Semi-groups and representations of Lie groups

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#### Abstract

With every Lie semi-group, $\Pi$, possessing certain regularity properties, there is associated a Lie algebra, $A$; and with every strongly continuous representation of $\Pi$ in a Banach space there is associated a representation $A(a)$ of $A$. Certain theorems regarding this representation are established.

The above theorems are valid for a representation of a Lie group also. In this case, it is shown that it is possible to extend the representation to elliptic elements of the universal enveloping algebra. It is also shown that the representatives of the strongly elliptic elements of the universal enveloping algebra are the infinitesimal generators of holomorphic semi-groups. Integral representations of these semi-groups are given.


## Introduction

The study of Lie semi-groups and their representations was initiated by E. Hille in [6]. For a survey of the basic problems and results the reader is referred to that paper and to Chapter XXV of [7]. This thesis is a continuation of work begun there; we summarize briefly the results it contains.

In Chapter I, the "Dense Graph Theorems" suggested in [6] are proved and it is shown that linear combinations of the infinitesimal generators form, in the precise sense of Theorems 4 and 6 , a representation of a Lie algebra canonically associated with the semi-group.

In Chapter II the study of the infinitesimal generators is continued. For the work of this chapter it is necessary to assume that the semi-group is a full Lie group. It is shown (Theorem 7) that the representation of the Lie algebra can be extended, in a natural manner, to a representation of the elliptic elements of the universal enveloping algebra. Then the spectral properties of operators corresponding to strongly elliptic elements are discussed; in particular it is shown (Theorem 8) that they are the infinitesimal generators of semi-groups holomorphic in a sector of the complex plane. Canonical representations of these semi-groups as integrals are given in Theorem 9 .

The reader interested in other work to which that of Chapter II is related is referred to [9, 13, 19], and a forthcoming paper by E. Nelson ([20] added in revision).

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## Chapter I

1. Lie semi-groups have been defined in [6] and [7]. We shall be concerned with semigroups, $\Pi$, whose underlying topological space is $\bar{E}_{n}^{+}=\left\{\left(x_{1}, \ldots, x_{n}\right) \mid x_{i} \geqslant 0, i=1, \ldots, n\right\}$, a subset of real Euclidean $n$-space. We denote the semi-group operation by either $F(p, q)$ or $p \circ q$. The following conditions, numbered as in [7] are supposed satisfied.
$P_{2} . F(a, 0)=F(0, a)$
$P_{3} . F(a, F(b, c))=F(F(a, b), c)$
$P_{5}$. There exists a fixed positive constant $B$ such that for all points $a_{1}, a_{2}$ and $b$ in $\Pi$

$$
\max \left\{\left|F\left(a_{1}, b\right)-F\left(a_{2}, b\right)\right|,\left|F\left(b, a_{1}\right)-F\left(b, a_{2}\right)\right|\right\} \leqslant(1+B|b|)\left|a_{1}-a_{2}\right|
$$

$P_{6}$. There exists a positive, monotone increasing continuous function $\omega(t), 0<t<\infty$, tending to zero with $t$ such that

$$
|F(a, b)-a-b| \leqslant r \omega(s), \quad r=\min \{|a|,|b|\}, s=|a|+|b|
$$

$P_{11}$. At every point of $\bar{E}_{n}^{+} \times \bar{E}_{n}^{+}$the $n$ coordinates of $F(p, q)$ have continuous partial derivatives with respect to the coordinates of $p$ and $q$ up to and including the third order.
Then, by Theorem 25.3.1 of [7], there is a continuous function $f(a)$ from $\Pi$ into $\Pi$ such that $f((\rho+\sigma) a)=f(\rho a) \circ f(\sigma a)$ for $a \in \Pi, \rho, \sigma \geqslant 0$.

Let $T(p)$ be a representation of $\Pi$ in a Banach space $X$, which is strongly continuous in a neighborhood of the origin, then for $a \in \Pi, \rho \geqslant 0, \rho \rightarrow T(f(\rho a))$ is a strongly continuous one-parameter semi-group. Denote its infinitesimal generator by $A(a)$. In this chapter we investigate the relations among the $A(a)$ and their adjoints $A^{*}(a)$. For the purposes of Chapter II, we remark that similar theorems are valid for a representation of a Lie group.

We first construct a common domain for the operators, $A(a), a \in \Pi$, which is large enough for our purposes. We use the following notation: $\frac{\partial F^{k}}{\partial p^{j}}(p, q)=F_{j}^{k}(p, q) ; \frac{\partial F^{k}}{\partial q^{j}}(p, q)=F_{; j}^{k}(p, q)$; $\frac{\partial^{2} F^{k}}{\partial q^{i} \partial p^{j}}=F_{j ; i}^{k}(p, q) ; F_{i ; j}^{k}(0,0)-F_{j ; i}^{k}(0,0)=\gamma_{i j}^{k}$. Observe that $F(p, q)$ may be extended to a twice continuously differentiable function defined on $E_{n} \times E_{n} \|^{1}$ Denote some fixed extension by $F(p, q)$. Since $F_{j ;}^{k}(0,0)=F_{; j}^{k}(0,0)=\delta_{j}^{k}$ (the Kronecker delta), there are open spheres $N_{1}, N_{2} \subseteq N$ about the origin and three times continuously differentiable functions $\psi(q, h)$ and $\chi(q, h)$ defined on $N_{1} \times N_{1}$ such that $\psi(0,0)=\chi(0,0)=0, F(h, \psi(q, h))=q$, and $F(\chi(q, h), h)=q$. Moreover if $F(h, p)=q[F(p, h)=q]$ with $p, h \in N_{2}$, then $q \in N_{1}$ and $\psi(q, h)=p[\chi(q, h)=p]$. We may also suppose that all derivatives of $\psi(q, h)$ and $\chi(q, h)$ up to the third order are bounded in $N_{1}$, that $T(p)$ is strongly continuous in $N_{1} \cap \Pi$, and that $\operatorname{det}\left(F_{j ;}^{k}(p, 0)\right) \geqslant 1 / 2$ and $\operatorname{det}\left(F_{; j}^{k}(p, 0)\right) \geqslant 1 / 2$ for $p$ in $N_{1}$. If $N \subseteq N_{1}$ is an open sphere

[^0]about the origin, set
$$
E(N)=\left\{y=\int_{\Pi} K(q) T(q) x d q \mid x \in X, K(q) \in C_{2}(N \cap \Pi)\right\}
$$

Here $C_{2}(N \cap \Pi)$ consists of twice continuously differentiable functions which are zero outside of $N \cap \Pi$. We refer the reader to [7] for a proof that $E(N)$ is dense in $X$.

Proposition 1. Let $N_{3}$ be an open sphere about the origin with $F\left(N_{3}, N_{3}\right) \subseteq N_{2}$. If $y \in E\left(N_{3}\right)$ then $T(p) y$ is a twice continuously differentiable function of $p$ in $N_{3} \cap \Pi$.

Proof. We understand that some derivatives at the boundary will be one-sided. If $y \in E\left(N_{3}\right)$ and $e_{j}=\left(\delta_{j}^{1}, \ldots, \delta_{j}^{n}\right)$ we have, recalling that $K(q)$ is zero outside of $N_{3} \cap \Pi$,

$$
\begin{aligned}
& \lim _{s \rightarrow 0} s^{-1}\left(T\left(p+s e_{j}\right) y-T(p) y\right) \\
& =\lim _{s \rightarrow 0} s^{-1} \int_{N_{3} \cap \Pi} K(q)\left(T\left(\left(p+s e_{j}\right) \circ q\right)-T(p \circ q)\right) x d q \\
& =\left.\lim _{s \rightarrow 0} s^{-1} \int_{N_{2} \cap \Pi}\left(K(\psi(q, r)) \operatorname{det}\left(\frac{\partial \psi^{k}}{\partial q^{i}}(q, r)\right)\right)\right|_{r=p} ^{r=p+s e_{j}} T(q) x d q \\
& =\int_{N_{2} \cap \Pi} \frac{\partial}{\partial p^{j}}\left(K(\psi(q, p)) \operatorname{det}\left(\frac{\partial \psi^{k}}{\partial q_{i}}(q, p)\right)\right) T(q) x d q+\lim _{s \rightarrow 0} \int_{N_{2} \cap \Pi} G(q, p, s) d q \\
& =\int_{N_{2} \cap \Pi} \frac{\partial}{\partial p_{j}}\left(K(\psi(q, p)) \operatorname{det}\left(\frac{\partial \psi^{k}}{\partial q^{i}}(q, p)\right)\right) T(q) x d q
\end{aligned}
$$

since $G(q, p, s)$ converges boundedly to 0 with $s$. The final integral is a continuous function of $p$. In a similar manner we show that it is once continuously differentiable.

We remark the following formulae, valid for $y \in E\left(N_{3}\right), p \in N_{3} \cap \Pi$ :

$$
\begin{align*}
& \lim _{s \rightarrow 0} s^{-1}(T(f(s a))-I) T(p) y=\lim _{s \rightarrow 0} s^{-1}(T(f(s a) \circ p) y-T(p) y)  \tag{i}\\
& =\lim _{s \rightarrow 0}\left[\sum_{j=1}^{n} s^{-1}\left(F^{j}(f(s a) \circ p)-p^{j}\right) \frac{\partial}{\partial p^{j}} T(p) y+s^{-1} o(|f(s a) \circ p-p|)\right]
\end{align*}
$$

which equals

$$
\begin{equation*}
\sum_{j=1}^{n}\left(\sum_{i=1}^{n} F_{i ;}^{j}(0, p) a^{i}\right) \frac{\partial}{\partial p^{j}} T(p) y . \tag{1.1}
\end{equation*}
$$

So $T(p) y \in D(A(a))$, and $A(a) T(p) y$ is given by 1.1.
(ii) We observe that $T(p) A(a) y=\lim _{s \rightarrow 0} s^{-1}(T(p \circ f(s a)) y-T(p) y)$, which equals

$$
\begin{equation*}
\sum_{j=1}^{n}\left(\sum_{k=1}^{n} F_{; k}^{j}(p, 0) a^{k}\right) \frac{\partial}{\partial p^{j}} T(p) y \tag{1.2}
\end{equation*}
$$

(iii) Setting $\left(F_{; k}^{j}(p, 0)\right)^{-1}=\left(\gamma_{k}^{j}(p)\right)$, we have

$$
\begin{equation*}
\frac{\partial}{\partial p_{j}} T(p) y=\sum_{k=1}^{n} \gamma_{k}^{j}(p) T(p) A\left(e_{k}\right) y \tag{1.3}
\end{equation*}
$$

(iv) Setting $\sum_{j=1}^{n} F_{i ;}^{j}(0, p) \gamma_{j}^{k}(p)=\beta_{i}^{k}(p)$, we have

$$
\begin{equation*}
A(a) A(b) T(p) y=\sum_{k, j=1}^{n}\left(\sum_{i=1}^{n} \beta_{i}^{k}(p) b^{i}\right)\left(\sum_{m=1}^{n} F_{m ;}^{j}(0, p) a^{m}\right) \frac{\partial}{\partial p^{j}} T(p) A\left(e_{k}\right) y \tag{v}
\end{equation*}
$$

$$
\begin{gather*}
A(a+b) y=A(a) y+A(b) y \\
A\left(e_{i}\right) A\left(e_{j}\right) y-A\left(e_{j}\right) A\left(e_{i}\right) y=\sum_{k=1}^{n} \gamma_{i j}^{k} A\left(e_{k}\right) y
\end{gather*}
$$

For a proof of the latter relation, see [7], page 758 .
2. The first theorem is known as a "Dense Graph Theorem" and has been suggested by E. Hille in [6] and [7].

Theorem 1. Let $\left\{a_{1}, \ldots, a_{p}\right\} \subseteq \Pi$. If $G_{0}$ is the closure in the product topology on $X \times \cdots \times X$ ( $p+1$ factors) of

$$
\left\{\left(x, A\left(a_{1}\right) x, \ldots, A\left(a_{p}\right) x\right) \mid x \in E\left(N_{3}\right)\right\}
$$

and

$$
G=\left\{\left(x, A\left(a_{1}\right) x, \ldots, A\left(a_{p}\right) x\right) \mid x \in \bigcap_{j=1}^{p} D\left(A\left(a_{j}\right)\right)\right\},
$$

then $G=G_{0}$.
Proof. Observe that $G \supseteq G_{0}$ since an infinitesimal generator is a closed operator. We show that $G_{0} \supseteq G$. Let $\left\{b_{r+1}, \ldots, b_{n}\right\}$ be a maximal linearly independent subset of $\left\{a_{1}, \ldots, a_{p}\right\}$; it is sufficient to prove the theorem for the former set. Let $\left\{b_{1}, \ldots, b_{n}\right\} \subseteq \Pi$ be a basis for $E_{n}$. If $t=\left(t^{1}, \ldots, t^{n}\right) \in \Pi$, set $p(t)=f\left(t^{1} b_{1}\right) \circ \cdots \circ f\left(t^{n} b_{n}\right)$. Then $p(t)$ is a twice continuously differentiable map of $\Pi$ into $\Pi$ and may be extended to a twice continuously differentiable map of $E_{n}$ into $E_{n}$. Denote some fixed extension by $p(t)$. The above process is analogous to the introduction of canonical coordinates of the second kind on a Lie group.

Since $\frac{\partial p^{k}}{\partial t^{j}}(0)=b_{j}^{k}, p(t)$ has a twice continuously differentiable inverse defined in a sphere $N_{4}$ about the origin. We may suppose that $F\left(N_{4}, N_{4}\right) \subseteq N_{3}$ and that all derivatives of the
inverse function up to the second order are bounded in $N_{4}$. If $y \in E\left(N_{4}\right)$ and $p \in N_{4} \cap \Pi$, then $T(p) y \in E\left(N_{3}\right)$. For $y \in E\left(N_{4}\right)$, set

$$
u(y, s)=\int_{R(s)} S(t) y d t
$$

where $s=\left(s^{1}, \ldots, s^{n}\right), S(t)=T(p(t)), R(s)$ is the rectangle with sides $\left[0, s^{j} e_{j}\right]$, and $R(s)$ is contained in the image of $N_{4}$ under the inverse map. By (1.1),

$$
A\left(b_{k}\right) u(y, s)=\int_{R(s)} A\left(b_{k}\right) S(t) y d t=\int_{R(s)} \sum_{i=1}^{n} \zeta_{k}^{i}(t) \frac{\partial}{\partial t^{i}} S(t) y d t
$$

where $\zeta_{k}^{i}(t)=\sum_{j, m=1}^{n} F_{m ;}^{j}(0, p(t)) b_{k}^{m} \frac{\partial t^{i}}{\partial p^{j}}$ is once continuously differentiable. Integrate by parts to obtain

$$
\begin{equation*}
A\left(b_{k}\right) u(y, s)=\left.\sum_{i=1}^{n} \int_{R\left(\widehat{s}^{i}\right)} \zeta_{k}^{i}(t) S(t) y\right|_{\left(\widehat{t^{i}}, 0\right)} ^{\left(\widehat{t}^{i}, s^{i}\right)} d \widehat{t}^{\imath}-\int_{R(s)} \sum_{i=1}^{n} \frac{\partial \zeta_{k}^{i}}{\partial t^{i}} S(t) y d t \tag{1.4}
\end{equation*}
$$

Since the integral of a function with values lying in a closed subspace of a Banach space is contained in that subspace,

$$
\begin{equation*}
\left(u(y, s), A\left(b_{r+1}\right) u(y, s), \ldots, A\left(b_{n}\right) u(y, s)\right) \in G_{0} \tag{1.5}
\end{equation*}
$$

Since (1.4) is a continuous function of $y$ and $E\left(N_{4}\right)$ is dense in $X$, for any $y \in X, u(y, s) \in$ $\bigcap_{j=1}^{n} D\left(A\left(b_{j}\right)\right)$ and (1.4) and (1.5) hold. To complete the proof it is sufficient to show

$$
\begin{align*}
\lim _{\sigma \rightarrow 0} \sigma^{-n} u(y, s(\sigma)) & =y  \tag{1.6}\\
\lim _{\sigma \rightarrow 0} A\left(b_{k}\right) \sigma^{-n} u(y, s(\sigma)) & =A\left(b_{k}\right) y \tag{1.7}
\end{align*}
$$

for $k \geqslant r+1, y \in \bigcap_{k=r+1}^{n} D\left(A\left(b_{k}\right)\right)$, and $s(\sigma)=(\sigma, \ldots, \sigma)$. The relation (1.6) is clear; to prove 1.7) we expand $\zeta_{k}^{i}(t)$ in a Taylor's series and consider

$$
\begin{aligned}
& \left.\lim _{\sigma \rightarrow 0} \sigma^{-n} \int_{R\left(\widehat{s}^{i}(\sigma)\right)} \zeta_{k}^{i}(t) S(t) y\right|_{\left(\widehat{t^{i}}, 0\right)} ^{\left(\widehat{t^{i}}, \sigma\right)} d \widehat{t^{i}} \\
& =\lim _{\sigma \rightarrow 0} \sigma^{-n+1} \int_{R\left(\widehat{s}^{i}\right)} \delta_{k}^{i} \sigma^{-1}\left(S\left(\widehat{t^{i}}, \sigma\right) y-S\left(\widehat{t^{i}}, 0\right) y\right) d \widehat{t^{i}} \\
& \quad+\sigma^{-n+1} \int_{R\left(\widehat{s}^{i}\right)} \frac{\partial \zeta_{k}^{i}}{\partial t^{i}}(0) S\left(\widehat{t^{i}}, 0\right) y d \widehat{t^{i}} \\
& \quad+\sigma^{-n+1} \int_{R\left(\widehat{s}^{i}\right)}\left(\sum_{j \neq i} \sigma^{-1} t^{j} \frac{\partial \zeta_{k}^{i}}{\partial t^{j}}(0)\right) \cdots\left(S\left(\widehat{t^{i}}, \sigma\right) y-S\left(\widehat{t^{i}}, 0\right) y\right) d \widehat{t^{i}} \\
& =\delta_{k}^{i} A\left(b_{k}\right) y+\frac{\partial \zeta_{k}^{i}}{\partial t^{i}}(0) y
\end{aligned}
$$

provided

$$
\begin{equation*}
\lim _{\sigma \rightarrow 0} \sigma^{-1}\left(S\left(t^{k}, \sigma\right) y-S\left(t^{k}, 0\right) y\right)=A\left(b_{k}\right) y \tag{1.8}
\end{equation*}
$$

But the left side is $\prod_{j=1}^{k-1} T\left(f\left(t^{j} b_{j}\right)\right)$ applied to

$$
\begin{aligned}
& \sigma^{-1}\left(T\left(f\left(\sigma b_{k}\right)\right) y-y\right)+\left(T\left(f\left(\sigma b_{k}\right)\right)-I\right) \\
& \times\left(\sum_{i=k+1}^{n}\left(\prod_{m=k+1}^{i-1} T\left(f\left(t^{m} b_{m}\right)\right)\right) \sigma^{-1}\left(T\left(f\left(t^{i} b_{i}\right)\right)-y\right)\right)
\end{aligned}
$$

and (1.8) follows if we recall that $t^{i} \leqslant \sigma$ and that $y \in D\left(A\left(b_{i}\right)\right)$ for $i \geqslant k \geqslant r+1$. Summing over $i$ and taking the last term of (1.4) into account we obtain (1.7).

The following theorem is not of so much interest as the one just proved but we want to use it to establish the analogue of a theorem of [7]. We merely sketch the proof.
Theorem 2. If $F_{0}$ is the closure in the product topology of

$$
\left\{\left(y, A\left(e_{1}\right) y, \ldots, A\left(e_{n}\right) y, A\left(e_{i}\right) A\left(e_{j}\right) y\right) \mid y \in E\left(N_{3}\right)\right\}
$$

and if

$$
F=\left\{\left(y, A\left(e_{1}\right) y, \ldots, A\left(e_{n}\right) y, A\left(e_{i}\right) A\left(e_{j}\right) y\right) \mid y \in \bigcap_{k=1}^{n} D\left(A\left(e_{k}\right)\right) \cap D\left(A\left(e_{i}\right) A\left(e_{j}\right)\right)\right\}
$$

then $F=F_{0}$.
Proof. The set $F$ is closed and thus $F \supseteq F_{0}$. We show $F_{0} \supseteq F$. Taking $b_{k}=e_{k}$ we use the notation of the proof of Theorem 1. For $y \in E\left(N_{4}\right)$,

$$
A\left(e_{i}\right) A\left(e_{j}\right) u(y, s)=\int_{R(s)} A\left(e_{i}\right) A\left(e_{j}\right) S(t) y d t=\int_{R(s)} \sum_{k, m=1}^{n} \delta_{m}^{k}(t) \frac{\partial}{\partial t^{m}}\left(S(t) A\left(e_{k}\right) y\right) d t
$$

where $\delta_{m}^{k}(t)=\sum_{r=1}^{n} \beta_{j}^{k}(p(t)) F_{i ;}^{r}(0, p(t)) \frac{\partial t^{m}}{\partial p^{r}}$ is once continuously differentiable. Integrating by parts, we obtain the following relation

$$
\begin{align*}
& A\left(e_{i}\right) A\left(e_{j}\right) u(y, s)=  \tag{1.9}\\
& \left.\quad \sum_{m=1}^{n} \int_{R\left(\widehat{s}^{m}\right)} \sum_{k=1}^{n} \delta_{m}^{k}(t) S(t) A\left(e_{k}\right) y\right|_{\left(\hat{t}^{m}, 0\right)} ^{\left(t^{m}, s^{m}\right)} d \widehat{t^{m}}-\int_{R(s)} \sum_{k, m=1}^{n} \frac{\partial \delta_{m}^{k}}{\partial t^{m}}(t) S(t) A\left(e_{k}\right) y d t .
\end{align*}
$$

Theorem 1 implies that 1.9 holds for $y \in \bigcap_{k=1}^{n} D\left(A\left(e_{k}\right)\right)$. The proof is now completed as above.
3. We now consider the adjoints of the infinitesimal generators and prove the corresponding dense graph theorem. If $y^{*} \in X^{*}$, the dual space of $X$, we denote the value of $y^{*}$ at $y \in X$ by ( $y, y^{*}$ ). If $N \subseteq N_{1}$, set

$$
E(N)=\left\{y^{*} \in X^{*} \mid\left(y, y^{*}\right)=\int_{\Pi}\left(y, K(q) T^{*}(q) x^{*}\right) d q\right\}
$$

with $x^{*} \in X^{*}, K(q) \in C^{2}(N \cap \Pi)$, and for all $y \in X$. The set $E^{*}(N)$ is dense in $X^{*}$ in the weak-* topology.

Proposition 2. If $y^{*} \in E^{*}\left(N_{3}\right)$ then $T^{*}(p) y^{*}$ is twice continuously differentiable in the weak-* topology, for $p$ in $N_{3} \cap \Pi$.

Proof. We merely sketch the calculations since the proof is essentially the same as that of Proposition 1.

$$
\begin{aligned}
& \lim _{s \rightarrow 0} s^{-1} \int_{\Pi}\left(y, K(q)\left(T^{*}\left(p+s e_{j}\right)-T^{*}(p)\right) T^{*}(q) x^{*}\right) d q \\
&=\lim _{s \rightarrow 0} s^{-1} \int_{\Pi}\left(y, K(q)\left(T^{*}\left(q \circ\left(p+s e_{j}\right) x^{*}-T^{*}(q) x^{*}\right)\right)\right) d q \\
&=\int_{N^{2} \cap \Pi}\left(y, \frac{\partial}{\partial p^{j}}\left(K(\chi(q, p)) \operatorname{det}\left(\frac{\partial \chi^{k}}{\partial q^{i}}(q, p)\right)\right)\right) T^{*}(q) x^{*} d q
\end{aligned}
$$

look at again The last integral is again a continuously differentiable function of $p$.
We remark the following:
(i) If $y^{*} \in E^{*}\left(N_{3}\right)$ and $p \in N_{3} \cap \Pi$ then

$$
\begin{equation*}
\lim _{s \rightarrow 0} s^{-1}\left(y,\left(T^{*}(f(s a))-I\right) T^{*}(p) y^{*}\right)=\sum_{j=1}^{n}\left(\sum_{m=1}^{n} F_{; m}^{j}(p, 0) a^{m}\right) \frac{\partial}{\partial p^{j}}\left(y, T^{*}(p) y^{*}\right) . \tag{1.10}
\end{equation*}
$$

This implies that $T^{*}(p) y^{*} \in D\left(A^{*}(a)\right)$ and that $\left(y, A^{*}(a) T^{*}(p) y^{*}\right)$ is given by the right side of (1.10).
(ii) As in the remarks following Proposition 1 we may show, for $y^{*} \in E^{*}\left(N_{3}\right)$,

$$
\begin{gather*}
A^{*}(a+b) y^{*}=A^{*}(a) y^{*}+A^{*}(b) y^{*} \\
A^{*}\left(e_{i}\right) A^{*}\left(e_{j}\right) y^{*}-A^{*}\left(e_{j}\right) A^{*}\left(e_{i}\right) y^{*}=-\sum_{k=1}^{n} \gamma_{i j}^{k} A^{*}\left(e_{k}\right) y^{*} .
\end{gather*}
$$

Theorem 3. Let $\left\{a_{1}, \ldots, a_{p}\right\} \subseteq \Pi$. If $H_{0}$ is the closure (in the product of the weak-* topologies) of $\left\{\left(y^{*}, A^{*}\left(a_{1}\right) y^{*}, \ldots, A^{*}\left(a_{p}\right) y^{*}\right) \mid y^{*} \in E^{*}\left(N_{3}\right)\right\}$ and

$$
H=\left\{\left(y^{*}, A^{*}\left(a_{1}\right) y^{*}, \ldots, A^{*}\left(a_{p}\right) y^{*}\right) \mid y^{*} \in \bigcap_{j=1}^{p} D\left(A^{*}\left(a_{j}\right)\right)\right\}
$$

then $H=H_{0}$.
Proof. First $H \supseteq H_{0}$ since $A^{*}(a)$ is closed in the weak-* topology. We show $H_{0} \supseteq H$. Let $\left\{b_{1}, \ldots, b_{r}\right\}$ be a maximal linearly independent subset of $\left\{a_{1}, \ldots, a_{p}\right\}$; it is sufficient to prove the theorem for the former set. Let $\left\{b_{1}, \ldots, b_{n}\right\}$ be a basis for $E_{n}$. Again we use the notation of the proof of Theorem 1. If $y^{*} \in E^{*}\left(N_{4}\right)$, define $u\left(y^{*}, s\right)$ by

$$
\left(y, u\left(y^{*}, s\right)\right)=\int_{R(s)}\left(y, S^{*}(t) y^{*}\right) d t
$$

with $S^{*}(t)=T^{*}(p(t))$. As above

$$
\begin{align*}
& \left(y, A^{*}\left(b_{k}\right) u\left(y^{*}, s\right)\right)  \tag{1.11}\\
& \quad=\left.\sum_{i=1}^{n} \int_{R\left(\widehat{s}_{i}\right)} \xi_{k}^{i}(t)\left(y, S^{*}(t) y^{*}\right)\right|_{\left.\widehat{t^{i}}, 0\right)} ^{\left(\widehat{t}^{i}, s^{i}\right)} d \widehat{t^{i}}-\int_{R(s)} \sum_{i=1}^{n} \frac{\partial \xi_{k}^{i}}{\partial t^{i}}(t)\left(y, S^{*}(t) y^{*}\right) d t
\end{align*}
$$

with $\xi_{k}^{i}(t)=\sum_{j, m=1}^{n} F_{; j}^{m}(p(t), 0) b_{k}^{j} \frac{\partial t^{i}}{\partial p^{m}}$. As above $u\left(y^{*}, s\right) \in \bigcap_{k=1}^{n} D\left(A^{*}\left(b_{k}\right)\right)$ for all $y^{*} \in X^{*}$ and $A^{*}\left(b_{k}\right) y^{*}$ is given by (1.11). Moreover,

$$
\left(u\left(y^{*}, s\right) A^{*}\left(b_{1}\right) u\left(y^{*}, s\right), \ldots, A^{*}\left(b_{r}\right) u\left(y^{*}, s\right)\right) \in H_{0}
$$

The proof may be completed as before if we show that

$$
\begin{equation*}
\lim _{\sigma \rightarrow 0} \sigma^{-1}\left(y,\left(S^{*}\left(\hat{t}^{k}, \sigma\right)-S^{*}\left(\hat{t}^{k}, 0\right)\right) y^{*}\right)=\left(y, A^{*}\left(b_{k}\right) y^{*}\right) \tag{1.12}
\end{equation*}
$$

for $1 \leqslant k \leqslant r, t^{j} \leqslant \sigma$, and $y^{*} \in \bigcap_{i=1}^{r} D\left(A^{*}\left(b_{i}\right)\right)$. But the expression on the left equals

$$
\begin{aligned}
&\left(\prod_{j=k+1}^{n} T\left(f\left(t^{j} b_{j}\right)\right) y, \sigma^{-1}\left(T^{*}\left(f\left(\sigma b_{k}\right)\right)-I\right) y^{*}\right) \\
&+\sum_{i=1}^{k-1} \\
&\left(\prod_{m=i+1}^{k-1} T\left(f\left(t^{m} b_{m}\right)\right)\left(T\left(f\left(\sigma b_{k}\right)\right)-I\right)\right.\left.\prod_{j=k+1}^{n} T\left(f\left(t^{j} b_{j}\right)\right) y, \sigma^{-1}\left(T^{*}\left(f\left(t^{i} b_{i}\right)\right)-I\right) y^{*}\right)
\end{aligned}
$$

and (1.12) follows since, see [11], $\sigma^{-1}\left(T^{*}\left(f\left(t^{i} b_{i}\right)\right)-I\right) y^{*}$ is uniformly bounded and

$$
\sigma^{-1}\left(T^{*}\left(f\left(\sigma b_{k}\right)\right)-I\right) y^{*}
$$

converges in the weak-* topology to $A^{*}\left(b_{k}\right) y^{*}$.
4. If $a=\left(a^{1}, \ldots, a^{n}\right) \in E_{n}$ then $A(a)=\sum_{j=1}^{n} a^{j} A\left(e_{j}\right) y$ is defined for $y \in E\left(N_{3}\right)$. By the remarks after Proposition $2, E^{*}\left(N_{3}\right)$ is contained in the domain of its adjoint so that $A(a)$ has a least closed extension which we again denote by $A(a)$. By Theorem 1, this notation is consistent with that used previously for $a$ in $\Pi$.
Lemma 1. The operator $A^{*}(a)$, the adjoint of $A(a)$, is the weak-* closure of $\sum_{j=1}^{n} a^{j} A^{*}\left(e_{j}\right)$ with domain $E^{*}\left(N_{3}\right)$.

Proof. Suppose $\left(y, x_{1}^{*}\right)=\left(A(a) y, x_{2}^{*}\right)$ for all $y \in E\left(N_{3}\right)$. Then, using Theorem 1 and the notation of its proof with $b_{j}=e_{j}$, for $y \in X$

$$
\begin{aligned}
& \sigma^{-n} \int_{R(s(\sigma))}\left(S(t) y, x^{*}\right) d t \\
& \quad=\sigma^{-n} \sum_{j=1}^{n} a^{j}\left[\left.\sum_{i=1}^{n} \int_{R\left(\widehat{s}^{i}\right)}\left(\zeta_{j}^{i}(t) S(t) y, x_{2}^{*}\right)\right|_{\left(t^{i}, 0\right)} ^{\left(t^{i}, \sigma\right)} d \widehat{t}^{i}-\int_{R(s)}\left(\sum_{i=1}^{n} \frac{\partial \zeta_{i}^{i}}{\partial t^{i}}(t) S(t) y, x_{2}^{*}\right) d t\right] .
\end{aligned}
$$

Transposing and taking limits, we have

$$
\lim _{\sigma \rightarrow 0} \sigma^{-n} \sum_{j=1}^{n} a_{j} \int_{R\left(\widehat{s}^{j}\right)}\left(y,\left(S^{*}\left(\widehat{t^{j}}, \sigma\right)-S^{*}\left(\widehat{t}^{j}, 0\right)\right) x_{2}\right) d \widehat{t}^{j}=\left(y, x_{1}^{*}\right) .
$$

Then using (1.11), we obtain

$$
\begin{equation*}
\lim _{\sigma \rightarrow 0} \sigma^{-n}\left(y, \sum_{j=1}^{n} a^{j} A^{*}\left(e_{j}\right) u\left(x_{2}^{*}, s(\sigma)\right)\right)=\left(y, x_{1}^{*}\right) \tag{1.13}
\end{equation*}
$$

Theorem 3 implies that $u\left(x_{2}^{*}, s(\sigma)\right)$ is in the domain of the weak-* closure of $\sum_{j=1}^{n} a^{j} A^{*}\left(e_{j}\right)$ and (1.13) then shows that $x_{2}^{*}$ is also.

By Theorem 25.8.1 of [7] the $\gamma_{i j}^{k}$, as defined in Paragraph 1, may be used as the structural constants of a Lie algebra $A$ over $E_{n}$. Denoting the Lie product, in this algebra, of $a$ and $b$ by $[a, b]$, we have $[a, b]^{k}=\sum_{i, j=1}^{n} \gamma_{i j}^{k} a^{i} b^{j}$. We can now prove the following theorem.

## Theorem 4.

I. The function $a \rightarrow A(a)$ defined on $A$ has the properties
(i) If $x \in D(A(a)) \cap D(A(b))$ then $x \in D(A(s a+t b))$ and

$$
A(s a+t b) x=s A(a) x+t A(B) x
$$

(ii) If $x \in D(A(a) A(b)) \cap D(A(b) A(a))$ then $x \in D(A([a, b]))$ and

$$
A([a, b]) x=A(a) A(b) x-A(b) A(a) x .
$$

II. The function $a \rightarrow A^{*}(a)$ has the properties
(i) If $x^{*} \in D\left(A^{*}(a)\right) \cap D\left(A^{*}(b)\right)$ then $x^{*} \in D\left(A^{*}([s a+t b])\right)$ and

$$
A^{*}([s a+t b]) x^{*}=s A^{*}(a) x^{*}+t A^{*}(b) x^{*} .
$$

(ii) If $x^{*} \in D\left(A^{*}(a) A^{*}(b)\right) \cap D\left(A^{*}(b) A^{*}(a)\right)$ then $x^{*} \in D\left(A^{*}([a, b])\right)$ and

$$
A^{*}([a, b]) x^{*}=A^{*}(b) A^{*}(a) x^{*}-A^{*}(a) A^{*}(b) x^{*}
$$

Proof. If $x \in D(A(a)) \cap D(A(b))$ there is a sequence $\left\{x_{n}\right\} \subseteq E\left(N_{3}\right)$ such that $x_{n} \rightarrow x$, $A(a) x_{n} \rightarrow A(a) x$ and $A(b) x_{n} \rightarrow A(b) x$; but then, using formula ( $\alpha$ ) on page 3 , $A(s a+$ $t b) x_{n}=s A(a) x_{n}+t A(b) x_{n} \rightarrow s A(a) x+t A(b) x$. Since $A(s a+t b)$ is a closed operator, $x \in D(A(s a+t b))$ and $A(s a+t b) x=s A(a) x+t A(b) x$.

If $x \in D(A(a) A(b)) \cap D(A(b) A(a))$, then for $x \in E^{*}\left(N_{3}\right)$

$$
\left(A(a) A(b) x-A(b) A(a) x, x^{*}\right)=\left(x, A^{*}(b) A^{*}(a) x^{*}-A^{*}(a) A^{*}(b) x^{*}\right)
$$

So, using formula $\left(\beta^{\prime}\right)$ on page 6 ,

$$
\begin{equation*}
\left(A(a) A(b) x-A(b) A(a) x, x^{*}\right)=\left(x, A^{*}([a, b]) x^{*}\right) \tag{1.14}
\end{equation*}
$$

The lemma implies that (1.14) holds for $x^{*} \in D\left(A^{*}([a, b])\right)$. In other words, the vector $u=(A(a) A(b) x-A(b) A(a) x, x)$ in $X \oplus X$ is annihilated by the annihilator of the subspace $U=\{(A([a, b]) y, y) \mid y \in D(A([a, b]))\}$. So $u \in U$, or $x \in D(A([a, b]))$ and $A([a, b]) x=$ $A(a) A(b) x-A(b) A(a) x$. The remainder of the theorem is proved in a similar manner.

Recalling that if a sequence of once continuously differentiable functions and the sequences of first order derivatives converge uniformly on some domain then the limit function is once continuously differentiable and its partial derivatives are the limits of the sequences of partial derivatives, we have, using (1.3) and Theorem 1, the following result.

Theorem 5. If $y \in \bigcap_{j=1}^{n} D\left(A\left(e_{j}\right)\right)$ then $T(p) y$ is once continuously differentiable in a neighborhood in $\Pi$, of the origin and (1.3) holds. Consequently, $T(p) y \in D(A(a))$ for $a \in E_{n}$ and $p$ in this neighborhood and (1.1) and (1.2) hold for $a \in \Pi$.

The following theorem, analogous to Theorem 10.9.4 of [7], is an immediate consequence of Theorem 2.

Theorem 6. If $y \in \bigcap_{k=1}^{n} D\left(A\left(e_{k}\right)\right) \cap D\left(A\left(e_{i}\right) A\left(e_{j}\right)\right)$ then $y \in D\left(A\left(e_{j}\right) A\left(e_{i}\right)\right)$.
The only properties of $E\left(N_{3}\right)$ used in the proof of Theorem 1 were that $T(p) E\left(N_{4}\right) \subseteq E\left(N_{3}\right)$ for $p$ in a neighborhood of the origin, that $E\left(N_{4}\right)$ was dense in $X$, and that equation (1.1) was valid. Thus, using Theorem 5, we could repeat the proof of Theorem 1 to obtain

Theorem 1'. Let $F \subseteq E \subseteq X$ be two dense subspaces of $X$ contained in $\bigcap_{a \in \Pi} D(A(a))$ and let $T(p) F \subseteq E$ for $p$ in a neighborhood of the origin, then Theorem 1 is valid with $E\left(N_{3}\right)$ replaced by $E$.

In the next chapter we shall consider strongly continuous representations of Lie groups only. The group will be denoted by $G$ and its Lie algebra by $A$. A little care is necessary in the definition of $A$ in order that the formulae above remain valid. We take $A$ to be an algebra isomorphic to the algebra of left-invariant infinitesimal transformations with the multiplication $X Y-Y X$ (cf. [2]). Then if $e(a)$ denotes the exponential map of $A$ into $G$, and the representation is $T(p), A(a)$ is the infinitesimal generator of the one parameter group $T(e(t a))$. With $a$ we associate the following left- and right-invariant infinitesimal transformations

$$
\begin{aligned}
L_{a} f(p) & =\lim _{t \rightarrow 0} t^{-1}(f(p e(t a))-f(p)) \\
R_{a} f(p) & =\lim _{t \rightarrow 0} t^{-1}(f(e(-t a) p)-f(p)) .
\end{aligned}
$$

These mappings are isomorphisms of the Lie algebras involved. Formulae (1.1) and (1.2) may now be written very simply.

$$
\begin{align*}
& A(a) T(p) y=-R_{a} T(p) y \\
& T(p) A(a) y=L_{a} T(p) y
\end{align*}
$$

The adjoint representation $p \rightarrow d \alpha_{p}$ of $G$ is defined in [2]. With respect to a fixed basis $\left\{e_{i}, \ldots, e_{n}\right\}$ of $A$ let the matrix of the representation be $\left(\alpha_{j}^{i}(p)\right)$ so that $d \alpha_{p}\left(\sum_{j=1}^{n} a^{j} e_{j}\right)=$ $\sum_{i=1}^{n}\left(\sum_{j=1}^{n} \alpha_{j}^{i}(p) a^{j}\right) e_{i}$. We state formally the following simple lemma.
Lemma 2. If $x \in D(A(a))$, then $T(p) x \in D\left(A\left(d \alpha_{p}(a)\right)\right)$ and

$$
\begin{equation*}
A\left(d \alpha_{p}(a)\right) T(p) x=T(p) A(a) x \tag{1.15}
\end{equation*}
$$

Proof. Note that $x \in D(A(a))$ if and only if

$$
\lim _{t \rightarrow 0} t^{-1}(T(e(t a)) x-x)=A(a) x
$$

exists, or

$$
\lim _{t \rightarrow 0} t^{-1} T(p)(T(e(t a)) x-x)=T(p) A(a) x
$$

exists, or

$$
\begin{aligned}
\lim _{t \rightarrow 0} t^{-1} T(p)(T(e(t a))-I) T\left(p^{-1}\right) T(p) x & =\lim _{t \rightarrow 0} t^{-1} T\left(e\left(t d \alpha_{p}(a)\right)\right) T(p) x-T(p) x \\
& =A\left(d \alpha_{p}(a)\right) T(p) x
\end{aligned}
$$

exists. This proves the lemma.
We may write 1.15) as $A\left(d \alpha_{p}(a)\right) x=T(p) A(a) T\left(p^{-1}\right) x$. Formula 1.15) is implicit in formulae (1.1), (1.2), and (1.3).

Using the basis of $A$ previously introduced we set $A_{i}=A\left(e_{i}\right)$. If $\left\{X_{i}\right\}, i=1, \ldots, n$, is a set of $n$ indeterminates and $\alpha=\left(\alpha_{1}, \ldots, \alpha_{m}\right)$, is an $m$-tuple of integers $1 \leqslant \alpha_{i} \leqslant n$, we write $X_{\alpha}=X_{\alpha_{1}} X_{\alpha_{2}} \cdots X_{\alpha_{m}}$. The absolute value $|\alpha|$ of $\alpha$ is equal to $m$. This notation is slightly unorthodox but it is necessary to allow for the fact that the $A_{i}$ 's do not commute. We shall be interested in forms $\sum_{|\alpha| \leqslant m} a_{\alpha} A_{\alpha}$ in the set $\left\{A_{i}\right\}$.

Let $E$ be the set of vectors $y$ in $X$ which can be written in the form

$$
y=\int_{G} K(p) T(p) x \mu(d p)
$$

with $\mu$ a left-invariant Haar measure, $x$ in $X$, and $K(p)$ an infinitely differentiable function with compact support in $G$. The set $E$ satisfies the conditions of Theorem 1'. Similarly $E^{*}$ is the set of $y^{*}$ in $X^{*}$ such that for $x \in X$

$$
\left(x, y^{*}\right)=\int_{G} K(p)\left(x, T^{*}(p) x^{*}\right) \mu(d p)
$$

With any form $\sum_{|\alpha| \leqslant m} a_{\alpha} X_{\alpha}$ we may associate the operator $B_{0}$, with domain $E$, defined by $B_{0} x=\sum_{|\alpha| \leqslant m} a_{\alpha} A_{\alpha} x$ and the operator $B_{0}^{*}$, with domain $E^{*}$, defined by $B_{0}^{*} x^{*}$ $=\sum_{|\alpha| \leqslant m} a_{\alpha} A_{\alpha *}^{*} x^{*}$. If $\alpha=\left(\alpha_{1}, \ldots, \alpha_{|\alpha|}\right)$ then $\alpha^{*}=\left(\alpha_{|\alpha|}, \ldots, \alpha_{1}\right)$.

The following simple proposition is of some interest. A special case has been considered in [17].

Proposition 3. If, for $x$ in $E, B_{0} T(p) x=T(p) B_{0} x$, then the adjoint of $B_{0}$ is the weak-* closure of $B_{0}^{*}$.

Proof. Suppose that for all $x$ in $E$

$$
\left(B_{0} x, x_{1}^{*}\right)=\left(x, x_{2}^{*}\right)
$$

Then, for $x$ in $E$,

$$
\begin{aligned}
\left(\int_{G} K(p) T(p) x, x_{2}^{*}\right) \mu(d p) & =\left(\int_{G} K(p) B_{0} T(p) x \mu(d p), x_{1}^{*}\right) \\
& =\left(\int_{G} K(p) T(p) B_{0} x \mu(d p), x_{1}^{*}\right) .
\end{aligned}
$$

We may write this as

$$
\left(x, \int_{G} K(p) T^{*}(p) x_{2}^{*} \mu(d p)\right)=\left(x, B_{0}^{*} \int_{G} K(p) T^{*}(p) x_{1}^{*} \mu(d p)\right) .
$$

The integrals in the final formula are taken in the weak-* topology. We now let $K(p)$ approach the $\delta$-function and obtain $\int_{G} K(p) T^{*}(p) x_{1}^{*} \mu(d p) \rightarrow x_{1}^{*}$ and $B_{0}^{*} \int_{G} K(p) T^{*}(p) x_{1}^{*} \mu(d p)=$ $\int_{G} K(p) T^{*}(p) x_{2}^{*} \mu(d p) \rightarrow x_{2}^{*}$ in the weak-* topology.

## Chapter II

1. Before proving the principal theorems of this chapter we must establish some estimates for the fundamental solutions of strongly elliptic differential equations and a differentiability property of weak solutions of elliptic equations. The estimates are deduced from familiar ones for the fundamental solutions of parabolic equations (cf. [3, 15, 18]). Since we are unable to refer the reader to complete proofs of the latter estimates we establish them below. Although the required property of weak solutions of elliptic equations is known (cf. [1]) we have included a proof.
2. A differential operator, $\sum_{|\alpha| \leqslant m}(-i)^{|\alpha|} a_{\alpha} \frac{\partial^{\alpha}}{\partial x^{\alpha}}$, with constant coefficients, is called strongly elliptic if for any real $n$-vector $\xi, \operatorname{Re}\left(\sum_{|\alpha|=m} a_{\alpha} \xi^{\alpha}\right) \geqslant \rho|\xi|^{m}$, with a fixed $\rho>0$. A fundamental solution for the operator $\sum_{|\alpha| \leqslant m}(-i)^{|\alpha|} a_{\alpha} \frac{\partial^{\alpha}}{\partial x^{\alpha}}+\lambda$ is

$$
G(x, \lambda) \sim \frac{1}{(2 \pi)^{n}} \int_{E_{n}} e^{i x \cdot \xi}\left(\sum_{|\alpha| \leqslant m} a_{\alpha} \xi^{\alpha}+\lambda\right)^{-1} d \xi .
$$

If

$$
g(x, t)=\frac{1}{(2 \pi)^{n}} \int_{E_{n}} e^{i x \cdot \xi} \exp \left(-t \sum_{|\alpha| \leqslant m} a_{\alpha} \xi^{\alpha}\right) d \xi
$$

then

$$
G(x, \lambda)=\int_{0}^{\infty} e^{-\lambda t} g(x, t) d t
$$

This is a basic observation since it allows us to obtain estimates for $G(x, \lambda)$ from those for $g(x, t)$.

We shall be interested in the case that $a_{\alpha}=a_{\alpha}(y),|\alpha| \leqslant m$, depends on a parameter, $y$, varying in a region, $U$, of $n$-dimensional real space. We shall suppose that $a_{\alpha}(y),|\alpha| \leqslant m$, is $m$ times continuously differentiable in $U$ and that, in $U$,

$$
\begin{gather*}
\left|\frac{\partial^{\gamma}}{\partial y^{\gamma}} a_{\alpha}(y)\right| \leqslant M ; \quad|\gamma| \leqslant m,  \tag{i}\\
\operatorname{Re}\left\{\sum_{|\alpha|=m} a_{\alpha}(y) \xi^{\alpha}\right\} \geqslant \rho|\xi|^{m} .
\end{gather*}
$$

We want to estimate the mixed partial derivatives of $g(x, y, t)$ and $G(x, y, \lambda)$ up to the order $m$. We notice that, for $t>0$,

$$
\begin{aligned}
\frac{\partial^{\gamma}}{\partial y^{\gamma}} \frac{\partial^{\beta}}{\partial x^{\beta}} g(x, y, t) & =\frac{1}{(2 \pi)^{n}} \int_{E_{n}} i^{|\beta|} \xi^{\beta} e^{i x \cdot \xi} \exp \left(-t \sum_{|\alpha| \leqslant m} a_{\alpha} \xi^{\alpha}\right) M_{\gamma}(\xi, t) d \xi \\
& =\frac{1}{(2 \pi)^{n} t^{|\beta| / m}} \int_{E_{n}} i^{|\beta|} \xi^{\beta} t^{|\beta| / m} e^{i x \cdot \xi} \exp \left(-t \sum_{|\alpha| \leqslant m} a_{\alpha} \xi^{\alpha}\right) M_{\gamma}(\xi, t) d \xi
\end{aligned}
$$

and that the integrand in the final integral (with the factor $e^{i x \cdot \xi}$ removed) as a function of the complex $n$-vector $\xi=\sigma_{1}+\sigma+i \tau, \sigma_{1}, \sigma$ and $\tau$ real, is dominated by an expression $c_{1} e^{-\rho_{1}\left|\sigma_{1}\right|^{m} t} e^{a_{1} t|\sigma+i \tau|^{m}} e^{a_{2} t}$ when $|\gamma+\beta| \leqslant m$. The constants $c_{1}, \rho_{1}, a_{1}, a_{2}$ depend on $n, m, M$, and $\rho$ only. Consequently

$$
\begin{aligned}
& \left|\frac{\partial^{k}}{\partial \xi_{i}^{k}}\left\{\xi^{\beta} t^{|\beta| / m} \exp \left(-t \sum_{|\alpha| \leqslant m} a_{\alpha} \xi^{\alpha}\right) M_{\gamma}(\xi, t)\right\}\right| \\
& \quad=\left|\frac{k!}{(2 \pi)^{n}} \int_{\left|\zeta_{1}-\xi_{1}\right|=r} d \zeta_{1} \cdots \int_{\left|\zeta_{n}-\xi_{n}\right|=r} d \zeta_{n}\left\{\frac{\zeta^{\beta} t^{|\beta| / m} \exp \left(-t \sum_{|\alpha| \leqslant m} a_{\alpha} \xi^{\alpha}\right) M_{\gamma}(\zeta, t)}{\prod\left(\zeta_{i}-\xi_{i}\right)}\right\}\right| \\
& \leqslant c_{2} k!e^{a_{2} t} e^{-\rho_{1}|\xi|^{m} t} \frac{e^{a_{3} t r^{m}}}{r^{k}}
\end{aligned}
$$

Here and in the following all constants, unless the contrary is mentioned, depend only on $n$, $m, M$, and $\rho$. Since $r$, in the above inequality, is arbitrary we choose it to be $(k / t)^{1 / m}$ and obtain

$$
\left|\frac{\partial^{k}}{\partial \xi_{i}^{k}}\left\{\xi^{\beta} t^{|\beta| / m} \exp \left(-t \sum_{|\alpha| \leqslant m} a_{\alpha} \xi^{\alpha}\right) M_{\gamma}(\xi, t)\right\}\right| \leqslant c_{2} c_{3}^{k} k!e^{a_{2} t} e^{-\rho_{1}|\xi|^{m} t}\left(\frac{t}{k}\right)^{k / m} .
$$

Then

$$
\begin{aligned}
& \quad|x|^{2 k}\left|\frac{\partial^{\gamma}}{\partial y^{\gamma}} \frac{\partial^{\beta}}{\partial x^{\beta}} g(x, y, t)\right| \leqslant n^{2 k-1}\left(\sum_{i=1}^{n} x_{i}^{2 k}\right)\left|\frac{\partial^{\gamma}}{\partial y^{\gamma}} \frac{\partial^{\beta}}{\partial x^{\beta}} g(x, y, t)\right| \\
& =\left|\frac{n^{2 k-1}}{(2 \pi)^{n}} \frac{1}{t^{|\beta| / m}} \int_{E_{n}} \sum_{i=1}^{n} \frac{\partial^{2 k}}{\partial \xi_{i}^{2 k}}\left\{\xi^{\beta} t^{|\beta| / m} \exp \left(-t \sum_{|\alpha| \leqslant m} a_{\alpha} \xi^{\alpha}\right) M_{\gamma}(\xi, t)\right\} e^{i x \cdot \xi} d \xi\right| \\
& \leqslant c_{4} \frac{e^{a_{2} t}}{t^{|\beta| / m}}\left(c_{5}\right)^{2 k}(2 k)!\left(\frac{t}{2 k}\right)^{2 k / m} \int_{E_{n}} e^{-\rho_{1}|\xi|^{m} t} d \xi \\
& \leqslant c_{7} \frac{e^{a_{2} t}}{t^{(n+|\beta|) / m}}\left(c_{6} t\right)^{2 k / m}(2 k)^{2 k\left(\frac{m-1}{m}\right)+1 / 2} e^{-2 k} . \\
& \text { If }|x| /\left(c_{6} t\right)^{1 / m}>2, \text { set } \\
& \qquad k=\left(\frac{1}{2} \frac{|x|^{m /(m-1)}}{\left(c_{6} t\right)^{1 / m-1}}\right)
\end{aligned}
$$

to obtain

$$
\left|\frac{\partial^{\gamma}}{\partial y^{\gamma}} \frac{\partial^{\beta}}{\partial x^{\beta}} g(x, y, t)\right| \leqslant c_{8} \frac{e^{a_{2} t}}{t^{(n+|\beta|) / m}} e^{-\rho_{2}\left(\frac{|x|}{t^{1 / m}}\right)^{\frac{m}{m-1}}}
$$

If $|x| \leqslant 2\left(c_{6} t\right)^{1 / m}$, then

$$
\left|\frac{\partial^{\gamma}}{\partial y^{\gamma}} \frac{\partial^{\beta}}{\partial x^{\beta}} g(x, y, t)\right| \leqslant c_{9} \frac{e^{a_{2} t}}{t^{(n+|\beta|) / m}} .
$$

Now we observe that

$$
\operatorname{Re}\left\{e^{i \varphi}\left(\sum_{|\alpha|=m} a_{\alpha}(y) \xi_{\alpha}\right)\right\} \geqslant(\rho \cos \varphi-k \sin \varphi)|\xi|^{m}
$$

So there exist $\phi_{1}$ and $\phi_{2}$ with $-\pi / 2<\phi_{1}<0<\phi_{2}<\pi / 2$ such that, for $\phi_{1} \leqslant \varphi \leqslant \phi_{2}$,

$$
\operatorname{Re}\left\{e^{i \varphi}\left(\sum_{|\alpha|=m} a_{\alpha}(y) \xi_{\alpha}\right)\right\} \geqslant(\rho / 2)|\xi|^{m}
$$

Consequently we have proved
Lemma 3. Let all the above conditions be fulfilled. Then, for $\phi_{1} \leqslant \arg t \leqslant \phi_{2}$ and $|\gamma+\beta| \leqslant m$, the following inequalities are valid.
(i) If $|x| /|t|^{1 / m} \geqslant b_{1}$, then

$$
\left|\frac{\partial^{\gamma}}{\partial y^{\gamma}} \frac{\partial^{\beta}}{\partial x^{\beta}} g(x, y, t)\right| \leqslant b_{2} \frac{e^{b_{3}|t|}}{|t|^{(n+|\beta|) / m}} e^{-\rho_{3}\left(\frac{|x|}{\mid t^{1 / m}}\right)^{\frac{m}{m-1}} . . . ~}
$$

(ii) If $|x| /|t|^{1 / m} \leqslant b_{1}$, then

$$
\left|\frac{\partial^{\gamma}}{\partial y^{\gamma}} \frac{\partial^{\beta}}{\partial x^{\beta}} g(x, y, t)\right| \leqslant b_{4} \frac{e^{b_{3}|t|}}{|t|^{(n+|\beta|) / m}} .
$$

The constants $b_{2}, b_{4}$ depend only on $n, m, \rho$, and $M$.
As a consequence, if $|\gamma+\beta| \leqslant m$ then

$$
\begin{aligned}
\left.\int_{U}\left|\frac{\partial^{\gamma}}{\partial y^{\gamma}} \frac{\partial^{\beta}}{\partial x^{\beta}} g(x-z, y, t)\right|_{y=x} \right\rvert\, d x & \leqslant b_{4} \frac{e^{b_{3}|t|}}{t^{|\beta| / m}} \int_{|x-z| \leqslant b_{1}|t|^{1 / m}} \frac{1}{|t|^{n / m}} d x \\
& +b_{2} \frac{e^{b_{3}|t|}}{t^{|\beta| / m}} \int_{|x-z| \geqslant b_{1}|t|^{1 / m}} \frac{e^{-\rho_{1}\left(\frac{|x-z|}{|t|^{1 / m}}\right)^{\frac{m}{m-1}}}}{|t|^{n / m}} d x \\
& \leqslant b_{5} \frac{e^{b_{3}|t|}}{|t|^{|\beta| / m}}
\end{aligned}
$$

Let $S$ be the sector in the complex plane defined by

$$
S=\left\{z \mid \operatorname{Re}\left(z e^{i \phi_{1}}\right) \leqslant b_{3} \text { and } \operatorname{Re}\left(z e^{i \phi_{2}}\right) \leqslant b_{3}\right\} .
$$

If $\lambda$ is not in $S$ we can find a $\varphi, \phi_{1} \leqslant \varphi \leqslant \phi_{2}$, such that $\operatorname{Re}\left(\lambda e^{i \varphi}\right)-b_{3} \geqslant \rho(\lambda, S)$, the distance from $\lambda$ to $S$.

Lemma 4. If $\lambda$ is not in $S$, then for $|\beta|<m$ and $|\gamma+\beta| \leqslant m$

$$
\left.\int_{U}\left|\frac{\partial^{\gamma}}{\partial y^{\gamma}} \frac{\partial^{\beta}}{\partial x^{\beta}} G(x-z, y, \lambda)\right|_{y=x} \right\rvert\, d x \leqslant \frac{C}{\rho(\lambda, S)^{1-|\beta| / m}}
$$

Proof. Choose $\varphi$ as above; then

$$
\begin{aligned}
\left.\int_{U}\left|\frac{\partial^{\gamma}}{\partial y^{\gamma}} \frac{\partial^{\beta}}{\partial x^{\beta}} G(x-z, y, \lambda)\right|_{y=x} \right\rvert\, d x & \left.\leqslant \int_{U} \int_{0}^{e^{i \varphi} \infty}\left|e^{-\lambda t}\right|\left|\frac{\partial^{\gamma}}{\partial y^{\gamma}} \frac{\partial^{\beta}}{\partial x^{\beta}} g(x-z, y, t)\right|_{y=x}| | d t \right\rvert\, d x \\
& \leqslant b_{5} \int_{0}^{\infty} \frac{e^{-\left(\operatorname{Re}\left(\lambda e^{i \varphi}\right)-b_{3}\right) t}}{t^{|\beta| / m}} d t \\
& \leqslant \frac{C}{\left(\operatorname{Re}\left(\lambda e^{i \varphi}\right)-b_{3}\right)^{1-|\beta| / m}} \leqslant \frac{C}{\rho(\lambda, S)^{1-|\beta| / m}}
\end{aligned}
$$

We must now estimate $\frac{\partial^{\gamma}}{\partial y^{\gamma}} \frac{\partial^{\beta}}{\partial x^{\beta}} G(x-z, y, \lambda)$ pointwise for $|x| \leqslant R, R>0$. Choose $\varphi$ as above; then

$$
\begin{aligned}
\left.\left|\frac{\partial^{\gamma}}{\partial y^{\gamma}} \frac{\partial^{\beta}}{\partial x^{\beta}} G(x-z, y, \lambda)\right|_{y=x} \right\rvert\, \leqslant & b_{4} \int_{|x-z| \leqslant b_{1} t^{1 / m}} \frac{e^{-\left(\operatorname{Re}\left(\lambda e^{i \varphi}\right)-b_{3}\right) t}}{t^{(n+|\beta|) / m}} d t \\
& +b_{2} \int_{|x-z| \geqslant b_{1} t^{1 / m}} \frac{e^{-\left(\operatorname{Re}\left(\lambda e^{i \varphi}\right)-b_{3}\right) t}}{t^{(n+|\beta|) / m}} \exp \left(-\rho_{3}\left(\frac{|x-z|}{t^{1 / m}}\right)^{\frac{m}{m-1}}\right) d t \\
& =b_{4} I_{1}+b_{2} I_{2} .
\end{aligned}
$$

We estimate the two terms separately for $\operatorname{Re}\left(\lambda e^{i \varphi}\right)-b_{3}=\omega \geqslant \delta_{0}>0$. For simplicity we replace $x-z$ by $x$.
(i) $0<\delta_{1} \leqslant|x| \leqslant R$. Then, changing variables $t \rightarrow t+\left(|x| / b_{1}\right)^{m}$, one has

$$
\begin{aligned}
I_{1} & \leqslant \exp \left(-\omega\left(\frac{|x|}{b_{1}}\right)^{m}\right) \int_{0}^{\infty} e^{-\omega t}\left|\left(\frac{|x|}{b_{1}}\right)^{m}+t\right|^{-(n+|\beta|) / m} d t \\
& \leqslant \exp \left(-\omega\left(\frac{|x|}{b_{1}}\right)^{m}\right) M\left(\delta_{0}, \delta_{1}, R\right)
\end{aligned}
$$

(ii) $|x| \leqslant \delta_{1}$. Then

$$
\begin{aligned}
I_{1} & \leqslant \int_{1}^{\infty} \frac{e^{-\omega t}}{t^{(n+|\beta|) / m}} d t+\int_{\left(|x| / b_{1}\right)^{m}}^{1} \frac{1}{t^{(n+|\beta|) / m}} d t \\
& \leqslant \begin{cases}c_{1}+c_{2}|x|^{m-n-|\beta|} & \text { if } m-n-|\beta| \neq 0 \\
c_{1}+c_{2}|\log | x| | & \text { if } m-n-|\beta|=0\end{cases}
\end{aligned}
$$

We remark that, for $|\beta|=m-1, m-n-|\beta|=1-n=0$ only if $n=1$, in which case

$$
\left.\left|\frac{\partial^{\gamma}}{\partial y^{\gamma}} \frac{\partial^{\beta}}{\partial x^{\beta}} G(x-z, y, \lambda)\right|_{y=x} \right\rvert\, \leqslant C(\lambda)
$$

for $|x-z| \leqslant \delta_{1}$. This is a simple fact about Fourier transforms in one variable and we do not prove it.
(iii) $0<\delta_{1}=|x| \leqslant R$. Then, changing variables $t \rightarrow t / \omega$, one has

$$
\begin{aligned}
I_{2} & =\omega^{\frac{n+|\beta|}{m}-1} \int_{0}^{\omega\left(|x| / b_{1}\right)^{m}} \frac{e^{-t}}{t^{(n+|\beta|) / m}} e^{-\rho_{3}\left(\frac{\omega|x|^{m}}{t}\right)^{\frac{1}{(m-1)}}} d t \\
& \leqslant \omega^{\frac{n+|\beta|}{m}-1} \int_{0}^{\infty} \frac{e^{-t}}{t^{(n+|\beta|) / m}} e^{-\rho_{3}\left(\frac{\omega|x|^{m}}{t}\right)^{\frac{1}{(m-1)}}} d t \leqslant \omega^{\frac{n+|\beta|}{m}-1}\left\{J_{1}+J_{2}\right\}
\end{aligned}
$$

where

$$
\begin{aligned}
J_{2} & =\int_{\left(\omega|x|^{m}\right)^{1 / m}}^{\infty} \frac{e^{-t}}{t^{(n+|\beta|) / m}} d t \\
& \leqslant e^{-\omega^{1 / m}|x|} \int_{0}^{\infty} \frac{e^{-t}}{\left(\omega^{1 / m}|x|+t\right)^{(n+|\beta|) / m}} d t \leqslant c_{3} e^{-\omega^{1 / m}|x|}
\end{aligned}
$$

by a change of variables $t \rightarrow t+\omega^{1 / m}|x|$. Moreover

$$
\begin{aligned}
J_{1} & =\int_{0}^{\left(\omega|x|^{m}\right)^{1 / m}} \frac{e^{-t}}{t^{(n+|\beta|) / m}} e^{-\rho_{3}\left(\frac{\omega x| |^{m}}{t}\right)^{\frac{1}{(m-1)}}} d t \\
& \leqslant\left(\omega|x|^{m}\right)^{1-\frac{(n+|\beta|)}{m}} \int_{\left(\omega|x|^{m}\right)^{\frac{(m-1)}{m}}}^{\infty} e^{-\rho_{3} s^{\frac{1}{(m-1)}}} s^{\frac{(n+|\beta|)}{m}-2} d s \\
& \leqslant c_{4}\left(\omega|x|^{m}\right)^{1-\frac{(n+|\beta|)}{m}} \int_{\omega^{1 / m}|x|}^{\infty} e^{-\rho_{3} u} u^{(m-1)\left(\frac{(n+|\beta|)}{m}-2\right)+m-2} d u \\
& \leqslant c_{5} e^{-\rho_{3} \omega^{1 / m}|x| / 2}\left\{\left(\omega|x|^{m}\right)^{q_{1}}+\left(\omega|x|^{m}\right)^{q_{2}}\right\} .
\end{aligned}
$$

The first estimate follows by a change of variables $t \rightarrow s=\omega|x|^{m} / t$. Then the second follows by setting $s=u^{m-1}$. The extra factor $1 / 2$ in the exponential in the last line is added so that the remaining part of the exponential in the integral ensures convergence at infinity.
(iv) $|x| \leqslant \delta_{1}$. Then

$$
\begin{aligned}
I_{2} & =\int_{0}^{\left(|x| / b_{1}\right)^{m}} \frac{\exp \left(-\rho_{3}\left(|x| / t^{1 / m}\right)^{\frac{m}{m-1}}\right)}{t^{(n+|\beta|) / m}} d t \\
& =|x|^{m-n-|\beta|} \int_{0}^{b_{5}} \frac{\exp \left(-\rho_{3} / t^{1 /(m-1)}\right)}{t^{(n+|\beta|) / m}} d t \leqslant c_{6}|x|^{m-n-|\beta|} .
\end{aligned}
$$

The estimates are precise enough for our purposes. All we need is that $G(x-z, x, \lambda)$ goes to zero uniformly as $\omega$ increases provided $|x-z|$ remains between two fixed positive constants and that the derivatives of order $m-1$ go to infinity like $|x-z|^{1-n}$ as $|x-z|$ goes to zero.
3. The differential operator, $\sum_{|\alpha|=m} a_{\alpha} \frac{\partial^{\alpha}}{\partial x^{\alpha}}$, with constant coefficients, is elliptic if $Q(\xi)=$ $\sum_{|\alpha|=m} a_{\alpha} \xi^{\alpha} \neq 0$ for any real $n$-vector $\xi$. F. John, in [10], has constructed fundamental solutions for such differential operators. These are, for $n$, the number of variables, odd and
even respectively,

$$
\begin{gather*}
K(x-y)=\frac{1}{4(2 \pi i)^{n-1}(m-1)!} \Delta_{x}^{\frac{n-1}{2}} \int_{\Omega_{\xi}} \frac{((x-y) \cdot \xi)^{m-1} \operatorname{sgn}((x-y) \cdot \xi)}{Q(\xi)} d \omega_{\xi}  \tag{2.1}\\
K(x-y)=\frac{-1}{(2 \pi i)^{n} m!} \Delta_{x}^{n / 2} \int_{\Omega_{\xi}} \frac{((x-y) \cdot \xi)^{m} \log |(x-y) \cdot \xi|}{Q(\xi)} d \omega_{\xi} \tag{2.2}
\end{gather*}
$$

where $\Omega_{\xi}$ is the unit sphere and $\Delta$ is the Laplacian. Actually John was concerned only with the case that the coefficients are real; however, a repetition of his argument shows that (2.1) and $(2.2)$ are fundamental solutions when the coefficients are complex. In order to use these fundamental solutions we must perform the indicated differentiations. Let $L_{i j}=x_{i} \frac{\partial}{\partial x_{j}}-x_{j} \frac{\partial}{\partial x_{i}}$; then

$$
\begin{gather*}
\Delta=\frac{1}{2 r^{2}} \sum_{i, j=1}^{n} L_{i j}^{2}+\frac{n-1}{r} \frac{\partial}{\partial r}+\frac{\partial^{2}}{\partial r^{2}}  \tag{2.3}\\
\frac{\partial}{\partial x_{k}}=\frac{1}{2 r^{2}} \sum_{i, j=1}^{n}\left(\delta_{k j} x_{i}-\delta_{k i} x_{j}\right) L_{i j}+\frac{x_{k}}{r} \frac{\partial}{\partial r} . \tag{2.4}
\end{gather*}
$$

With a suitable skew-symmetric matrix, $A_{i j}$,

$$
\begin{aligned}
L_{i j} \int_{\Omega_{\xi}} g(x \cdot \xi) f(\xi) d \xi & =\lim _{t \rightarrow 0} \frac{1}{t}\left[\int_{\Omega_{\xi}} g\left(e^{t A_{i j}} x \cdot \xi\right) f(\xi) d \omega_{\xi}-\int_{\Omega_{\xi}} g(x \cdot \xi) f(\xi) d \omega_{\xi}\right] \\
& =\lim _{t \rightarrow 0} \frac{1}{t}\left[\int_{\Omega_{\xi}} g(x \cdot \xi)\left\{f\left(e^{t A_{i j}} \xi\right)-f(\xi)\right\} d \omega_{\xi}\right] \\
& =\int_{\Omega_{\xi}} g(x \cdot \xi) L_{i j} f(\xi) d \omega_{\xi}
\end{aligned}
$$

Of course, in the last integrand, $x$ has been replaced by $\xi$ in the operator $L_{i j}$. Setting $\widetilde{x}=\frac{x}{|x|}$, we have for $n$ odd

$$
\begin{equation*}
K(x)=\frac{1}{4(2 \pi i)^{n-1}(m-1)!} r^{m-n} \int_{\Omega_{\xi}}(\widetilde{x} \cdot \xi)^{m-1} \operatorname{sgn}(\widetilde{x} \cdot \xi) \frac{P(\xi)}{\{Q(\xi)\}^{n}} d \omega_{\xi} . \tag{2.5}
\end{equation*}
$$

Here $P(\xi)$ is a polynomial in $\xi$. A similar formula is valid for $n$ even. We may also show that, for $n$ odd,

$$
\frac{\partial^{\alpha}}{\partial x^{\alpha}} K(x)=\frac{1}{4(2 \pi i)^{n-1}(m-1)!} r^{m-n-|\alpha|} \int_{\Omega_{\xi}}(\widetilde{x} \cdot \xi)^{m-1} \operatorname{sgn}(\widetilde{x} \cdot \xi) \frac{P(\widetilde{x}, \xi)}{\{Q(\xi)\}^{n+|\alpha|}} d \omega_{\xi}
$$

where $P(\widetilde{x}, \xi)$ is a polynomial in $\widetilde{x}$ and $\xi$. Again, a similar formula is valid for $n$ even. For $x \neq 0, \sum_{|\alpha|=m} a_{\alpha} \frac{\partial^{\alpha}}{\partial x^{\alpha}} K(x)=0$. If $\varphi(y)$ is an infinitely differentiable function with compact
support and $\varphi(x) \equiv 1$ in a neighborhood of 0 , then (cf. page 57 of [10])

$$
\begin{aligned}
1=\varphi(0) & =\int_{E_{n}} K(-x) \sum_{|\alpha|=m} a_{\alpha} \frac{\partial^{\alpha}}{\partial x^{\alpha}} \varphi(x) \\
& =\lim _{\varepsilon \rightarrow 0} \frac{1}{\varepsilon} \int_{|x|=\varepsilon}\left\{\sum_{|\alpha|=m} a_{\alpha}\left(\frac{\partial^{\widehat{\alpha}}}{\partial x^{\widehat{\alpha}}} K\right)(-x) x_{\alpha_{|\alpha|}}\right\} \varphi(x) d \omega
\end{aligned}
$$

with $\widehat{\alpha}=\left(\alpha_{1}, \ldots, \alpha_{|\alpha|-1}\right)$; or

$$
\begin{equation*}
1=\lim _{\varepsilon \rightarrow 0} \frac{1}{\varepsilon} \int_{|x|=\varepsilon} \sum_{|\alpha|=m} a_{\alpha}\left(\frac{\partial^{\widehat{\alpha}}}{\partial x^{\widehat{\alpha}}} K\right)(-x) x_{\alpha_{|\alpha|}} d \omega . \tag{2.6}
\end{equation*}
$$

Moreover, 2.6) is valid for the fundamental solutions discussed in Paragraph 1.
We can now prove the lemma of this paragraph. We consider a differential operator $B=\sum_{|\alpha| \leqslant m} a_{\alpha}(x) \frac{\partial^{\alpha}}{\partial x^{\alpha}}$ which is defined and uniformly elliptic in a domain $V$ of Euclidean $n$-space; that is, for any real $n$-vector $\xi$ and any $x \in V,\left|\sum_{|\alpha|=m} a_{\alpha}(x) \xi^{k}\right| \geqslant \rho|\xi|^{m}$ with some fixed constant $\rho>0$. We suppose that $a_{\alpha}(x)$ is $|\alpha|$-times continuously differentiable in $V$ and that its derivatives up to the $|\alpha|$ th order are bounded in $V$. The set $C_{c}^{\infty}(V)$ consists of infinitely differentiable functions with compact support in $V$. Then we have:

Lemma 5. Suppose $u(x)$ and $f(x)$ are two continuous functions in $V$ such that

$$
\begin{equation*}
\int_{V} B \varphi(x) u(x) d x=\int_{V} \varphi(x) f(x) d x \tag{2.7}
\end{equation*}
$$

for all functions $\varphi$ in $C_{c}^{\infty}(V)$. Then $u(x)$ is $(m-1)$-times continuously differentiable in $V$ and the modulus of continuity of any $(m-1)$ th order derivative is $O(\delta \log 1 / \delta)$ uniformly in any compact subset $U$ of $V$.

Proof. By the usual arguments it can be shown that (2.7) holds for $\varphi(x) m$-times continuously differentiable with compact support in $V$. Let $K(x-z, y)$ be the fundamental solution of the operator $\sum_{|\alpha|=m} a_{\alpha}(y) \frac{\partial^{\alpha}}{\partial x^{\alpha}}$; let $\psi(y)$ be infinitely differentiable with compact support in $V$ and be identically 1 in a neighborhood $W$ of $y$. Let $j_{k}(y)$ be infinitely differentiable; $j_{k}(y) \geqslant 0$; $\int_{E_{n}} j_{k}(y) d y=1$; and $j_{k}(y)=0$ if $|y|>\frac{1}{k}$. Then, for large $k$, 2.7) is valid with

$$
\varphi(y)=\int_{E_{n}} j_{k}(y-z) \psi(z) K(x-z, y) d z
$$

We calculate

$$
\begin{aligned}
& \sum_{|\alpha| \leqslant m} a_{\alpha}(y) \frac{\partial^{\alpha}}{\partial y^{\alpha}} \int_{E_{n}} j_{k}(y-z) \psi(z) K(x-z, y) d z \\
& =\int_{E_{n}} \sum_{|\alpha| \leqslant m} a_{\alpha}(y) \sum_{\alpha_{1}+\alpha_{2}=\alpha}(-1)^{\left|\alpha_{1}\right|}\left(\frac{\partial^{\alpha_{1}}}{\partial z^{\alpha_{1}}} j_{k}(y-z)\right)\left(\frac{\partial^{\alpha_{2}}}{\partial y^{\alpha_{2}}} K(x-z, y)\right) \psi(z) d z \\
& =\int_{E_{n}}(-1)^{m} \sum_{|\alpha|=m} a_{\alpha}(y)\left(\frac{\partial^{\alpha}}{\partial z^{\alpha}} j_{k}(y-z)\right) \psi(z) K(x-z, y) d z \\
& +\sum_{|\alpha| \leqslant m} \sum_{\substack{\alpha_{1}+\alpha_{2}=\alpha \\
\left|\alpha_{1}\right|<m}} \int_{E_{n}} a_{\alpha}(y) j_{k}(y-z) \frac{\partial^{\alpha_{1}}}{\partial z^{\alpha_{1}}}\left\{\psi(z) \frac{\partial^{\alpha_{2}}}{\partial y^{\alpha_{2}}} K(x-z, y)\right\} d z
\end{aligned}
$$

With our unorthodox notation the symbol $\alpha_{1}+\alpha_{2}=\alpha$ is a little difficult to explain. It means that $\alpha_{1}$ and $\alpha_{2}$ are subsequences of the sequence $\alpha$ whose union exhausts $\alpha$. Integrate the first term by parts to obtain

$$
\begin{aligned}
& -\lim _{\varepsilon \rightarrow 0} \int_{|x-z|=\varepsilon} \sum_{|\alpha|=m} a_{\alpha}(y) j_{k}(y-z) \frac{\partial^{\widehat{\alpha}}}{\partial z^{\widehat{\alpha}}} K(x-z, y) \frac{(x-z)_{\alpha_{|\alpha|} \mid}}{|x-z|} d \omega \\
& \quad+\int_{V-W} j_{k}(y-z) \sum_{|\alpha|=m} a_{\alpha}(y) \frac{\partial^{\alpha}}{\partial z^{\alpha}}\{K(x-z, y) \psi(z)\} d z \\
& \quad=j_{k}(y-x)+\int_{V-W} j_{k}(y-z) \sum_{|\alpha|=m} a_{\alpha}(y) \frac{\partial^{\alpha}}{\partial z^{\alpha}}\{\psi(z) K(x-z, y)\} d z .
\end{aligned}
$$

Substituting these formulae into 2.7 and letting $k \rightarrow \infty$ we obtain, for $x \in W$,

$$
\begin{align*}
u(x) & =\int_{V} \psi(y) K(x-y, y) f(y) d y \\
& -\left.\int_{V-W} \sum_{|\alpha|=m} a_{\alpha}(y)\left\{\frac{\partial^{\alpha}}{\partial z^{\alpha}} \psi(z) K(x-z, y)\right\}\right|_{z=y} u(y) d y  \tag{2.8}\\
& -\left.\sum_{|\alpha| \leqslant m} \sum_{\substack{\alpha_{1}+\alpha_{2}=\alpha \\
\left|\alpha_{1}\right|<m}} \int_{V} a_{\alpha}(y)\left\{\frac{\partial^{\alpha_{1}}}{\partial z^{\alpha_{1}}} \psi(z) \frac{\partial^{\alpha_{2}}}{\partial y^{\alpha_{2}}} K(x-z, y)\right\}\right|_{z=y} u(y) d y
\end{align*}
$$

We use this representation of $u(x)$ to prove the lemma. We first show that if $\omega(\delta)$ is the modulus of continuity, in a compact subset of $W$, of a typical term of the right hand side, as a function of $x$, then $\omega(\delta)=O(\delta \log 1 / \delta)$. This is obvious for the second term since it is an infinitely differentiable function of $x$. The only terms which give trouble are those which contain derivatives of $K$, with respect to $z$, of order $m-1$. Consider then

$$
L(x)=\left.\int_{V} u(y) a_{\alpha}(y) \frac{\partial^{\alpha_{1}}}{\partial y^{\alpha_{1}}} \psi(y)\left\{\frac{\partial^{\alpha_{2}}}{\partial z^{\alpha_{2}}} \frac{\partial^{\alpha_{3}}}{\partial y^{\alpha_{3}}} K(x-z, y)\right\}\right|_{z=y} d y
$$

with $\left|\alpha_{2}\right|=m-1$. We estimate $L(x+w)-L(x)$, which is

$$
\begin{aligned}
& \int_{E_{n}} u(y+x) a_{\alpha}(y+x) \frac{\partial^{\alpha_{1}}}{\partial y^{\alpha_{1}}} \psi(y+x) \\
& \times\left\{\frac{\partial^{\alpha_{2}}}{\partial z^{\alpha_{2}}} \frac{\partial^{\alpha_{3}}}{\partial y^{\alpha_{3}}} K(w-y, y+x)-\frac{\partial^{\alpha_{2}}}{\partial z^{\alpha_{2}}} \frac{\partial^{\alpha_{3}}}{\partial y^{\alpha_{3}}} K(-y, y+x)\right\} d y
\end{aligned}
$$

We remark that $\frac{\partial^{\alpha_{2}}}{\partial z^{\alpha_{2}}} \frac{\partial^{\alpha_{3}}}{\partial y^{\alpha_{3}}} K(w-y, y+x)$ is $\frac{\partial^{\alpha_{2}}}{\partial z_{1}^{\alpha_{2}}} \frac{\partial^{\alpha_{3}}}{\partial y_{1}^{\alpha_{3}}} K\left(x_{1}-z_{1}, y_{1}\right)$ evaluated at $x_{1}-z_{1}=$ $w-y$ and $y_{1}=y+x$. This notation is perhaps a little confusing; but it is desirable to keep the number of letters and subscripts introduced to a minimum. Also $K(w-y, y+x)$ is defined only for $y+x \in V$; but since we are multiplying by a derivative of $\psi(y+x)$ there is no difficulty in taking the integral over $E_{n}$. Now

$$
\begin{aligned}
\frac{\partial^{\alpha_{2}}}{\partial z^{\alpha_{2}}} \frac{\partial^{\alpha_{3}}}{\partial y^{\alpha_{3}}} K(w-y, y+x) & =|y-w|^{1-n} \int g(\widetilde{w-y} \cdot \xi) P(\widetilde{w-y}, \xi, y+x) d w_{\xi} \\
& =|y-w|^{1-n} G(w-y, y+x)
\end{aligned}
$$

Observe that $G(w-y, y+x)$ is once continuously differentiable, with respect to $w$, when $w \neq y$ and

$$
\left|\frac{\partial}{\partial w_{i}} G(w-y, y+x)\right| \leqslant \frac{K}{|w-y|}
$$

for $y+x$ in $V$.
Write $L(x+w)-L(x)$ as

$$
\begin{aligned}
& \int_{E_{n}} u(y+x) a_{\alpha}(y+x) \frac{\partial^{\alpha_{1}}}{\partial y^{\alpha_{1}}} \psi(y+x)\left\{\frac{G(w-y, y+x)-G(-y, y+x)}{|y|^{n-1}}\right\} d y \\
& +\int_{E_{n}} u(y+x) a_{\alpha}(y+x) \frac{\partial^{\alpha_{1}}}{\partial y^{\alpha_{1}}} \psi(y+x) G(w-y, y+x)\left\{\frac{1}{|y-w|^{n-1}}-\frac{1}{|y|^{n-1}}\right\} d y \\
& =I_{1}+I_{2}
\end{aligned}
$$

If $|w|$ is small enough

$$
\begin{aligned}
\left|I_{1}\right| & \leqslant \int_{|y| \leqslant|w| \log 1 /|w|}+\int_{|y| \geqslant|w| \log 1 /|w|} \\
& \leqslant O(|w| \log 1 /|w|)+K_{1} \int_{R \geqslant|y| \geqslant|w| \log 1 /|w|} \frac{|G(w-y, y+x)-G(-y, y+x)|}{|y|^{n-1}} d y
\end{aligned}
$$

The integrand in the second term is dominated by

$$
\frac{K|w|}{|y|^{n-1}|y-\theta w|} \leqslant \frac{K}{|y|^{n}} \frac{|w|}{\left|\widetilde{y}-\frac{\theta w}{|y|}\right|} \leqslant \frac{K_{0}|w|}{|y|^{n}}
$$

where $0 \leqslant \theta \leqslant 1$. Integrating

$$
\begin{aligned}
I_{1} & =O\left(|w| \log \frac{1}{|w|}\right)+O\left(|w| \log \left(\frac{1}{|w|} \log \frac{1}{|w|}\right)\right) \\
& =O\left(|w| \log \frac{1}{|w|}\right)
\end{aligned}
$$

and

$$
\begin{aligned}
\left|I_{2}\right| & \leqslant K_{2} \int_{|y| \leqslant R}\left|\frac{1}{|y-w|^{n-1}}-\frac{1}{|y|^{n-1}}\right| d y \\
& =O\left(|w| \log \frac{1}{|w|}\right)
\end{aligned}
$$

If $m=1$, there is nothing more to prove. We suppose $m>1$. Now we observe that the equations

$$
\frac{d^{\beta}}{d y^{\beta}}\left[\frac{\partial^{\gamma}}{\partial y^{\gamma}} K(w-y, y)\right]=\sum_{\beta_{1}+\beta_{2}=\beta} \frac{\partial^{\beta_{1}}}{\partial z^{\beta_{1}}} \frac{\partial^{\beta_{2}+\gamma}}{\partial y^{\beta_{2}+\gamma}} K(x-y, y)
$$

allow us to replace, in (2.8), partial derivatives of $K(x-y, y)$ by sums of total derivatives of terms $\frac{\partial^{\gamma}}{\partial y^{\gamma}} K(x-y, y)$. To avoid confusion, we explain this in detail.

Until now we have when differentiating the function $K=K(x-z, y)$ regarded it as a function of the three variables $x, y$, and $z$ and only after taking derivatives have we substituted $y$ for $z$. However, in the following it will be necessary to integrate by parts. To do this it is necessary to replace the function

$$
\left.\frac{\partial^{\beta}}{\partial z^{\beta}} \frac{\partial^{\gamma}}{\partial y^{\gamma}} K(x-z, y)\right|_{z=y}
$$

by partial derivatives of some function of $y$. The above formula is the means to do this. The right hand side is obtained by taking $\frac{\partial^{\gamma}}{\partial y^{\gamma}}$ of $K(x-z, y)$; setting $z=y$; and then taking $\frac{\partial^{\beta}}{\partial y^{\beta}}$ of the resulting function of $x$ and $y$. We have indicated this by writing the sign for a total derivative.

We wish to invoke the lemmas of E. Hopf [8]. First we must observe that if we replace $u(y)$ by 1 in the terms of (2.8) containing partial derivatives of $K(x-z, y)$ with respect to $z$ of order $m-1$ we may replace partial derivatives by total derivatives and integrate by parts, for the $a_{\alpha}(y)$ involved in these expressions will be once continuously differentiable. This lowers the order of the singularity of the integrand so that we may now differentiate with respect to $x$ to obtain a continuous function. The lemmas just mentioned now imply that $u(x)$ is once continuously differentiable in a neighborhood of $U$.

Now that we know $u(x)$ is once continuously differentiable in a neighborhood of $U$ we return to the expression (2.8). We replace $\psi(y)$, which has served its purpose, by another infinitely differentiable function which has its support in a neighborhood of $U$ in which we know $u(x)$ to be once continuously differentiable. We write all partial derivatives as sums of total derivatives; integrate those terms involving total derivatives of order $m-1$ by parts; and then take the derivative, with respect to $x$, of the integrand in every integral on the right hand side of (2.8). This gives us an expression similar to (2.8) for $u^{\prime}(x)$. The lemma is now established by induction. It is only necessary to observe that the derivatives of the coefficients and of $K(x-z, y)$, with respect to $y$, which are taken in the proof all exist. For the purposes of this thesis it may be assumed that the coefficients are infinitely differentiable; then this difficulty does not arise.
4. We return now to the study of representations of Lie groups. We use the same notation as before. Set

$$
W_{k}=\left\{x \in X \mid x \in \bigcap_{a_{1}, \ldots, a_{k} \in A} D\left(A\left(a_{1}\right) \cdots A\left(a_{k}\right)\right)\right\}
$$

and set

$$
W_{k}^{*}=\left\{x^{*} \in X^{*} \mid x^{*} \in \bigcap_{a_{1}, \ldots, a_{k} \in A} D\left(A^{*}\left(a_{1}\right) \cdots A^{*}\left(a_{k}\right)\right)\right\}
$$

In analogy to the terminology in the theory of partial differential equations, we call the form $\sum_{|\alpha| \leqslant m} a_{\alpha} X_{\alpha}$ elliptic if when we substitute a real non-zero $n$-vector $\xi$ for $X, \sum_{|\alpha|=m} a_{\alpha} \xi_{\alpha} \neq 0$. We proceed as in Chapter 1, page 11. With an elliptic form, $\sum_{|\alpha| \leqslant m} a_{\alpha} X_{\alpha}$, we associate the operator $B_{0}$ with domain $W_{m}$, defined by $B_{0} x=\sum_{|\alpha| \leqslant m} a_{\alpha} A_{\alpha} x$. We shall need to consider also the operator $B_{0}^{*}$, with domain $W_{m}^{*}$, defined by $B_{0}^{*} x^{*}=\sum_{|\alpha| \leqslant m} a_{\alpha} A_{\alpha^{*}}^{*} x^{*}$. Since the domain of $B_{0}$ is dense and that of $B_{0}^{*}$ is dense in the weak-* topology and since they are adjoint, the closure $B$ and the weak-* closure $B^{*}$, of $B_{0}$ and $B_{0}^{*}$, respectively, are well-defined. The following theorem shows this notation to be justified.
Theorem 7. The operator $B^{*}$ is the adjoint of $B$.
Proof. Suppose that for all $x \in W_{m}$

$$
\left(\sum_{|\alpha| \leqslant m} a_{\alpha} A_{\alpha} x, x_{1}^{*}\right)=\left(x, x_{2}^{*}\right) .
$$

We shall show that $x_{1}^{*} \in W_{m-1}^{*}$. Let $\mu$ be a left-invariant Haar measure on $G$ and set $R_{i}=R\left(e_{i}\right)$. If $K(p)$ is infinitely differentiable with compact support in $G$,

$$
\sum_{|\alpha| \leqslant m} a_{\alpha} A_{\alpha}\left\{\int_{G} K(p) T(p) x \mu(d p)\right\}=\int_{G}\left\{\sum_{|\alpha| \leqslant m} a_{\alpha} R_{\alpha} K(p)\right\} T(p) x \mu(d p)
$$

Consequently

$$
\int_{G} \sum_{|\alpha| \leqslant m} a_{\alpha} R_{\alpha} K(p)\left(T(p) x, x_{1}^{*}\right) \mu(d p)=\int_{G} K(p)\left(T(p) x, x_{2}^{*}\right) \mu(d p)
$$

Let $\left\{t_{i}\right\}$ be an analytic coordinate system of the second kind [14] corresponding to the basis $\left\{e_{i}\right\}$, in a neighborhood $V$ of the identity; then, assuming that $K$ has support in $V$,

$$
\int_{V}\left\{\sum_{|\alpha| \leqslant m} b_{\alpha}(t) \frac{\partial^{\alpha}}{\partial t^{\alpha}} K(p(t))\right\}\left(T(p(t)) x, x_{1}^{*}\right) F(t) d t=\int_{V} K(p(t))\left(T(p(t)) x, x_{2}^{*}\right) F(t) d t
$$

Here $F(t)$ and $b_{\alpha}(t)$ are analytic functions; $F(t)$ is nowhere zero; and $\sum_{|\alpha| \leqslant m} b_{\alpha}(t) \frac{\partial^{\alpha}}{\partial t^{\alpha}}$ is elliptic in a neighborhood $U \subseteq V$ of the origin since $b_{\alpha}(0)=a_{\alpha}$. It is then a consequence of Lemma 5 that $\left(T(p) x, x_{1}^{*}\right)$ is $(m-1)$-times continuously differentiable. This implies that
$x_{1}^{*} \in W_{m-1}^{*}$. If $x \in W_{m},\left(x, x_{2}^{*}\right)=\sum_{|\alpha| \leqslant m} a_{\alpha}\left(A_{\alpha} x, x_{1}^{*}\right)=\sum_{|\alpha| \leqslant m} a_{\alpha}\left(A_{\alpha_{|\alpha|}} x, A_{\widehat{\alpha}^{*}}^{*} x_{1}^{*}\right)$. Since $E \subseteq W_{m}$, Theorem $1^{\prime}$ implies that

$$
\begin{equation*}
\left(x, x_{2}^{*}\right)=\sum_{|\alpha| \leqslant m} a_{\alpha}\left(A_{\alpha_{|\alpha|}} x, A_{\widehat{\alpha}^{*}}^{*} x_{1}^{*}\right) \tag{2.9}
\end{equation*}
$$

for all $x \in W_{1}$. Since $\left\{t_{i}\right\}$ is a canonical coordinate system of the second kind we may infer as in the proof of Theorem 1 that $\int_{R(s(\sigma))} S(t) x d t$ is in $W_{1}$ for all $x \in X$. The notation is the same as in the proof of that theorem; in particular, $S(t)=T(p(t))$. Also

$$
A_{i} \int_{R(s)} S(t) x d t=\int_{R\left(\widehat{s}^{i}\right)} S\left(\widehat{t^{i}}, \sigma\right) x-S\left(\widehat{t^{\imath}}, 0\right) x d \widehat{t^{\imath}}+G(\sigma)
$$

with $\lim _{\sigma \rightarrow 0} G(\sigma) / \sigma^{n}=0$. Then, using (2.9),

$$
\begin{aligned}
& \lim _{\sigma \rightarrow 0}\left\{\sum_{|\alpha| \leqslant m} a_{\alpha} \frac{1}{\sigma^{n}} \int_{R\left(\widehat{s}^{\alpha \alpha}|\alpha|\right)}\left(S\left(\widehat{t}^{\alpha_{|\alpha|}}, \sigma\right) x-S\left(\widehat{t}^{\alpha_{|\alpha|}}, 0\right) x, A_{\widehat{\alpha}^{*}}^{*} x_{1}^{*}\right) d \widehat{t}^{\alpha_{|\alpha|}}+\frac{G_{1}(\sigma)}{\sigma^{n}}\right\}= \\
& \lim _{\sigma \rightarrow 0} \frac{1}{\sigma^{n}} \int_{R(s)}\left(S(t) x, x_{2}^{*}\right) d t .
\end{aligned}
$$

Here $\frac{G_{1}(\sigma)}{\sigma^{n}} \rightarrow 0$ as $\sigma \rightarrow 0$ for all $x \in X$. Consequently

$$
\begin{equation*}
\lim _{\sigma \rightarrow 0} \frac{1}{\sigma^{n}}\left(\sum_{|\alpha| \leqslant m} a_{\alpha} \int_{R\left(\widehat{s}^{\alpha}|\alpha|\right)}\left(S\left(\widehat{t}^{\alpha_{|\alpha|}}, \sigma\right) x-S\left(\widehat{t}^{\alpha_{|\alpha|}}, 0\right) x, A_{\widehat{\alpha}^{*}}^{*} x_{1}^{*}\right) d \widehat{t}^{\alpha_{|\alpha|}}\right)=\left(x, x_{2}^{*}\right) \tag{2.10}
\end{equation*}
$$

Now $\int_{R(s)} S^{*}(t) x_{1}^{*} d t$ (the integral is taken in the weak-* topology) is in $W_{m}^{*}$; and by Lemma 2 and formula $1.2^{\prime}$ we have, for $x \in W_{m}$,

$$
\begin{aligned}
\int_{R(s)}\left(A_{\alpha_{1}} \cdots A_{\alpha_{|\alpha|} \mid} x, S^{*}(t) x_{1}^{*}\right) d t & =\int_{R(s)}\left(S(t) A_{\alpha_{1}} \cdots A_{\alpha_{|\alpha|}} x, x_{1}^{*}\right) d t \\
& =\int_{R(s)} \sum_{|\beta|=|\alpha|} c_{\alpha \beta}(t)\left(A_{\beta} S(t) x, x_{1}^{*}\right) d t \\
& =\int_{R(s)} \sum_{|\beta|=|\alpha|} c_{\alpha \beta}(t)\left(A_{\beta_{|\beta|} \mid} S(t) x, A_{\widehat{\beta}^{*}}^{*} x_{1}^{*}\right) d t \\
& =\int_{R(s)} \sum_{|\beta|=|\alpha|} c_{\alpha \beta}(t) \sum_{j} \zeta_{\beta_{|\beta|} \mid}^{j} \frac{\partial}{\partial t_{j}}\left(S(t) x, A_{\widehat{\beta}^{*}}^{*} x_{1}^{*}\right) d t
\end{aligned}
$$

We may choose the $c_{\alpha \beta}(t)$ so that $c_{\alpha \beta}(0)=0$ unless $\alpha=\beta$ and $c_{\alpha \alpha}(0)=1$. Also $\zeta_{i}^{j}(0)=\delta_{i}^{j}$. Integrate by parts to obtain

$$
\int_{R\left(\widehat{s}^{\alpha}|\alpha|\right)}\left(S\left(\widehat{t}^{\alpha_{|\alpha|}}, \sigma\right) x-S\left(\widehat{t}^{\alpha_{|\alpha|}}, 0\right) x, A_{\widehat{\alpha}^{*}}^{*} x_{1}^{*}\right) d \widehat{t}^{\alpha_{|\alpha|}}+G_{2}(\sigma, x)
$$

We observe that $G_{2}(\sigma, x)$ is a linear function of $x$ which is uniformly bounded as $\sigma \rightarrow 0$. Since it clearly converges to 0 for $x \in W_{m}$ it converges to 0 for all $x$. Consequently, summing
over $\alpha$ and using (2.10,

$$
\lim _{\sigma \rightarrow 0}\left(x, \sum_{|\alpha| \leqslant m} a_{\alpha} A_{\alpha^{*}}^{*} \int_{R(s)} S^{*}(t) x_{1}^{*} d t\right)=\left(x, x_{2}^{*}\right)
$$

This completes the proof of the theorem.
The form $\sum_{|\alpha| \leqslant m} a_{\alpha} x_{\alpha}$ is called strongly elliptic if

$$
\operatorname{Re}\left\{\sum_{|\alpha|=m} a_{\alpha} \xi_{\alpha}\right\} \geqslant \rho|\xi|^{m}, \quad \rho>0
$$

for any real $n$-vector $\xi$. Let $\sum_{|\alpha| \leqslant m} a_{\alpha} x_{\alpha}$ be strongly elliptic and let $B$ be the operator associated, by the previous theorem, to the form $-\sum_{|\alpha| \leqslant m}(-i)^{|\alpha|} a_{\alpha} x_{\alpha}$. Then we have the following theorem.

Theorem 8. The operator $B$ is the infinitesimal generator of a semi-group, $U(t)$, of class $H\left(\phi_{1}, \phi_{2}\right)$ [7].

Proof. If $x \in W_{m}$ and $\lambda$ is a complex number

$$
\begin{aligned}
\left(B x-\lambda x, T^{*}(p) x^{*}\right) & =\left(-\sum_{|\alpha| \leqslant m}(-i)^{|\alpha|} a_{\alpha} A_{\alpha} x-\lambda x, T^{*}(p) x^{*}\right) \\
& =-\sum_{|\alpha| \leqslant m}(-i)^{|\alpha|} a_{\alpha}\left(T(p) A_{\alpha} x, x^{*}\right)-\lambda\left(T(p) x, x^{*}\right) \\
& =-\sum_{|\alpha| \leqslant m}(-i)^{|\alpha|} a_{\alpha} L_{\alpha}\left(T(p) x, x^{*}\right)-\lambda\left(T(p) x, x^{*}\right)
\end{aligned}
$$

where $L_{\alpha}$ is the product of the left-invariant infinitesimal transformations defined in Chapter 1, page 10. Let $t=\left(t_{1}, \ldots, t_{n}\right)$ be a canonical coordinate system of say, the first kind associated with $\left\{e_{1}, \ldots, e_{n}\right\}$, in a neighborhood $V$ of the identity and let

$$
-\sum_{|\alpha| \leqslant m}(-i)^{|\alpha|} a_{\alpha} L_{\alpha}=-\sum_{|\alpha| \leqslant m}(-i)^{|\alpha|} b_{\alpha}(t) \frac{\partial^{\alpha}}{\partial t^{\alpha}}
$$

in this coordinate system. Since we may choose the $b_{\alpha}(t)$ in such a manner that $b_{\alpha}(0)=a_{\alpha}$, the right hand side is uniformly strongly elliptic in a neighborhood $U \subset V$ of 0 . Let $K(s-t, r, \lambda)$ be the fundamental solution of $\sum_{|\alpha| \leqslant m}(-i)^{|\alpha|} b_{\alpha}(r) \frac{\partial^{\alpha}}{\partial t^{\alpha}}+\lambda$ considered in Section 1. We have established estimates for $K(s-t, r, \lambda)$ for $\rho(\lambda, S) \geqslant \delta>0$, with $S$ a certain sector in the complex plane. Let $\varphi(t)$ be an infinitely differentiable function with support in $U$ and with
$\varphi(t)=1$ if $|t| \leqslant \delta_{1}$ for some small $\delta_{1}$. Then, if $|s| \leqslant \delta_{1} / 2$,

$$
\begin{aligned}
& \int_{U} \varphi(t) K(s-t, t, \lambda)\left(B x-\lambda x, S^{*}(t) x^{*}\right) d t \\
& \quad=-\int_{U} \varphi(t) K(s-t, t, \lambda)\left\{\sum_{|\alpha| \leqslant m}(-i)^{|\alpha|} b_{\alpha}(t) \frac{\partial^{\alpha}}{\partial t^{\alpha}}+\lambda\right\}\left(x, S^{*}(t) x^{*}\right) d t \\
& \quad=-\lim _{\varepsilon \rightarrow 0} \int_{|s-t|=\varepsilon} \sum_{|\alpha| \leqslant m}(-i)^{|\alpha|} b_{\alpha}(t) \frac{\partial^{\widehat{\alpha}}}{\partial s^{\widehat{\alpha}}} K(s-t, t, \lambda) \frac{(s-t)_{\alpha_{|\alpha|} \mid}}{|s-t|}\left(x, S^{*}(t) x^{*}\right) d \omega \\
& \quad-\int_{|s-t| \geqslant \delta_{1}} \varphi(t) \sum_{|\alpha| \leqslant m}(-i)^{|\alpha|} b_{\alpha}(t) \frac{\partial^{\alpha}}{\partial s^{\alpha}} K(s-t, t, \lambda)\left(x, S^{*}(t) x^{*}\right) d t \\
& - \\
& \sum_{|\alpha| \leqslant m} \sum_{\alpha_{1}+\alpha_{2}+\alpha_{3}=\alpha}^{\left|\alpha_{1}\right|<|\alpha|} \int_{i|\alpha|} \frac{\partial^{\alpha_{3}}}{\partial t^{\alpha_{3}}} b_{\alpha}(t) \frac{\partial^{\alpha_{2}}}{\partial r^{\alpha_{2}}} \frac{\partial^{\alpha_{1}}}{\partial t^{\alpha_{1}}} K(s-t, t, \lambda)\left(x, S^{*}(t) x^{*}\right) d t \\
& =- \\
& =-\lim _{\varepsilon \rightarrow 0} \int_{|s-t|=\varepsilon} \sum_{|\alpha| \leqslant m}(-i)^{|\alpha|} b_{\alpha}(s) \frac{\partial^{\widehat{\alpha}}}{\partial s^{\widehat{\alpha}}} K(s-t, s, \lambda) \frac{(s-t)_{\alpha_{|\alpha|}}}{|s-t|}\left(x, S^{*}(t) x^{*}\right) d \omega-\cdots \\
& =-\left(x, S^{*}(x) x^{*}\right)-\cdots
\end{aligned}
$$

where, in the third line, we have used (2.6). Here, as before, $S^{*}(t)=T^{*}(p(t))$. Also we have used our usual convention regarding partial derivatives of the function $K(s-t, r, \lambda)$. Since $\left|b_{\alpha}(s)-b_{\alpha}(t)\right| \leqslant M_{0}|s-t|$ and

$$
\left|\frac{\partial^{\widehat{\alpha}}}{\partial s^{\widehat{\alpha}}} K(s-t, s, \lambda)-\frac{\partial^{\widehat{\alpha}}}{\partial s^{\widehat{\alpha}}} K(s-t, t, \lambda)\right| \leqslant \frac{M_{1}}{|s-t|^{n-2}},
$$

we could replace $s$ by $t$ in the appropriate places in the surface integral. We now set $s=0$, choose an $x^{*}$ such that $\left\|x^{*}\right\|=1,\left(x, x^{*}\right)=\|x\|$, and make use of the estimates of Paragraph 2 to obtain

$$
\frac{N_{1}}{\rho(\lambda, S)}\|B x-\lambda x\| \geqslant\|x\|-\frac{N_{2}\|x\|}{\rho(\lambda, S)}-\frac{N_{3}\|x\|}{\rho(\lambda, S)^{1 / m}}
$$

Consequently, for $\rho(\lambda, S) \geqslant N_{4}$,

$$
\|x\| \leqslant \frac{N_{5}}{\rho(\lambda, S)}\|B x-\lambda x\|
$$

This inequality remains valid for $x \in D(B)$. For $x^{*} \in W_{m}^{*}$, consider

$$
\begin{aligned}
\left(T(p) x, B^{*} x^{*}-\lambda x^{*}\right) & =\left(T(p) x,-\sum_{|\alpha| \leqslant m}(-i)^{|\alpha|} a_{\alpha} A_{\alpha^{*}}^{*} x^{*}-\lambda x^{*}\right) \\
& =-\sum_{|\alpha| \leqslant m} i^{|\alpha|} a_{\alpha} R_{\alpha^{*}}\left(T(p) x, x^{*}\right)-\lambda\left(T(p) x, x^{*}\right)
\end{aligned}
$$

Change into local coordinates and perform the same calculations as above to obtain

$$
\begin{equation*}
\int_{U_{1}} \varphi_{1}(t) K_{1}(s-t, t, \lambda)\left(S(t) x, B^{*} x^{*}-\lambda x^{*}\right) d t=-\left(S(s) x, x^{*}\right)-\cdots \tag{2.11}
\end{equation*}
$$

By the proof of the previous theorem, if $x^{*} \in D\left(B^{*}\right)$ we can choose a sequence $\left\{x_{n}^{*}\right\} \in W_{m}^{*}$ such that $\left(x, x_{n}^{*}\right) \rightarrow\left(x, x^{*}\right)$ and $\left(x, B^{*} x_{n}^{*}\right) \rightarrow\left(x, B^{*} x^{*}\right)$ for all $x \in X$. By the principle of uniform boundedness, $\left\|x_{n}^{*}\right\|$ and $\left\|B^{*} x_{n}^{*}\right\|$ are uniformly bounded. Consequently, for $t \in U_{1}$, one deduces that $\left(S(t) x, B^{*} x_{n}^{*}-\lambda x_{n}^{*}\right) \rightarrow\left(S(t) x, B^{*} x^{*}-\lambda x^{*}\right)$ boundedly and $\left(S(t) x, x_{n}^{*}\right) \rightarrow\left(S(t) x, x^{*}\right)$ boundedly. The dominated convergence theorem now allows us to assert the validity of (2.11) for all $x^{*} \in D\left(B^{*}\right)$. Now, given an $x^{*} \in D\left(B^{*}\right)$, we choose an $x \in X$ such that $\|x\| \leqslant 1$, $\left(x, x^{*}\right) \geqslant\left\|x^{*}\right\| / 2$, and set $s=0$ in (2.11) to obtain the inequality

$$
\frac{N_{1}^{\prime}}{\rho\left(\lambda, S^{\prime}\right)}\left\|B^{*} x^{*}-\lambda x^{*}\right\| \geqslant \frac{\left\|x^{*}\right\|}{2}-\frac{N_{2}^{\prime}}{\rho\left(\lambda, S^{\prime}\right)}\left\|x^{*}\right\|-\frac{N_{3}^{\prime}}{\rho\left(\lambda, S^{\prime}\right)^{1 / m}}\left\|x^{*}\right\| .
$$

Here we make use of the estimates for the function $K_{1}(s-t, r, \lambda)$ established in Paragraph 2. Consequently, for $\rho\left(\lambda, S^{\prime}\right) \geqslant N_{4}^{\prime}$,

$$
\left\|x^{*}\right\| \leqslant \frac{N_{5}^{\prime}}{\rho\left(\lambda, S^{\prime}\right)}\left\|B^{*} x^{*}-\lambda x^{*}\right\| .
$$

Thus the resolvent $R(\lambda, B)$ exists for $\rho\left(\lambda, S^{\prime}\right) \geqslant N_{4}^{\prime}$ and $\|R(\lambda, B)\| \leqslant N_{5}$ if $\rho(\lambda, S) \geqslant N_{4}$. The theorem is now a consequence of Theorem 12.8.1 of [7].
5. In this paragraph the strongly elliptic form $\sum_{|\alpha| \leqslant m} a_{\alpha} x_{\alpha}$ will be fixed. We denote the operator associated with $-\sum_{|\alpha| \leqslant m}(-i)^{|\alpha|} a_{\alpha} x_{\alpha}$ by $B$ and the semi-group it generates by $U(t)$. Since the space $X$ on which the group $G$ acts will vary in the course of the proof, we shall specify the space by writing $B(X)$ and $U(t, X)$ when there is a danger of confusion.

Let $\mu$ be left-invariant Haar measure on $G$ and let $L_{1}(\mu)$ be the Banach space of functions on $G$ integrable with respect to $\mu$. Two representations of $G$ in $L_{1}(\mu)$ of particular interest are $(L(p) f)(q)=f\left(p^{-1} q\right)$ and $(R(p) f)(q)=f(q p)$. It is easily shown that these representations are strongly continuous. We may call them, respectively, the representation by left translations and by right translations. A linear operator on $L_{1}(\mu)$ is said to commute with right translations if it commutes with all operators $R(p)$. We shall need the following lemma, proved in the general case just as it is for the line [7].

Lemma 6. Let $T$ be a bounded linear operator on $L_{1}(\mu)$ which commutes with right translations. Then there is a finite, countably additive Borel set function, $\nu$, such that

$$
\begin{equation*}
(T f)(p)=\int_{G} f\left(q^{-1} p\right) \nu(d q) \tag{2.12}
\end{equation*}
$$

for almost all p. Moreover $\operatorname{var}(\nu)=\|T\|$.
Proof. Let $\left\{g_{k}(p)\right\}$ be an approximation to the identity on $G$ and let $f$ be a function in $L_{1}(\mu)$ with compact support. Set

$$
\begin{aligned}
h_{k}(p) & =\int_{G} f\left(q^{-1} p\right) g_{k}(q) \mu(d q) \\
& =\int_{G} f\left(q^{-1}\right) g_{k}(p q) \mu(d q)
\end{aligned}
$$

Then

$$
\begin{align*}
\left(T h_{k}\right)(p) & =\int_{G} f\left(q^{-1}\right)\left(T g_{k}\right)(p q) \mu(d q) \\
& =\int_{G} f\left(q^{-1} p\right)\left(T g_{k}\right)(q) \mu(d q)  \tag{2.13}\\
& =\int_{G} f\left(q^{-1} p\right) \nu_{k}(d q)
\end{align*}
$$

with $\nu_{k}(d q)=\left(T g_{k}\right)(q) \mu(d q)$. Since $\left\|g_{k}\right\|_{L_{1}(\mu)}=1, \operatorname{var}\left(\nu_{k}\right) \leqslant\|T\|$. Let $\nu$ be an accumulation point of the sequence $\left\{\nu_{k}\right\}$ in the space of bounded, countably additive set functions with its weak-* topology as the conjugate space of $C_{0}$, the space of continuous functions on $G$ vanishing at infinity. For any $f$ in $L_{1}(\mu), h_{k}$ is defined and (2.13) is valid. Moreover $h_{k} \rightarrow f$ as $k \rightarrow \infty$; and then $T h_{k} \rightarrow T f$. But if $f$ is continuous with compact support, $\int_{G} f\left(q^{-1} p\right) \nu(d q)$ is an accumulation point of $\left(T h_{k}\right)(p)$, as given by (2.13). Consequently, for all $f \in L_{1}(\mu)$,

$$
(T f)(p)=\int_{G} f\left(q^{-1} p\right) \nu(d q)
$$

for almost all $p$. Clearly $\operatorname{var}(\nu) \leqslant\|T\|$ and $\|T\| \leqslant \operatorname{var} \nu$.
We remark that the $\nu$ satisfying $(2.12)$ is unique. We may now state the theorem of this paragraph.

Theorem 9. There exist finite, countably additive Borel set functions, $\mu(t, \cdot)$, depending only on the form $\sum_{|\alpha| \leqslant m} a_{\alpha} X_{\alpha}$, and $G$ such that

$$
\begin{equation*}
U(t) x=\int_{G} T(p) x \mu(t, d p) \tag{2.14}
\end{equation*}
$$

at least for $\psi_{1} \leqslant \arg t \leqslant \psi_{2} ; \psi_{1}<0<\psi_{2}$.
The integral is, of course, a Bochner integral. As the theorem is stated $\psi_{1}$ and $\psi_{2}$ may vary with the representation. It is true, however, that $\psi_{1}$ and $\psi_{2}$ may be taken to depend only on the form and on $G$. To establish this we have only to observe that the angles of the sector, outside of which the estimates for $R(\lambda, B)$ were established, depend only on the form and on $G$.
Proof. Consider first the representation $L(p)$ of $G$ in $L_{1}(\mu)$. The semi-group $U\left(t, L_{1}(\mu)\right)$ generated by the operator $B\left(L_{1}(\mu)\right)$ associated with the form $-\sum_{|\alpha| \leqslant m}(-i)^{|\alpha|} a_{\alpha} X_{\alpha}$ in this representation commutes with right translations and, consequently, is given by

$$
\begin{equation*}
U\left(t, L_{1}(\mu)\right) f(p)=\int f\left(q^{-1} p\right) \mu(t, d q) \tag{2.15}
\end{equation*}
$$

This establishes the theorem in this case. We next establish it for the case of the representation by left translations in $C_{0}$. If $f$ is in $L_{1}(\mu)$ and $g$ is in $C_{0}$, the function

$$
h(p)=\int_{G} f(p g) g\left(q^{-1}\right) \mu(d q)
$$

is in $C_{0}$ and $\|h\|_{C_{0}} \leqslant\|f\|_{L_{1}(\mu)}\|g\|_{C_{0}}$. Let $f_{t}=U\left(t, L_{1}(\mu)\right) f$ and set

$$
h_{t}(p)=\int_{G} f_{t}(p q) g\left(q^{-1}\right) \mu(d q)
$$

We assert that $h_{t}=U\left(t, C_{0}\right) h$. To prove this we notice that

$$
\begin{align*}
\left\|h_{t}\right\|_{C_{0}} & \leqslant\left\|f_{t}\right\|_{L_{1}(\mu)}\|g\|_{C_{0}}  \tag{i}\\
& \leqslant\left\|U\left(t, L_{1}(\mu)\right)\right\|\|f\|_{L_{1}(\mu)}\|g\|_{C_{0}} \\
& \leqslant K e^{\omega t}\|f\|_{L_{1}(\mu)}\|g\|_{C_{0}} .
\end{align*}
$$

Here $\omega$ and $K$ are some constants and $t$ is greater then or equal to zero.

$$
\begin{align*}
& \left\|h_{t}-h\right\|_{C_{0}} \leqslant\left\|f_{t}-f\right\|_{L_{1}(\mu)}\|g\|_{C_{0}} \rightarrow 0 \text { as } t \rightarrow 0  \tag{ii}\\
\frac{d}{d t} h_{t}= & \frac{d}{d t} \int_{G} f_{t}(\cdot q) g\left(q^{-1}\right) \mu(d q) \\
= & \int_{G} \frac{d}{d t} f_{t}(\cdot q) g\left(q^{-1}\right) \mu(d q) \\
= & \int_{G} B\left(L_{1}(\mu)\right) f_{t}(\cdot q) g\left(q^{-1}\right) \mu(d q)=B\left(C_{0}\right) h_{t}
\end{align*}
$$

The derivatives are taken in the strong topology.
For $t \geqslant 0$ the asserted equality now follows from Theorem 23.7.1 of [7]. By analytic continuation $h_{t}=U\left(t, C_{0}\right) h$ in the domain common to the two sectors in which they are defined. We may now write

$$
\begin{align*}
U\left(t, C_{0}\right) h(p) & =\int_{G}\left\{\int_{G} f\left(r^{-1} p q\right) \mu(t, d r)\right\} g\left(q^{-1}\right) \mu(d q) \\
& =\int_{G} h\left(r^{-1} p\right) \mu(t, d r) \tag{2.16}
\end{align*}
$$

Since functions $h$ of the above form are dense in $C_{0}$ the theorem is established for $C_{0}$. In order to complete the proof we must introduce two new spaces of functions. These function spaces are closely related to the given representation $T(p)$ of $G$ in $X$. Let $Y$ be the space of continuous functions, $f$, on $G$ satisfying

$$
\begin{gather*}
\|f\|_{Y}=\sup _{q} \frac{|f(q)|}{\lambda(q)}<\infty  \tag{a}\\
\left\|f\left(p^{-1} \cdot\right)-f(\cdot)\right\|_{Y} \rightarrow 0 \text { as } p \rightarrow 1 \tag{b}
\end{gather*}
$$

For brevity, we have set $\|T(q)\|+\left\|T\left(q^{-1}\right)\right\|=\lambda(q)$. Note that $Y$ is a Banach space and the representation by left translations of $G$ in $Y$ is strongly continuous. In particular

$$
\begin{aligned}
\|L(p) f\|_{Y} & =\sup _{q} \frac{\left|f\left(p^{-1} q\right)\right|}{\lambda(q)} \\
& =\sup _{q} \frac{\left|f\left(p^{-1} q\right)\right|}{\lambda\left(p^{-1} q\right)} \frac{\lambda\left(p^{-1} q\right)}{\lambda(q)} \\
& \leqslant \lambda(p)\|f\|_{Y}
\end{aligned}
$$

for $\lambda(p)=\lambda\left(p^{-1}\right)$ and $\lambda(p q) \leqslant \lambda(p) \lambda(q)$. It is important to notice that if $x$ is in $X$ and $x^{*}$ is in $X^{*}$ then $\left(T\left(p^{-1}\right) x, x^{*}\right)$ and $\left\|T\left(p^{-1}\right) x\right\|$ are functions in $Y$. Moreover, if $x$ is in $W_{1}(X)$ and
$a$ is in $A$, then

$$
\begin{array}{r}
\sup _{q} \frac{\left|t^{-1}\left\{\left(T\left(q^{-1} e(t a)\right) x, x^{*}\right)-\left(T\left(q^{-1}\right) x, x^{*}\right)\right\}-\left(T\left(q^{-1}\right) A(a) x, x^{*}\right)\right|}{\lambda(q)} \\
\leqslant\left\|x^{*}\right\|\left\|t^{-1}\{T(e(t a)) x-x\}-A(a) x\right\| \rightarrow 0
\end{array}
$$

as $t \rightarrow 0$. Consequently $\left(T\left(p^{-1}\right) x, x^{*}\right)$ is in $W_{1}(Y)$ and

$$
A(a, Y)\left(T\left(p^{-1}\right) x, x^{*}\right)=\left(T\left(p^{-1}\right) A(a) x, x^{*}\right)
$$

The same relation holds between $W_{k}(X)$ and $W_{k}(Y)$. The converse statement is weaker. If $f_{x^{*}}(p)=\left(T\left(p^{-1}\right) x, x^{*}\right)$ is in $W_{1}(Y)$ for every $x^{*}$ in $X^{*}$ and $(L(e(t a))-I) A(a, Y) f_{x^{*}}=O\left(t^{\alpha}\right)$ as $t \rightarrow 0$ for some $\alpha>0$, then $x$ is in $W_{1}(x)$. First of all $A(a, Y) f_{x^{*}}(0)=x_{0}\left(x^{*}\right)$ defines a bounded linear functional $x_{0}$ on $X^{*}$. But

$$
t^{-1}\left\{\left(L(e(t a)) x-x, x^{*}\right)-\left(x_{0}, x^{*}\right)\right\}=\frac{1}{t} \int_{0}^{t}(L(e(t a))-I) A(a, Y) f_{x^{*}}(0) d t=O\left(t^{\alpha}\right)
$$

Consequently

$$
\left\|t^{-1}(L(e(t a)) x-x)-x_{0}\right\|_{X^{* *}}=O\left(t^{\alpha}\right)
$$

Thus $x_{0}$ is in $X$ and $x_{0}=A(a) x$. The same relation holds between $W_{k}(Y)$ and $W_{k}(X)$.
The second space, $Z$, to be introduced is, in a certain sense, dual to $Y$. It is the space of measurable functions, $f$, on $G$ satisfying

$$
\begin{equation*}
\int_{G}|f(q)| \lambda(q) \mu(d q)=\|f\|_{Z}<\infty \tag{c}
\end{equation*}
$$

It is essential to observe that $\lambda(q)$ is lower semi-continuous and therefore measurable. The representation by left translations of $G$ in $Z$ is strongly continuous. The space $Z$ is a subset of $L_{1}(\mu)$ and $\|f\|_{Z} \geqslant\|f\|_{L_{1}(\mu)}$. Moreover, if $f \in D(B(Z))$, then $f \in D\left(B\left(L_{1}(\mu)\right)\right)$ and $B(Z) f=B\left(L_{1}(\mu)\right) f$. Thus a solution of normal type of the abstract Cauchy problem for $B(Z)$ is a solution of normal type of the abstract Cauchy problem for $B\left(L_{1}(\mu)\right)$. Again, Theorem 23.7.1 of [7] allows us to assert that $U(t, Z) f=U\left(t, L_{1}(\mu)\right) f$. We make use of (2.15) to write

$$
\begin{equation*}
U(t, Z) f(p)=\int_{G} f\left(q^{-1} p\right) \mu(t, d q) \tag{2.17}
\end{equation*}
$$

This is a weaker assertion, in this case, than that of the theorem. We have not yet shown that $\int_{G} f\left(q^{-1} \cdot\right) \mu(t, d q)$ exists as a Bochner integral. Let $f$ be in $Z$ and $g$ be in $Y$. Consider

$$
h(p)=\int_{G} f(p q) g\left(q^{-1}\right) \mu(d q)
$$

Then

$$
\begin{aligned}
|h(p)| & \leqslant \int_{G}|f(p q)|\left|g\left(q^{-1}\right)\right| \mu(d q) \\
& \leqslant\|g\|_{Y} \int_{G}|f(p q)| \lambda(q) \mu(d q) \\
& \leqslant\|g\|_{Y} \int_{G}|f(q)| \lambda\left(p^{-1} q\right) \mu(d q) \\
& \leqslant \lambda(p)\|g\|_{Y}\|f\|_{Z}
\end{aligned}
$$

In other words, $\|h\|_{Y} \leqslant\|g\|_{Y}\|f\|_{Z}$. We remark another simple fact, which allows us to assert that functions, $h$, of the above form are dense in $Y$. If $f$ has compact support and $\int_{G} f(p) \mu(d p)=1$ then

$$
\begin{aligned}
\frac{|h(p)-g(p)|}{\lambda(p)} & =\frac{1}{\lambda(p)}\left|\int_{G} f(p q)\left\{g\left(q^{-1}\right)-g(p)\right\} \mu(d q)\right| \\
& \leqslant \frac{1}{\lambda(p)} \int_{G}|f(q)|\left|g\left(q^{-1} p\right)-g(p)\right| \mu(d q) \\
& \leqslant \sup _{q \in \operatorname{supp} f}\left\|g\left(q^{-1} \cdot\right)-g(\cdot)\right\|_{Y} \int_{G}|f(q)| \mu(d q) .
\end{aligned}
$$

Using the same technique as before, we set $f_{t}=U(t, Z) f$ and then set

$$
h_{t}(p)=\int_{G} f_{t}(p q) g\left(q^{-1}\right) \mu(d q) .
$$

Again the uniqueness theorem for the abstract Cauchy problem assures us that $h_{t}=U(t, Y) h$. Making use of (2.17) we may write

$$
\begin{equation*}
U(t, Y) h(p)=\int_{G}\left\{\int_{G} f\left(r^{-1} p q\right) \mu(t, d r)\right\} g\left(q^{-1}\right) \mu(d q) \tag{2.18}
\end{equation*}
$$

Formally changing the order of integration, we obtain

$$
U(t, Y) h(p)=\int_{G} h\left(r^{-1} p\right) \mu(t, d r)
$$

However, we have not yet proved that the integral in (2.18) is absolutely convergent and we are, consequently, unable to justify the change in the order of integration.

The space $C_{0}$ is a subset of $Y$ and $\|g\|_{Y}=\|g\|_{C_{0}}$. Consequently, $U\left(t, C_{0}\right) g$ is a solution of normal type of the abstract Cauchy problem for $B(Y)$. The uniqueness theorem again implies that $U\left(t, C_{0}\right) g=U(t, Y) g$. Making use of (2.16), we write

$$
U(t, Y) g(p)=\int_{G} g\left(q^{-1} p\right) \mu(t, d q)
$$

Then

$$
\left|\int_{G} \frac{g\left(q^{-1} p\right) \mu(t, d q)}{\lambda(p)}\right| \leqslant\|U(t, Y)\|\|g\|_{Y} .
$$

By the usual argument it follows that

$$
\int_{G} \frac{\left|g\left(q^{-1} p\right)\right||\mu|(t, d q)}{\lambda(p)} \leqslant\|U(t, Y)\|\|g\|_{Y}
$$

But if $f(q)$ is in $Y$ we can find a sequence $\left\{g_{n}(q)\right\}$ in $C_{0}$ such that $g_{n} \rightarrow|f|$. Consequently

$$
\int_{G}\left|f\left(q^{-1} p\right)\right||\mu|(t, d q) \leqslant \lambda(p)\|U(t, Y)\|\|f\|_{Y}
$$

In particular, setting $f(q)=\left\|T\left(q^{-1}\right) x\right\|$ and setting $p=1$, we obtain

$$
\int_{G}\|T(q) x\||\mu|(t, d q) \geqslant 2\|U(t, Y)\|\|x\|
$$

We are now able to justify the inversion of the order of integration in (2.18). We apply the last inequality to the space $Z$ and to the representation $L(p)$ of $G$ in $Z$.

$$
\begin{aligned}
\int_{G} \int_{G}\left|f\left(r^{-1} p q\right)\right| & \left|g\left(q^{-1}\right)\right||\mu|(t, d r) \mu(d q) \\
& \leqslant \int_{G} \int_{G}\left|f\left(r^{-1} q\right)\right| \lambda(p) \lambda(q)|\mu|(t, d r) \mu(d q)\|g\|_{Y} \\
& =\lambda(p) \int_{G}\|L(r) f\|_{Z}|\mu|(t, d r)\|g\|_{Y} \\
& <\infty
\end{aligned}
$$

We now show that if $x(t)=\int_{G} T(p) x \mu(t, d p)$ then $x(t)=U(t, X) x$. We first observe that

$$
\begin{aligned}
\left(T\left(q^{-1}\right) x(t), x^{*}\right) & =\int_{G}\left(T\left(q^{-1}\right) T(p) x, x^{*}\right) \mu(t, d p) \\
& =\int_{G}\left(T\left(q^{-1} p\right) x, x^{*}\right) \mu(t, d p) \\
& =U(t, Y)\left(T\left(q^{-1}\right) x, x^{*}\right)
\end{aligned}
$$

We know that $\|x(t)\| \leqslant 2\|U(t, Y)\|\|x\| \leqslant K_{1} e^{\omega_{1} t}\|x\|$, with some constants $c_{1}$ and $\omega_{1}$ when $t \geqslant 0$. If $x \in W_{m}(x)$ then $\left(T\left(q^{-1}\right) x, x^{*}\right)$ is in $W_{m}(Y)$ and, taking $q=1$ in the above equality, it follows that $t^{-1}\left\{\left(x(t), x^{*}\right)-\left(x, x^{*}\right)\right\}$ converges to $\left(B x, x^{*}\right)$ as $t \rightarrow 0$. In particular, applying the principle of uniform boundedness, $\|x(t)-x\| \rightarrow 0$ as $t \rightarrow 0$. Since $U(t, Y)$ is a holomorphic semi-group, $\left(x(t), x^{*}\right)$ is a holomorphic function and $x(t)$ is a holomorphic function. Moreover $\left(T\left(q^{-1}\right) x(t), x^{*}\right)$ is in $D\left(B^{k}(Y)\right)$ for any $k$; the work of the next paragraph shows that $\left(T\left(q^{-1}\right) x(t), x^{*}\right)$ is in $W_{k}(Y)$ for any $k$. Consequently $x(t)$ is in $W_{k}(X)$ for any $k$. We observe finally that $\frac{d}{d t}\left(x(t), x^{*}\right)=\left(B x(t), x^{*}\right)$ and, thus, $\frac{d}{d t} x(t)=B x(t)$. Another application of the uniqueness theorem for the abstract Cauchy problem shows that $x(t)=U(t, X) x$ when $x$ is in $W_{m}(X)$. Since $W_{m}(X)$ is dense in $x$, the equation is valid for all $x$ in $X$.
6. In this paragraph we establish the basic analytical properties of $U(t) x$ and of $\mu(t, d p)$. Observe that $U(t) x$ is an analytic function of $t$ and

$$
B^{k} U(t) x=\frac{d^{k}}{d t^{k}} U(t) x=\frac{k!}{2 \pi i} \int_{|\zeta-t|=r(t)} \frac{U(\zeta) x}{(\zeta-t)^{k+1}} d \zeta .
$$

We observe further that $B^{k}$, as a power of $B$, is the operator associated, by Theorem 7, with the elliptic form $(-1)^{k}\left(\sum_{|\alpha| \leqslant m}(-i)^{|\alpha|} a_{\alpha} x_{\alpha}\right)^{k}$ for it is equal to that operator on $W_{m k}$ and its adjoint is equal to that operator's adjoint on $W_{m k}^{*}$. Let $\nu$ be a right-invariant Haar measure
on $G$ and let $K(p)$ be an infinitely differentiable function on $G$ with compact support. If $x$ is in $W_{m k}$, then

$$
\begin{aligned}
\int_{G} K(p)\left(B^{k} x, T^{*}(p) x^{*}\right) \nu(d p) & =\int_{G} K(p) \sum_{|\alpha| \leqslant m k} b_{\alpha}\left(A_{\alpha} x, T^{*}(p) x^{*}\right) \nu(d p) \\
& =\int_{G}\left\{-\sum_{|\alpha| \leqslant m k}(-1)^{|\alpha|} b_{\alpha} L_{\alpha} K(p)\right\}\left(x, T^{*}(p) x^{*}\right) \nu(d p) .
\end{aligned}
$$

Here $\left\{L_{i}\right\}$ is the set of left-invariant differential operators introduced in Chapter I. This formula remains valid for $x$ in $D\left(B^{k}\right)$. As above, by Lemma 5, if $x$ in $D\left(B^{k}\right)$ then $x$ is in $W_{m k-1}$. In particular, $U(t) x$ is in $\bigcap_{k \geqslant 1} W_{k}$ and $T(p) U(t) x$ is an infinitely differentiable function of $p$. Now $A_{\alpha} U(t) x$ is defined for all $x$ in $X$ and we show that it is a bounded linear function of $x$. If $|\alpha|=1$ then $A_{\alpha} U(t)$ is a closed, everywhere defined linear operator on $X$; consequently, it is bounded. By induction, it is apparent that $A_{\alpha} U(t)$ is a bounded linear operator. Consequently $\left\|A_{\alpha} U(t) x\right\| \leqslant N_{\alpha}(t)\|x\|$. Next $T(p) U(t) x$ is infinitely differentiable as a function of $p$ and $t$ and

$$
\left\|\frac{d^{k}}{d t^{k}} A_{\alpha} U(t) x\right\|=\left\|\frac{k!}{2 \pi i} \int_{|\zeta-t|=r(t)} \frac{A_{\alpha} U(\zeta) x}{(\zeta-t)^{k+1}} d \zeta\right\| \leqslant N(k, \alpha, t)\|x\|
$$

Then the equation

$$
\begin{aligned}
\frac{\partial}{\partial t}\left(T(p) U(t) x, x^{*}\right) & =\left(T(p) B U(t) x, x^{*}\right) \\
& =-\sum_{|\alpha| \leqslant m}(-i)^{|\alpha|} a_{\alpha} L_{\alpha}\left(T(p) U(t) x, x^{*}\right)
\end{aligned}
$$

when written in an analytic coordinate system $\left\{s_{i}\right\}$ about the identity is a parabolic equation with analytic coefficients. We now apply the results of [3]. The facts which we need from this paper are not explicitly stated as theorems and the proofs are not given in complete detail. However, since the proofs are quite complicated and the assertions to be derived from these facts ancillary to the rest of the thesis, we prefer not to perform the calculations in detail here.

The work in the paper shows that $\left(T(p(s)) U(t) x, x^{*}\right)=u(s, t)$ may be extended to an analytic function in a complex neighborhood, $N(t)$ of the origin in $s$-space. But $N(t)$ may be taken locally in $t$, to be independent of $t$; and the upper bound of $|u(s, t)|$ in $N(t)$ depends only on upper bounds for the absolute value of $u(s, t)$ and a certain number of its derivatives for real $s$. Thus $u(s, t)$ may be extended to an analytic function of $s$ and $t$ in a certain open set, $M$, of complex $(s, t)$-space, which contains all the points $(s, t)$ with $t$ in the sector in which $U(t)$ was shown to exist and $s$ real and close to the origin. In a neighborhood of any point $\left(s_{0}, t_{0}\right),|u(s, t)|$ is bounded by an expression $K\left(s_{0}, t_{0}\right)\|x\|\left\|x^{*}\right\|$. For fixed $x$ and varying $x^{*}, u(s, t)$ defines a bounded linear functional $v(s, t, x)$ on $X^{*}$. This linear functional $v(s, t, x)$ is an analytic map of $M$ into $X^{* *}$. But $v(s, t, x)$ is in $X$ for $s$ real and close to the origin; so $v(s, t, x)$ is in $X$ for all $(s, t)$ in $M$. In particular, $U(t) x$ is a well-behaved vector, in the sense of [5], in the interior of the sector in which $U(t)$ was shown to exist. Since $U(t) x \rightarrow x$ as $t \rightarrow 0$, we have

Theorem 10. The well-behaved vectors are dense for any strongly continuous representation of $G$.

We now show that there is a function, $h(t, p)$, analytic in $t$ and $p$ such that $\mu(t, d p)=$ $h(t, p) \mu(d p)$. Recall that $\mu$ is a left-invariant Haar measure on $G$. If $f(x)$, in $L_{1}(\mu)$, is infinitely differentiable with compact support and $\left\{s_{i}\right\}$ is an analytic coordinate system in a neighborhood of the identity, then there are analytic functions, $a_{i j}(s)$, independent of $f$ such that, for small $s$,

$$
\frac{\partial}{\partial s_{i}} f(s)=\sum_{j=1}^{n} a_{i j}(s) L_{j} f(s)
$$

Consequently, for small $\delta$,

$$
\begin{aligned}
\int_{|s| \leqslant \delta}\left|\frac{\partial}{\partial s_{i}} f(s)\right| d s & \leqslant \sum_{j=1}^{n} k \int_{|s| \leqslant \delta}\left|L_{j} f(s)\right| d s \\
& \leqslant K_{1} \sum_{j=1}^{n}\left\|L_{j} f\right\|_{L_{1}(\mu)} .
\end{aligned}
$$

Theorem $1^{\prime}$ implies that if $f$ is in $W_{1}\left(L_{1}(\mu)\right)$ then it may be approximated by a sequence $\left\{f_{n}\right\}$ of infinitely differentiable functions with compact support in such a manner that $L_{j} f_{n} \rightarrow L_{j} f$ in $L_{1}(\mu)$. Thus, if $f$ is in $W_{1}\left(L_{1}(\mu)\right)$, its distribution derivatives, with respect to $\left\{s_{i}\right\}$, in a neighborhood, $N$, of the origin are in $L_{1}(\mu, N)$ and

$$
\int_{|s| \leqslant \delta}\left|\frac{\partial}{\partial s_{i}} f_{t}(s)\right| d s \leqslant K_{1} \sum_{j=1}^{n}\left\|L_{j} f\right\|_{L_{1}}(\mu) .
$$

Similar remarks apply to the higher-order derivatives. Since, when $f$ is in $L_{1}(\mu), f_{t}=$ $U\left(t, L_{1}(\mu)\right) f$ is in $W_{k}\left(L_{1}(\mu)\right)$ for any $k$, we have

$$
\int_{|s| \leqslant \delta}\left|\frac{\partial^{\alpha}}{\partial s^{\alpha}} f_{t}(s)\right| d s \leqslant C_{\alpha}(t)\|f\| .
$$

It is well-known [1] that this implies that $f_{t}$ may be taken as an infinitely differentiable function in a neighborhood $O$, of the origin and that

$$
\begin{align*}
\left|f_{t}(s)\right| & \leqslant D_{1}(t)\|f\|  \tag{i}\\
\left|\frac{\partial}{\partial s_{i}} f_{t}(s)\right| & \leqslant D_{2}(t)\|f\| \tag{ii}
\end{align*}
$$

in $O$. Consequently, for every $p=p(s), s$ in $O$, there is a bounded measurable function $g(t, p, q)$ such that

$$
f_{t}(p)=\int_{G} f(q) g(t, p, q) \mu(d q)
$$

Moreover $\|g(t, p, \cdot)-g(t, 1, \cdot)\|_{L_{\infty}(\mu)} \rightarrow 0$ as $p \rightarrow 1$. If $f$ is continuous with compact support

$$
\begin{aligned}
f_{t}(p) & =\int_{G} f\left(q^{-1} p\right) \mu(t, d q) \\
& =\int_{G} f(q) \mu\left(t, p d q^{-1}\right)
\end{aligned}
$$

Consequently $\mu\left(t, p d q^{-1}\right)=g(t, p, q) \mu(d q)$. In particular (cf. [4], page 265)

$$
\mu(t, d q)=g\left(t, 1, q^{-1}\right) \Delta\left(q^{-1}\right) \mu(d q)=h(t, q) \mu(d q) \mu(d q \cdot r)=\Delta(r) \mu(d q)
$$

where $\Delta$ is the modular function of $G$. Then

$$
\mu(t, p d q)=h(t, p q) \mu(d q)=g\left(t, p, q^{-1}\right) \Delta\left(q^{-1}\right) \mu(d q)
$$

so that $h(t, p q)=g(t, p, q)^{-1} \Delta\left(q^{-1}\right)$. Here $h(t, p)$ satisfies the following two conditions:
(i) $\|h(t, \cdot)\|_{V}=\operatorname{esssup}_{q}|\Delta(q) h(t, q)|=\operatorname{ess} \sup _{q}\left|g\left(t, 1, q^{-1}\right)\right|<\infty$,
(ii) $\operatorname{ess} \sup _{q}\left|\Delta(q)\left\{h\left(t, p^{-1} q\right)-h(t, q)\right\}\right|=\operatorname{ess}_{\sup }^{q}\left|g\left(t, p^{-1}, q^{-1}\right)-g\left(t, 1, q^{-1}\right)\right| \rightarrow 0$ as $p \rightarrow 1$.
As anticipated in the notation, the Banach space of functions satisfying (i) and (ii), with the norm given by (i), is called $V$. The functions in $V$ are equivalent to continuous functions so we take $V$ to be a space of continuous functions. The representation $L(p)$ by left-translations of $G$ in $V$ is strongly continuous. In order to use this fact we must observe that

$$
\int_{G} h\left(t_{1}, q^{-1} p\right) h\left(t_{2}, q\right) \mu(d q)=h\left(t_{1}+t_{2}, p\right)
$$

To prove this we notice that for $f$ in $C_{0}$

$$
\begin{aligned}
\int_{G} f\left(q^{-1} r\right) h\left(t_{1}+t_{2}, q\right) \mu(d q) & =U\left(t_{1}+t_{2}, C_{0}\right) f(r) \\
& =U\left(t_{1}, C_{0}\right) U\left(t_{2}, C_{0}\right) f(r) \\
& =\int_{G}\left\{f\left(p^{-1} q^{-1} r\right) h\left(t_{1}, p\right) \mu(d p)\right\} h\left(t_{2}, q\right) \mu(d q) \\
& =\int_{G}\left\{\int_{G} f\left(p^{-1} r\right) h\left(t_{1}, q^{-1} p\right) \mu(d p)\right\} h\left(t_{2}, q\right) \mu(d q) \\
& =\int_{G} f\left(p^{-1} r\right)\left\{\int_{G} h\left(t_{1}, q^{-1} p\right) h\left(t_{2}, q\right) \mu(d q)\right\} \mu(d p)
\end{aligned}
$$

However, setting $U\left(t_{2}, V\right) h\left(t_{1}, \cdot\right)=h_{t_{2}}\left(t_{1}, \cdot\right)$, we also have

$$
h_{t_{2}}\left(t_{1}, p\right)=\int_{G} h\left(t_{1}, q^{-1} p\right) h\left(t_{2}, q\right) \mu(d q)
$$

Consequently $h\left(t_{1}+t_{2}, p\right)=h_{t_{2}}\left(t_{1}, p\right)$. Then $h\left(t_{1}+t_{2}, q^{-1} \cdot\right)=L(q) h_{t_{2}}\left(t_{1}, \cdot\right)$ is an analytic function of $t_{2}$ and $q$ with values in $Z$. Applying the linear functional which evaluates a function at the identity we see that $h(t, p)$ is an analytic function of $t$ and $p$.

Note added in revision. This version of the thesis was prepared by Anthony Pulido (Institute for Advanced Study, Princeton) and Derek Robinson (Australian National University, Canberra) in November-December 2017. It differs from the 1960 original in two respects. First, a large number of typographical errors have been corrected. Secondly, some of the display formulae have been reformatted and a small number of additions and rearrangements have been made to the text for clarity.

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[^0]:    ${ }^{1} \mathrm{Cf}$. the construction on page 12 of $\mathbf{1 2}$.

