
It remains to discuss the argument when there exists a pair $(X, p)$ with

$$
T_{p} X \cap T Z_{\mathrm{rat}}^{2}(X) \neq 0
$$

defined over a general field $k$; say $k$ is a finite algebraic extension of $\mathbb{Q}\left(\alpha_{1}, \ldots, \alpha_{N}\right)$. The important fact is that, if $X$ is general, then the KodairaSpencer map

$$
\Omega_{k / \mathbb{Q}}^{1 *} \rightarrow H^{1}\left(\Theta_{X(k)}\right) \cong V^{d} / J^{d}
$$

should be surjective. With this being so the previous argument can be easily extended to cover the more general case.

Analysis of the proof shows that essentially the same argument gives

For $X \subset \mathbb{P}^{3}$ a general surface of degree $d \geqq 6$ and $p, q$ any distinct points of $X$ we have

$$
\left(T_{p}(X)+T_{q}(X)\right) \cap T Z_{\mathrm{rat}}^{2}(X)=0
$$

Corollary: A general surface of degree at least six contains no curve having a $g_{2}^{1}$.

We suspect that the method can be extended to give a proof of the
Conjecture: Given $k$ there is $d(k)$ such that a general surface in $\mathbb{P}^{3}$ of degree $d \geqq d(k)$ contains no curve having a $g_{k}^{1}$.
Discussion: What is needed to prove (9.31) is first of all to replace (9.27) by the surjectivity of

$$
H^{o}(\mathcal{R}(d-4)) \otimes \mathcal{O}_{\mathbb{P}^{3}} \rightarrow \mathcal{R}(d-4)_{p} \oplus \mathcal{R}(d-4)_{q},
$$

and this follows from (9.26) together with the surjectivity of

$$
H^{o}\left(\mathcal{O}_{\mathbb{P}^{3}}(d-5)\right) \otimes \mathcal{O}_{\mathbb{P}^{3}} \rightarrow \mathcal{O}_{\mathbb{P}^{3}}(d-5)_{p} \oplus \mathcal{O}_{\mathbb{P}^{3}}(d-5)_{q}
$$

for $d \geqq 6$. This means that effectively in the proof of (9.24) we may treat $p$ and $q$ as acting independently - i.e., we may repeat the argument just below (9.23) where the $H_{I}(q)=0$. This gives (9.24) for each of $p$ and $q$. Then under (9.30) we may repeat the argument to conclude the result.

### 9.3.1 Appendix A to section 9.3: On a theorem of Voisin

In [31] the following result is established: ${ }^{5}$
(i) Let $X \subset \mathbb{P}^{3}$ be a general surface of degree at least seven. Then no two distinct points of $X$ are rationally equivalent.

This result is similar to proposition 9.16 above, and Voisin's proof has the similarities that infinitesimal methods are used and that the argument is reduced to polynomial algebra. But the result does not follow from our descriptions of $T Z^{2}(X)$ and $T C H^{2}(X)$. Rather the proof uses the holomorphic 2-forms on $X$ in a fashion similar to that discussed in the appendix to section 10.1 above, only where now $X$ is allowed to vary.

In outline the argument goes as follows: We consider the situation

where $X=\left\{X_{s}\right\}_{s \in S}$ is the family of smooth surfaces of degree $d$ in $\mathbb{P}^{3}$ (passing here to a finite covering of the moduli space and restricting to a Zariski open set), and $Z=\left\{Z_{s}\right\}_{s \in S}$ is a family of 0-cycles of degree zero on the $X_{s}$. The fundamental class

$$
[z] \in H^{2}\left(\Omega_{x / \mathbb{C}}^{2}\right)
$$

[^23]Also, the Leray spectral sequence associated to the filtration

$$
F^{p} \Omega_{x / \mathbb{C}}^{p+q}=\operatorname{image}\left\{\Omega_{S / \mathbb{C}}^{p} \otimes \Omega_{X / \mathbb{C}}^{q} \rightarrow \Omega_{x / \mathbb{C}}^{p+q}\right\}
$$

degenerates at $E_{2}$ (cf. [18]). Moreover, the terms

$$
\left\{\begin{array}{l}
{[z]^{4,0}=0 \quad \text { in } E_{2}^{4,0} \text { since } \operatorname{deg} z_{s}=0} \\
{[z]^{3,1}=0 \quad \text { in } E_{2}^{3,2} \text { since } h^{3}\left(X_{s}\right)=0}
\end{array}\right.
$$

The $E_{2}^{2,2}$-term is expressed in terms of the variation of Hodge structure associated to $X \rightarrow S$ in a well-known manner

$$
E_{2}^{2,2}=\left(H^{2}\left(\Omega_{S / \mathbb{C}}^{2} \otimes \mathcal{H}^{2}\right)\right)_{\nabla}
$$

where

$$
\left\{\begin{array}{l}
\mathcal{H}^{2}=\mathbb{R}_{\pi}^{2} \Omega_{x / S} \\
\nabla=\text { Gauss-Manin connection and }()_{\nabla} \\
\text { is the cohomology computed from } \nabla
\end{array}\right.
$$

Passing to the quotient $\mathcal{H}^{2} \rightarrow R_{\pi}^{2} \mathcal{O}$, the class [ []$^{2,2}$ gives

$$
\begin{equation*}
\delta \mathcal{Z} \in H^{0}\left(\Omega_{S / \mathbb{C}}^{2} \otimes \mathcal{H}^{0,2}\right) / \nabla H^{0}\left(\Omega_{S / \mathbb{C}}^{1} \otimes \mathcal{H}^{1,1}\right) \tag{ii}
\end{equation*}
$$

This $\delta \mathcal{Z}$ is the extension to variable $X$ of the trace construction discussed above. In the language of S. Saito [20] it may be thought of as a higher normal function.
Next, using a variant of the argument of Bloch-Srinivas [17], Voisin infers that if for a general $s \in S$

$$
z_{s} \equiv_{\mathrm{rat}} 0,
$$

then modifying $Z$ by a rational equivalence - which does not change $[\mathcal{Z}]$ - we may assume that $\pi(Z)$ is supported in a proper subvariety of $S$. It follows at a general point

$$
\begin{equation*}
\delta \mathcal{Z}(s)=0 . \tag{iii}
\end{equation*}
$$

We now assume that for a general point $s \in S$ there are distinct points $p(s), q(s) \in X_{s}$ such that

$$
p(s) \equiv_{r a t} q(s) .
$$

Taking $z_{s}=p(s)-q(s)$ we are in the above situation. The final geometric step is to show by explicit computation that for a general $s$

$$
\begin{equation*}
\delta \mathcal{Z}(s) \neq 0 \tag{iv}
\end{equation*}
$$

in contradiction to (iii). Shrinking $S$ if necessary, $H^{0}\left(\Omega_{S / \mathbb{C}}^{2} \otimes \mathcal{H}^{0,2}\right)$ is the space of sections of a vector bundle with fibers

$$
\frac{\Lambda^{2} T_{s}^{*} S \otimes H^{2}\left(\mathcal{O}_{X_{s}}\right)}{\nabla\left(T_{s}^{*} S \otimes H^{1}\left(\Omega_{X_{s} / \mathbb{C}}^{1}\right)\right)} \cong \operatorname{Hom}\left(H^{0}\left(\Omega_{X_{s} / \mathbb{C}}^{2}\right), \Lambda^{2} T_{s}^{*} S\right)
$$

The right hand side of this isomorphism has a polynomial description, and calculations very similar to those above may now be used to establish (iv). We refer to [31] for details.

At this juncture, very roughly speaking
we may say that for arguments using 2-forms "generic" means "outside a countable union of proper subvarieties", while for those using $T Z^{p}(X)$ and $T C H^{2}(X)$ "generic" refers to the "transcendental independence of suitable coefficients of defining relations".

### 9.4 EXAMPLE: $\left(\mathbb{P}^{2}, T\right)$

The one example where the non-classical part of the Chow group is nontrivial and understood seems to be the case of 0 -cycles on the relative variety $\left(\mathbb{P}^{2}, T\right)$ where $T$ is a triangle. We will explain this result, which is due to Bloch and Suslin (cf. [7], [21], [26]), and discuss how it relates to our infinitesimal story. Before doing that we want to set a context for why one might be interested in $\left(\mathbb{P}^{2}, T\right)$.

In the early days of algebraic geometry it was recognized that the integral

$$
\begin{equation*}
\int \frac{d x}{\sqrt{x^{3}+a x+b}} \tag{9.32}
\end{equation*}
$$

was fundamentally different from the trigonometric/logarithmic integrals that arise from integrals of rational differentials on rational curves. One might hope to gain some insight into (9.32) by degenerating a smooth cubic into one with an ordinary double point. The singular curve is a $\mathbb{P}^{1}$ with two points, say 0 and $\infty$, identified. Functions on the singular curve are given by rational functions $f$ on $\mathbb{P}^{1}$ with $f(0)=f(\infty)$, and the limit of the integrand in (9.33) is a rational differential on $\mathbb{P}^{1}$ with logarithmic singularities at 0 and $\infty$. Setting $T_{0}=\{0, \infty\}$ we are studying the relative curve $\left(\mathbb{P}^{1}, T_{0}\right)$ and the limit of (9.32) on the singular curve is easily understood.

Specifically, denoting by $x$ a coordinate on $\mathbb{C}^{*} \subset \mathbb{P}^{1}$ we consider zero cycles

$$
z=\sum_{i} n_{i} x_{i} \quad x_{i} \in \mathbb{P}^{1} \backslash T_{0} \cong \mathbb{C}^{*}
$$

and the (mixed) Hodge-theoretic conditions that $z$ be the divisor of a function $f \in \mathbb{C}\left(\mathbb{P}^{1}\right)$ with $f(0)=f(\infty)$ are

$$
\begin{align*}
& \psi_{0}(z)=\int_{z} 1=0  \tag{i}\\
& \psi_{1}(z)=\int_{\gamma} \omega \equiv 0 \bmod \text { periods } \tag{9.33}
\end{align*}
$$

where $\partial \gamma=z$ and $\omega=d x / x$. Conditions (i) and (ii) may of course be expressed in closed form as

$$
\begin{aligned}
& \sum_{i} n_{i}=0 \\
& \prod_{i} x_{i}^{n_{i}}=1
\end{aligned}
$$

We note that $x$ is determined up to scaling $x \rightarrow \lambda x$, and $\prod_{i} x_{i}^{n_{i}}$ is independent of the scaling if (i) is satisfied. In summary we have isomorphisms

$$
\left\{\begin{array}{l}
\psi_{0}: C H^{1}(X) \rightarrow \mathbb{Z} \\
\psi_{1}: C H^{1}(X)_{0} \rightarrow \mathbb{C}^{*}
\end{array}\right.
$$

where $C H^{1}(X)_{0}$ is the kernel of $\psi_{0}$.
Implicit in the above discussion is the following point: If for $a \in \mathbb{P}^{1} \backslash T_{0} \cong$ $\mathbb{C}^{*}$ we denote by $(a) \in Z^{1}\left(\mathbb{P}^{1}, T_{0}\right)$ that point considered as a 0 -cycle, then we may define a map

$$
\mathbb{C}^{*} \rightarrow C H^{1}\left(\mathbb{P}^{1}, T\right)_{0}
$$

by

$$
a \rightarrow(a)-(1)
$$

Then this map is a group homomorphism. For the proof we set

$$
f=\frac{(x-a b)(x-1)}{(x-a)(x-b)} \in \mathbb{C}\left(\mathbb{P}^{1}, T_{0}\right)
$$

and observe that

$$
\begin{align*}
& \operatorname{div} f=(a b)-(a)-(b)+(1)  \tag{9.34}\\
& \Rightarrow(a b)-1 \equiv_{\mathrm{rat}}(a)-1+(b)-(1)
\end{align*}
$$

Actually, anticipating what will happen below for surfaces, in terms of equations we could degenerate the above cubic into what is in some ways the simplest singular cubic, namely a triangle $T$


Each side of $T$ is a $\mathbb{P}^{1}$ with two marked points, and the above discussion of ( $\mathbb{P}^{1}, T_{0}$ ) can be easily extended to the triangle case using that the limit of the regular differential $d x / \sqrt{x^{3}+a x+b}$ on the smooth cubic induces on $T$ a differential with logarithmic singularities and having opposite residues at the vertices.

When we turn to algebraic surfaces, say smooth surfaces $X \subset \mathbb{P}^{3}$, the first one for which $C H^{2}(X)$ isn't understood is when $\operatorname{deg} X=4$. By analogy with the curve case above, one might degenerate $X$ into a tetrahedron $X_{0}$ and seek to understand $C H^{2}(X)$. Now the faces of a tetrahedron may be considered as relative surfaces biregularly equivalent to $\left(\mathbb{P}^{2}, T\right)$, and it turns
out that one may also describe $C H^{2}\left(X_{0}\right)$ by understanding $C H^{2}\left(\mathbb{P}^{2}, T\right)$. The latter is what we shall now describe.

We identify $\mathbb{P}^{2} \backslash T$ with $\mathbb{C}^{*} \times \mathbb{C}^{*}$ having coordinates $x, y$; these are unique up to scalings. The (mixed) Hodge theory of $\left(\mathbb{P}^{2}, T\right)$ has as basis the following differential forms

$$
\left\{\begin{array}{l}
1 \in F^{0} H^{0}\left(\Omega_{\mathbb{P}^{2}}^{0}(\log T)\right) \\
\frac{d x}{x}, \frac{d y}{y} \in F^{1} H^{0}\left(\Omega_{\mathbb{P}^{2}}^{1}(\log T)\right) \\
\frac{d x}{x} \wedge \frac{d y}{y} \in F^{2} H^{0}\left(\Omega_{\mathbb{P}^{2}}^{2}(\log T)\right)
\end{array}\right.
$$

We may write 0-cycles $z \in Z^{2}\left(\mathbb{P}^{2}, T\right)=Z^{2}\left(\mathbb{P}^{2} \backslash T\right)$ as

$$
z=\sum_{i} n_{i}\left(x_{i}, y_{i}\right)
$$

and define

$$
\begin{aligned}
& \psi_{0}: Z^{2}\left(\mathbb{P}^{2}, T\right) \rightarrow \mathbb{Z} \\
& \psi_{1}: Z^{2}\left(\mathbb{P}^{2}, T\right)_{0} \rightarrow \mathbb{C} \oplus \mathbb{C} \bmod \text { periods }
\end{aligned}
$$

by

$$
\psi_{0}(z)=\int_{z} 1=\sum_{i} n_{i}
$$

and

$$
\psi_{1}(z)=\left(\int_{\gamma} \frac{d x}{x}, \int_{\gamma} \frac{d y}{y}\right)
$$

where $\partial \gamma=z$. The periods are in $2 \pi \sqrt{-1} \mathbb{Z}=\mathbb{Z}(1)$, and identifying $\mathbb{C} / \mathbb{Z}(1)$ with $\mathbb{C}^{*}$ we have as in the case of $\left(\mathbb{P}^{1}, T_{0}\right)$

$$
\psi_{1}(z)=\left(\prod_{i} x_{i}^{n_{i}}, \Pi_{i} y_{i}^{n_{i}}\right) \in \mathbb{C}^{*} \oplus \mathbb{C}^{*}
$$

Since $\sum_{i} n_{i}=0$ this is independent of the scalings.
To complete the story, recall that in section 9.2 above we have discussed how one may define

$$
\psi_{2}(z)=\int_{\Gamma} \frac{d x}{x} \wedge \frac{d y}{y} \bmod \text { periods }
$$

in case $\psi_{0}(z)=\psi_{1}(z)=0$. We will turn to this below after we have identified $C H^{2}(X)_{1}$.

We set

$$
z_{a, b}=(a, b)-(a, 1)-(1, b)+(1,1) \in Z^{2}\left(\mathbb{P}^{2}, T\right)_{1}
$$

In the following picture of the projective plane the dotted lines all look like $\left(\mathbb{P}^{1}, T_{0}\right)$


Thus, e.g., by the argument that gives (9.34)

$$
\begin{cases}z_{a_{1} a_{2}, b} \equiv_{\mathrm{rat}} z_{a_{1}, b}+z_{a_{2}, b} & (\text { using } y=b) \\ z_{a, b_{1} b_{2}} \equiv_{\mathrm{rat}} z_{a, b_{1}}+z_{a}, b_{2} & (\text { using } x=a) \\ z_{a b, a b} \equiv_{\mathrm{rat}} 0 & (\text { using } x=y)\end{cases}
$$

Expanding the third relation using the first two gives

$$
z_{a, b}+z_{b, a} \equiv_{\text {rat }} 0
$$

Letting $\equiv_{\text {rat }} \subset Z^{2}\left(\mathbb{P}^{2}, T\right)_{1}$ be the equivalence relation generated by divisors of rational functions on algebraic curves $Y$ that have the same regular value on $Y \cap T$, the above shows that we have a well-defined map

$$
Z^{2}\left(\mathbb{P}^{2}, T\right)_{1} / \equiv_{\mathrm{rat}} \rightarrow \mathbb{C}^{*} \otimes_{\mathbb{Z}} \mathbb{C}^{*}
$$

given by

$$
z_{a, b} \rightarrow a \otimes b
$$

and whose image lies in $\Lambda_{\mathbb{Z}}^{2} \mathbb{C}^{*}$.
We have now used all the lines that meet the triangle in two points (all the lines $x=\lambda y$ are equivalent after scaling). Consider now the line $L$ given by

$$
x+y=1
$$

and on $L$ the function

$$
f=\prod_{i}\left(x-a_{i}\right)^{n_{i}}
$$

Then if $\sum_{i} n_{i}=0$ and

$$
\prod_{i} a_{i}^{n_{i}}=\prod_{i}\left(1-a_{i}\right)^{n_{i}}=1
$$

we have that $f \in \mathbb{C}(L, L \cap T)$ and thus

$$
\sum_{i} n_{i} z_{a_{i}, 1-a_{i}} \equiv_{\mathrm{rat}} 0
$$

This shows that the mapping

$$
\Lambda_{\mathbb{Z}}^{2} \mathbb{C}^{*} \rightarrow C H^{2}\left(\mathbb{P}^{2}, T\right)
$$

given by $a \wedge b \rightarrow z_{a, b}$ cannot be injective, and that in fact for rather simple geometric reasons Steinberg relations necessarily enter. We shall show that:

Proposition: The mapping

$$
Z^{2}\left(\mathbb{P}^{2}, T\right)_{1} \rightarrow K_{2}(\mathbb{C})
$$

given by

$$
\sum_{i} n_{i}\left(x_{i}, y_{i}\right) \rightarrow \prod_{i}\left\{x_{i}, y_{i}\right\}^{n_{i}}
$$

induces an isomorphism

$$
\begin{equation*}
C H^{2}\left(\mathbb{P}^{2}, T\right)_{1} \xrightarrow{\varphi} K_{2}(\mathbb{C}) . \tag{9.35}
\end{equation*}
$$

Proof: The proof proceeds in two steps. The proof of Totaro [9] was helpful in explaining the role of Suslin reciprocity here.

Step one: The mapping $\varphi$ in (9.35) is well-defined. Surprisingly, this is the harder step, since the second step will give an existence result. We have to show the following:

Let $Y$ be a smooth algebraic curve and

$$
Y \xrightarrow{F} \mathbb{P}^{2}
$$

a regular mapping which maps generically one-to-one onto its image. Let

$$
w=\sum_{i} n_{i} p_{i}, \quad p_{i} \in Y
$$

with $F\left(p_{i}\right)=\left(x_{i}, y_{i}\right)$, so that

$$
F(w)=z
$$

Set $D=F^{-1}(T)$ and let $h \in \mathbb{C}(Y, D)$; i.e., $h \in \mathbb{C}(Y)$ and $h=1$ on $D$. Then if

$$
\operatorname{div} h=\sum_{i} n_{i} p_{i}
$$

it follows from the Suslin reciprocity law that

$$
\begin{equation*}
\prod_{i}\left\{x_{i}, y_{i}\right\}^{n_{i}}=1 \in K_{2}(\mathbb{C}) \tag{9.36}
\end{equation*}
$$

We now sketch how this goes. For $p \in Y$ we define

$$
\partial_{p}: K_{m}^{M}(\mathbb{C}(Y)) \rightarrow K_{m-1}^{M}(\mathbb{C})
$$

by

$$
\begin{equation*}
\partial_{p}\left\{f_{1}, \ldots, f_{m}\right\}=\prod_{i<j}\left\{T_{p}\left\{f_{i}, f_{m}\right\}, f_{1}(p), \ldots, \hat{f}_{i}, \ldots, \hat{f}_{j}, . ., f_{m}(p)\right\}^{i+j-1} \tag{9.37}
\end{equation*}
$$

where we need a slightly more delicate definition if $f_{k}$ has a zero or a pole at $p$ for some $i \neq j$. Then Suslin's generalization of the Weil reciprocity law is

$$
\prod_{p \in Y} \partial_{p}\left\{f_{1}, \ldots, f_{m}\right\}=1 \in K_{m-1}^{M}(\mathbb{C})
$$

Now suppose that $Y \rightarrow \mathbb{P}^{2}$ is given in affine coordinates by $(f, g)$ where $f, g \in \mathbb{C}(Y)$. Then by (9.37) where $f_{1}=f, f_{2}=g$ and $f_{3}=h$

$$
\prod_{i}\left\{f\left(p_{i}\right), g\left(p_{i}\right)\right\}^{n_{i}} \underbrace{\prod_{\operatorname{div} f}\{g, h\} \prod_{\operatorname{div} g}\{h, f\}}=1
$$

The last two terms over the bracket are equal to one since $\{1, a\}=1$ in $K_{2}(\mathbb{C})$ and $h=1$ on $\operatorname{div} \cup \operatorname{div} g$.
Step two: The mapping $\varphi$ in (9.35) is injective. For the proof we consider the map

$$
Z^{1}\left(\mathbb{P}^{1}-\{0,1, \infty\}\right) \xrightarrow{\mathrm{St}} \Lambda_{\mathbb{Z}}^{2} \mathbb{C}^{*}
$$

given by

$$
\begin{equation*}
a \rightarrow a \wedge(1-a) \tag{i}
\end{equation*}
$$

In $Z^{1}\left(\mathbb{P}^{1}-\{0,1, \infty\}\right)$ we consider the subgroup of all

$$
\left\{\sum_{i} n_{i} a_{i}: \quad \sum_{i} n_{i}=0, \prod_{i} a_{i}^{n_{i}}=\prod_{i}(1-a)^{n_{i}}=1\right\}
$$

which under (i) maps by

$$
\begin{equation*}
\sum_{i} n_{i} a_{i} \rightarrow \sum_{i} n_{i} a_{i} \wedge\left(1-a_{i}\right) \tag{ii}
\end{equation*}
$$

It will suffice to show that

$$
\begin{equation*}
\text { Image }(\mathrm{i})=\text { Image }(\mathrm{ii}) \tag{iii}
\end{equation*}
$$

Indeed, we have seen above that

$$
\text { Image } \equiv_{\mathrm{rat}} \supseteq \text { Image (ii) }
$$

and by definition

$$
K_{2}(\mathbb{C})=\Lambda_{\mathbb{Z}}^{2} \mathbb{C}^{*} / \text { image }(\mathrm{i})
$$

from which our claim follows.
We set $B_{2}=$ ker St (this is the well known Bloch group). One set of elements in $B_{2}$ is, for any distinct points $a_{1}, \ldots, a_{5} \in \mathbb{P}^{1}-\{0,1, \infty\}$,

$$
\begin{equation*}
\sum_{\lambda}(-1)^{\lambda} \mathrm{CR}\left(a_{1}, \ldots, \widehat{a_{\lambda}}, \ldots, a_{5}\right) \tag{iv}
\end{equation*}
$$

where CR is closely related to the cross-ratio. (The fact that St (iv) $=0$ is closesly related to the famous 5 -term functional equation for the dilogarithm.) In particular, for any distinct points $a, b \in \mathbb{P}^{1}-\{0,1, \infty\}$

$$
(a)-(b)+\left(\frac{b(1-a)}{b-a}\right)-\left(\frac{b}{b-a}\right)+\left(\frac{b-1}{b-a}\right) \in B_{2}
$$

Now

$$
\frac{a\left(\frac{b(1-a)}{b-a}\right)-\left(\frac{b-1}{b-a}\right)}{b\left(\frac{b}{b-a}\right)}=\frac{a(a-1)(b-1)}{b(b-a)}
$$

and

$$
\frac{(1-a)\left(1-\frac{b(1-a)}{b-a}\right)\left(1-\frac{b-1}{b-a}\right)}{(1-b)\left(1-\frac{b}{b-a}\right)}=\frac{(1-a)^{2}}{b-a}
$$

For all $\alpha, \beta \in \mathbb{C}^{*}$ except for $\alpha=-\beta$ one may solve

$$
\left\{\begin{array}{c}
\frac{a(1-a)(b-1)}{b(b-a)}=\alpha  \tag{v}\\
\frac{1-a)}{b-a}^{2}=\beta
\end{array}\right.
$$

for $a, b \in \mathbb{P}^{1}-\{0,1, \infty\}$. In the exceptional case $\alpha=-\beta$ equation (v) forces $a=b=1$; in this case by a product of such relations one can obtain any $\alpha, \beta \in \mathbb{C}^{*}$.

Given a product

$$
\prod_{\nu}\left(c_{\nu} \wedge\left(1-c_{\nu}\right)\right)^{m_{v}} \in \text { Image St }
$$

with

$$
\prod_{\nu} c_{\nu}^{m_{\nu}}=\alpha, \prod_{\nu}\left(1-c_{\nu}\right)^{m_{\nu}}=\beta, \quad \sum_{\nu} m_{\nu}=m
$$

one may use an element of $B_{2}$ to change to the same element in Image St with $\alpha=\beta=1$. One may then use an element of $B_{2}$ to change to the same element in Image St with $m \rightarrow m-1$. This establishes (iii) and completes the proof of the proposition.
Remark. Proof analysis shows that rational equivalence of 0-cycles in $\mathbb{P}^{2}-T$ is generated by divisors of rational functions $f$ or lines $L$ such that $f=1$ or $L \cap T$.

In general, for any algebraic surface $X$ the relation of rational equivalence is generated by choosing a fixed very ample linear system $|L|$ and taking the divisors of rational functions on curves $Y \in|L|$.

Although we have not formally developed our infinitesimal theory for $T Z^{p}(X, Y)$ and $T C H^{p}(X, Y)$ in the relative case, it seems reasonable that this might be done. Making the identification

$$
F^{2} H^{0}\left(\Omega_{\mathbb{P}^{2} / \mathbb{C}}^{2}(\log T)\right) \cong \mathbb{C} \omega
$$

where $\omega=(d x / x) \wedge(d y / y)$, one would then expect that

$$
\begin{equation*}
T G r^{2} C H^{2}\left(\mathbb{P}^{2}, T\right) \cong \Omega_{\mathbb{C} / \mathbb{Q}}^{1} \tag{9.38}
\end{equation*}
$$

On the other hand, if we combine (9.35) with van der Kallen's theorem we obtain a potentially different way to make identification (9.38). We will show that this does not happen. More precisely, let

$$
z_{t}=\sum n_{i}\left(x_{i}(t), y_{i}(t)\right)
$$

be an arc in $Z^{1}\left(\mathbb{P}^{2}, T\right)_{1}$ with tangent $z^{\prime}$ at $t=0$. Then from the general theory we would expect that

$$
\begin{equation*}
\left\langle\omega, z^{\prime}\right\rangle=\sum_{i} n_{i}\left(\frac{x_{i}^{\prime}}{x_{i}} \frac{d y_{i}}{y_{i}}-\frac{y_{i}^{\prime}}{y_{i}} \frac{d x_{i}}{x_{i}}\right) \tag{9.39}
\end{equation*}
$$

where $x_{i}^{\prime}=d x^{i}(t) / d t$ at $t=0$ and $d x_{i}=d_{\mathbb{C} / \mathbb{Q}}\left(x_{i}(0)\right)$, etc. We will show that

With $\left\langle\omega, z^{\prime}\right\rangle$ defined by (9.39), we have

$$
\begin{equation*}
d \varphi\left(\frac{d}{d t}\right)=-\left\langle\omega, z^{\prime}\right\rangle \tag{9.40}
\end{equation*}
$$

where the left hand side is defined using van der Kallen's isomorphism.
Proof: This follows by writing, as in the proof of van der Kallen's theorem

$$
\left\{x_{0}(1+\epsilon a), y_{0}(1+\epsilon b)\right\}=\left\{x_{0}, y_{0}\right\}\left\{x_{0}, 1+\epsilon b\right\}\{1+\epsilon a, 1+\epsilon b\}\left\{1+\epsilon a, y_{0}\right\}
$$

The first and third terms contribute zero when we take $d / d \epsilon$, and the second and fourth terms give

$$
-b \frac{d x_{0}}{x_{0}}+a \frac{d y_{0}}{y_{0}}
$$

where $d=d_{\mathbb{C} / \mathbb{Q}}$.
A more conceptual argument follows from the commutative diagram (6.33), noting that $\omega$ essentially gives the $d \log \wedge d \log$ mapping discussed above (6.33).

Finally, we want to discuss the integration of Abel's differential equations

$$
\left\langle\omega, z^{\prime}\right\rangle=0
$$

Any $z \in Z^{1}\left(\mathbb{P}^{2}, T\right)_{1}$ may be written as

$$
z=\sum_{i} z_{a_{i}, b_{i}}
$$

Considering an individual $z_{a, b}$, we suppose that $a, b \in k^{*}$ where $\operatorname{tr} \operatorname{deg} k=1$ so that

$$
\begin{equation*}
k \cong \mathbb{Q}(S) \tag{9.41}
\end{equation*}
$$

for some algebraic curve $S$. In section 10.2 above we have defined the differential character, defined for $\lambda \in H_{1}(S, \mathbb{Z})$ by

$$
I\left(z_{a, b}, \omega, \lambda\right)=\int_{\Gamma} \omega \quad \text { mod periods. }
$$

We may think of $I\left(z_{a, b}, \omega, \cdot\right)$ as landing in $H^{1}(S, \mathbb{C} / \mathbb{Z}(2))$, and thus we have a map

$$
\mathbb{C}^{*} \times \mathbb{C}^{*} \longrightarrow H^{1}(S, \mathbb{Z}(2))
$$

$$
\begin{array}{cc}
\uplus & \uplus \\
(a, b) & \longrightarrow I\left(z_{a, b}, \omega, \cdot\right) .
\end{array}
$$

Essentially because $I$ is an invariant of rational equivalence, this induces a map

$$
\begin{equation*}
K_{2}(\mathbb{C}) \xrightarrow{I} H^{1}(S, \mathbb{C} / \mathbb{Z}(2)) \tag{9.42}
\end{equation*}
$$

sending $\prod_{i}\left\{a_{i}, b_{2}\right\}$ to $\sum_{i} I\left(z_{a_{i}, b_{i}}, \omega, \cdot\right)$. On the other hand, there is a well known map, the regulator (whose definition will be recalled below)

$$
R: K_{2}(\mathbb{Q}(S)) \rightarrow H^{1}(S, \mathbb{C} / \mathbb{Z}(2))
$$

Proposition: Using the identification (9.35) these two maps agree; i.e.

$$
\begin{equation*}
R(\{a, b\})=I(\{a, b\}) \tag{9.43}
\end{equation*}
$$

Proof: For $S^{o}=S-D$ a Zariski open set in $S$ we have the spread

$$
\mathcal{Z} \subset\left(\mathbb{P}^{2}, T\right) \times S^{o}
$$

of $z_{a, b}$; we write $\mathcal{Z}=\left\{z_{a(s), b(s)}\right\}_{s \in S}$. As $S$ traces out a closed curve $\lambda$ in $S^{o}$, $z_{a(s), b(s)}$ traces out $\mathcal{Z}(\lambda)$ in $\mathbb{P}^{2}-T$. Since the homology class of $\mathcal{Z}(\lambda)$ is zero in $H_{1}(\mathbb{P}-T, \mathbb{Z})$ we may write

$$
\mathcal{Z}(\lambda)=\partial \Gamma
$$

and then

$$
I\left(z_{a, b}, \omega, \lambda\right)=\int_{\Gamma} \omega
$$

We have to rewrite the integral that will show it is equal to the usual definition of the regulator.

We write

$$
z_{a(s), b(s)}=(a(s), b(s))-(a(s), 1)-(1, b(s))+(1,1)
$$

and may picture $\Gamma$ as a surface with boundary

where

$$
\left\{\begin{array}{l}
\mu_{1}=\{\text { the curve }(a(s), 1)\} \\
\mu_{2}=\{\text { the curve }(1, b(s))\} \\
\mu_{3}=\{\text { the curve }(a(s), b(s))\}
\end{array}\right.
$$

and $\rho_{1}, \rho_{2}, \rho_{3}$ are the cuts indicated where $y=1$ along $\rho_{1}$ and $x=1$ along $\rho_{2}$. On the cut open surface we may write

$$
\frac{d x}{x} \wedge \frac{d y}{y}=d\left(\log x \frac{d y}{y}\right)
$$

Since $\mathcal{Z}(\lambda)=\mu_{1}+\mu_{2}+\mu_{3}$, by Stokes' theorem

$$
\begin{aligned}
\int_{\Gamma} \frac{d x}{x} \wedge \frac{d y}{y}= & \sum_{i} \int_{\mu_{i}} \log x \frac{d y}{y}-\int_{\rho_{3}} \frac{d y}{y} \int_{\mu^{3}} \frac{d x}{x} \\
& +\int_{\rho_{2}} \frac{d y}{y} \int_{\mu_{2}} \frac{d x}{x}+\int_{\rho_{1}} \frac{d y}{y} \int_{\mu_{1}} \frac{d x}{x} \\
& +\int_{\alpha} \log ^{+} x \frac{d y}{y}+\int_{\beta} \log ^{+} x \frac{d y}{y}
\end{aligned}
$$

where $\log ^{+} x$ is the jump in $\log x$ across the cuts $\alpha$ and $\beta$. The last two terms are in $\mathbb{Z}(2)$ and hence get factored out. In the first three terms, the one corresponding to $\mu_{1}$ is zero and the one corresponding to $\mu_{2}$ is in $\mathbb{Z}(2)$. Of the next three terms only

$$
\int_{\rho_{3}} \frac{d y}{y} \int_{\mu_{3}} \frac{d x}{x}=\log y\left(s_{0}\right) \int_{\mu_{3}} \frac{d x}{x}
$$

is non-zero, where $s_{0} \in \lambda$ corresponds to our base point. Collecting the terms we have

$$
\int_{\Gamma} \frac{d x}{x} \wedge \frac{d y}{y}=\int_{\lambda} \log x \frac{d y}{y}-\log y\left(s_{0}\right) \frac{d x}{x}
$$

which is the usual expression for the regulator.
For $X$ a complete curve, we define $K_{2}(X)$ to be the subgroup of $K_{2}(\mathbb{C}(X))$ given by the kernel of the tame symbol maps $T_{x}$ for all $x \in X$. Then the regulator defines a map

$$
K_{2}(X) \xrightarrow{R} H^{1}(X, \mathbb{C} / \mathbb{Z}(2))
$$

A well-known conjecture is that

$$
\operatorname{ker} R=K_{2}(\mathbb{C})
$$

(cf. [37] for references and a discussion of Image $R$.)

PUTangSp March 1, 2004

## Chapter Ten

## Speculations and questions

### 10.1 DEFINITIONAL ISSUES

There are three main questions:
(10.1) Can one define $T Z^{p}(X)$ in general?

The technical issue that arises in trying to straightforwardly extend the definitions given in the text for $p=n, 1$ concerns cycles that are linear combinations of irreducible subvarieties

$$
Z=\sum_{i} n_{i} Z_{i}
$$

where some $Z_{i}$ may not be the support of a locally Cohen-Maculay scheme. Similar issues are not unfamiliar - e.g. in duality theory - and we can see no geometric reason why the question (10.1) should not have an affirmative answer.

The second main question is:
(10.2) For $p=n, 1$ can one define $T Z^{p}(X)$ axiomatically?

This issue has been raised several times in the text. Specifically, in section 6.1 we have in a significant example given a set of axioms that define $\equiv_{1^{\text {st }}}$ geometrically and agrees with the general definition. And again in sections 7.3, 7.4 we have illustrated and discussed the question (10.2).

Finally, an obvious question is
(10.3) Can one define the Bloch-Gersten-Quillen sequence $\mathcal{G}_{k}$ on infinitesimal neighborhoods $X_{k}$ so that

$$
\begin{equation*}
\operatorname{ker}\left\{\mathcal{G}_{1} \rightarrow \mathcal{G}_{0}\right\} \cong \underline{\underline{T}} \mathcal{G}_{0} \tag{10.4}
\end{equation*}
$$

Here, $X_{k}$ is $X \times \operatorname{Spec}\left(\mathbb{C}[\epsilon] / \epsilon^{k+1}\right)$. Using the case $k=1$ and $\operatorname{dim} X=2$ for illustration, we are asking for something like

$$
\begin{equation*}
0 \rightarrow \mathcal{K}_{2}\left(\mathcal{O}_{X_{1}}\right) \rightarrow \mathbb{C}\left(X_{1}\right)^{*} \rightarrow \underset{Y_{1}}{\oplus} \mathbb{C}\left(Y_{1}\right)^{*} \rightarrow \underset{x_{1}}{\oplus} \underset{=}{\mathbb{Z}} x_{x_{1}} \rightarrow 0 \tag{10.5}
\end{equation*}
$$

which gives a flasque "Cousin-type" resolution of $\mathcal{K}_{2}\left(\mathcal{O}_{X_{1}}\right)$. There are obvious difficulties in defining the last two terms in (10.5). For example,

$$
{\underset{x_{1}}{ }{\underset{\underline{Z}}{=}}_{x_{1}},}
$$

is supposed to be something like "the sum of skyscraper sheaves supported on equivalence classes of irreducible codimension- 2 subschemes of $X_{1}$ that
meet $X_{0}$ properly." The equivalence relation should be that two ideals $\mathcal{J}_{1}, \mathcal{J}_{2}$ in $\mathcal{O}_{X_{1}}$ are equivalent if they define the "same" irreducible subvariety of $X_{1}$. Simple examples based on the failure of nullstellesatz for non-reduced schemes show that, at least to us, there are significant difficulties in directly defining (10.4). In fact, the definition of $\underline{\underline{T}} Z^{2}(X)$ in the text may be thought of as giving the left hand term in a possible exact sequence

$$
\begin{equation*}
0 \rightarrow \underline{\underline{T}} Z^{2}(X) \rightarrow \underset{x_{1}}{\oplus}{\underset{\underline{Z}}{x_{1}}} \rightarrow \underset{x}{\oplus} \underline{\underline{Z}}_{x} \rightarrow 0 \tag{10.6}
\end{equation*}
$$

Also the definition of $\underline{\underline{T}} Z_{1}^{1}(X)$ may be thought of as giving the first term in a possible exact sequence

$$
\begin{equation*}
0 \rightarrow \underset{\underline{T}}{\underline{T}} Z_{1}^{1}(X) \rightarrow \underset{Y_{1}}{\oplus} \underline{\mathbb{C}}(Y)^{*} \rightarrow \underset{Y}{\oplus} \underset{=}{\mathbb{C}}(Y)^{*} \rightarrow 0 \tag{10.7}
\end{equation*}
$$

and (10.6), (10.7) might fit in an exact sequence

$$
0 \rightarrow \underline{\underline{T}} \mathcal{G}_{0} \rightarrow \mathcal{G}_{1} \rightarrow \mathcal{G}_{0} \rightarrow 0
$$

explaining in this case what would be meant by (10.4).

### 10.2 OBSTRUCTEDNESS ISSUES

We have defined, for $p=\operatorname{dim} X$ and $p=1$, the tangent sheaf $\underline{\underline{T}} Z^{p}(X)$ and tangent space $T Z^{p}(X)=H^{0}\left(\underline{\underline{T}} Z^{p}(X)\right)$ to the space of codimension $p$ algebraic cycles on a smooth variety $X$, and for the purpose of this discussion we shall assume that these definitions have been extended to all codimensions. We may think of a tangent vector as a first order variation of a cycle, and the obstructedness question asks when this may be successively extended to a formal infinite order variation of the cycle. The convergence question asks when the tangent vector is tangent to a geometric arc in the space of algebraic cycles. There are essentially four (not mutually exclusive) possibilities:
(i) $T Z^{p}(X)$ may be obstructed. This means that there exists $X$ and $\tau \in$ $T Z^{p}(X)$ such that, thinking of $\tau$ as a map

$$
\begin{equation*}
\operatorname{Spec}\left(\mathbb{C}[\epsilon] / \epsilon^{2}\right) \rightarrow Z^{p}(X) \tag{10.8}
\end{equation*}
$$

this map cannot be lifted to a map

$$
\operatorname{Spec}\left(\mathbb{C}[\epsilon] / \epsilon^{k+1}\right) \rightarrow Z^{p}(X)
$$

for some $k \geqq 2$.
Remark: If this happens, then one expects that it already occurs for $k=2$. The question of the equivalence on maps $\operatorname{Spec}\left(\mathbb{C}[\epsilon] / \epsilon^{k+1}\right) \rightarrow \operatorname{Hilb}^{2}(X)$ to define the "same" cycle has been raised in the preceeding subsection.
(ii) $T Z^{p}(X)$ is formally unobstructed. This means that any tangent vector (10.1) may be lifted to a map

$$
\lim _{k}\left(\operatorname{Spec} \mathbb{C}[\epsilon] / \epsilon^{k+1}\right) \rightarrow Z^{p}(X)
$$

Remark: Let $Y \subset X$ be a smooth subvariety of codimension $p$ and $\nu \in$ $H^{0}\left(N_{Y / X}\right)$ a normal vector field. It is well-known that $\nu$ may be obstructed as an element of $T_{Y} \operatorname{Hilb}^{p}(X)$; i.e., $\operatorname{Hilb}^{p}(X)$ may be non-reduced at $Y$. However, as will be seen below, for $p=1$ (and trivially for $p=n$ ) when we consider $Y$ as a cycle in $Z^{p}(X)$ and $\nu$ as a tangent vector $\tau(\nu) \in T Z^{p}(X)$, the obstruction to lifting $\nu$ will disappear.
(iii) $T Z^{p}(X)$ is formally unobstructed, but there exist $\tau \in T Z^{p}(X)$ that are not tangent to geometric arcs in $Z^{p}(X)$.

One may ask similar questions at the sheaf level. The results proved in section 8 imply that:
(10.9) For a smooth algebraic surface, every tangent vector in the stalks of the tangent sheaves

$$
\underline{\underline{T}} Z^{1}(X), \underline{\underline{T}} Z^{2}(X), \underline{\underline{T}} Z_{1}^{1}(X)
$$

is tangent to a geometric arc in $Z^{1}(X), Z^{2}(X), Z_{1}^{1}(X)$ respectively.
Returning to the general discussion we have the fourth possibility
(iv) Every $\tau \in T Z^{p}(X)$ is tangent to a geometric arc in $Z^{p}(X)$.

As to what is known about (i)-(iv), as noted in the introduction Ting Fai Ng has shown that for $X$ smooth of any dimension
(10.10) Every $\tau \in T Z^{1}(X)$ is tangent to a geometric arc in $Z^{1}(X)$.

The geometric idea behind this result is quite simple and elegant. We illustrate it by explaining how, given a normal vector $\nu$ to a smooth curve $Y$ on a smooth surface $X$, one may eliminate the $1^{\text {st }}$ obstruction to lifting the corresponding tangent vector $\tau(\nu) \in T Z^{1}(X)$. It is well-known that the obstruction $\mathcal{O}(\nu)$ to lifting $\nu$ viewed as a map

$$
\operatorname{Spec}\left(\mathbb{C}[\epsilon] / \epsilon^{2}\right) \rightarrow \operatorname{Hilb}^{1}(X)
$$

to $\operatorname{Spec}\left(\mathbb{C}[\epsilon] / \epsilon^{3}\right)$ is in $H^{1}\left(N_{Y / X}\right)$. Choose an ample divisor $D$ on $Y$ so that $H^{1}\left(N_{Y / X}(D)\right)=0$. Then in terms of a Čech covering the image in $C^{1}\left(N_{Y / X}(D)\right)$ of $\mathcal{O}(\nu)$ obstruction cocycle $\mathcal{O}(\nu)$ may be written as a coboundary. What does this mean geometrically?

Suppose that $D=W \cap Y$ where $W \subset X$ is a sufficiently ample smooth curve. Then extending $\nu$ to be zero along $W$ it gives an element

$$
\widetilde{\nu} \in H^{0}\left(N_{Y \cup W / X}\right)
$$

as depicted by


Here $N_{Y \cup W / X}$ is the normal sheaf $\operatorname{Hom}_{\mathcal{O}_{X}}\left(\mathcal{J}_{Y \cup W} / \mathcal{J}_{Y \cup W)}^{2}, \mathcal{O}_{X}\right)$ to the subscheme $Y \cup W$ of $X$. If $H^{1}\left(\mathcal{O}_{X}(Y+W)\right)=0$, then Ng shows that the obstruction to lifting $\widetilde{\nu}$ to a map

$$
\operatorname{Spec}\left(\mathbb{C}[\epsilon] / \epsilon^{3}\right) \rightarrow \operatorname{Hilb}^{1}(X)
$$

which maps $\epsilon=0$ to $Y \cup W$ vanishes. Thus writing

$$
Y=(Y+W)-W
$$

we may consider $\widetilde{\nu}$ as giving $\tau(\widetilde{\nu}) \in T Z^{1}(X)$ which may then be lifted to $2^{\text {nd }}$ order by moving $Y+W$ to $2^{\text {nd }}$ order and leaving $-W$ constant.

We may illustrate this locally around the point of intersection with coordinates $x, y$ where $Y=\{y=0\}$ and $\nu=\partial / \partial y$. Then the $1^{\text {st }}$ order deformation is locally the divisor of

$$
f_{1}(x, y, t)=y-t
$$

Writing the obstruction as a coboundary with a $1^{\text {st }}$ order pole at the origin we find that the $2^{\text {nd }}$ order deformation is given by taking the divisor of

$$
\begin{aligned}
f_{2}(x, y, t) & =y-t-\frac{t^{2}}{x} \\
& =\frac{1}{x}\left(x y-x t-t^{2}\right)
\end{aligned}
$$

Thus, $Y+W$ deforms into $x y-x t-t^{2}=0$, which is something like the picture


In contrast to the codimension one case, we have
(10.11) For $p \geqq 2$, there exist $X$ and tangent vectors $\tau \in T Z^{p}(X)$ that are not tangent to a geometric arc.
The reason for this is as follows: Let $X$ be a smooth threefold. The formal tangent space to the Chow group of codimension 2 cycles is given by

$$
\begin{equation*}
T C H^{2}(X) \cong H^{2}\left(\Omega_{X / \mathbb{Q}}^{1}\right) \tag{10.12}
\end{equation*}
$$

The differential $\delta \psi_{1}$ of the Abel-Jacobi mapping

$$
C H^{2}(X)_{0} \xrightarrow{\psi_{1}} J^{2}(X)
$$

is given, using the identification (10.5), by

$$
H^{2}\left(\Omega_{X / \mathbb{Q}}^{1}\right) \xrightarrow{\delta \psi_{1}} H^{2}\left(\Omega_{X / \mathbb{C}}^{1}\right)
$$

Thus

$$
\text { Image } \delta \psi_{1}=\operatorname{ker}\left\{H^{2}\left(\Omega_{X / \mathbb{C}}^{1}\right) \xrightarrow{\nabla} H^{3}\left(\mathcal{O}_{X}\right) \otimes \Omega_{\mathbb{C} / \mathbb{Q}}^{1}\right\}
$$

where $\nabla$ is the arithmetic Gauss-Manin connection. In particular, if $H^{3}\left(\mathcal{O}_{X}\right)$ $=0$ or if $X$ is defined over $\mathbb{Q}$

$$
\text { Image } \delta \psi_{1}=H^{2}\left(\Omega_{X / \mathbb{C}}^{1}\right)
$$

Since

$$
T\left(\text { Image } \psi_{1}\right) \subseteq H^{2}\left(\Omega_{X / \mathbb{C}}^{1}\right)
$$

corresponds to a sub-Hodge structure - i.e. it plus its conjugate is spanned by a $\mathbb{Q}$-lattice in $H^{3}(X, \mathbb{R})$ - we know that in general Image $\delta \psi_{1}$ is too big. Since

$$
T C H^{2}(X) \cong T Z^{2}(X) / T Z_{\mathrm{rat}}^{2}(X)
$$

we infer that we may have geometric tangent vectors in $T Z^{2}(X)$ that are not tangent to any geometric arc in the space of codimension 2 cycles.

Thus of the possibilities listed above, only (i)-(iii) can actually occur. Our guess is that
(ii) and (iii) above are the possibilities that actually occur for $p \geqq 2$.

### 10.3 NULL CURVES

Next we want to mention another curious phenomenon that arises in the infinitesimal theory of Chow varieties, this being what we call null curves. For simplicity, taking $X$ to be a regular algebraic surface defined over $\mathbb{Q}$, a null curve is given by a picture

$$
\begin{equation*}
Y \subset B \times X \tag{10.13}
\end{equation*}
$$

where $Y$ and $B$ are algebraic curves with $Y \rightarrow B$ a branched covering such that the induced mapping

$$
J(Y) \rightarrow C H^{2}(X)
$$

is non-constant but has differential that vanishes identically. (The terminology null-curve is introduced by analogy with the theory of relativity.) From the discussion in $\S 4$ we see that

The diagram (10.13) defines a null-curve if it is defined over $\mathbb{Q}$.
The phenomenon of null curves has, in our view, the following explanation: At each value of $t, z^{\prime}(t)$ lies in the image of the tangent space to rational equivalences on $X$. However, this tangent vector to rational equivalences does not necessarily arise from a geometric family of rational equivalences. We expect that there is no obstruction to an infinite-order formal lift of the tangent vector, but there is one going from a formal lift to a geometric family.

We will show elsewhere that, as a consequence of the Bloch-Beilinson conjectures, this is the only way that null curves can arise.

### 10.4 ARITHMETIC AND GEOMETRIC ESTIMATES

One motivation for defining $T Z^{p}(X)$ is to have the possibility of using iterative methods to construct algebro-geometric objects - e.g., rational equivalences. Were $Z^{p}(X)$ a classical space - i.e., a manifold or a variety one could hope to integrate Abel's DE's by analytic methods. However, as just pointed out this is not the case. Now solving a differential equation is an iterative geometric process, and as $Z^{p}(X)$ one might seek to devise iterative geometric/arithmetic processes that would in the limit produce algebro-geometric objects. Convergence of an iterative process requires estimates and in closing we wish to offer some observations/speculations as to what form these might take.

For illustrative purposes we consider a regular algebraic surface $X$ defined over $\mathbb{Q}$. Then the Bloch-Beilinson conjecture has the following implication:

$$
\begin{align*}
& \text { Let } p, q \in X(\overline{\mathbb{Q}}) \text {. Then there is an integer } d_{p, q} \text { and a rational map }  \tag{10.14}\\
& \qquad f_{p, q}: \mathbb{P}^{1} \rightarrow X^{\left(d_{p, q}\right)}
\end{align*}
$$

such that

$$
\begin{aligned}
f_{p, q}(0) & =p+z \\
f_{p, q}(\infty) & =q+z
\end{aligned}
$$

In fact, we may take $f_{p, q}$ to be defined over $\overline{\mathbb{Q}}$. Let $\delta_{p, q}$ be the degree of $f_{p, q}$ relative to some projective embedding of $X$ - that is, $\delta_{p, q}$ is the degree of the curve traced out on $X$ by the family of 0 -cycles $f_{p, q}(t)$. We observe that

$$
\text { It is not possible to bound } d_{p, q} \text { and } \delta_{p, q} \text { for all } p, q \in X(\overline{\mathbb{Q}}) \text {. }
$$

The reason is that if such bounds exist then by standard reasoning using Hilbert schemes and/or Chow varieties we will be able to infer that

$$
p \equiv_{\mathrm{rat}} q
$$

for all $p, q \in X(\mathbb{C})$, which is not the case if $p_{g}(X) \neq 0$.
Let $H(p, q)$ be some measure of the arithmetic complexity of $p, q \in X(\overline{\mathbb{Q}})$. For example, relative to a projective embedding

$$
X \rightarrow \mathbb{P}^{N}
$$

defined over a finite extension of $\mathbb{Q}$, we may think of the coordinates of $p$ and $q$ as algebraic numbers. The arithmetic complexity of an algebraic number can then be measured by the heights of the coefficients of this equation. More generally, one may define the height of subvarieties defined over $\overline{\mathbb{Q}}$ (cf. [38]). Let $D(p, q)$ be some measure of the geometric size of (10.14); e.g., we might take

$$
D(p, q)=d_{p, q}+\delta_{p, q} .
$$

Then one might suspect that

$$
H(p, q) \rightarrow \infty \Rightarrow D(p, q) \rightarrow \infty ;
$$

maybe there is even a bound

$$
\begin{equation*}
H(p, q) \leqq c D(p, q) \tag{10.14}
\end{equation*}
$$

for some constant $c>0$.
In other words, one may imagine that for a not necessarily regular algebraic surface defined over $\overline{\mathbb{Q}}$
(10.16) If Bloch-Beilinson is true, then for a general $z \in Z^{2}(X(\overline{\mathbb{Q}}))$ satisfying

$$
\left\{\begin{array}{l}
\operatorname{deg} z=0 \\
\text { Alb } z=0
\end{array}\right.
$$

the geometric size of any rational equivalence

$$
z \equiv_{\mathrm{rat}} 0
$$

is bounded dfrom below by the arithmetic complexity of $z$.
In the one case where one knows Bloch-Beilinson, namely the relative variety $\left(\mathbb{P}^{2}, T\right)$ discussed in section 9.4 above, we shall give heurestic reasoning in support of the converse to (10.16); namely

For $a, b \in \mathbb{Q}^{*}$, there is a rational equivlance

$$
\begin{equation*}
z_{a, b} \equiv_{\mathrm{rat}} 0 \tag{10.17}
\end{equation*}
$$

whose geometric size is bounded from above by the arithmetic complexity of $a, b$, expressed as a computable function of the heights of $a, b$.
The proof to be given also gives what we feel is strong evidence also for a lower bound in this case.
Proof: It is a result of Garland [40] that $K_{2}(\overline{\mathbb{Q}})=0$, i.e. in $\overline{\mathbb{Q}}^{*} \otimes_{\mathbb{Z}} \overline{\mathbb{Q}}^{*}$ we may write

$$
\begin{equation*}
a \otimes b=\prod_{\nu=1}^{N_{a, b}} c_{\nu} \otimes\left(1-c_{\nu}\right) \tag{10.18}
\end{equation*}
$$

where $c_{\nu} \in \overline{\mathbb{Q}}^{*}$. We claim that we may bound $N_{a, b}$ and the heights of the $c_{\nu}$ by the heights of $a, b$. One way to see this is as follows.

First, if $a, b \in \mathbb{Q}^{*}$ the theorem of Bass and Tate [35] gives that for some positive integer $N$

$$
\begin{equation*}
\{a, b\}^{N}=1 \text { in } K_{2}(\mathbb{Q}) \tag{10.19}
\end{equation*}
$$

The proof is by writing $b=m / n$ where $m$ and $n$ are relative prime integers, and then using bilinearity and skew-symmetry of the Steinberg symbols to reduce to the case where $b=p$ is a prime. That $\{a, p\}$ is torsion then follows by an argument using Fermat's theorem. The number and arithmetic complexity of the Steinberg relations that are introduced, as well as the order $N$ of torsion in (10.19), are bounded by the arithmetic complexity of $a, b$.

Next, an elementary argument shows that by adjoining roots of unity we may show that

$$
\{a, b\}=1 \text { in } K_{2}(\overline{\mathbb{Q}})
$$

Again, the number and arithmetic complexity of the Steinberg relations that are introduced are bounded by the heights of $a, b$.

Next, as is shown in the proof of proposition (9.36) we have in $\Lambda_{\mathbb{Z}}^{2} \overline{\mathbb{Q}}^{*}$

$$
\begin{equation*}
\prod_{\nu} c_{\nu} \otimes\left(1-c_{\nu}\right) \equiv \prod_{i} e_{i} \otimes\left(1-e_{i}\right)^{n_{i}} \text { modulo } \operatorname{In}(\mathrm{St}) \tag{10.20}
\end{equation*}
$$

where

$$
\left\{\begin{array}{l}
\sum_{i} n_{i}=0 \\
\prod_{i} e_{i}^{n_{i}}=\prod_{i}\left(1-e_{i}\right)^{n_{i}}=1
\end{array}\right.
$$

Moreover, analysis of the proof of (10.20) shows that again the arithmetic complexities of the elements in $Z^{1}\left(\mathbb{P}^{1}-\{0,1, \infty\}\right)$ that are introduced in the map

$$
Z^{1}\left(\mathbb{P}^{1}-\{0,1, \infty\}\right) \xrightarrow{\mathrm{St}} \Lambda_{\mathbb{Z}}^{2} \overline{\mathbb{Q}}^{*}
$$

to obtain the congruence in (10.20) are bounded by a computable function of the heights of the $c_{\nu}$.

Finally, referring to the explicit construction of a rational equivalence

$$
\begin{equation*}
\sum_{i} n_{i} z_{e_{i}, 1-e_{i}} \equiv_{\mathrm{rat}} 0 \tag{10.21}
\end{equation*}
$$

given in the proof of (9.26), we see that the geometric size of that particular rational equivalence $\equiv_{\text {rat }}$ is bounded by the arithmetic complexity of the RHS of (10.20).

Remark: Presumably analysis of the proof of Garland's theorem would enable one to extend (10.17) to the case where $a, b$ are algebraic numbers.

Returning to the case of an algebraic surface one may ask
(10.22) For an algebraic cycle $z$ satisfying (10.17), is there an iterative scheme

$$
z_{i} \rightarrow z_{i+1}, \quad z_{0}=z
$$

where $z_{i} \in Z^{1}(\overline{\mathbb{Q}})$ and

$$
\left\{\begin{array}{l}
z_{i} \equiv_{\mathrm{rat}} z_{i+1} \\
h\left(z_{i+1}\right)<h\left(z_{i}\right) .
\end{array}\right.
$$

Such an iterative scheme is in fact implicit in the analysis of $\left(\mathbb{P}^{2}, T\right)$ discussed above. Evidently such a scheme would establish the Bloch-Beilinson conjecture for 0-cycles on a general algebraic surface defined over $\overline{\mathbb{Q}}$.

The absence of derivations of $\overline{\mathbb{Q}}$ means that the usual infinitesimal/geometric methods (DE's) break down, at least on the face of it. Refering to (8.40), for a tangent vector

$$
\tau=\sum_{i}\left(x_{i}, \tau_{i}\right)
$$

where $x_{i} \in X(\overline{\mathbb{Q}})$ (assumed for simplicity to be distinct) and any $\tau_{i} \in$ $T_{x_{i}}(X(\mathbb{C}))$ satisfying

$$
\langle\varphi, \tau\rangle=0, \quad \varphi \in H^{0}\left(\Omega_{X / \mathbb{C}}^{1}\right)
$$

were have

$$
\tau \in T Z_{\mathrm{rat}}^{2}(X)
$$

Clearly, to "point" in the direction of an actual rational equivalence we must in general have

$$
\tau_{i} \in T_{x_{i}}(X(\overline{\mathbb{Q}}))
$$

Intuitively, one might like to choose $\tau_{i}$ to point in the direction of decreasing the height of $x_{i}$. At the moment any such scheme would seem to require completely new ideas.

In concluding we would like to formulate a problem that is on the one hand a sort of infinitesimal analogue of (10.22), and the other hand is an interesting and perhaps double problem in arithmetic algebraic geometry. For this we assume that $X$ is defined over a number field $k$ and let

$$
\tau \in T_{z} Z^{2}(X(k))
$$

be a tangent to a 0 -cycle $z$ both defined over $k$ and satisfying

$$
\langle\varphi, \tau\rangle=0 \quad \text { for all } \varphi \in H^{0}\left(\Omega_{X(k) / k}^{1}\right)
$$

Then we have shown that there are infinitesimal rational equivalences

$$
\xi \in T Z_{1}^{1}(X(K))
$$

defined over a finite extension field $K$ of $k$ and which map to $\tau$ under the rational mapping

$$
T Z_{1}^{1}(X(K)) \rightarrow T Z^{2}(X(k))
$$

The problem is
(10.23) Can one choose $\xi$ so that the height of $\xi$ is bounded by the height of $\tau$ ?

Essentially, constructing $\xi$ amounts to writing a cocycle as a coboundary. We are asking if this can be done in a manner that controls heights.

PUTangSp March 1, 2004

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[^0]:    ${ }^{1}$ Throughout this work, unless stated otherwise we will use the Zariski topology. We

[^1]:    ${ }^{2}$ Of course, for curves one may introduce creation/annihilation arcs, but as noted in e) above it is only in higher codimension, due to the presence of "irrelevant" rational equivalences, that they play an essential role.

[^2]:    ${ }^{3}$ The regularity of $X$ enters in the rigorous construction and in the uniqueness of the lifting of $\omega$ to $H^{0}\left(\Omega_{X / \mathbb{Q}}^{2}\right)$. Also, the construction is only well-defined modulo torsion. Finally, as discussed in section 9.3 one must "enlarge" the construction (1.24) to take into account all the transcendental part $H^{2}(X)_{\operatorname{tr}}$ of the $2^{\text {nd }}$ cohomology group of $X$.

[^3]:    ${ }^{4}$ The issue of the equivalence relation on such maps to define the same cycle is nontrivial - cf. section 10.2. In fact, the purpose of section 10 is to raise issues that we feel merit further study.

[^4]:    ${ }^{1}$ The generalization is, however, interesting and will be discussed in the next section.

[^5]:    ${ }^{1}$ As we are interested in the infinitesimal structure of 0 -cycles, the geometry of symmetric products along the diagonals is fundamental. Here, understanding the principal diagonals is sufficient.

[^6]:    ${ }^{2}$ For example, are a Riemannian manifold - or for that matter any $G$-structure - Cartan used the full frame bundle, and viewed a connection as a means of infinitesimal displacement in the frame bundle. We will see below that the use of absolute differentials and the evaluation maps give a structure similar to a connection on the space of arcs in $Z^{n}(X)$.

[^7]:    ${ }^{3}$ For $q=1$ and $\Phi=\operatorname{Tr} \omega$ where $\omega \in \Omega_{X \mid \mathbb{C}}^{1}, \widetilde{I}(z, \operatorname{Tr} \omega)$ is the same as $I(z, \omega)$ defined in (3.1). Only for $q \geqq 2$ will there be a refinement of the definition of $\widetilde{I}(z, \Phi)$ to give what will eventually be denoted by $I(z, \Phi)$ without the tilde. Thus, when $q=1$ we will always drop the tilde.

[^8]:    ${ }^{4}$ As explained at the end of this section, the final definition of universal abelian invariants only works using absolute differentials in the algebraic setting.

[^9]:    ${ }^{1}$ Not every $s \in S(\mathbb{C})$ will give an embedding $k \hookrightarrow \mathbb{C}$. For example, taking $k=\mathbb{Q}(x)$ then $x \rightarrow s$ gives an embedding unless $s \in \overline{\mathbb{Q}}$, when it does not.

[^10]:    ${ }^{2}$ To be precise, the spread family (4.14) is specified by the complex variety $X$ together with a choice of field $k \subset \mathbb{C}$ over which $X$ is defined.

[^11]:    ${ }^{1}$ Everything we shall do in this section extends to 0 -cycles on an $n$-dimensional smooth variety. Since no essentially new ideas are involved in this extension, we shall restrict attention to the surface case.

[^12]:    ${ }^{1}$ This result is true for all dimensions; we will only use it for surfaces.

[^13]:    ${ }^{2}$ The point is this: We have a rational differential form $\omega=f(\xi, \eta) d \xi \wedge d \eta$ on $X$. At a general point of $Y$, locally in the analytic topology we may expand $f(\xi, \eta)$ in a Laurent series on $\eta$ and define the residue as above. In the overlap of two such analytic neighborhoods we get the same answer.

[^14]:    ${ }^{3}$ The "auxilary parameter" may be taken to be a local uniformizing parameter on $Y$ given by the restriction to $Y$ of a function $\eta \in \mathbb{C}(X)$. Combining this with a function $\xi \in \mathbb{C}(X)$ such that $\xi=0$ on $Y$ gives a retraction.

[^15]:    ${ }^{4}$ cf. the "Afterword" below.

[^16]:    ${ }^{5}$ This procedure may break down when $d t$ vanishes along a component of the support of $\mathcal{Z} \cdot\left(X \times\left\{t_{0}\right\}\right)$. When this happens a perturbation argument may be used to calculate the map (ii). This phenomena will be further discussed and illustrated in section 8(ii) below.

[^17]:    ${ }^{6}$ We assume that the retraction is smooth in a neighborhood of $x$, as singularities produced by singularities of the retractions are non-intrinsic and therefore should not be counted.

[^18]:    ${ }^{7}$ The discussion in this section is modulo torsion.
    ${ }^{8}$ This discussion will work for the formal tangent space $T C H^{p}(X)$ for all $p$, and thus will work in general if $T Z^{p}(X)$ can be defined so that the analogue of (8.47) holds.

[^19]:    ${ }^{9}$ Here, for any $\mathbb{Z}$-module $M$ we are setting $M_{\mathbb{Q}}=M \otimes_{\mathbb{Z}} \mathbb{Q}$. Also, H. Saito-Jannsen give the (same) definition of $F^{m} C H^{p}(X)$ for all $p$.

[^20]:    ${ }^{1}$ For $\operatorname{dim} X=n$ we may denote by $L T_{X, x}$ the finite $\left(2^{n}\right)^{\text {th }}$ quadrant Laurent tails at $x$. Then for $n=1, L T_{X, x} \cong \mathcal{P P}_{X, x}$, and in general

    $$
    T_{\{x\}} Z^{n}(X) \cong L T_{X, x} \otimes \Omega_{X / \mathbb{Q}, x}^{n-1}
    $$

    ${ }^{2}$ Here, $\varphi \wedge \tau_{i}$ denotes the image in $L T_{X, i} \otimes \Omega_{X / \mathbb{C}, x_{i}}^{2}$ using the natural map $\Omega_{X / \mathbb{C}}^{1} \otimes$ $\Omega_{X / \mathbb{Q}}^{1} \rightarrow \Omega_{X / \mathbb{C}}^{2}$.

[^21]:    ${ }^{3}$ In his paper Mumford observes that the trace construction was used by Severi to study 0-cycles on a surface - only Severi drew the wrong conclusion. Mumford famously remarks that in this case the Italian's technique was superior to their vaunted intuition.

[^22]:    ${ }^{4}$ The proposition is stronger than the corollary, since the former precludes moving in certain rational equivalences on symmetric products - i.e., we can add to $v \in T_{p}(X)$ infinitesimal creation/annihilation notions.

[^23]:    ${ }^{5} \mathrm{cf}$. [24] where a related result is proved.

